

# living planet symposium | BONN 23–27 May 2022

TAKING THE PULSE  
OF OUR PLANET FROM SPACE



## Application of Very-High-Resolution Optical CubeSat Images at a Rewetted Peatland Site

Zhan Li<sup>1,2,\*</sup>, Daniel Scheffler<sup>2</sup>, Nicholas C. Coops<sup>3</sup>, Nicholas Leach<sup>3</sup>, Mirjam Weituschat<sup>4</sup>, Aram Kalhori<sup>2</sup>, Christian Wille<sup>2</sup>, Torsten Sachs<sup>2</sup>

1: Department of Remote Sensing, Helmholtz Centre for Environmental Research – UFZ, Leipzig, 04318, Germany

2: Remote Sensing and Geoinformatics, Helmholtz Centre Potsdam, GFZ German Research Centre for Geosciences, Telegrafenberg, 14473 Potsdam, Germany

3: Integrated Remote Sensing Studio, Faculty of Forestry, University of British Columbia, 2424 Main Mall, Vancouver BC, V6T1Z4, Canada

4: Institute of Botany and Landscape Ecology, University of Greifswald, Domstraße 11, 17489 Greifswald, Germany

\*: Currently at BASF Digital Farming GmbH, Cologne, 50678, Germany

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# What is Peatland?

- Peat is usually defined as soil with a required minimum percentage of soil organic carbon (e.g., 20% - 50% per dry mass). (Joosten and Clarke, 2002; IUSS Working Group WRB, 2015)
- Peatland is peat-covered terrain, usually with a required minimum depth of peat (most common threshold is 30 cm). (Joosten and Clarke, 2002)



Kenya



Canada



Russia



Sweden



Malaysia



Argentina



(Parish et al., 2008)

(Joosten and Clarke, 2002)

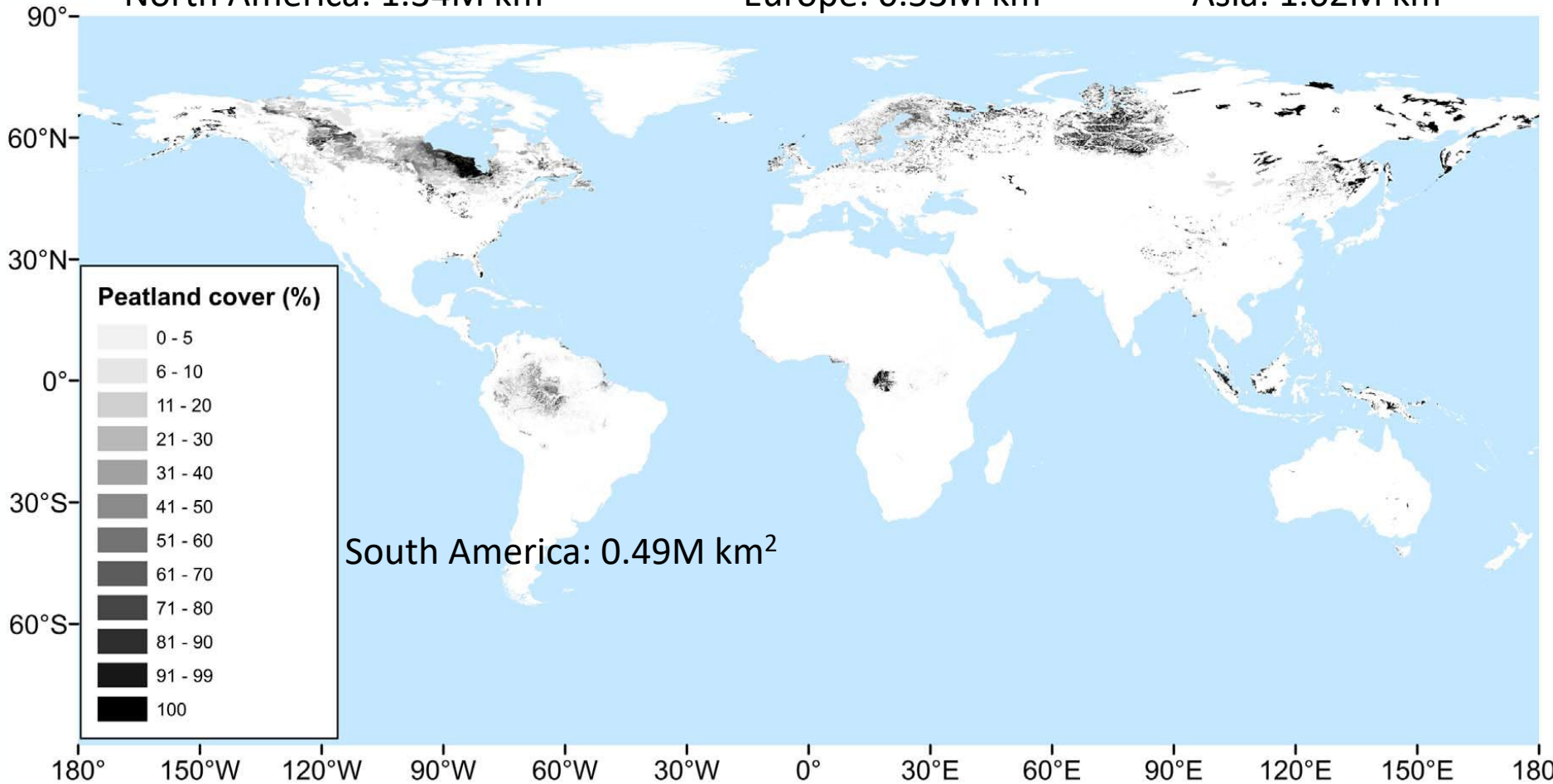
# Why Peatlands?

**4.23M km<sup>2</sup> (Including drained peatlands), ~3% land area**

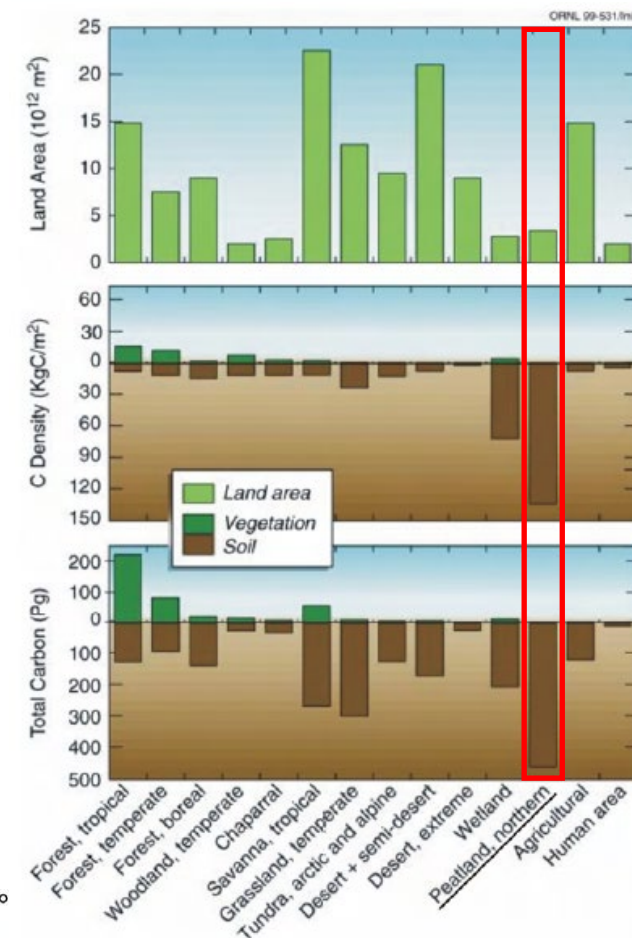
North America: 1.34M km<sup>2</sup>

Europe: 0.53M km<sup>2</sup>

Asia: 1.62M km<sup>2</sup>



**25-30% of soil carbon**  
**50-75% of atmospheric CO<sub>2</sub>**

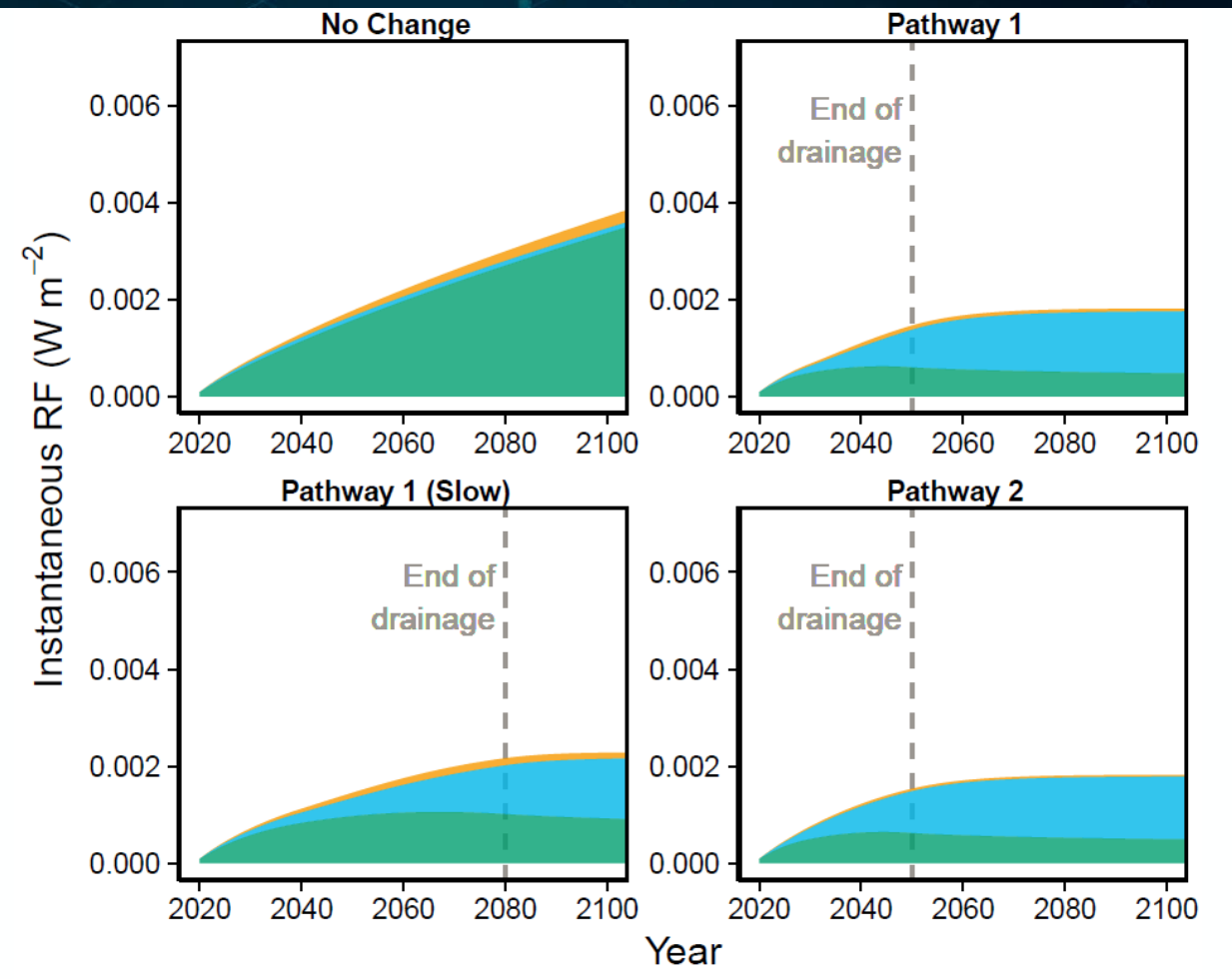
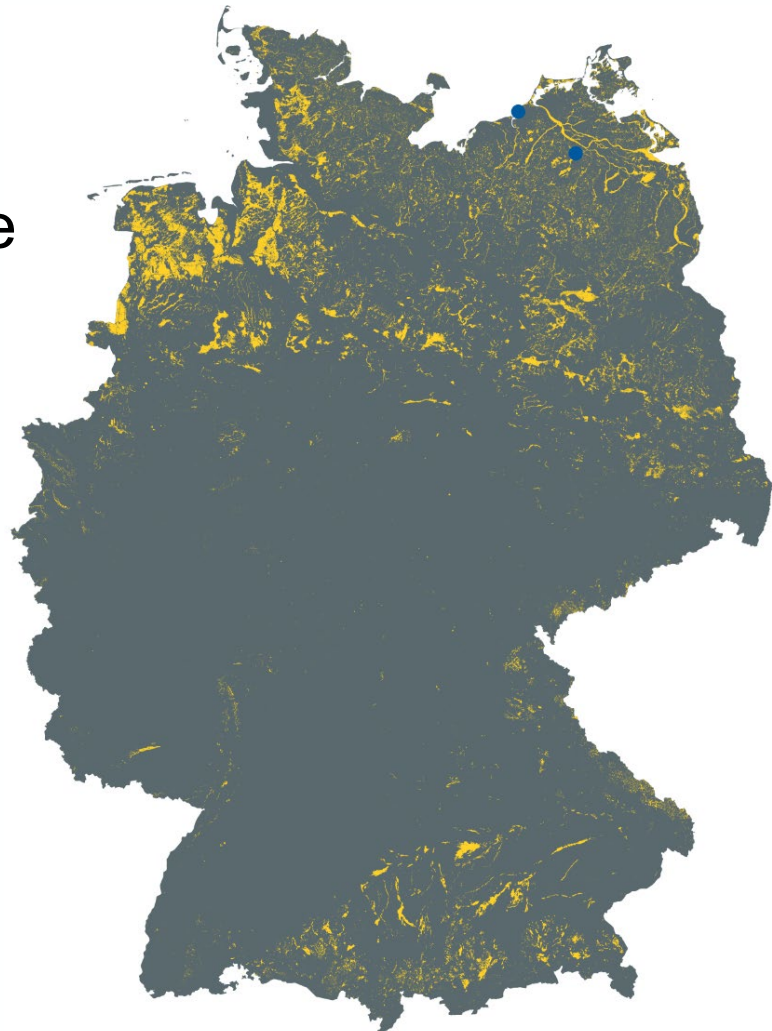


(Xu et al., 2018)

(Parish et al., 2008; Rydin and Jeglum, 2013; Adams and Faure, 1998)

# Drained Peatland & Rewetting

1.41 Mha of organic soil in Germany, more than 98% is drained

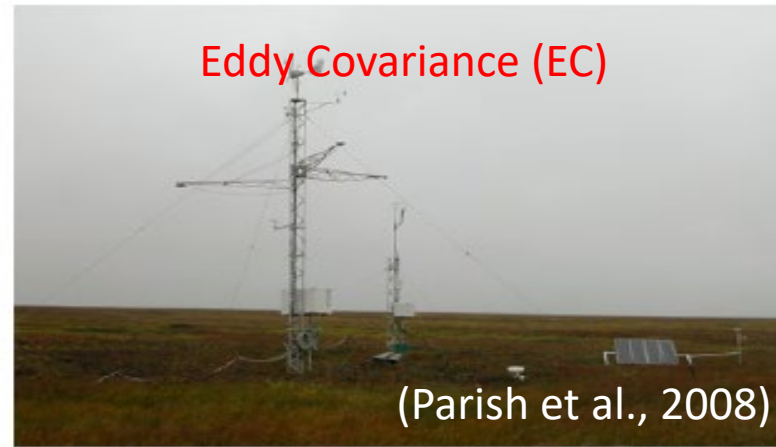


■ N<sub>2</sub>O  
 ■ CH<sub>4</sub>  
 ■ CO<sub>2</sub>  
 (Tanneberger et al., 2021)

Greifswald Mire Centre  
 (Trepel et al., 2017)

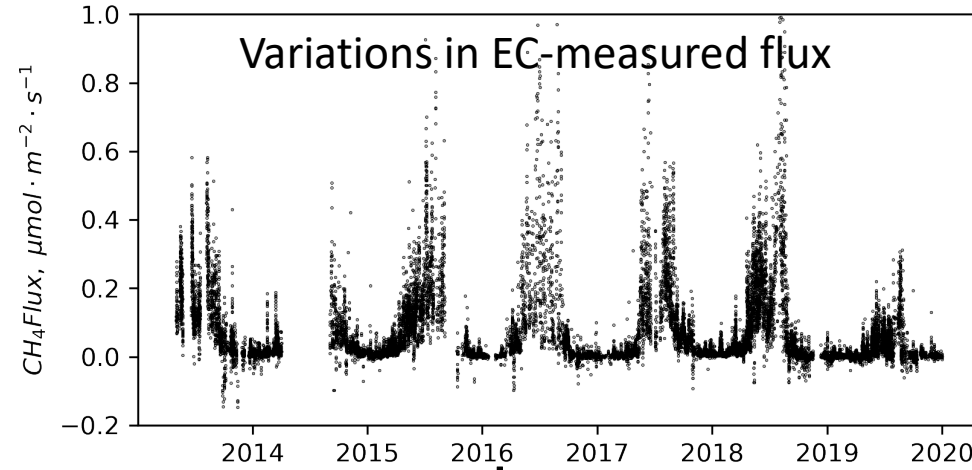
■ Organic Soil Distribution for Potential Peatlands  
● Experimental Sites for Carbon Flux Measurement

# Measure CO<sub>2</sub> and CH<sub>4</sub> fluxes

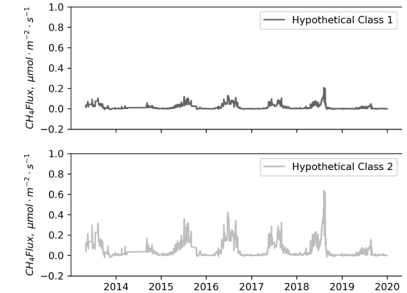


# How can CubeSats VHR images help analyze EC measurements of carbon flux?

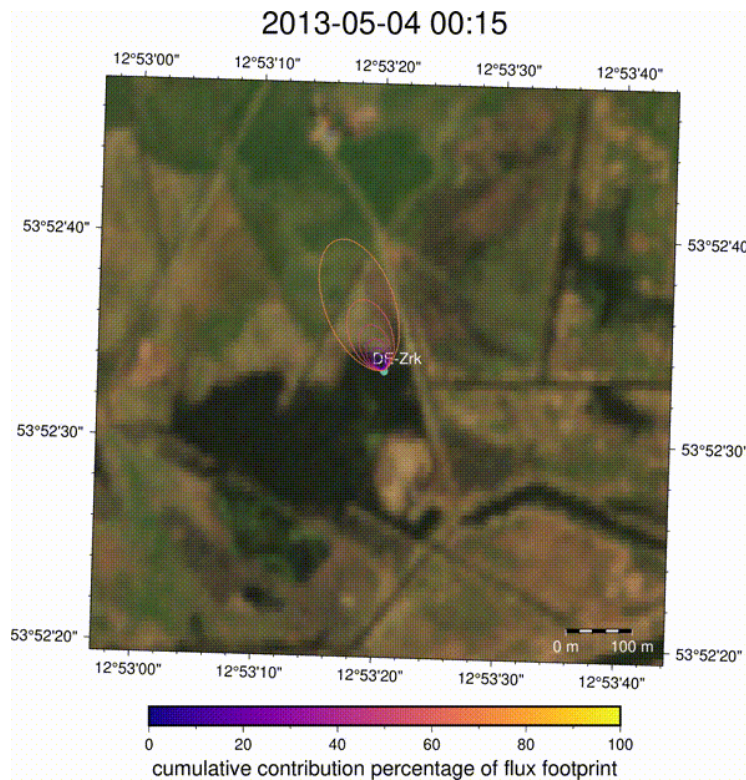
- Time series of carbon flux



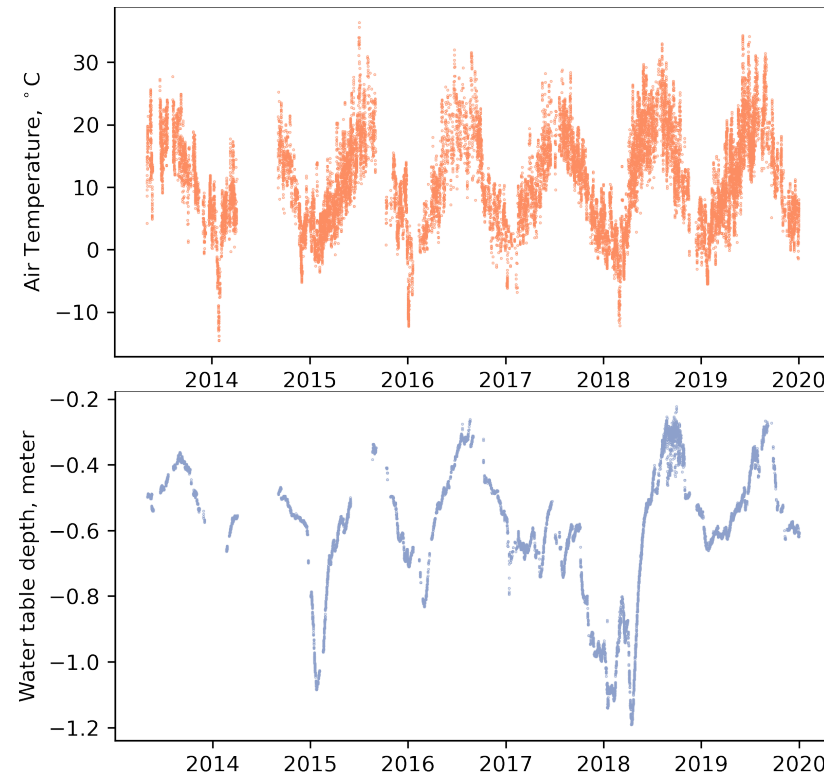
- Decomposed carbon fluxes per relative homogeneous surface cover



Spatial variations in surface cover and condition within EC footprints



Temporal variations in environmental conditions



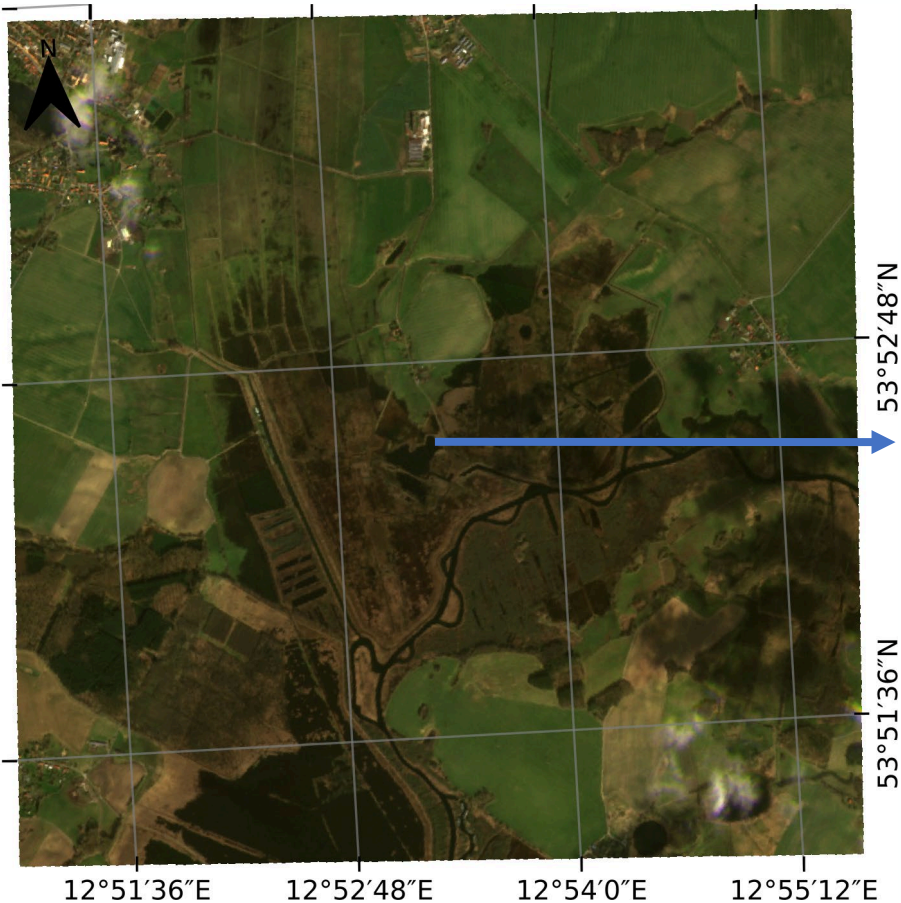
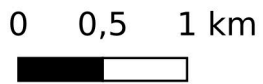
- Time series of environmental conditions

- Time series of Very-High-Resolution (VHR) images
- Time series of EC footprints

# Test Site: Zarnekow



True-color composite of an example PlanetScope image acquired on 2020-03-14 before normalization.



- **Ground Observation<sup>1</sup>**
  - 2013 to present
  - CO<sub>2</sub> and CH<sub>4</sub> flux
  - Biomet data
  - Water table depth
  - Soil temperature and heat flux
- **Earth Observation<sup>2</sup>**
  - 2013 to 2020
  - ~120 VHR images from RapidEye (5-m) and PlanetScope (3-m) sensors
  - 5 km x 5 km Region

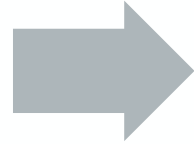
<sup>1</sup>:Site PI: Prof. Dr. Torsten Sachs, [torsten.sachs@gfz-potsdam.de](mailto:torsten.sachs@gfz-potsdam.de)

<sup>2</sup>:ESA TPM Programme <sub>7</sub>

# Workflow

## Image Normalization

- Consistent time series of CubeSat VHR images



## Surface Partition

- Relatively homogeneous surface covers based on vegetation and water coverages



## Flux Decomposition

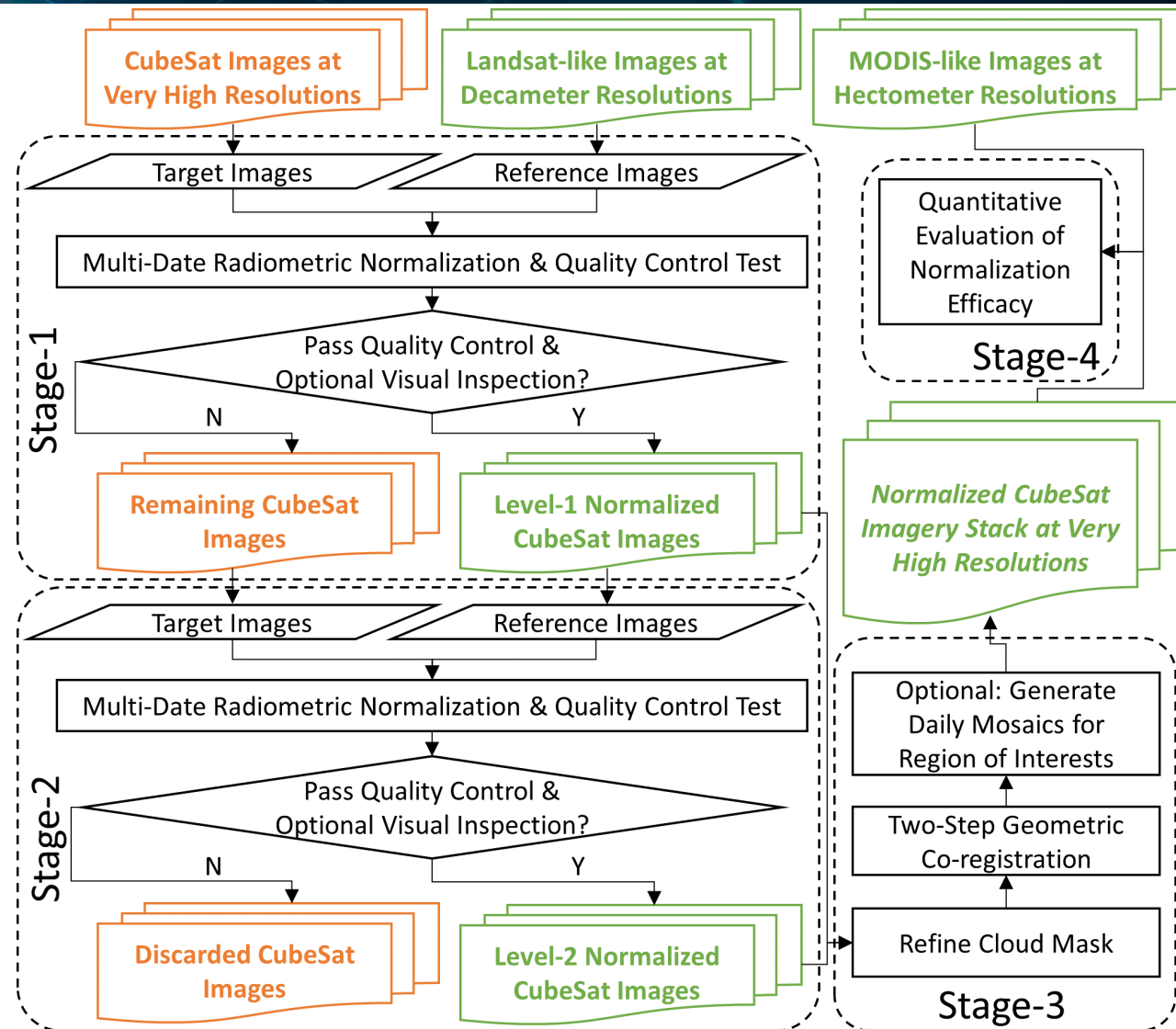
- Time series of cover-specific gas flux



# Image Normalization

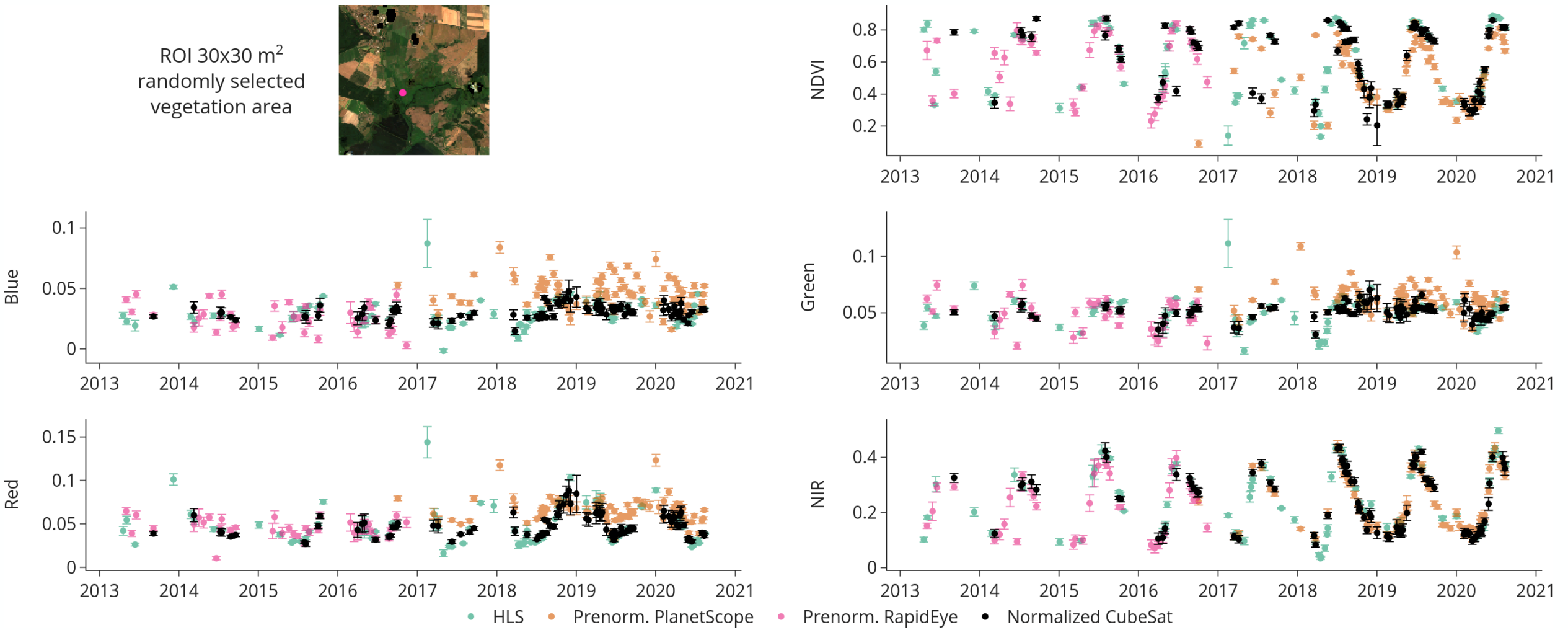
A procedure customized to our small-area case to generate quasi-Analysis Ready Data (ARD)

(Li et al., 2021)



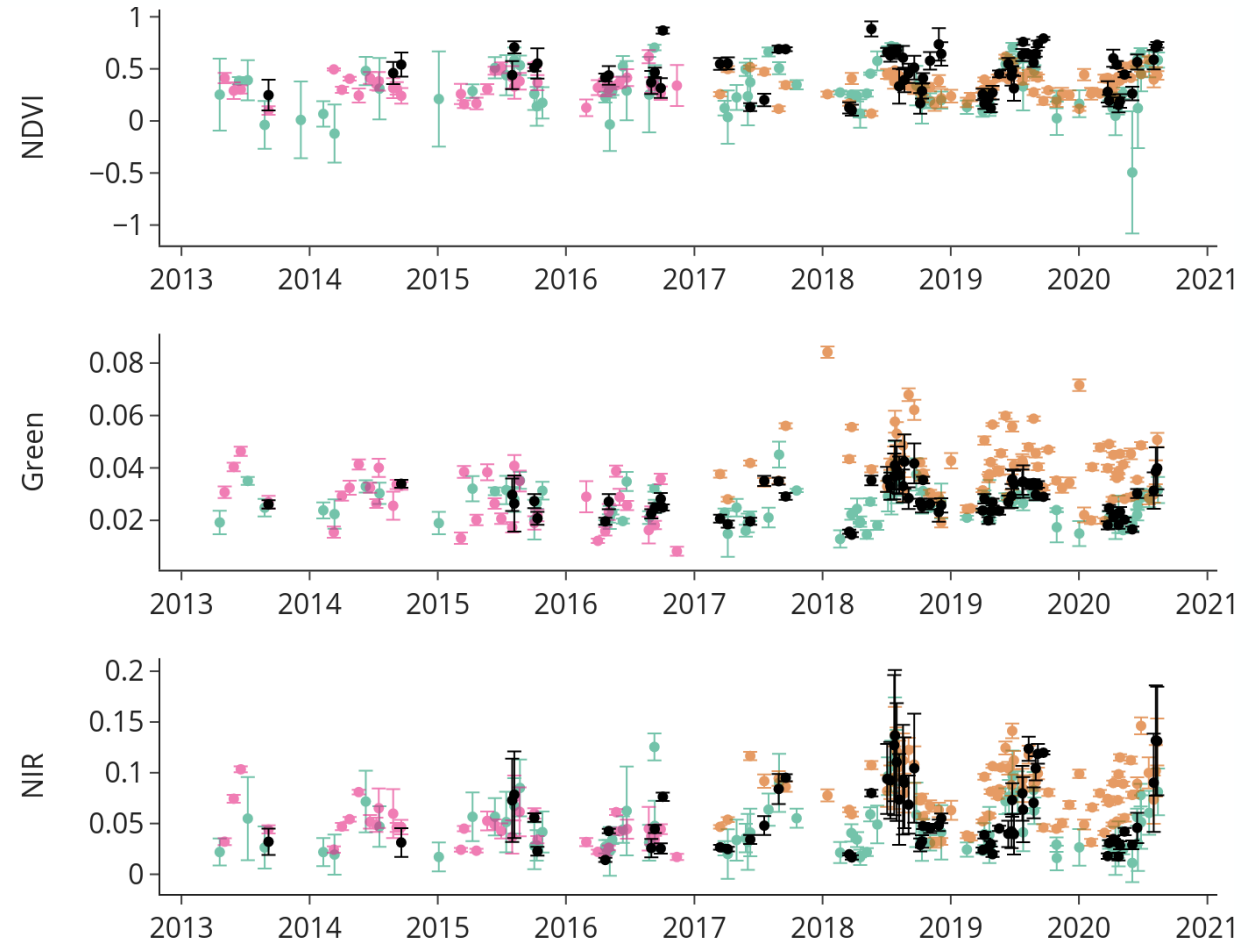
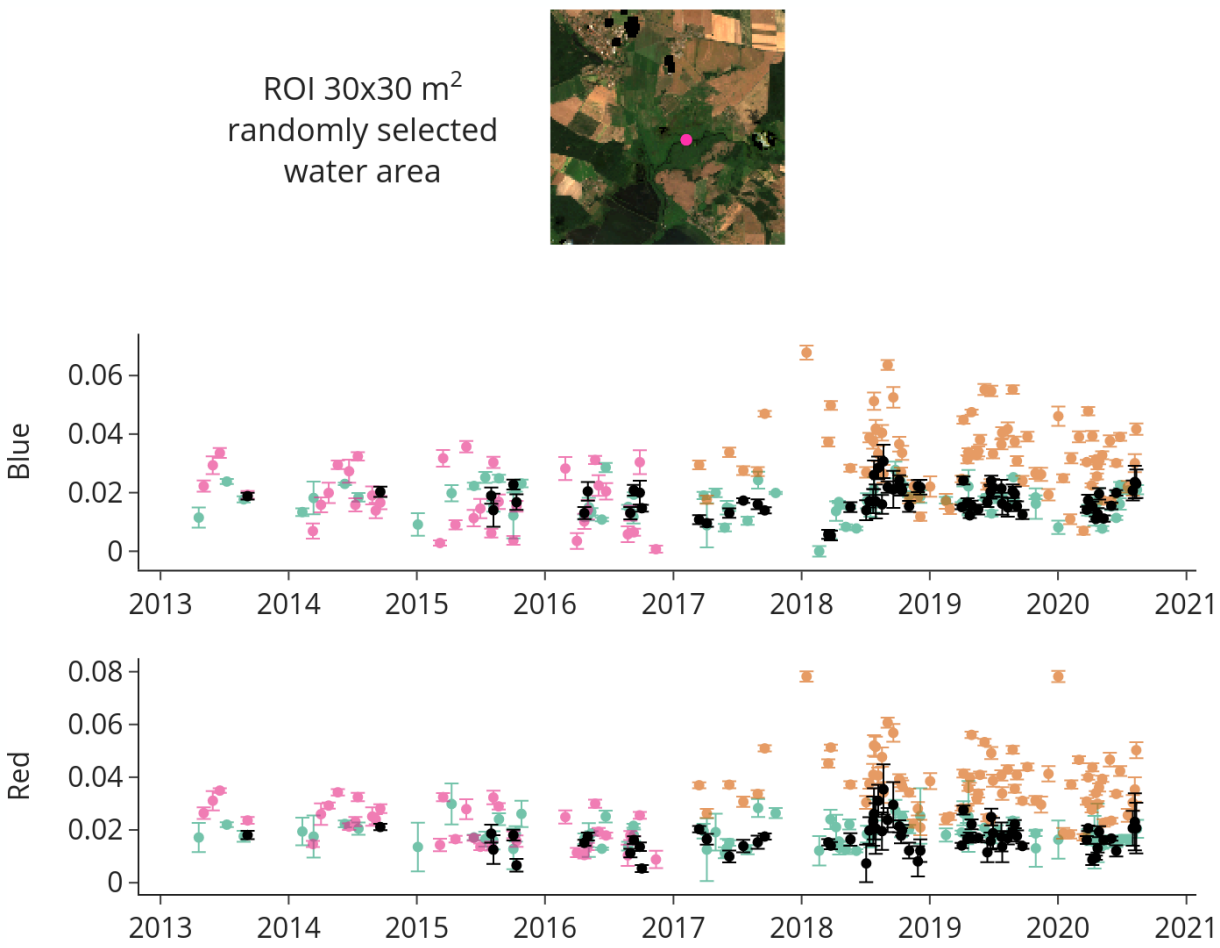
# Image Normalization

ROI 30x30 m<sup>2</sup>  
randomly selected  
vegetation area



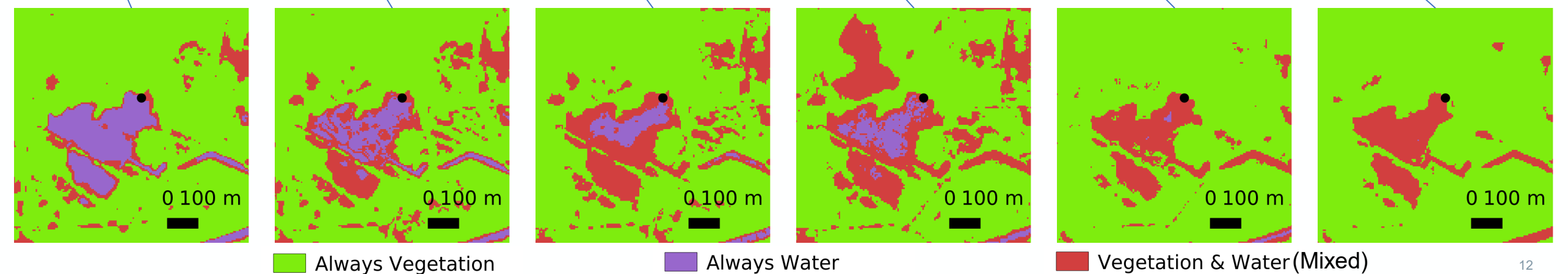
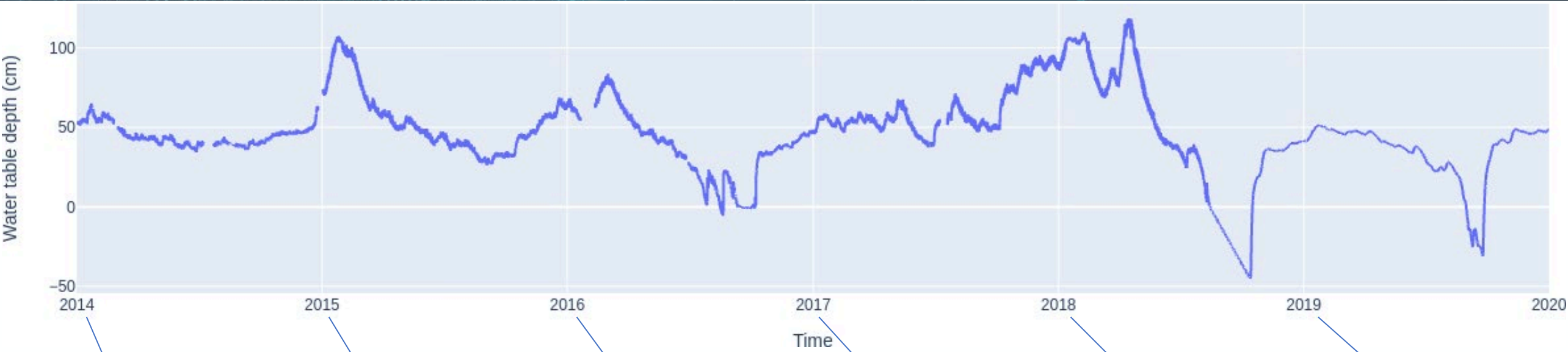
# Image Normalization

ROI 30x30 m<sup>2</sup>  
randomly selected  
water area



● HLS ● Prenorm. PlanetScope ● Prenorm. RapidEye ● Normalized CubeSat

# Surface Partition



# Flux Decomposition

## Nonparametric Linear Unmixing

- In a short temporal window and in a cluster of measurements under similar values of environment variables:
  - Assume no temporal variation of cover-specific flux.
  - Assume only spatial variation of surface cover fractions within EC measurement footprints



$m$  measurements  
 $k$  cover types

Fractional contribution  
of surface cover types



$m \times k$



Cover-specific flux

- per environmental cluster
- per temporal window



$k \times 1$



EC-measured flux



$m \times 1$

## Generate half-hourly footprint-weighted fractions of surface cover types

- Roughness length and zero displacement height (Graf et al., 2014)
- Georeferenced half-hourly footprint rasters (Kormann and Meixner, 2001)

## Cluster selected environment variables per temporal moving window

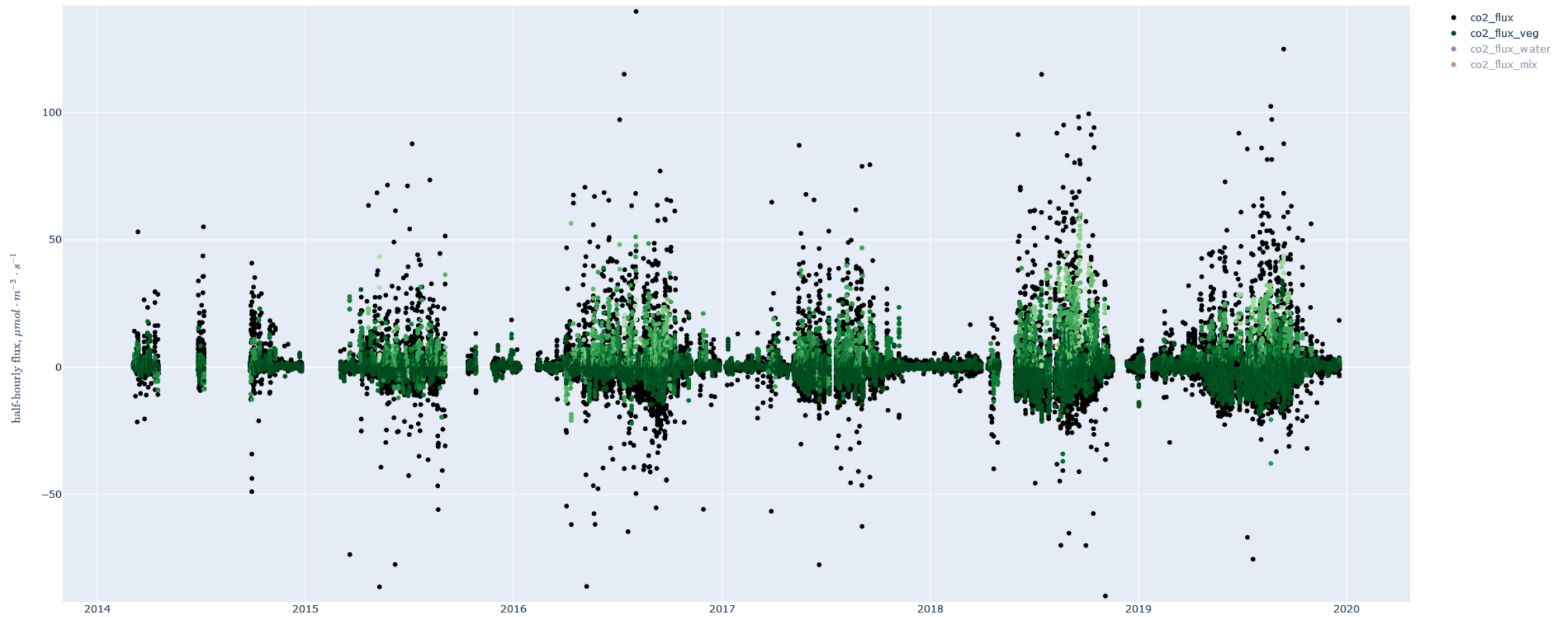
- Analysis of correlation and feature importance (16 variables selected)
- Agglomerative clustering

## Linear unmix gas flux per environmental cluster in each short temporal window

- Constrained linear least square regression
- Similar to (Chen et al., 1999) for the decomposition of airborne flux measurements

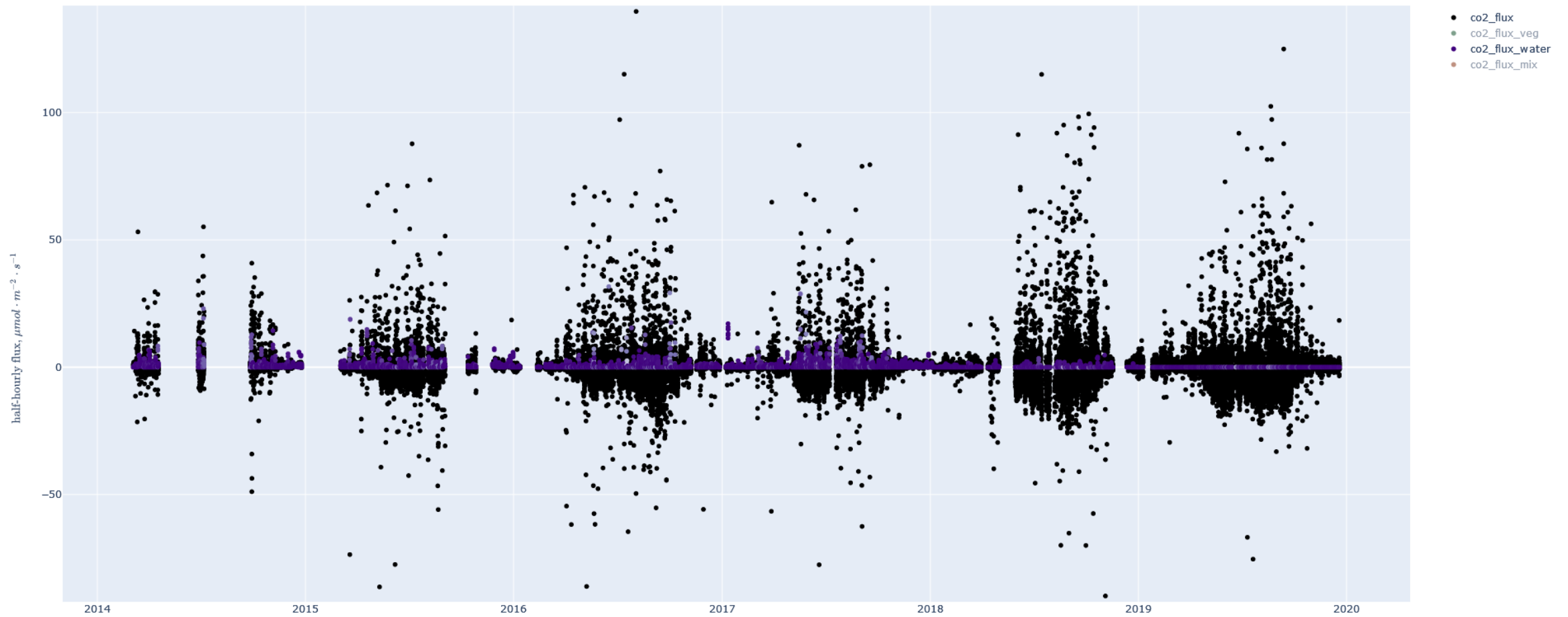
# Flux Decomposition

## CO<sub>2</sub> Flux, EC-measured & **Vegetation-cover-specific**



# Flux Decomposition

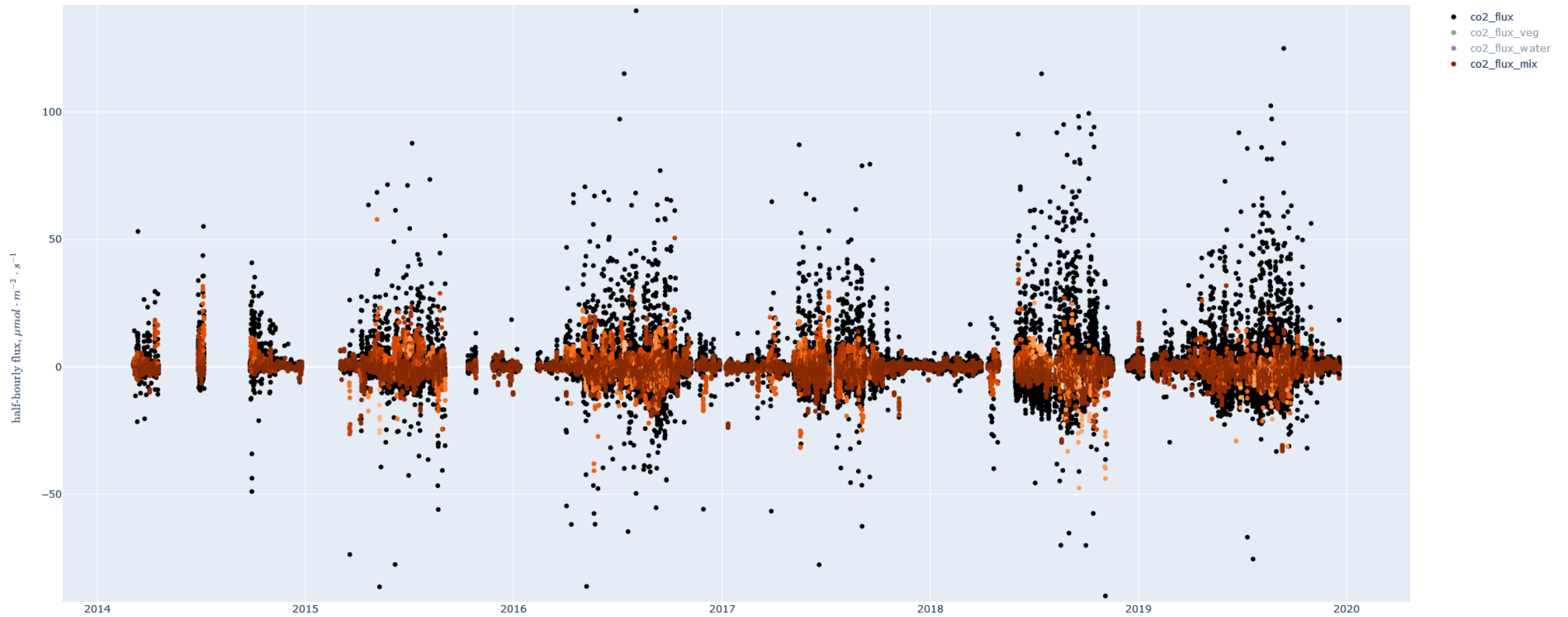
## CO<sub>2</sub> Flux, EC-measured & Water-cover-specific





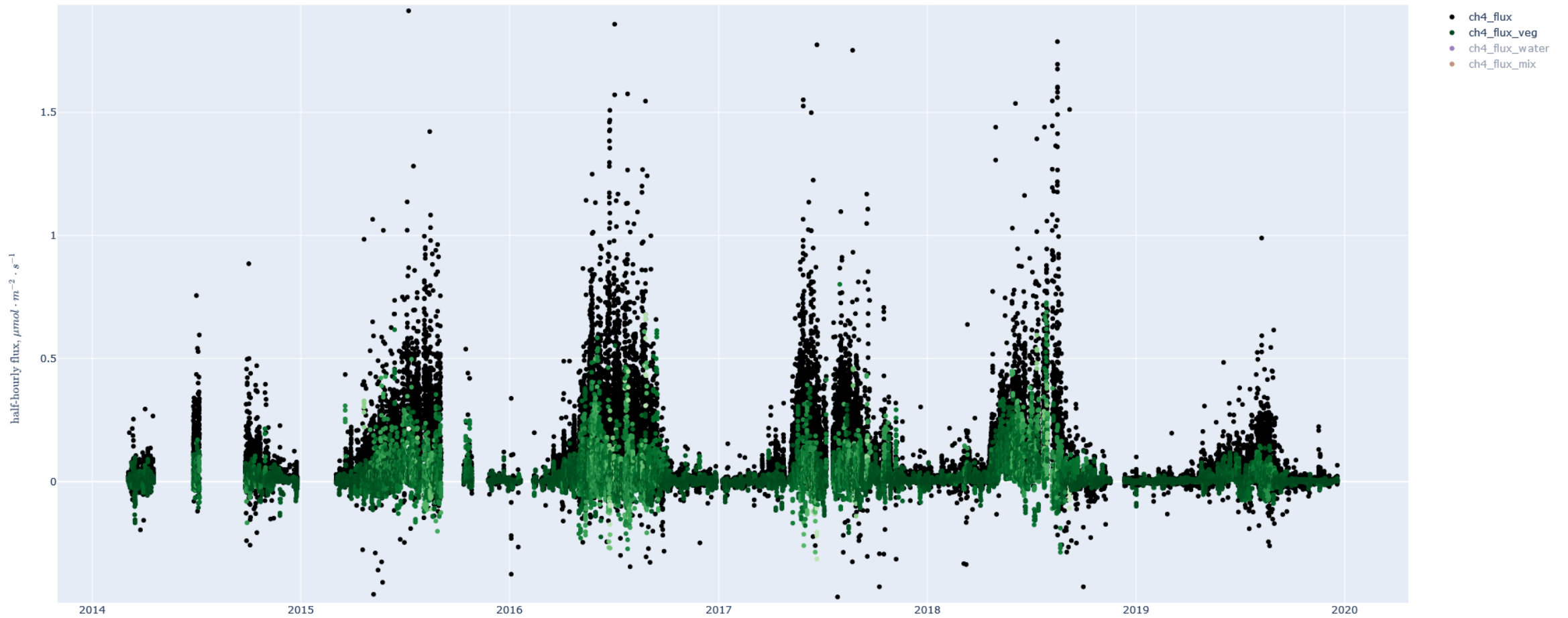
# Flux Decomposition

## CO<sub>2</sub> Flux, EC-measured & Mixed-cover-specific



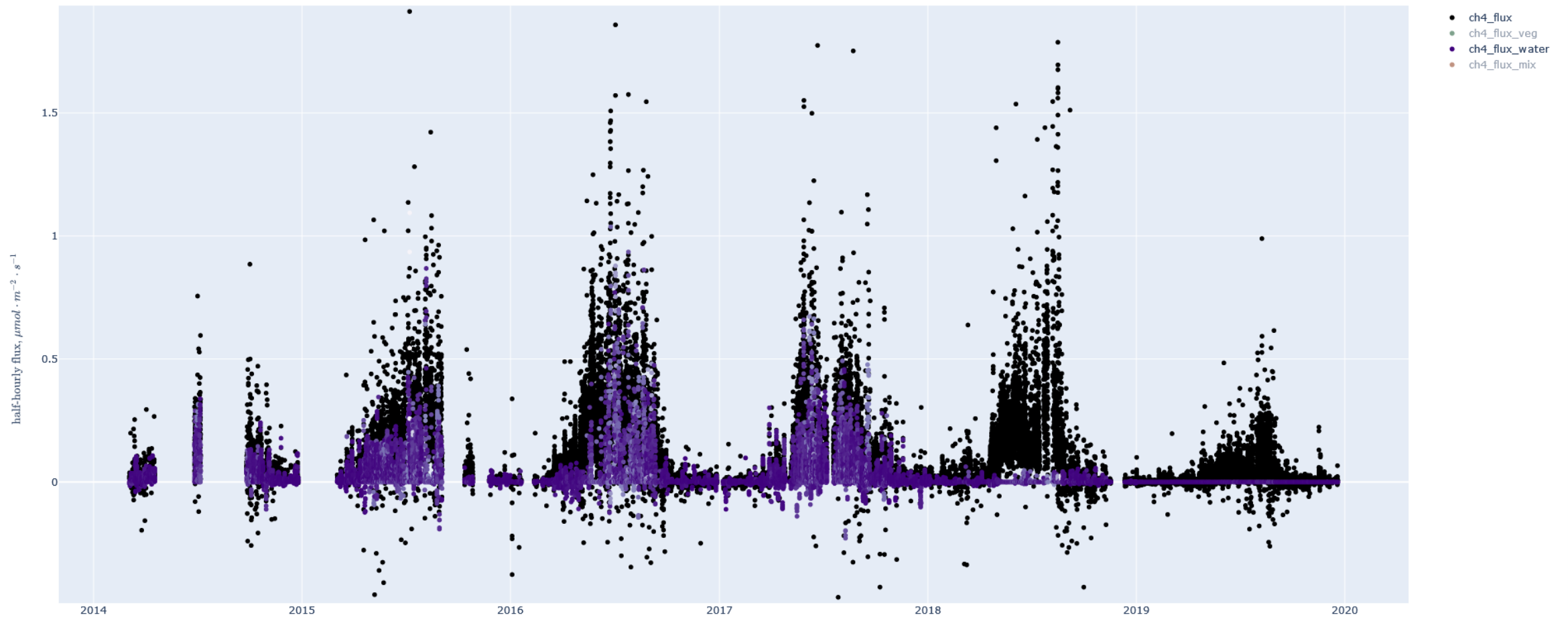
# Flux Decomposition

## CH<sub>4</sub> Flux, EC-measured & **Vegetation-cover-specific**



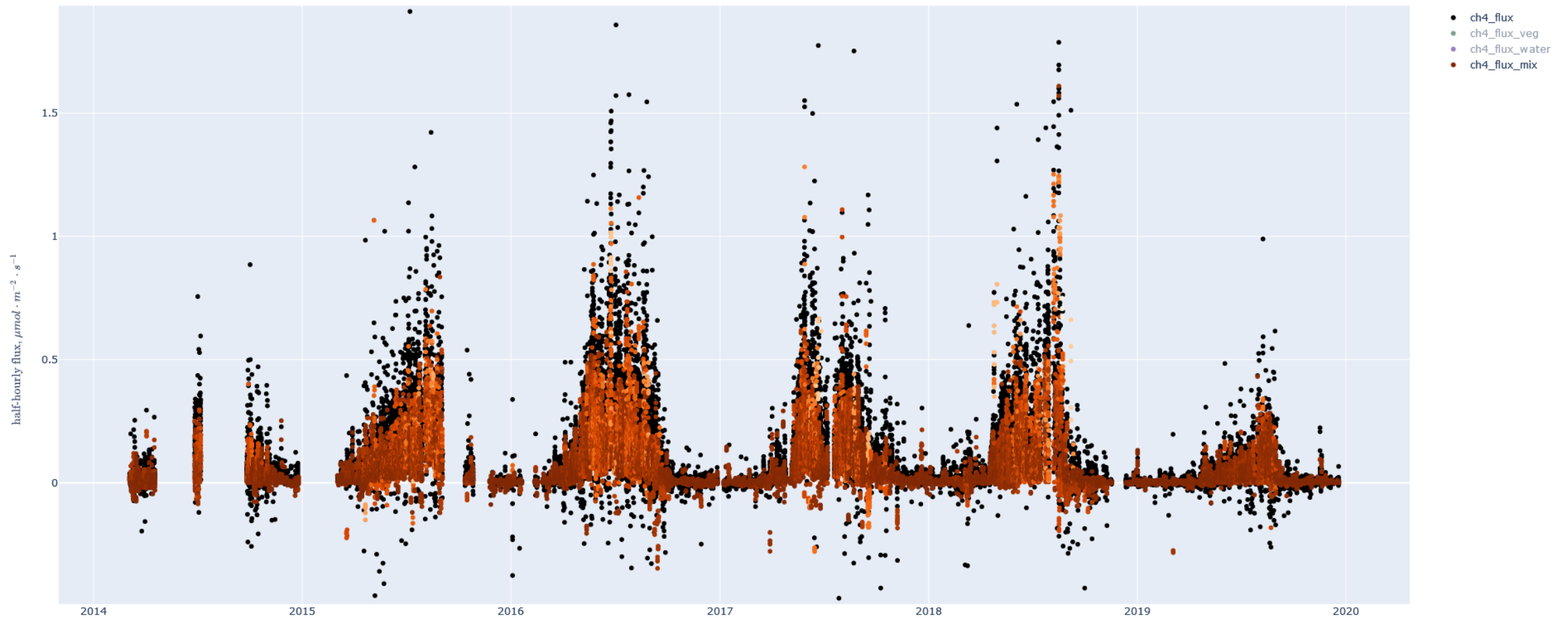
# Flux Decomposition

## CH<sub>4</sub> Flux, EC-measured & Water-cover-specific

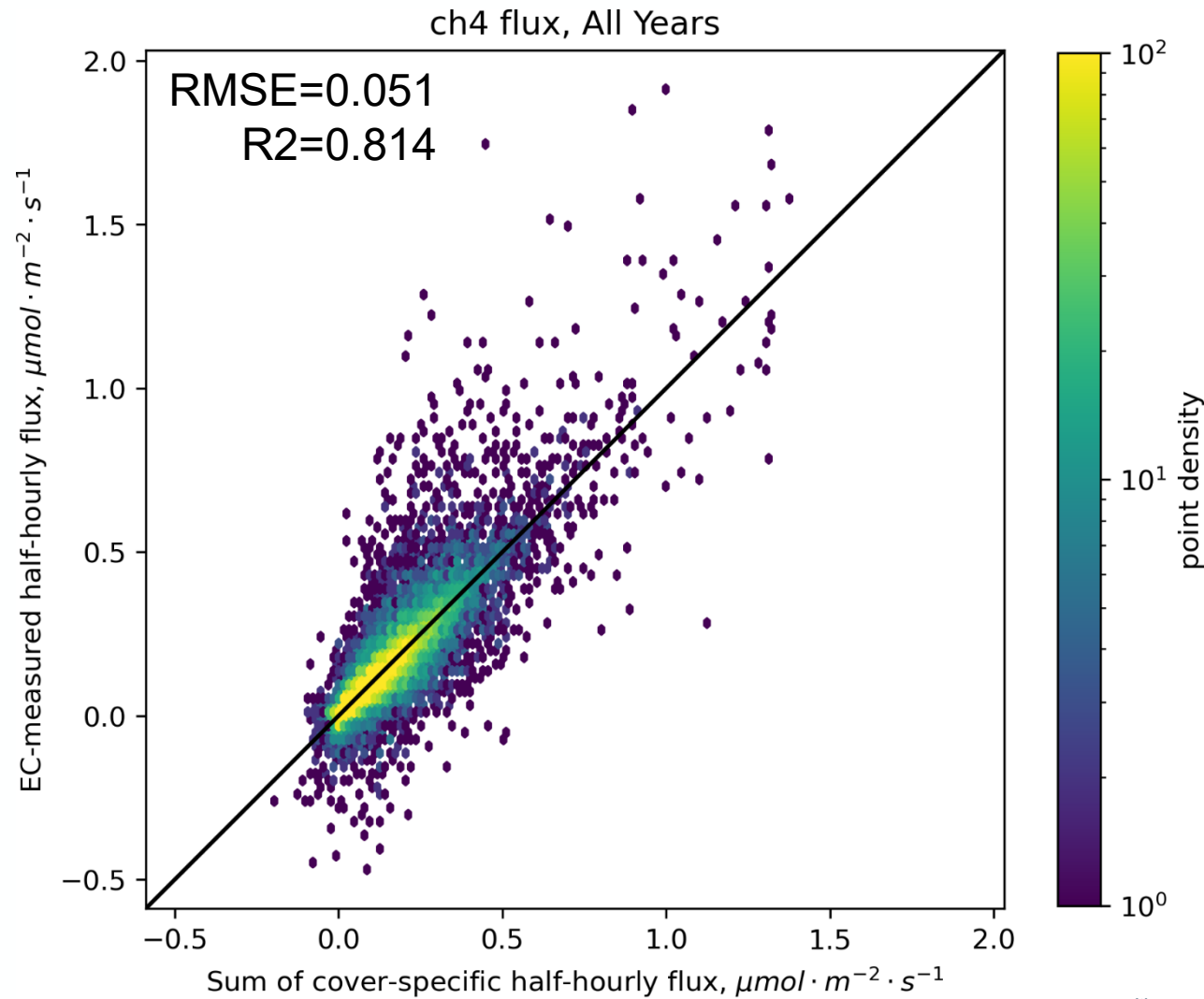
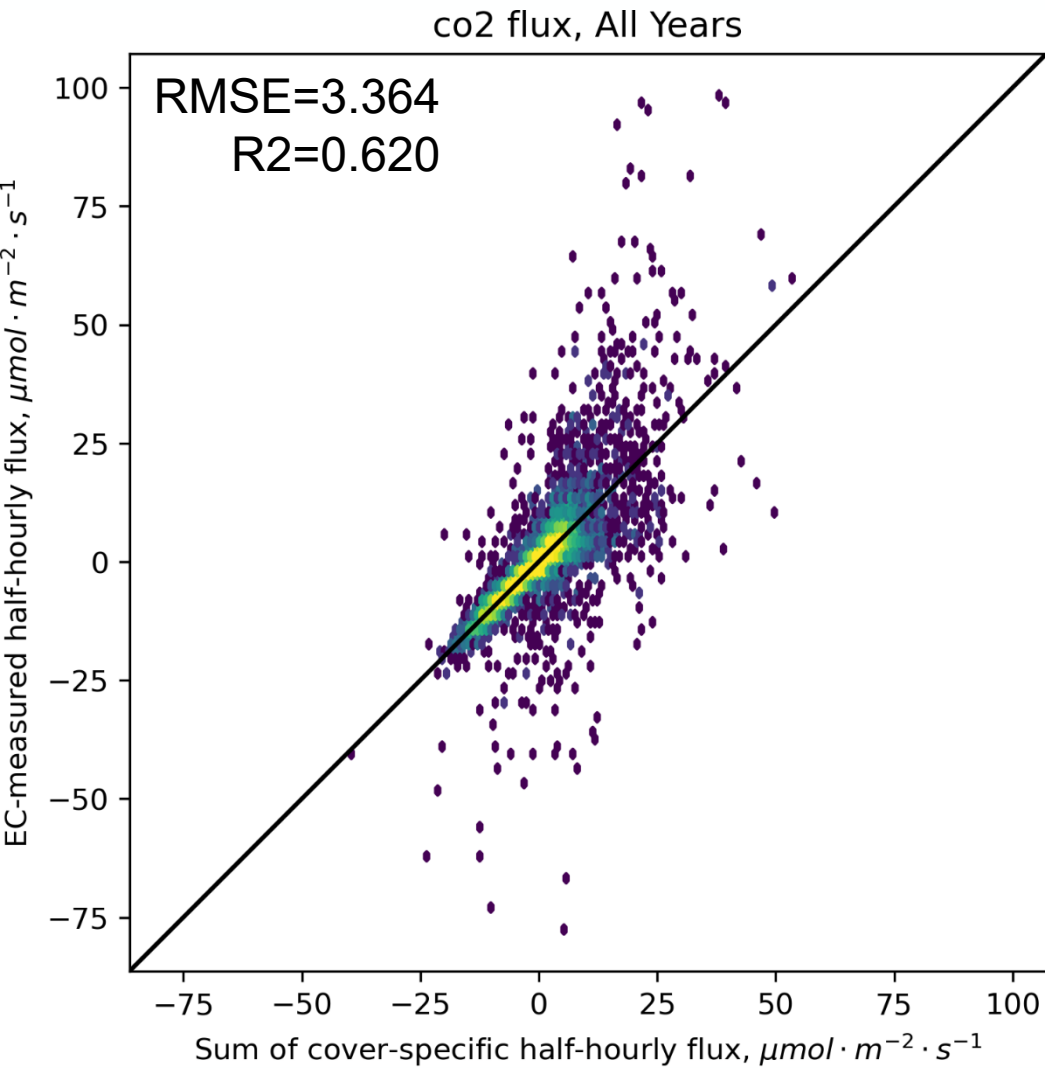


# Flux Decomposition

## CH<sub>4</sub> Flux, EC-measured & Mixed-cover-specific



# Flux Decomposition



# Concluding Remarks

- Know the areal coverage of your EC flux measurements!
  - EC measurements are areal like imagery data, not point-based.
  - Geo-referenced footprint raster data are needed for using VHR images with EC measurements<sup>1</sup>.
- Vegetation as a proxy sensor of soil and belowground conditions.
  - Change in areas of vegetation and surface water is a reasonable indicator of changes in water table depth (at least at this fen peatland in Northeast Germany!).
- Reasonable estimates of cover-specific flux using linear unmixing.
  - Decomposition of CH<sub>4</sub> performs better than CO<sub>2</sub>.

<sup>1</sup>:My scripts to generate geo-referenced footprint rasters in NetCDF, <https://github.com/zhanlilz/scripts-ec-z0d-fp>

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