



Classifying direct drivers of forest disturbance in near realtime, using multi-sensor Sentinel data and deep learning

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ESA Living Planet Symposium 27-05-2022

Background – Near real-time disturbance alerts (RADD)





RADD alerts (Reiche et al. 2021 Env. Res. Lett.)

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Concept – Classifying direct disturbance drivers



- At the level of a detected forest disturbance patch (spatially explicit)
- As timely as possible (near real-time)
- Using Sentinel-1-based RADD alerts, Sentinel-1 and Sentinel-2 data, and a convolutional neural network
- Mapping 4 classes:
 - Road development
 - Selective logging
 - Mining
 - Smallholder agriculture

Concept – Convolutional neural network



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Methods – Training sample acquisition





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Methods – Study areas





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Results – Image classification



6 months

Sm. agriculture (0.77)



Mining (0.96)





2 months

Sel. logging (0.97)



Road dev. (0.86)



Sel. logging (0.69)



Sentinel-2



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Results – Near real-time scenario



Classifying disturbance patches:

- Within 2 months
- > 0.80 confidence

Alerts: 2021-2022

Road developmentSelective loggingMining



Results – Classification accuracies





Precision	Recall	F1
Sm. agriculture		
P: 0.976	R: 0.951	F1: 0.964
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Road development		
P: 0.773	R: 0.872	F1: 0.820
Selective logging		
P: 0.876	R: 0.749	F1: 0.808

MiningP: 0.771R: 0.874F1: 0.819

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Take-aways and conclusion



- Drivers could be classified rapidly with accuracies up to 0.85 for different user scenarios.
- Driver classifications are most accurate when a longer postdisturbance time period or a confidence threshold is used.
- Potential end users could weigh classification rapidness, confidence and accuracy suiting their needs.



Thank you

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