

# living planet | BONN symposium | 23-27 May 2022

TAKING THE PULSE  
OF OUR PLANET FROM SPACE



**UNRAVELING THE SPATIAL HETEROGENEITY OF FLOATING MACROPLASTICS AT SEA USING UNMANNED AERIAL VEHICLES (UAVs)**

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<sup>1</sup>The Ocean Cleanup

25 May 2022



# UAVS

Timeframe:  
July – August 2021

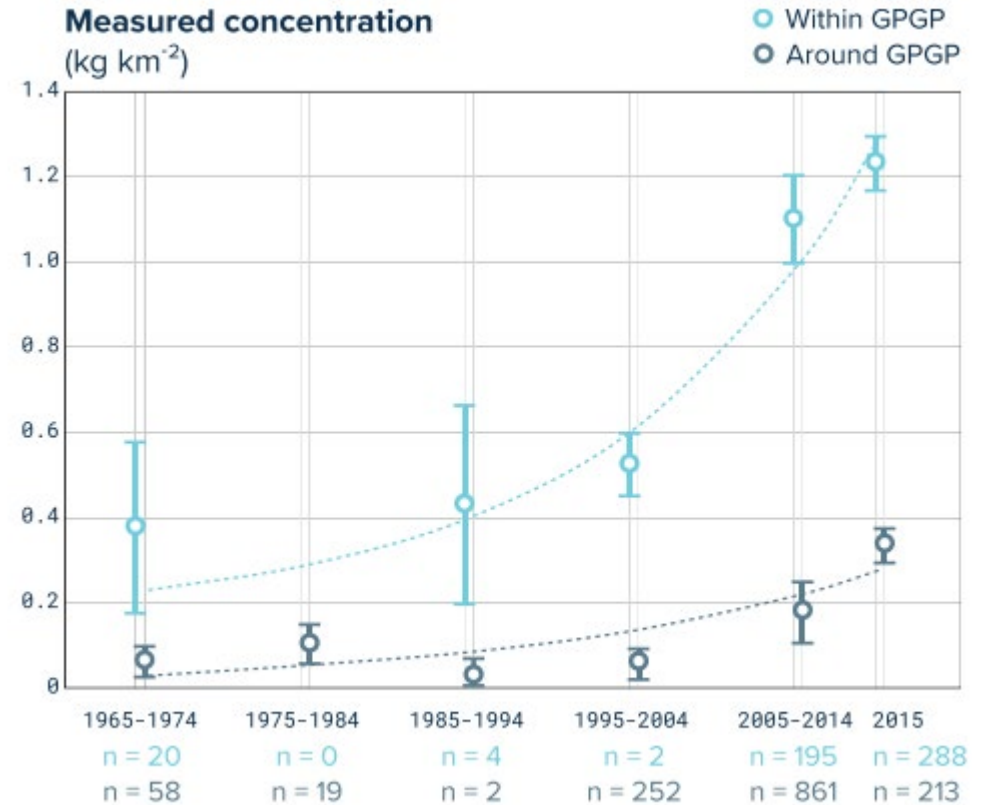
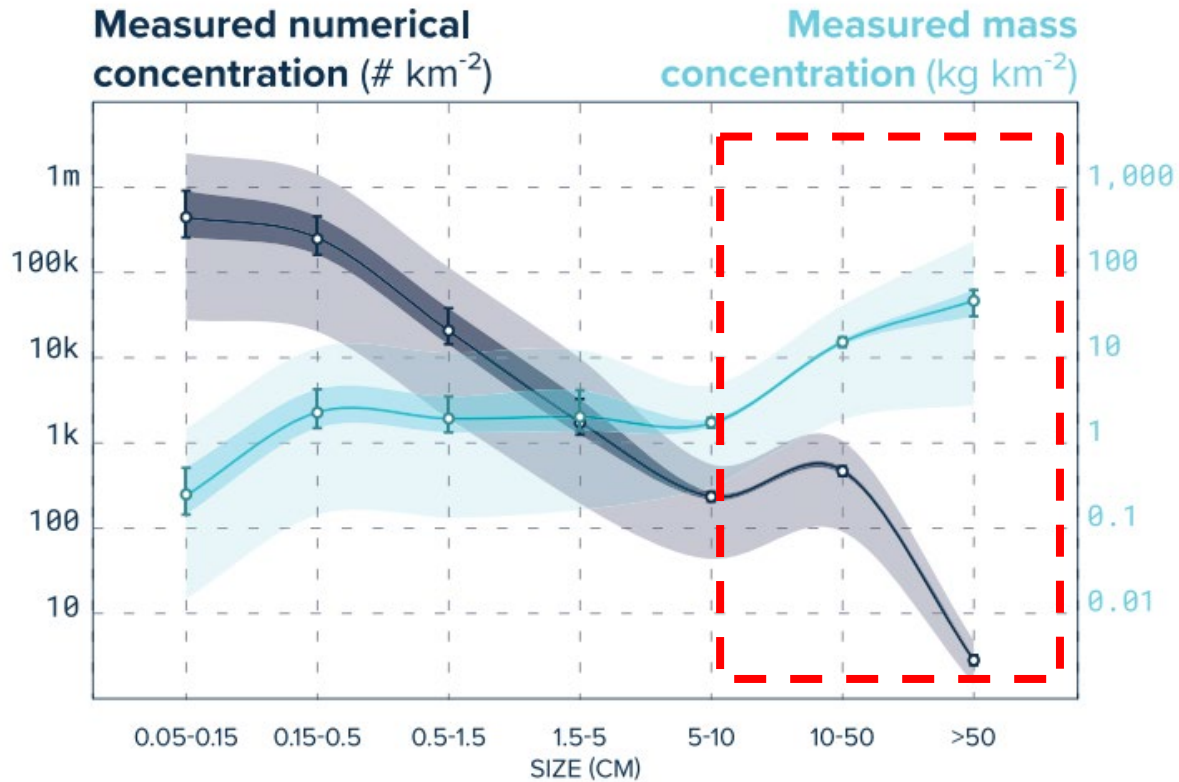
UAV:  
Aeromapper Talon  
Amphibious

Operator:  
Oceans Unmanned



Wingspan:	2m
Weight:	3600g
Cruise Speed:	62km/h
Maximum Speed:	85km/h
Range:	>30 km
Endurance:	Two hours
Maximum Altitude:	4,500m asl

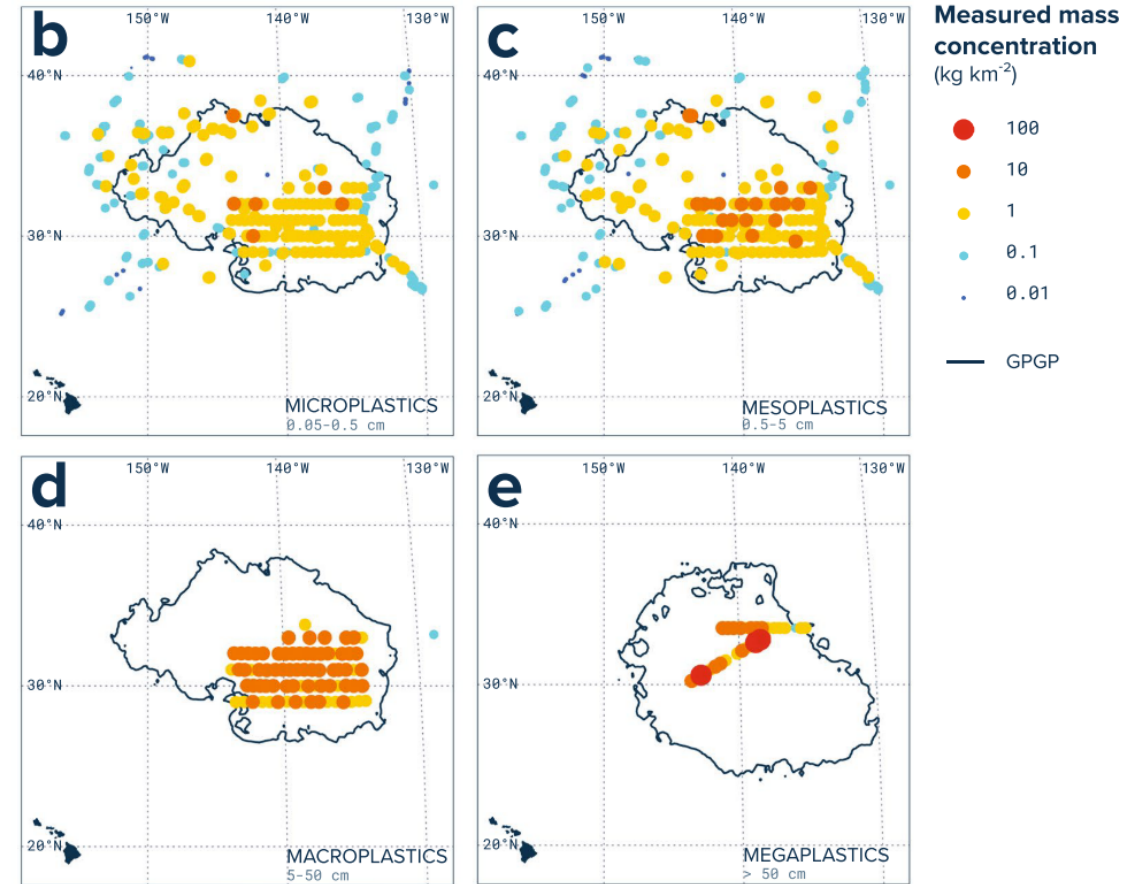
# REPETITIVE MEASUREMENTS ARE NECESSARY



Lebreton, L., Slat, B., Ferrari, Et al. Evidence that the Great Pacific Garbage Patch is rapidly accumulating plastic. *Sci Rep* 8, 4666 (2018). <https://doi.org/10.1038/s41598-018-22939-w>

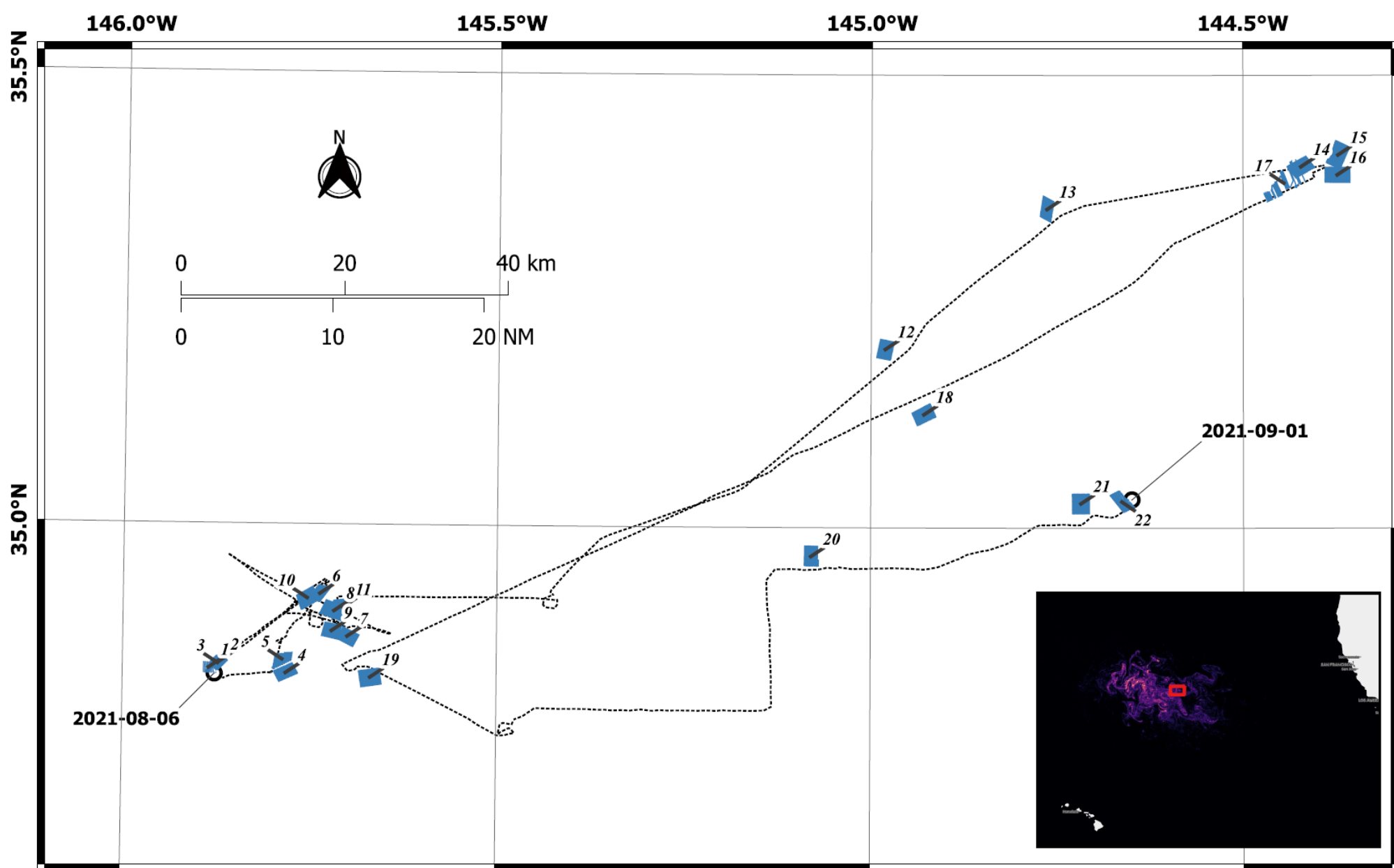
# OCEAN PLASTICS AND INDIVIDUAL MACROPLASTICS (>50 CM)

Lebreton, L., Slat, B., Ferrari, Et al. *Evidence that the Great Pacific Garbage Patch is rapidly accumulating plastic*  
*Sci Rep* 8, 4666 (2018). <https://doi.org/10.1038/s41598-018-22939-w>



**Figure 3.** Modelled and measured mass concentration in the Great Pacific Garbage Patch (GPGP). (a) Ocean plastic mass concentrations for August 2015, as predicted by our data-calibrated model. The bold black line represents our established limit for the GPGP. (b) Microplastics (0.05–0.5 cm) mass concentrations as measured by Manta trawl ( $n = 501$  net tows, 3.8 km<sup>2</sup> surveyed). (c) Mesoplastics (0.5–5 cm) mass concentrations as measured by Manta trawl; (d) Macroplastics (5–50 cm) mass concentrations as measured by Mega trawl ( $n = 151$  net tows, 13.6 km<sup>2</sup> surveyed); (e) Megaplastics (>50 cm) mass concentrations as estimated from aerial imagery ( $n = 31$  mosaic segments, 311.0 km<sup>2</sup> surveyed). All observational maps are showing mid-point mass concentration estimates as well as the predicted GPGP boundaries for the corresponding sampling period: August 2015 for net tow samples, and October 2016 for aerial mosaics. Maps were created using QGIS version 2.18.1 ([www.qgis.org](http://www.qgis.org)).

# UAV CAMPAIGN SPATIAL OVERVIEW



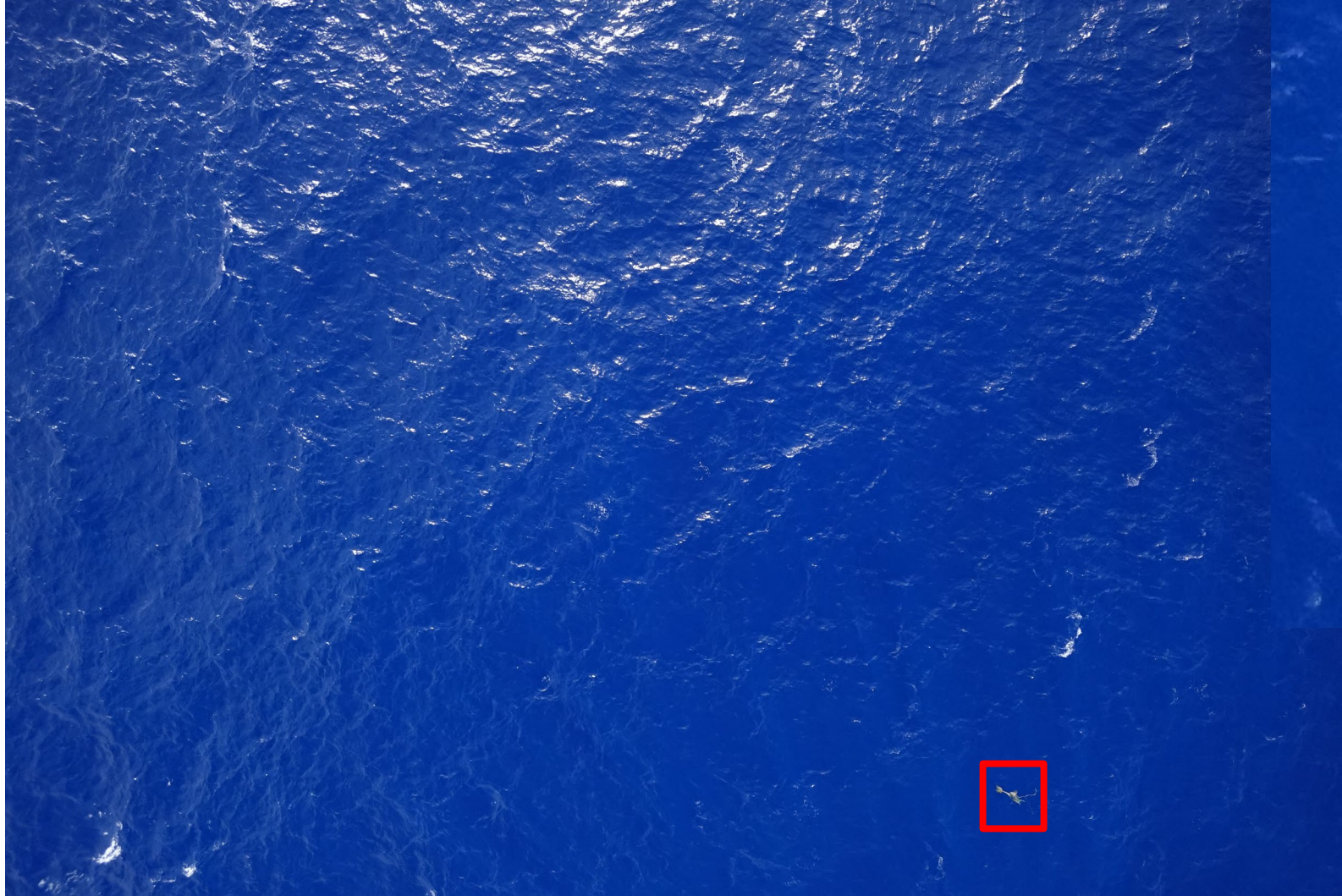
Legend

- Flights
- Start/End Point
- System Track

System 002 Trip 1,  
Overview of Trajectory and Fixed-Wing UAV campaign flights

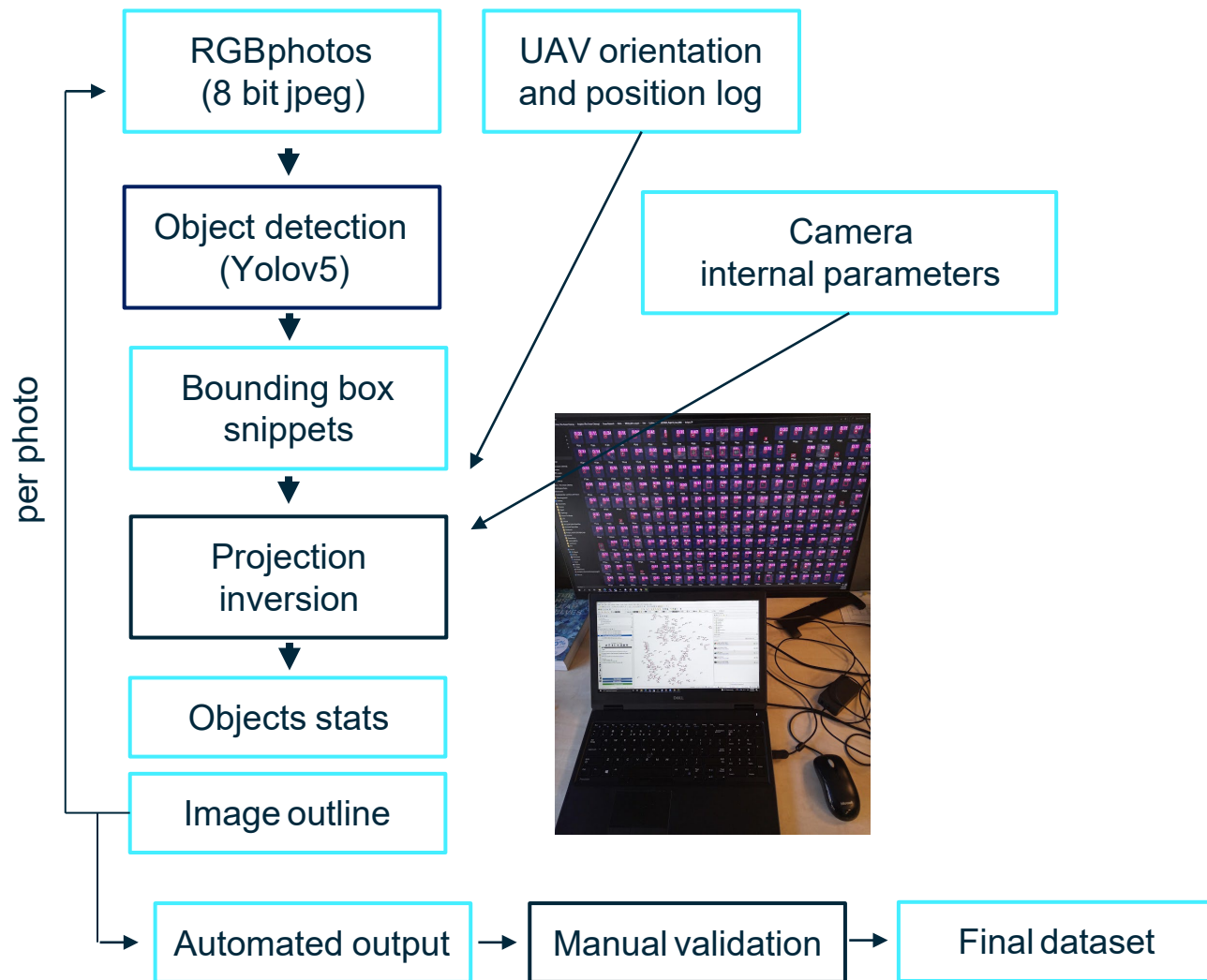
12 October 2021  
The Ocean Cleanup

# THE VIEW FROM ABOVE (80 M)



Sony RX0  
4800 x 3200 pixels

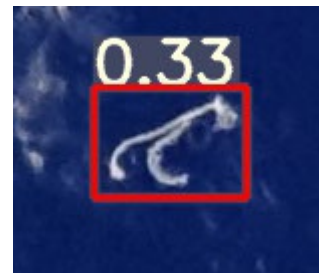
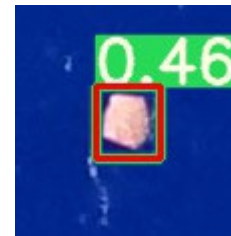
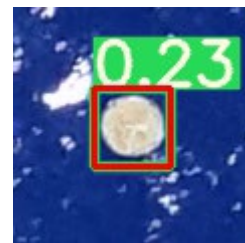
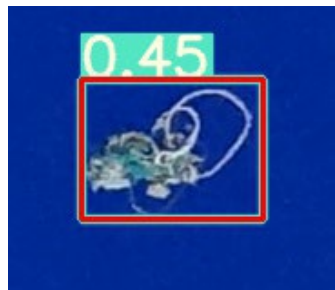
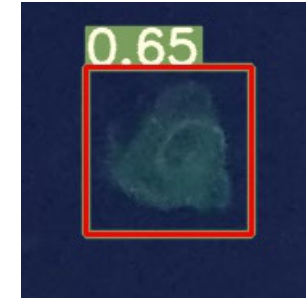
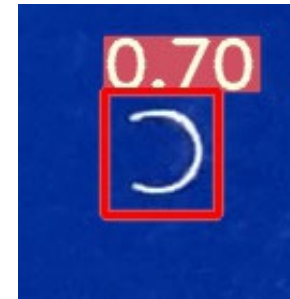
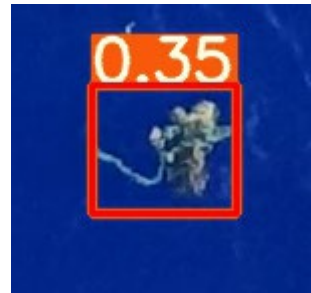
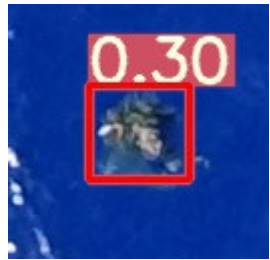
# PROCESSING



1 km



# EXAMPLES OF OBJECTS



# RESULTS

Number of flights **22 flights**

Total airtime **26.85 hours**

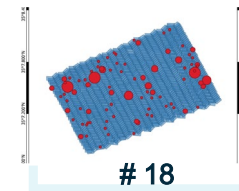
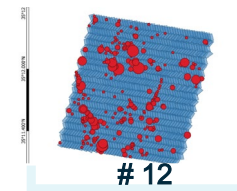
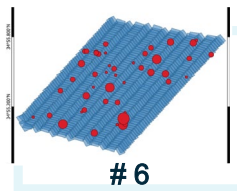
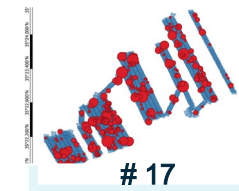
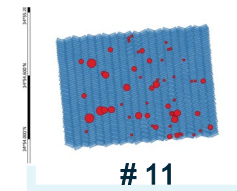
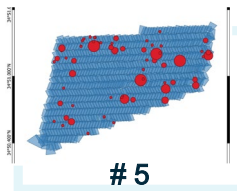
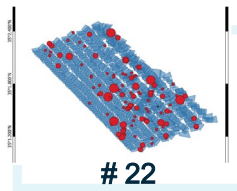
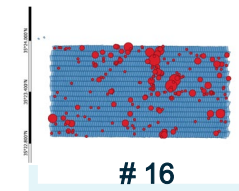
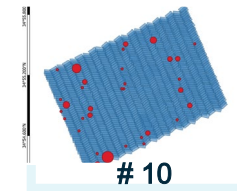
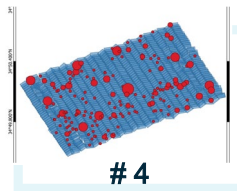
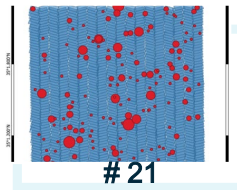
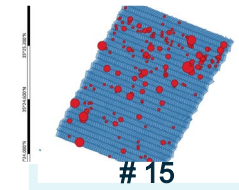
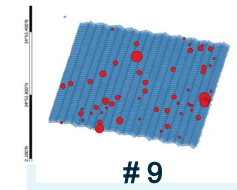
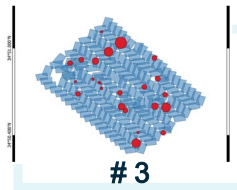
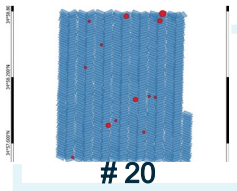
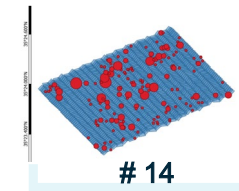
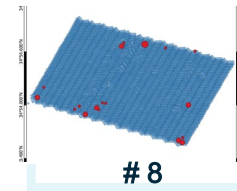
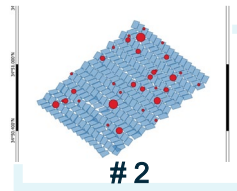
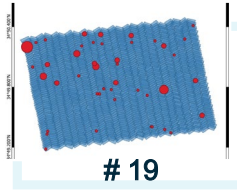
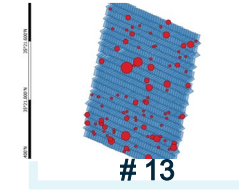
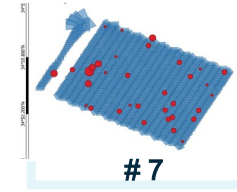
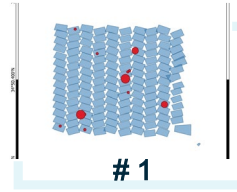
Photos taken **21,185**

Total area scanned **95 km<sup>2</sup>**

# of plastic >50 cm **1,839**

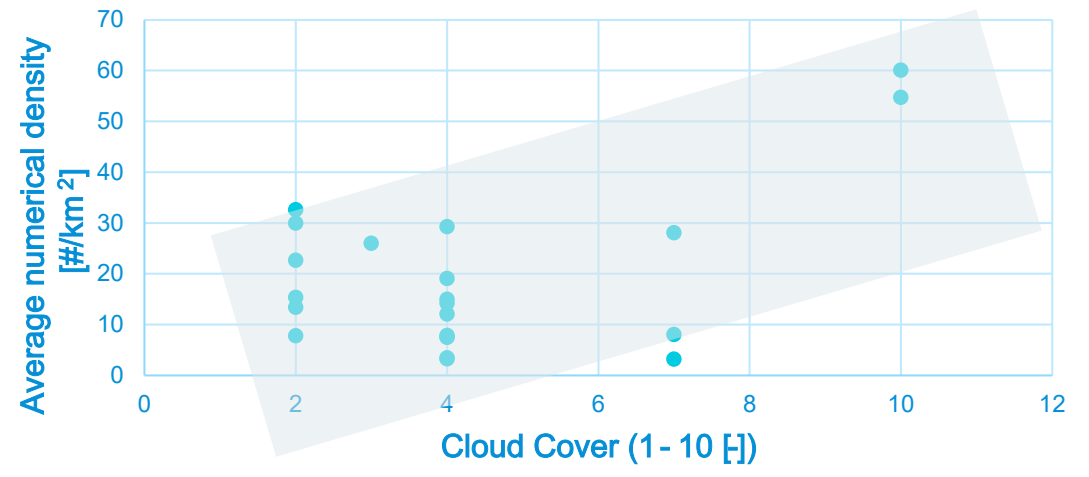
Minimum background Concentration **3 #/km<sup>2</sup>**

Maximum background Concentration **60 #/km<sup>2</sup>**

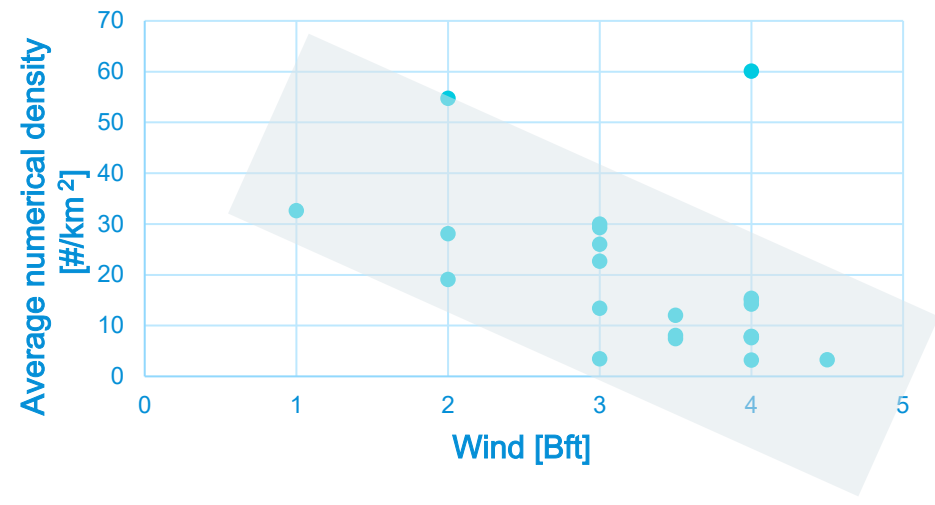


# WEATHER

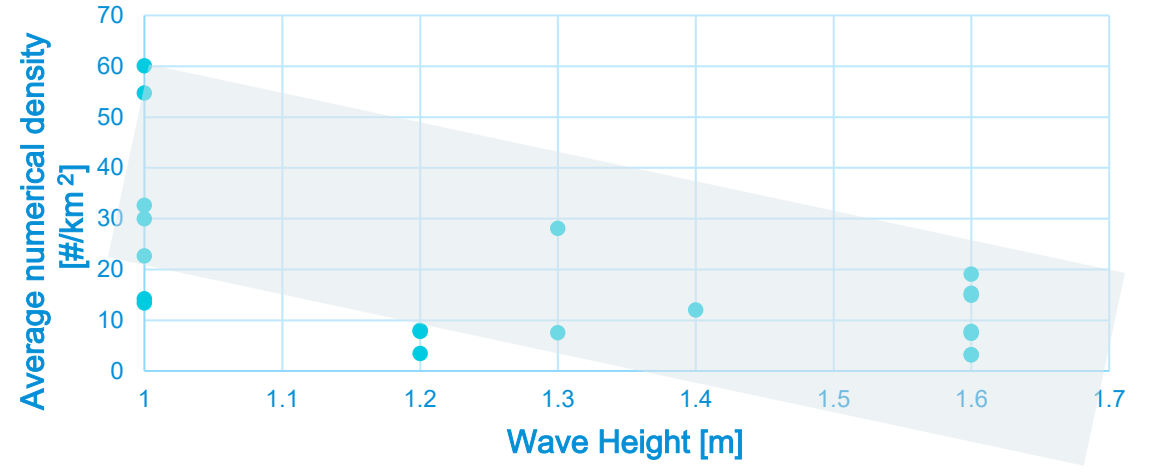
### Clouds & Detections



### Wind & Detections

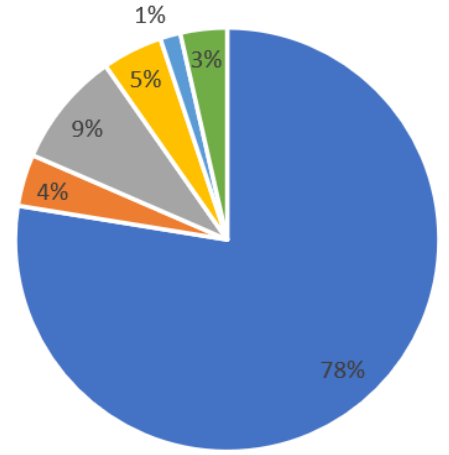


### Waves & Detections

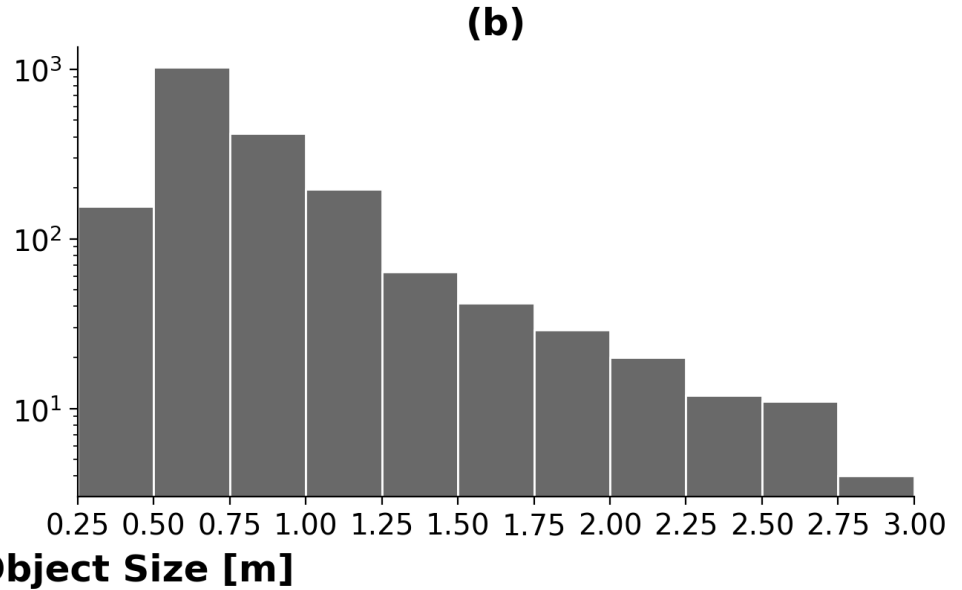
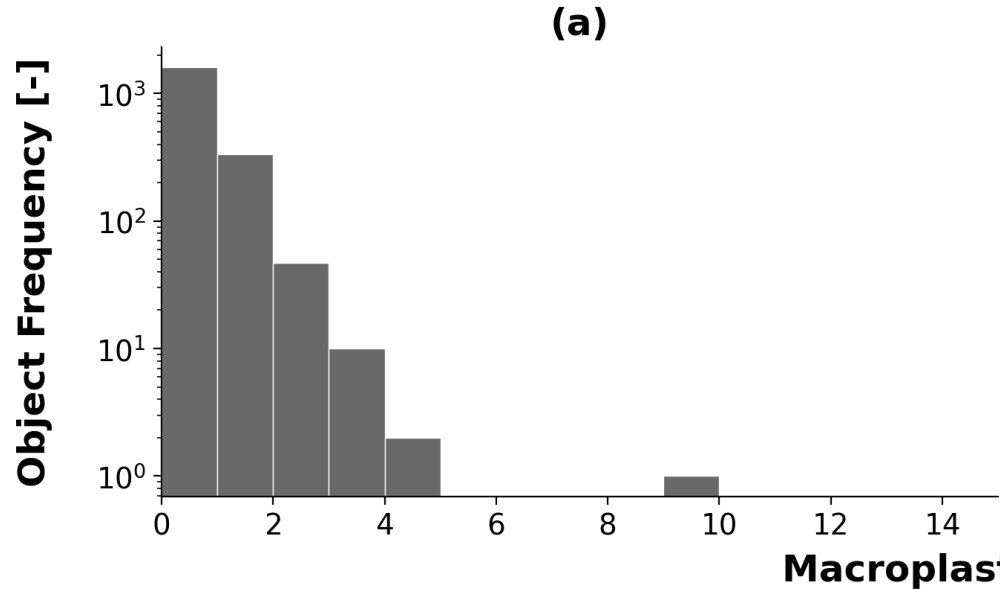


# OBJECTSIZES AND CLASSES

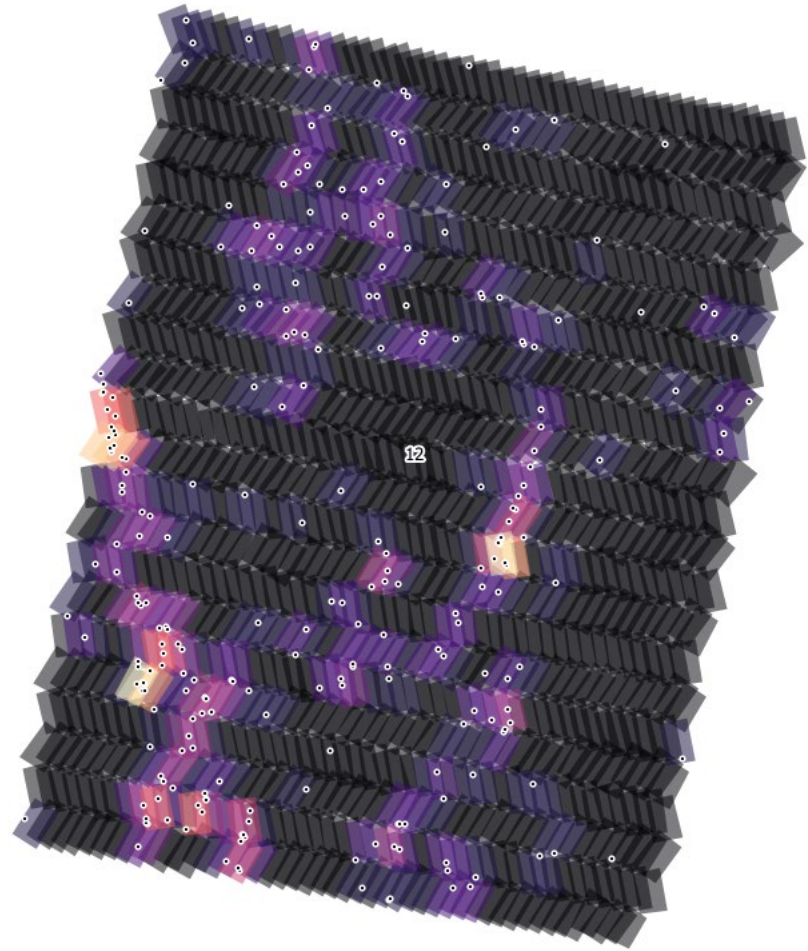
Category	# [-]
Unknown	1549
Buoy	79
Container	175
Rope	92
Loose Net	31
Bundled Net	71



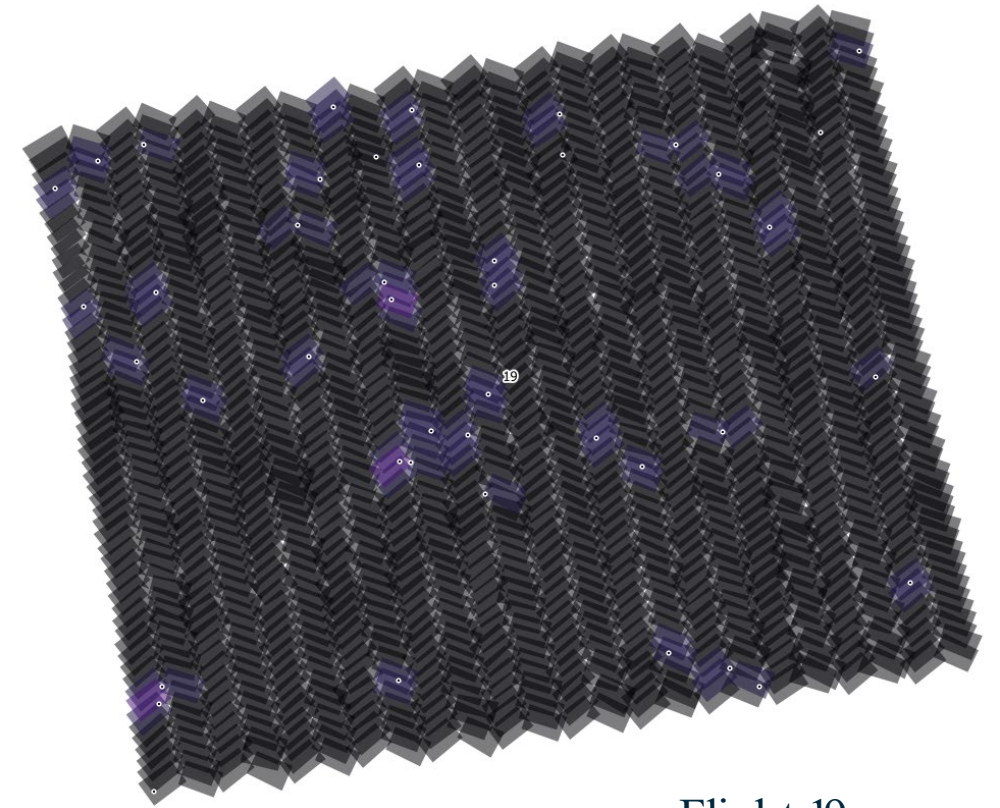
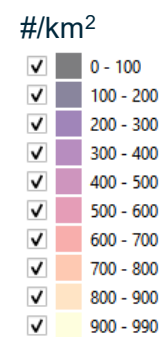
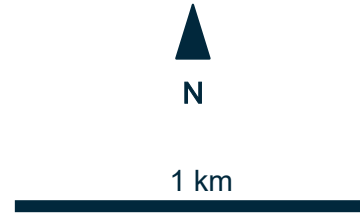
■ Unknown ■ Buoy ■ Container ■ Rope ■ Loose Net ■ Bundled Net



# SPATIAL HETEROGENEITY (CLUSTERING)



Flight 12

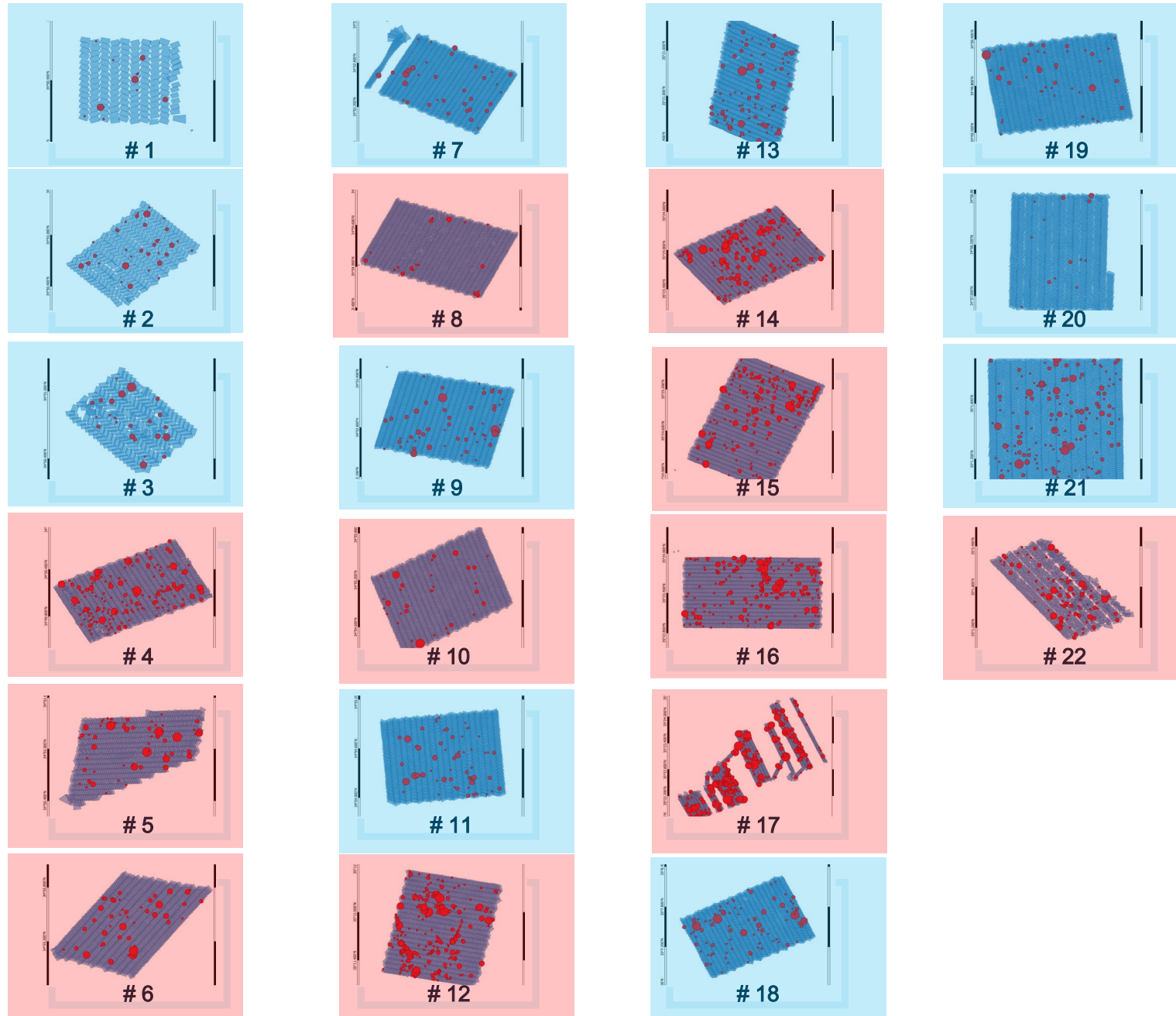
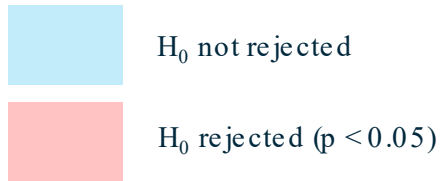


Flight 19

RESULTS

# STATISTICAL TESTING FOR CLUSTERS

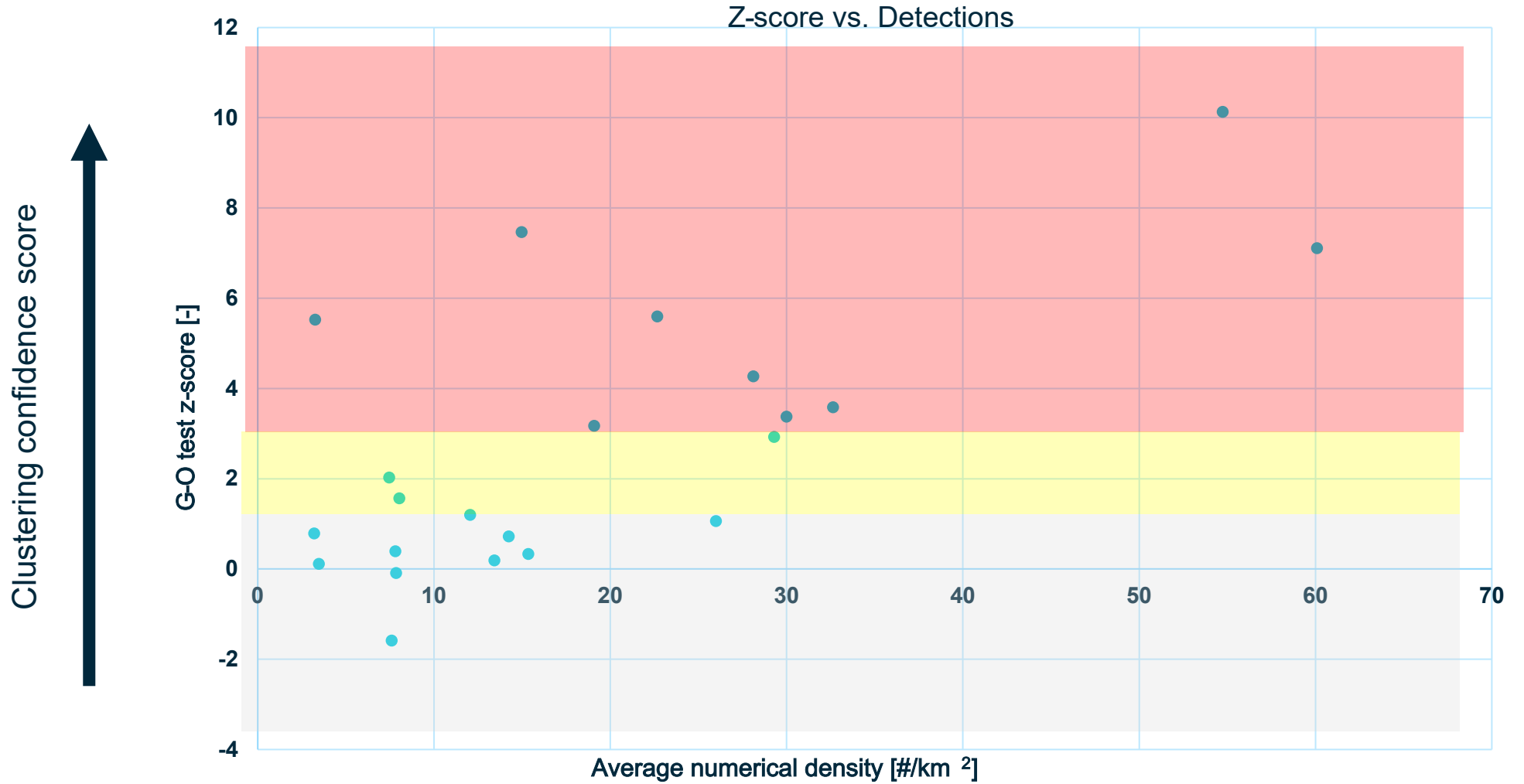
$H_0$ : There is no cluster present in this flight. Objects are distributed randomly.



Getis, Arthur, and J. K. Ord. "The Analysis of Spatial Association by Use of Distance Statistics." *Geographical Analysis* 24, no. 3. 1992.

Mitchell, Andy. *The ESRI Guide to GIS Analysis*, Volume 2. ESRI Press, 2005.

# PER FLIGHT: TEST SCORES



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# CONCLUSIONS & PERSPECTIVE

## Conclusions

- Successful tests of amphibious fixed-wing UAVs in the North Pacific Ocean.
- Revealing microscale spatial variability of megaplastic (>50 cm).
- New local extremes of megaplastic (>50 cm) numerical concentration.
- High concentrations coincide with presence of spatial clusters.

## Perspective

- Refinement of method: object sizes, false positives, processing speed.
- Deeper study of accumulation patterns and comparison to other.
- Renewed applications for studying microscale accumulation of marine plastic litter.



# THE OCEAN<sup>TM</sup> CLEANUP

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Feel free to reach out if you have any tips or further questions!

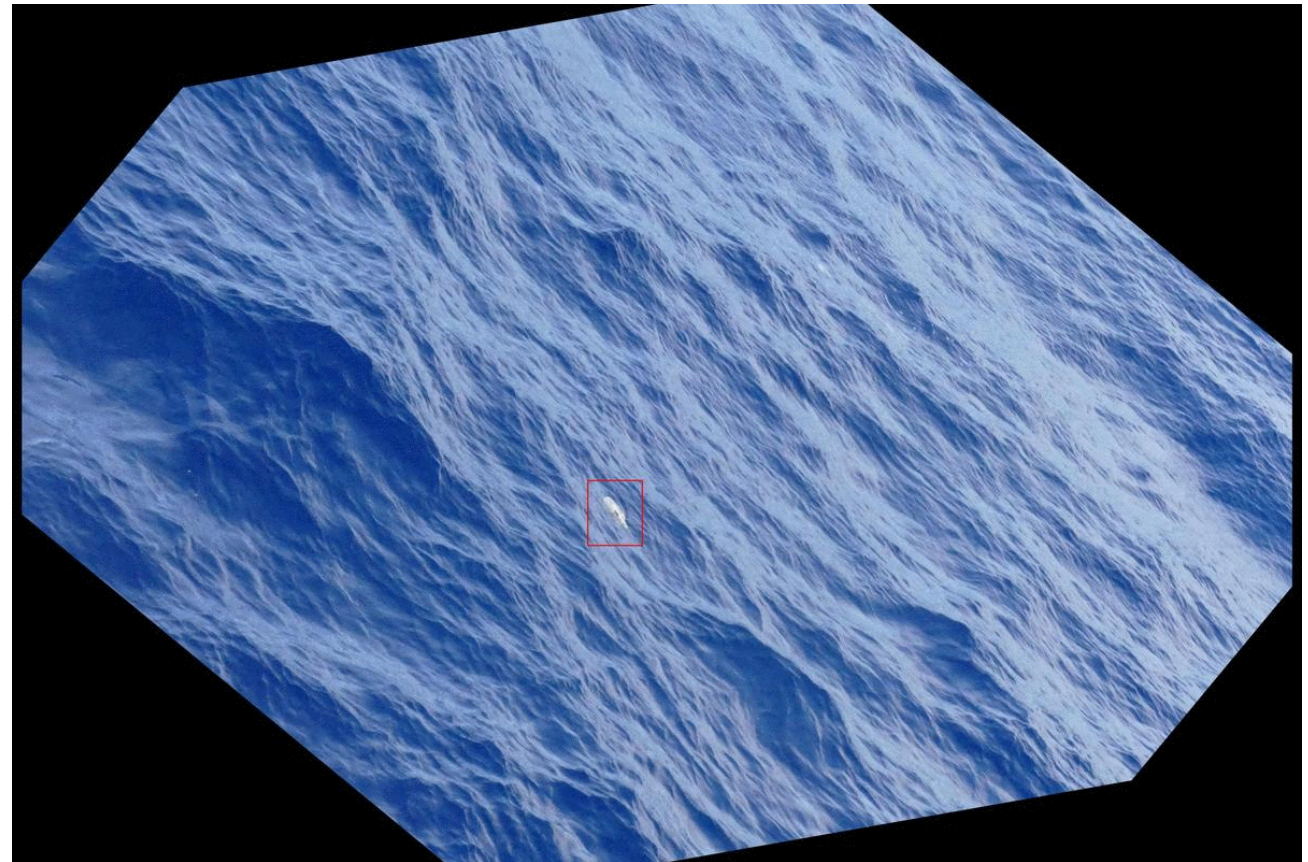
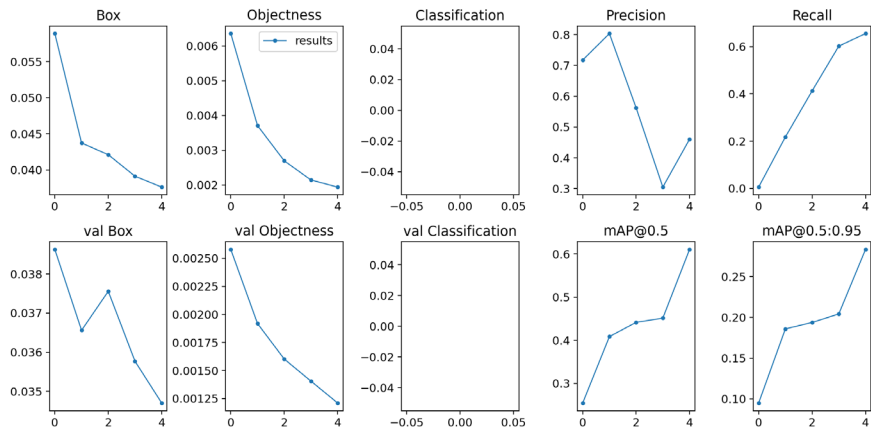
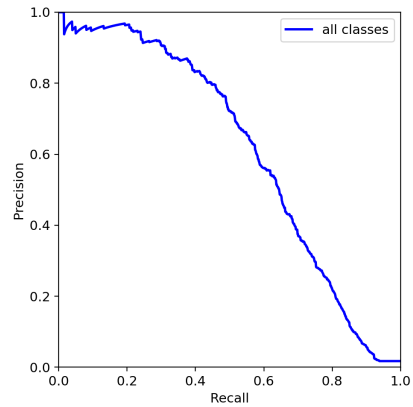


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00316 42099603

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 Visit our website  
[theoceancleanup.com](https://theoceancleanup.com)

# YOLOV5 OBJECT DETECTION TRAINING AND PERFORMANCE



Data augmentation: generating synthetic data by rotating, skewing, shifting, etc.

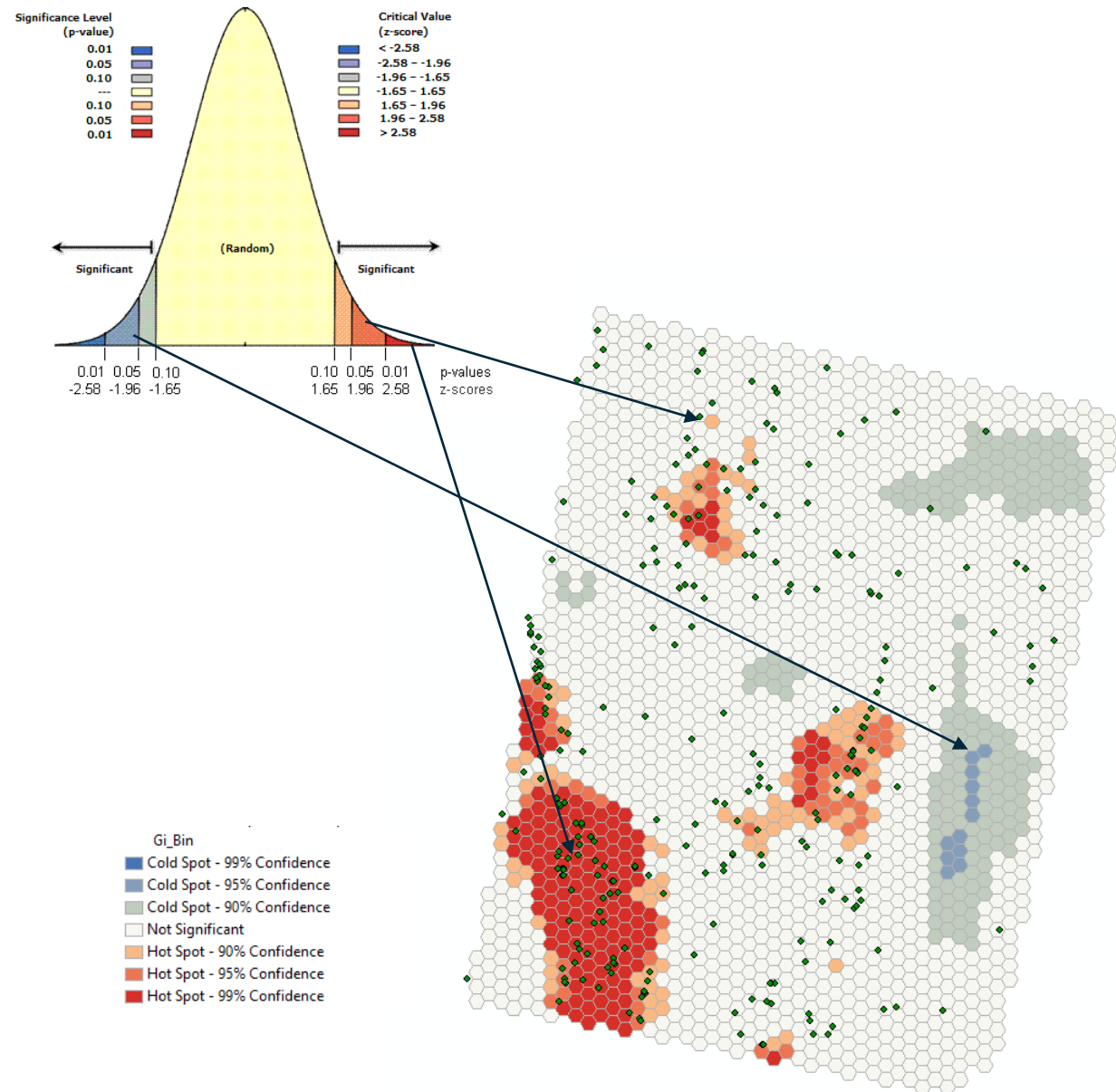
Training set: **18,589 images**

Training: prevent overfitting by limiting the number of training steps

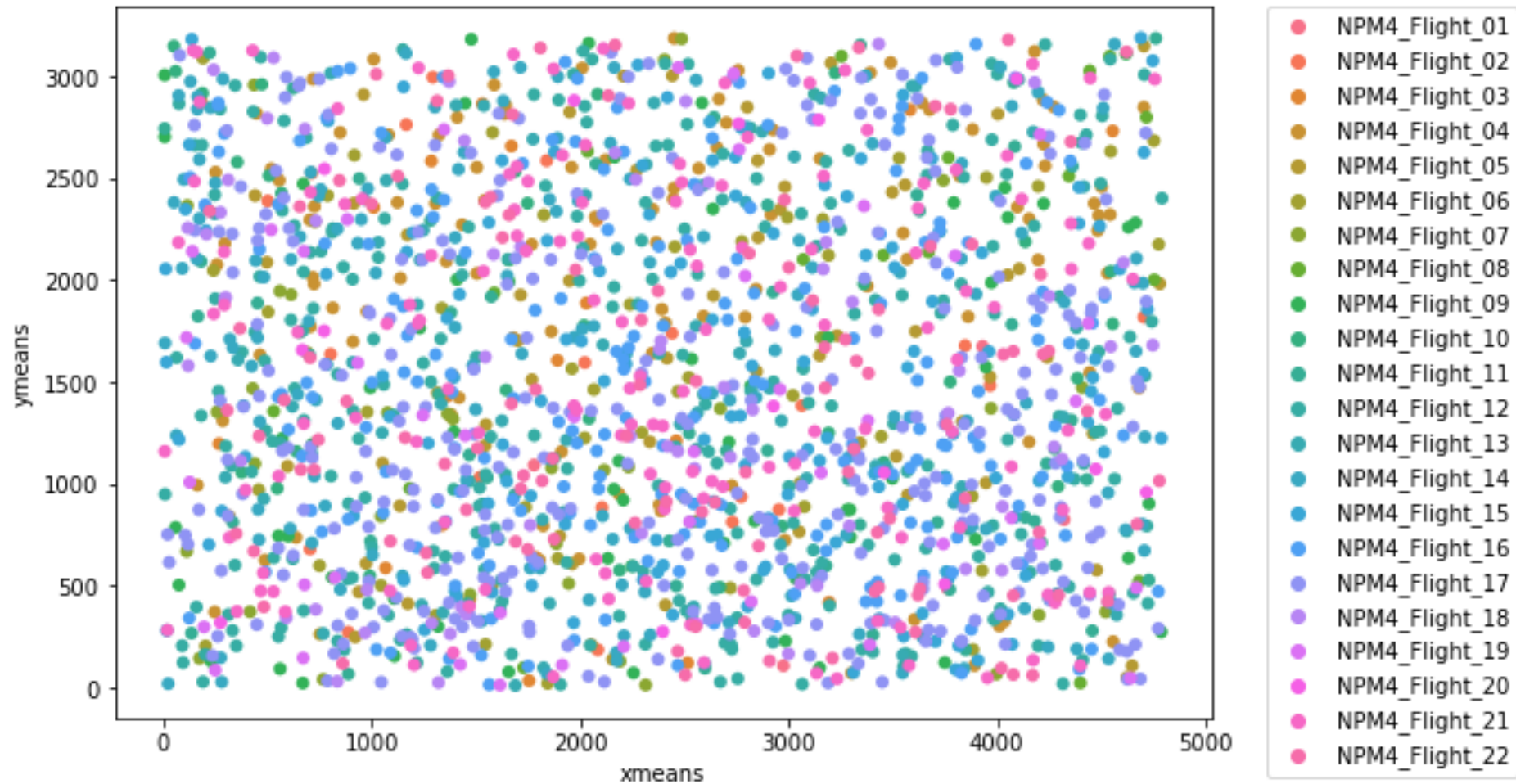
# CLUSTERS ANALYSIS

Hex bins, 50 m cell size, 250 m search window.

**308 cells** with 99% hotspot confidence.

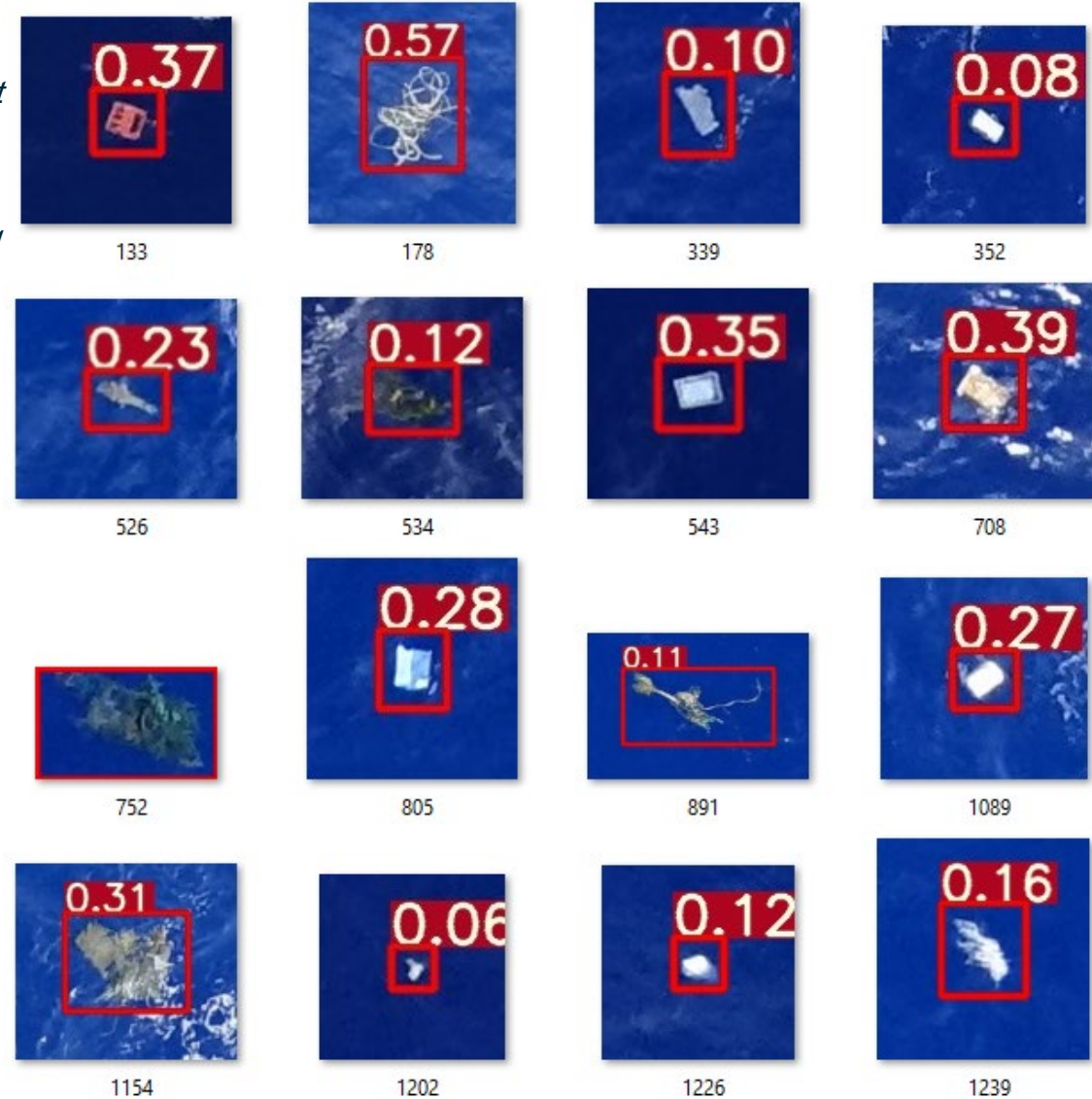
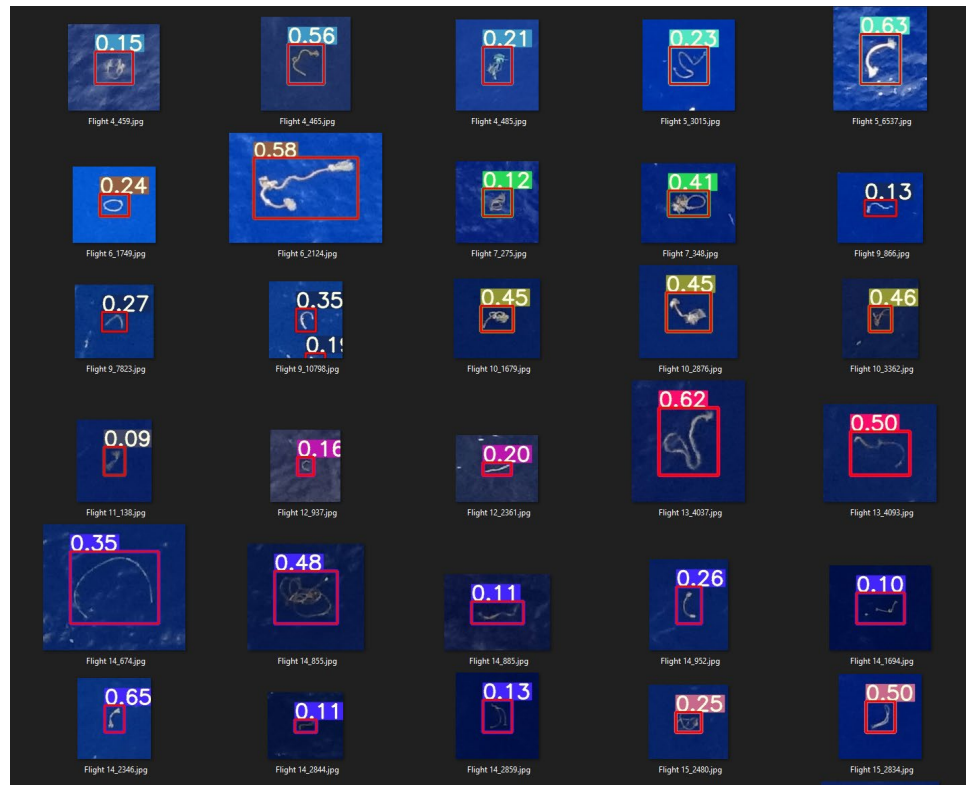


# OBJECTDETECTION POSITIONS WITHIN IMAGE FRAME

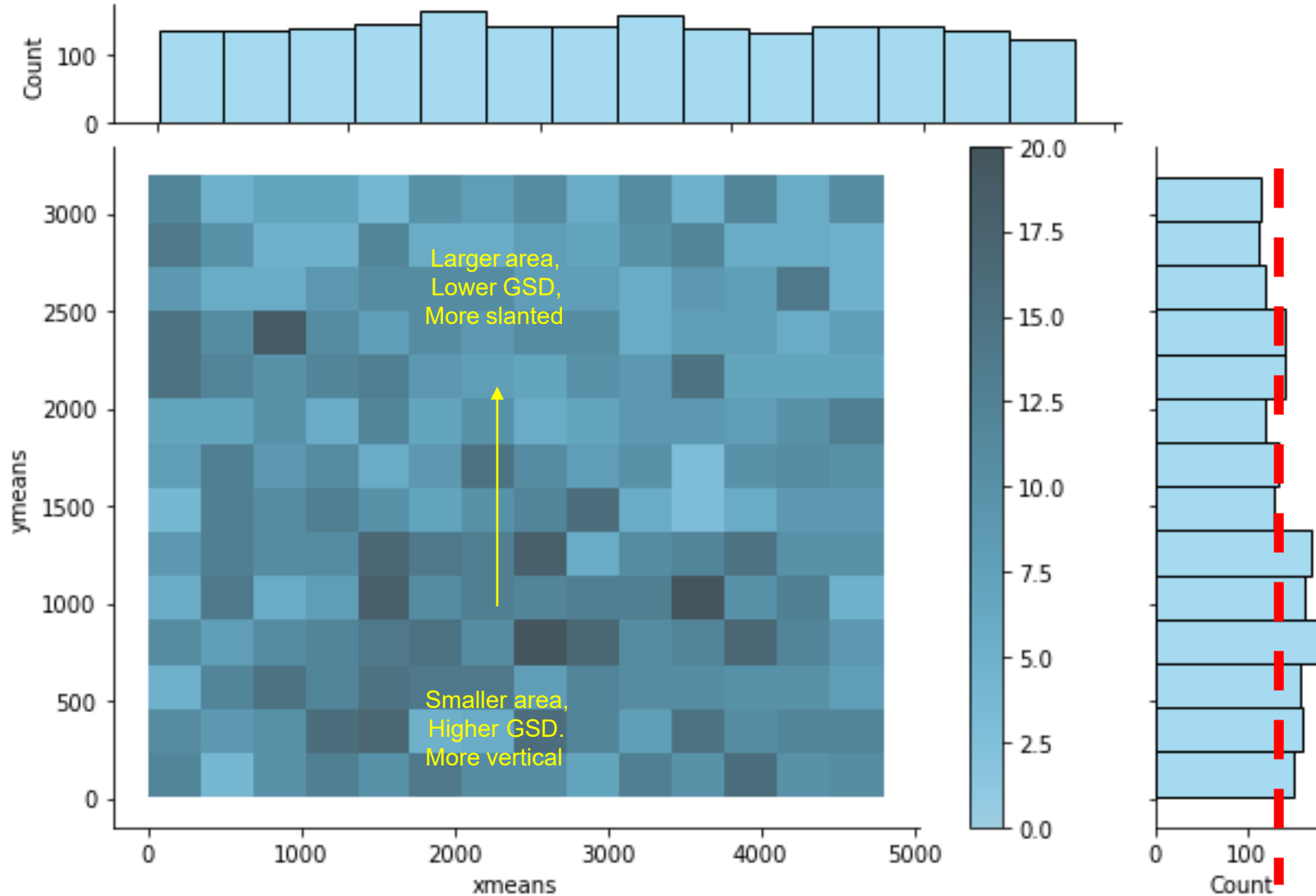


# AI FOR MASS-PROCESSING

Robin de Vries, Matthias Egger, Thomas Mani, and Laurent Lebreton. 2021. *Quantifying Floating Plastic Debris at Sea Using Vessel-Based Optical Data and Artificial Intelligence* Remote Sensing 13, no. 17: 3401. <https://doi.org/10.3390/rs13173401>



# IMAGEBLUR, DOES IT AFFECT DETECTIONS AROUND CORNERS?



# OBJECTDETECTION POSITIONS WITHIN IMAGE FRAME VARY BY ~10%

