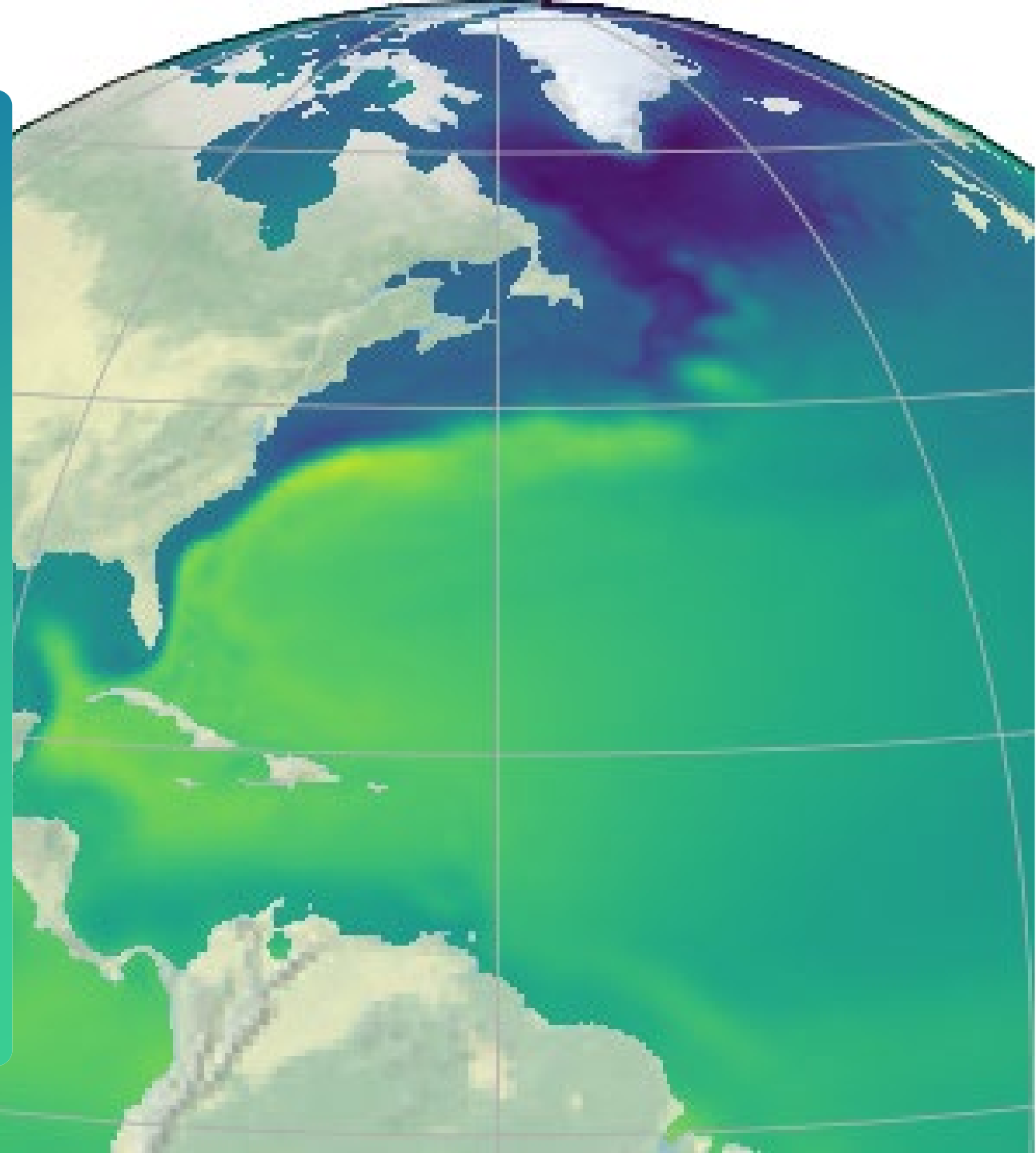




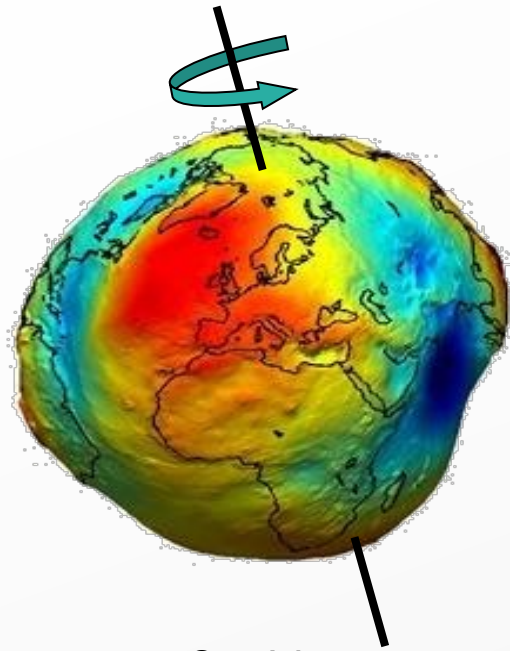
Combining coastal altimetry data with High Frequency radar, drifters and hydrological profiles data to estimate a Mean Dynamic topography on the Mid Atlantic Bight

Solène Jousset (CLS), Sandrine Mulet (CLS), John Wilkin (Rutgers University), Eric Greiner (CLS), Gerald Dibarboure (CNES) and Nicoals Picot (CNES)



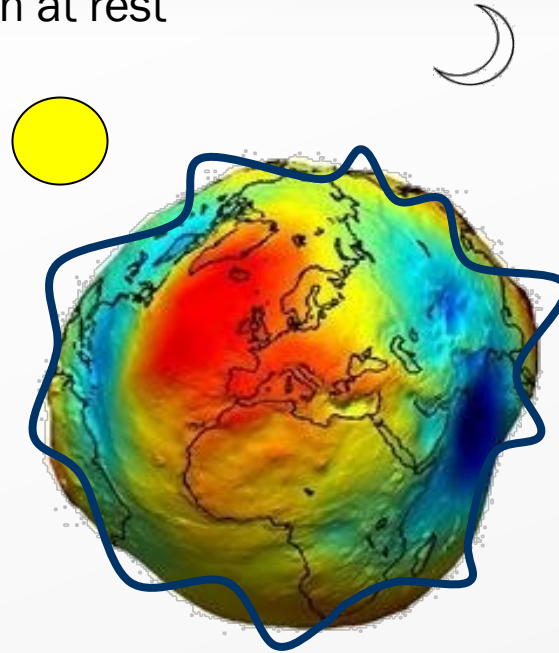
Height referenced to which surface ?

→ **Geoid** = surface of the ocean at rest



Geoid

Ocean at rest,
submitted only to the
Earth's gravity field



Dynamic of the ocean
→ **Absolute Dynamic
Topography (ADT)**

$$\text{ADT} = \text{SLA} + \text{MDT}$$

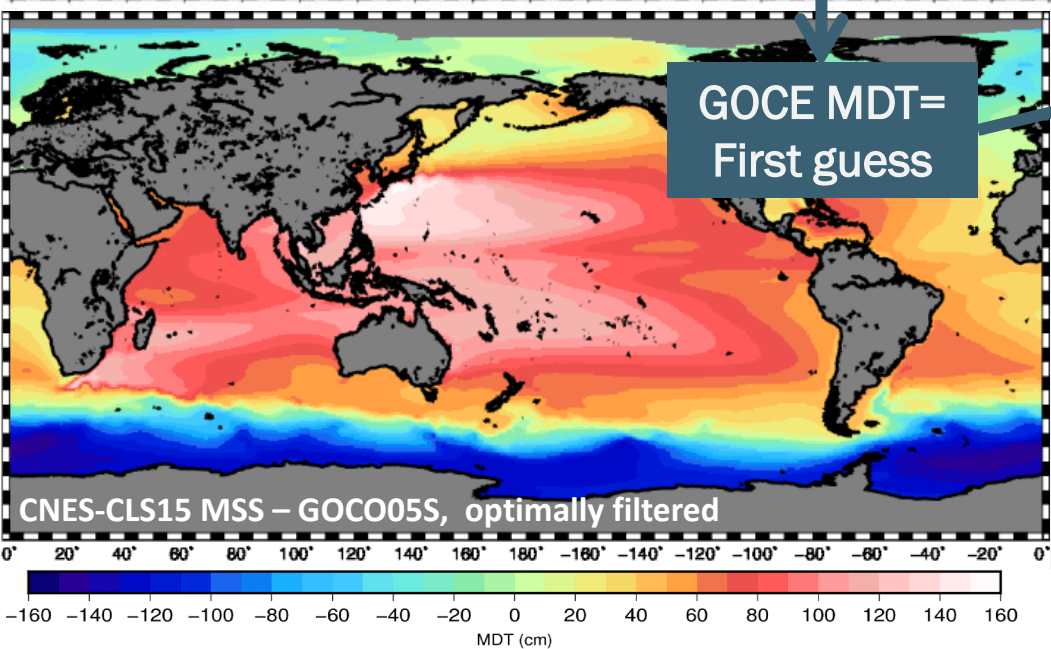
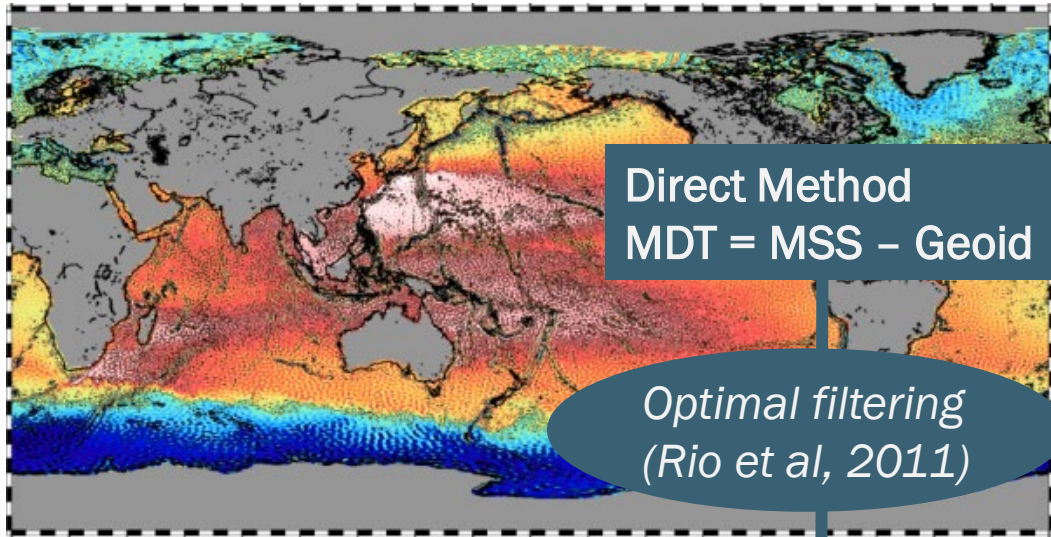
Sea Level Anomalies

Altimetric product

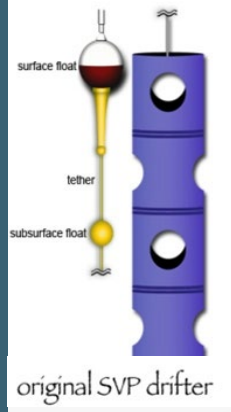
Mean Dynamic Topography

Need to be estimated !

MDT estimation method

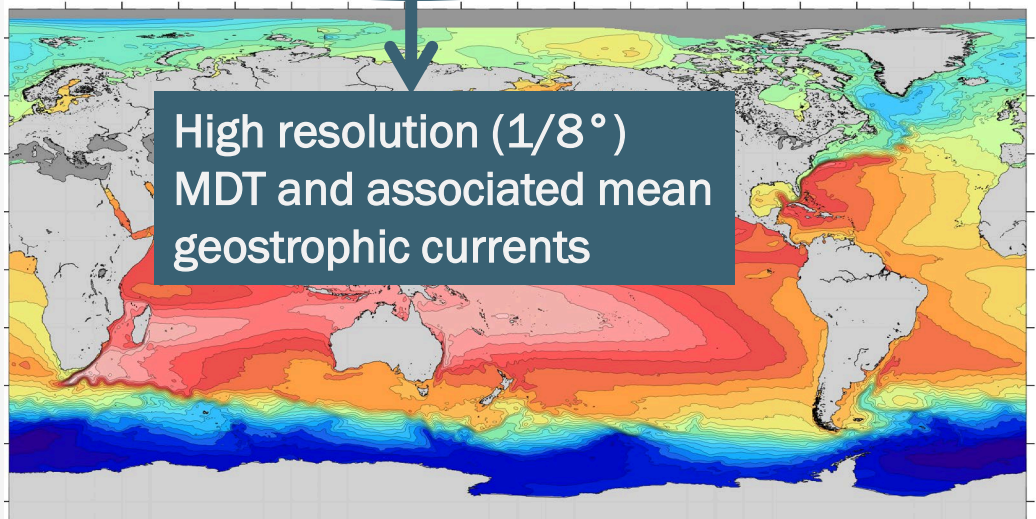


Synthetic Method:
The short scales of the MDT (and corresponding geostrophic currents) are estimated by combining altimetric anomalies and in-situ data (Argo floats, drifting buoys)



Multivariate Objective Analysis

Rio and Hernandez, 2004
Rio et al, 2005, 2011, 2014

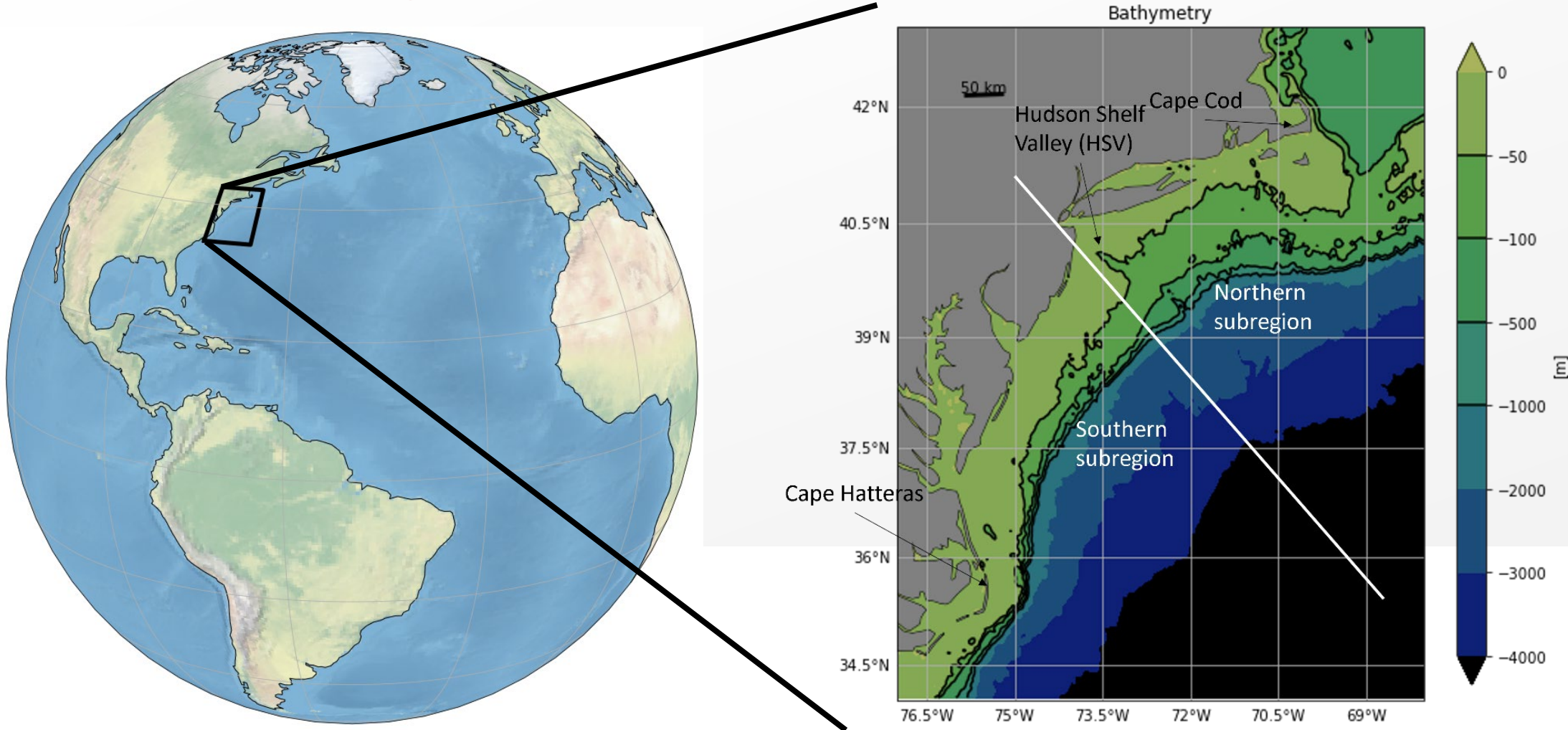


MDT CNES-CLS18 : last available MDT in global



MDT in Mid Atlantic Bight (MAB)

- Objective: to improve the MDT in the coastal zone (Preparation of the new global MDT CNES-CLS2022)
- How to do it? Add coastal data: test the contribution of current data estimated by High Frequency (HF) radar in the Mid Atlantic Bight (area well observed by U.S. HF radars)



1. First-guess
2. In-situ data processing
3. Additional data in Mid Atlantic Bight : HF radar data
4. Final MDT analysis
5. Conclusions



1. First-guess

2. In-situ data processing

3. Additional data in Mid Atlantic Bight : HF radar data

4. Final MDT analysis

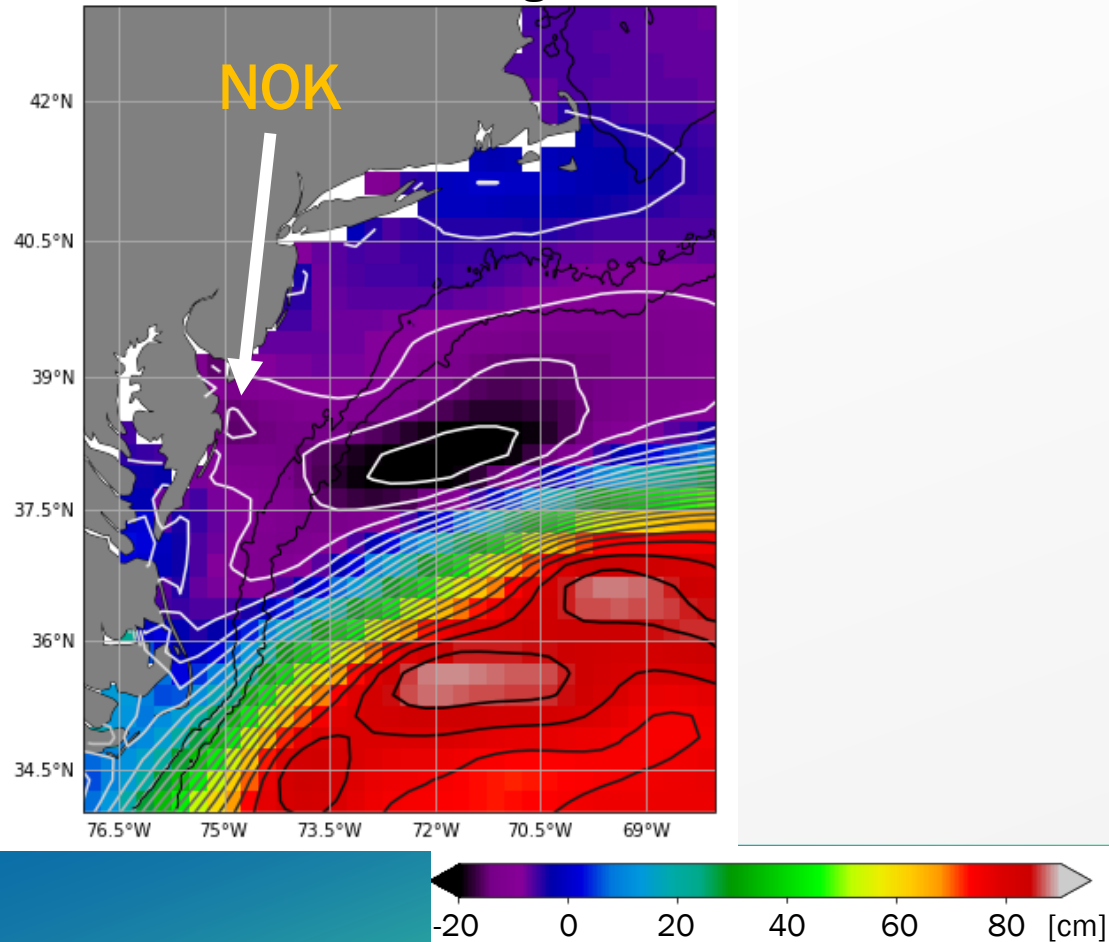
5. Conclusions



Improved first-guess with Lagrangian filtering

- Very noisy MDT at the coast with current lines perpendicular to the coast (not realistic)

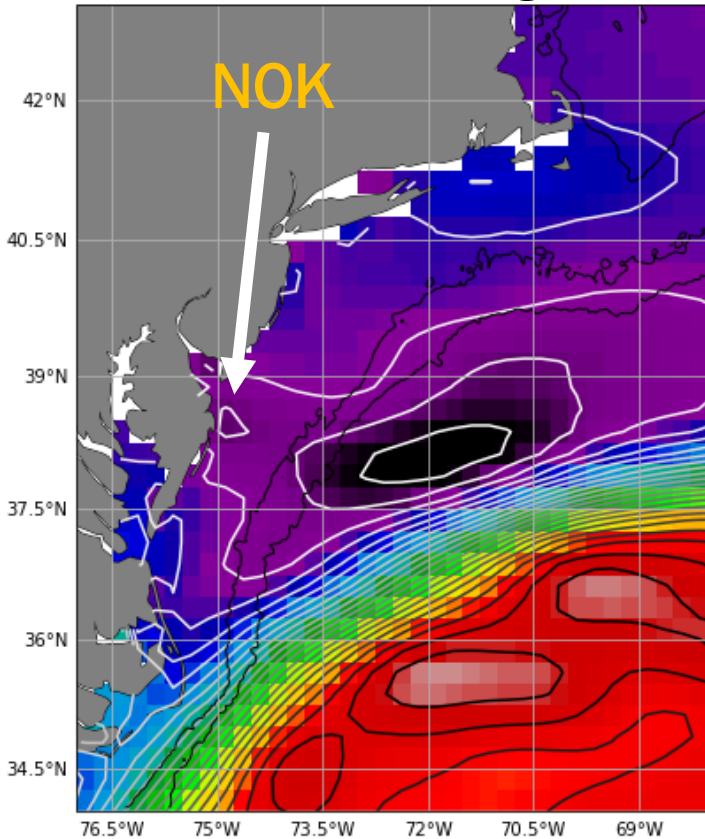
CNES-CLS18 First-guess



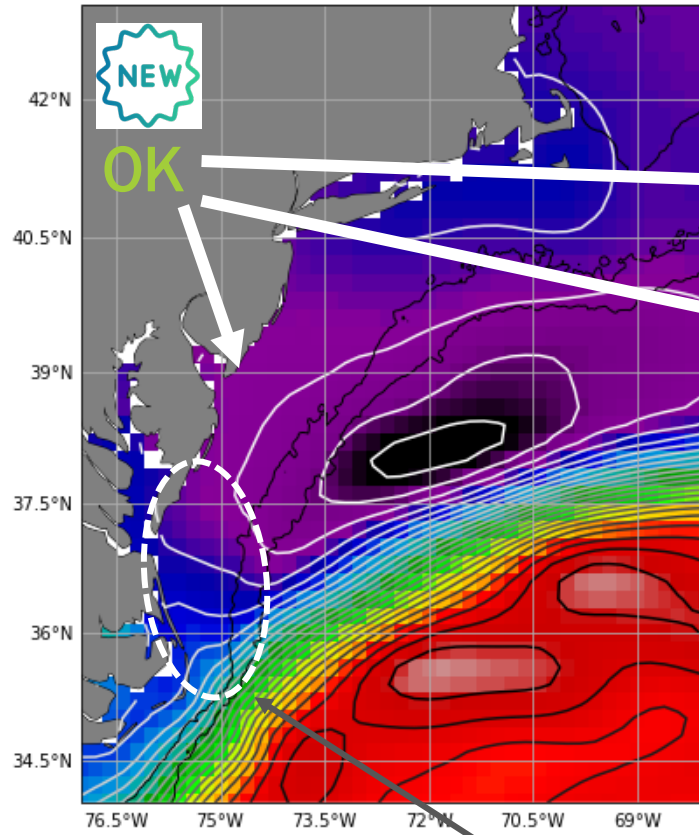
Improved first-guess with Lagrangian filtering

- Very noisy MDT at the coast with current lines perpendicular to the coast (not realistic)
- Lagrangian filtering to improve near shore current lines and to reduce normal geostrophic speed associated

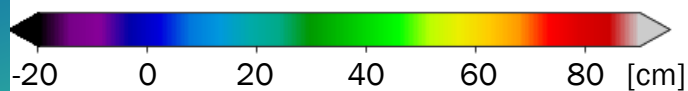
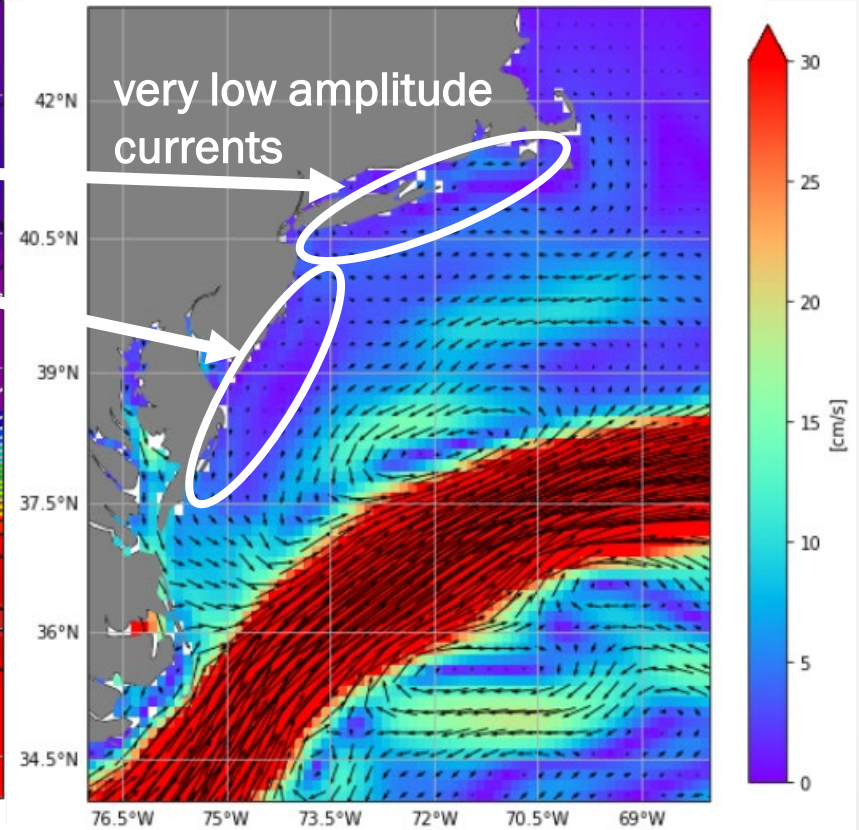
CNES-CLS18 First-guess



New First-guess



New First-guess current associated



Lagrangian filtering can be improved in the presence of a strong MDT gradient (Gulf Stream)

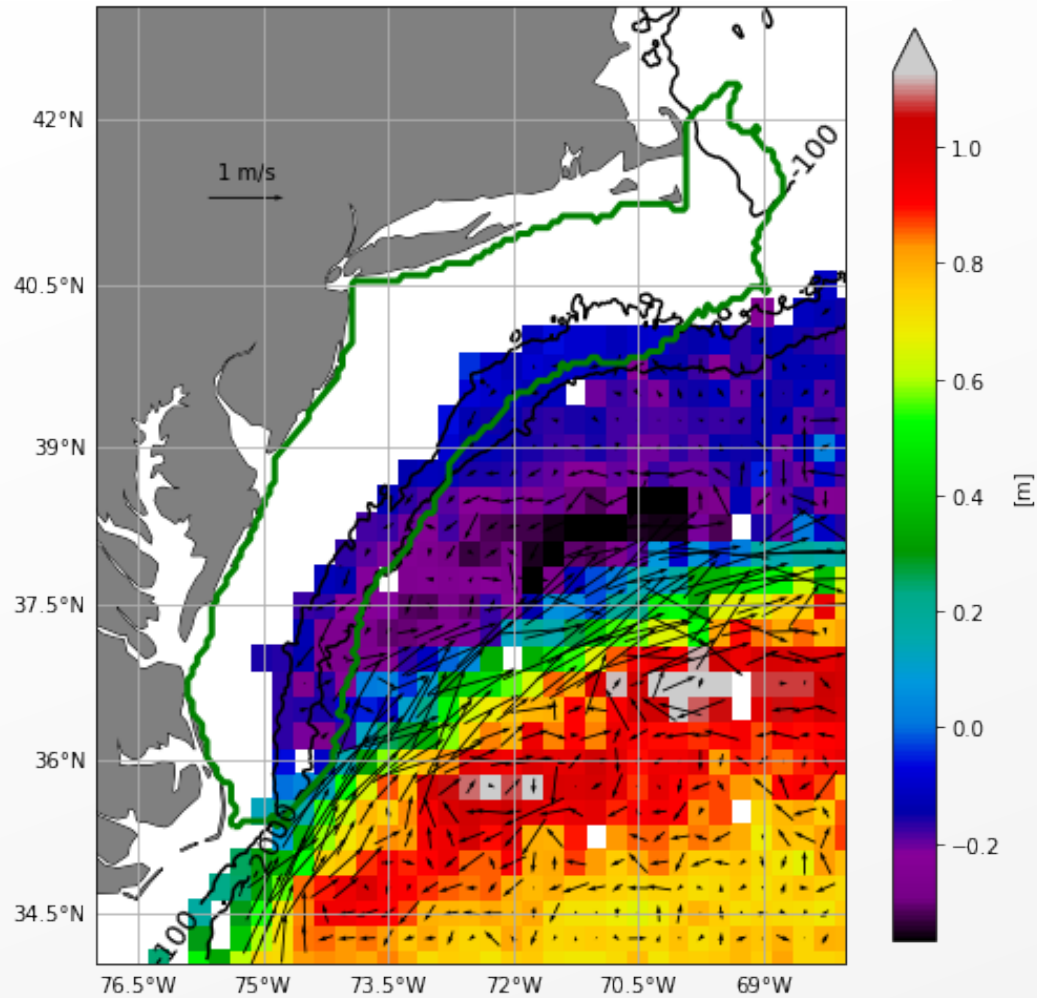
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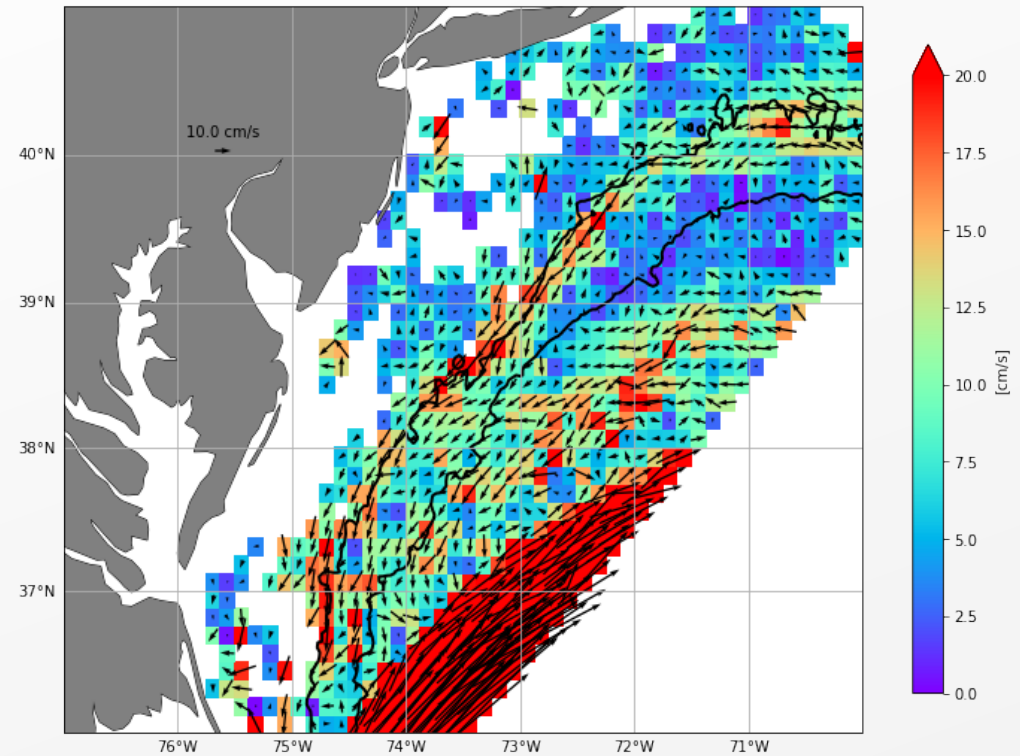
Synthetic mean heights and velocity

- In-situ data are processed to be consistent in terms of physical content with altimetry

Mean Synthetic Heights 1/4° from T/S profiles



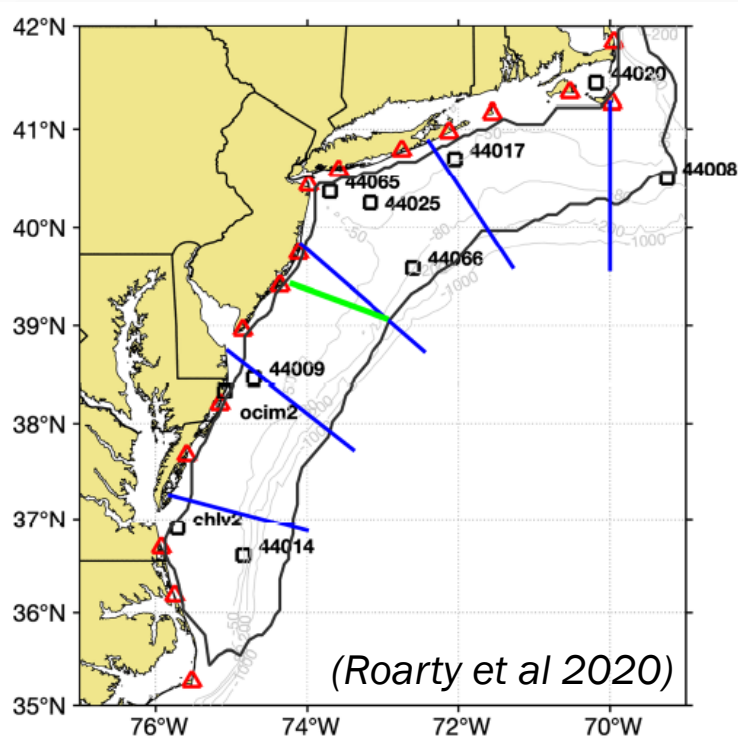
Mean Synthetic Velocities 1/8° from drifters



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Processing of current data estimated by HF radar



△ 16 5-MHz-SeaSondes (CODAR)
from 2007 to 2016

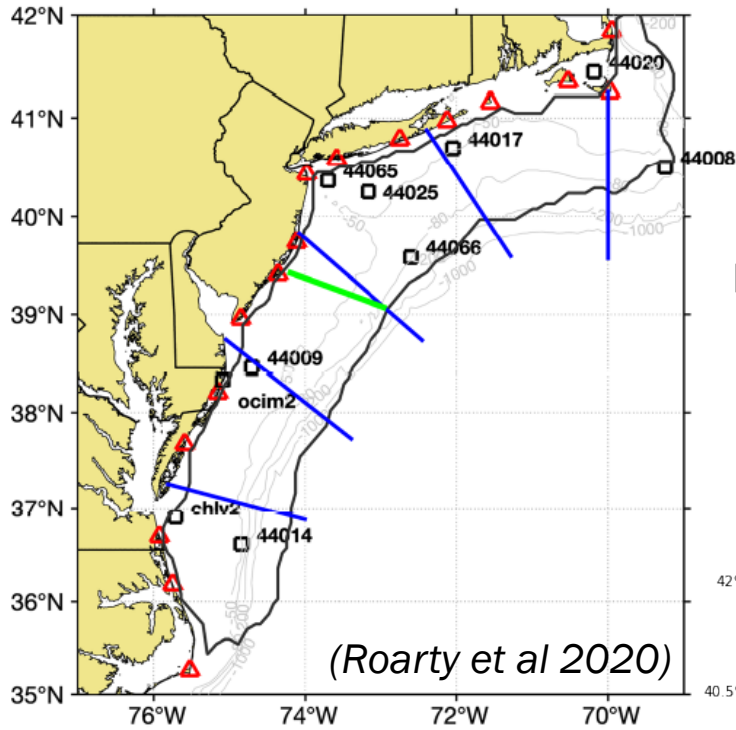
[http://tds.marine.rutgers.edu/
thredds/cool/codar/cat_totals.
html](http://tds.marine.rutgers.edu/thredds/cool/codar/cat_totals.html)


Processing of current data estimated by HF radar

November 2006 –
December 2016

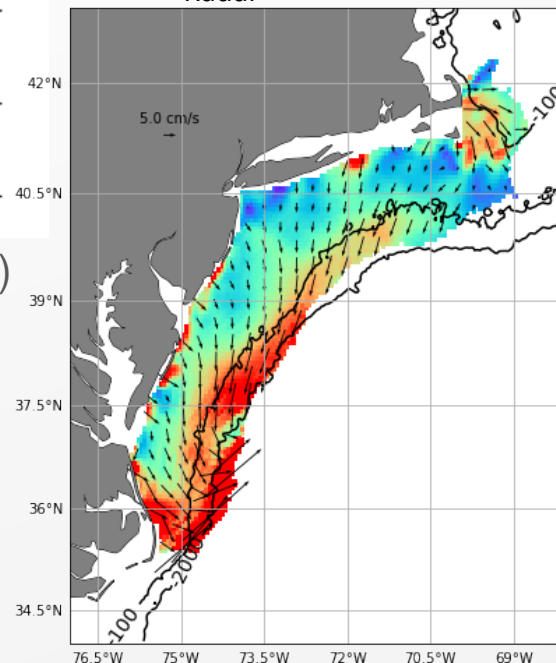
Mean HF radar currents
processed by Rutgers University:
detided, filtered currents (high
frequency signal removed)
Roarty et al 2020

U_{Radar} 2007-2016

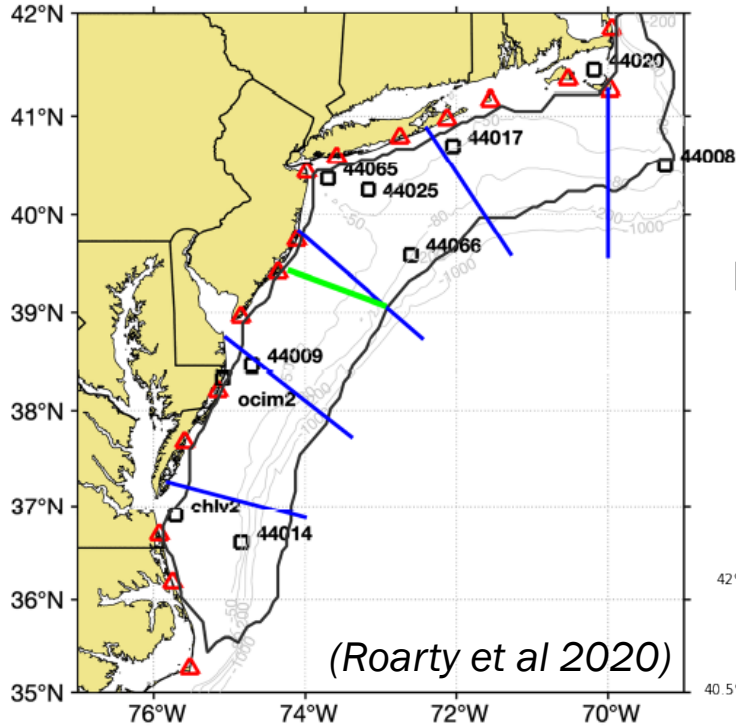


 16 5-MHz-SeaSondes (CODAR)
from 2007 to 2016

[http://tds.marine.rutgers.edu/
thredds/cool/codar/cat_totals.
html](http://tds.marine.rutgers.edu/thredds/cool/codar/cat_totals.html)



Processing of current data estimated by HF radar



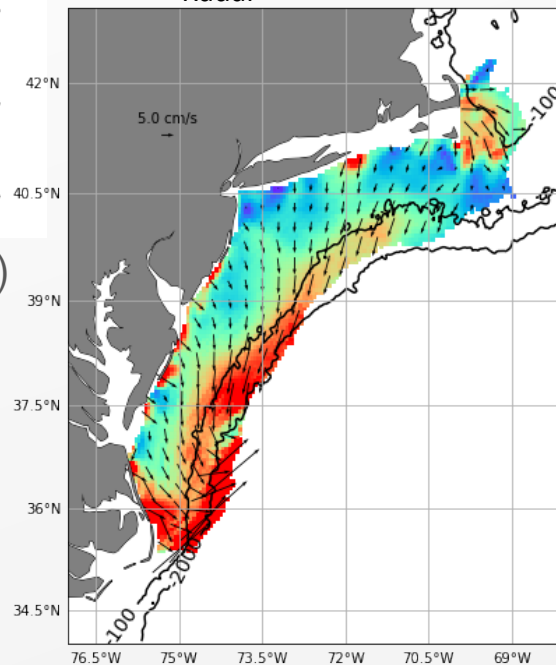
 16 5-MHz-SeaSondes (CODAR)
from 2007 to 2016

http://tds.marine.rutgers.edu/thredds/cool/codar/cat_totals.html

November 2006 –
December 2016

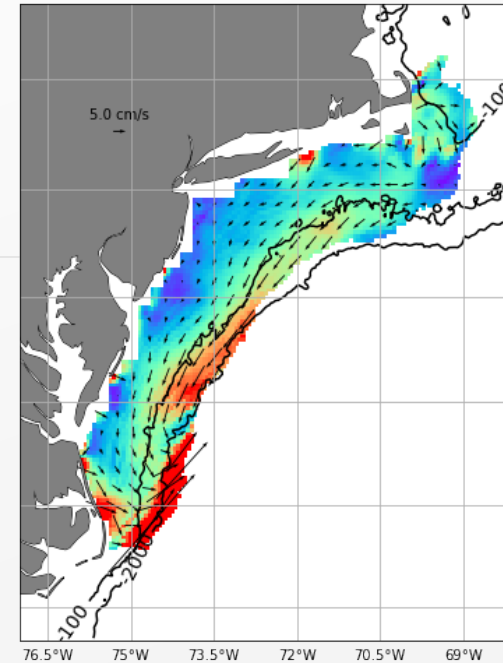
Mean HF radar currents
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frequency signal removed)
Roarty et al 2020

U_{Radar} 2007-2016

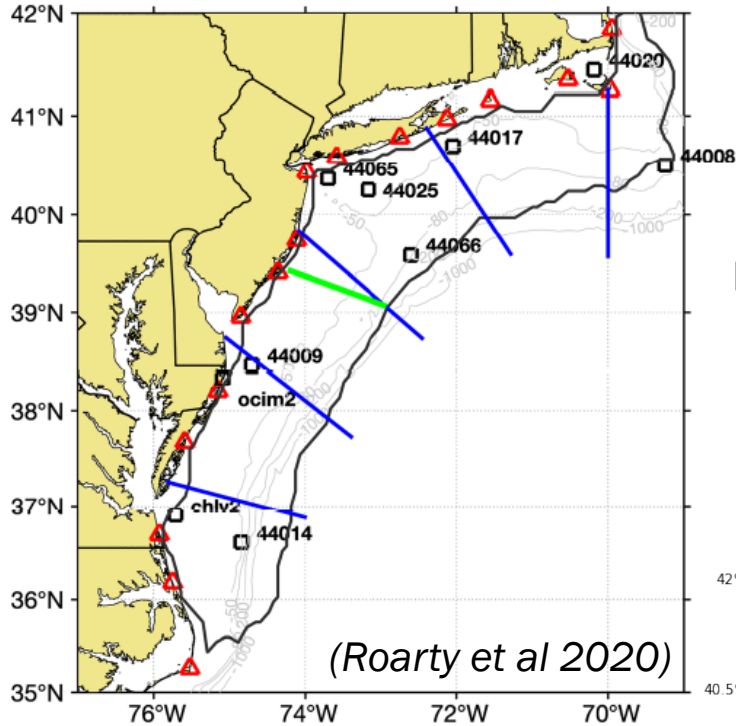



Remove Ekman mean
currents

$U_{\text{Radar}} - U_{\text{Ekman}}$ 2007-2016



Processing of current data estimated by HF radar



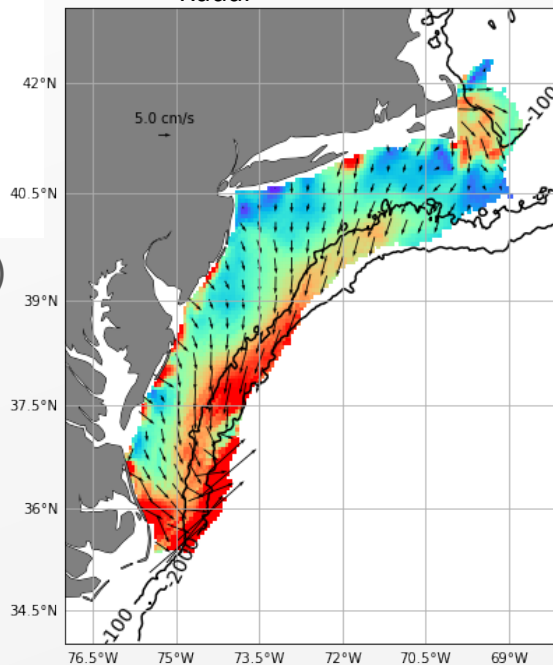
 16 5-MHz-SeaSondes (CODAR) from 2007 to 2016

http://tds.marine.rutgers.edu/thredds/cool/codar/cat_totals.html

November 2006 – December 2016

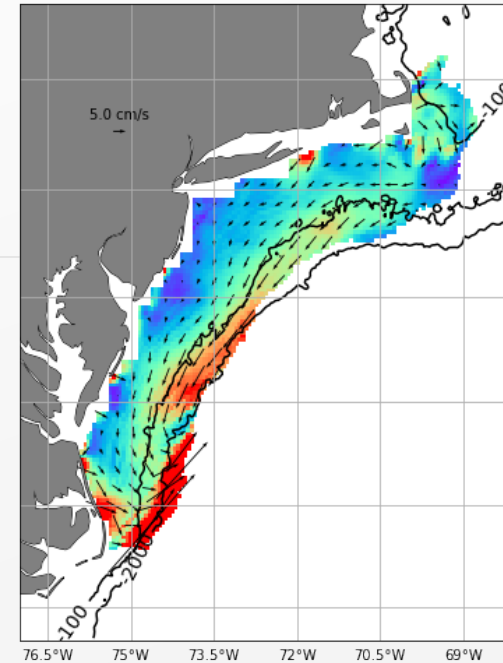
Mean HF radar currents processed by Rutgers University: detided, filtered currents (high frequency signal removed)
Roarty et al 2020

U_{Radar} 2007-2016



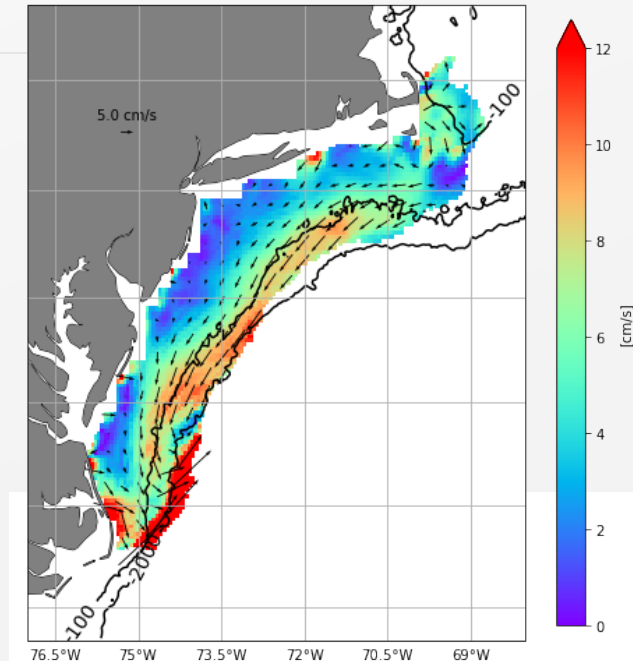
Remove Ekman mean currents

$U_{\text{Radar}} - U_{\text{Ekman}}$ 2007-2016



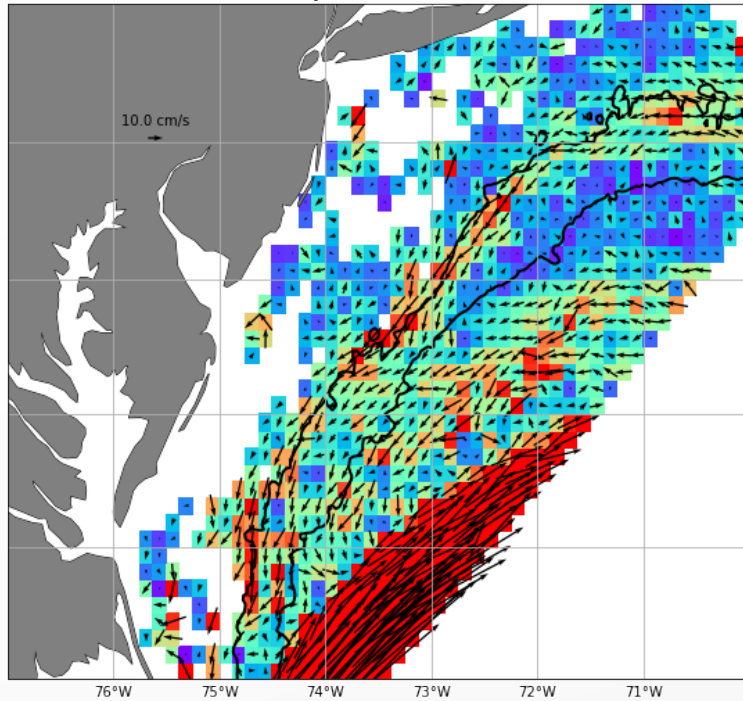
Re-reference radar data mean on the period 1993-2012

$U_{\text{Radar}} - U_{\text{Ekman}}$ 1993-2012

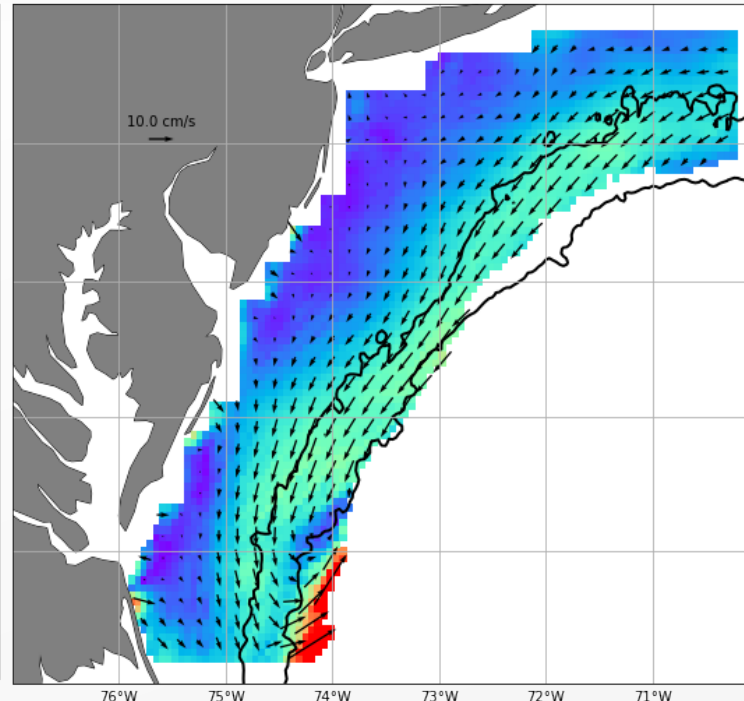


Comparison of radar/drifters currents

Drifters 1/8° 1993-2012



Radar-Ekman 1993-2012



How to explain the differences between the two data sets ?

- Sampling:

- Poor seasonal sampling for near-shore drifters (only summer and fall observations) and on the shelf-break (only spring observations)

- For radars on the shelf-break: only winter observations

- Drifters have a tendency to accumulate in this front because of convergence and subduction, so there may be a sampling bias toward a narrow jet. [J. Wilkin].

- Current along the shelf-break seen by drifters more intense and narrower than in the HF radar current

➤ Which data should we trust the most?

➤ We have chosen to rely more on HF radars because there is much more data

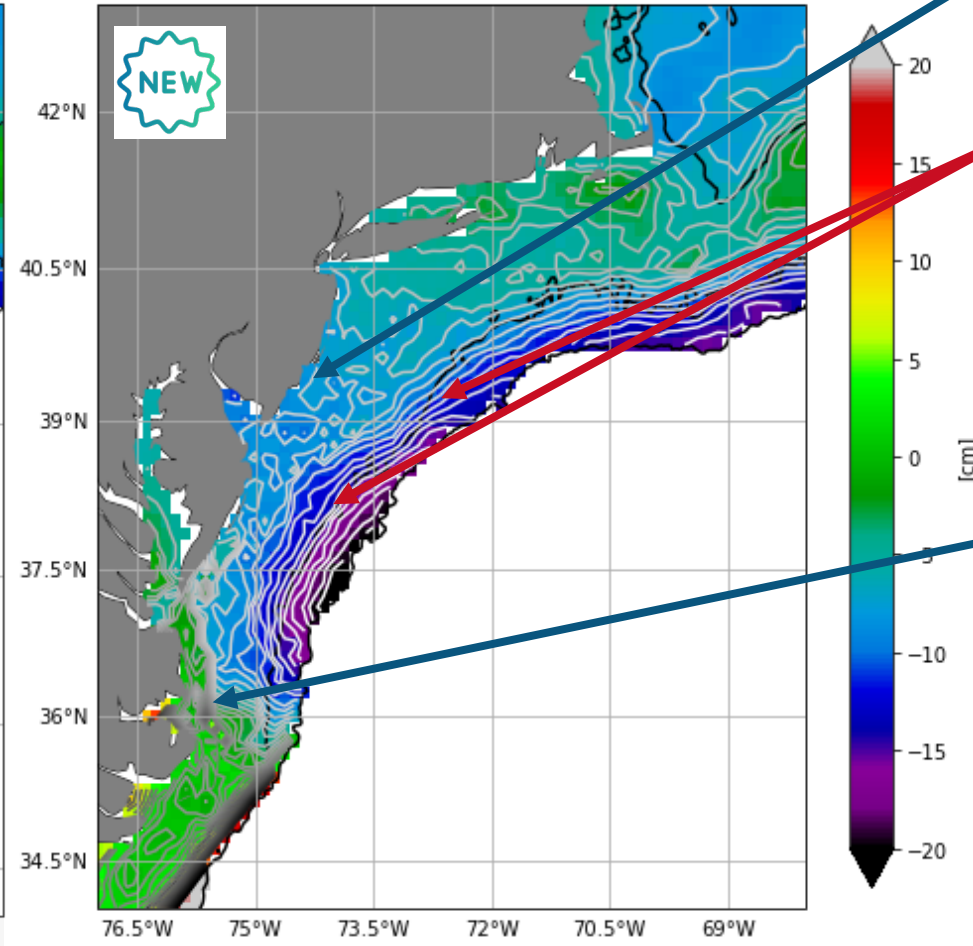
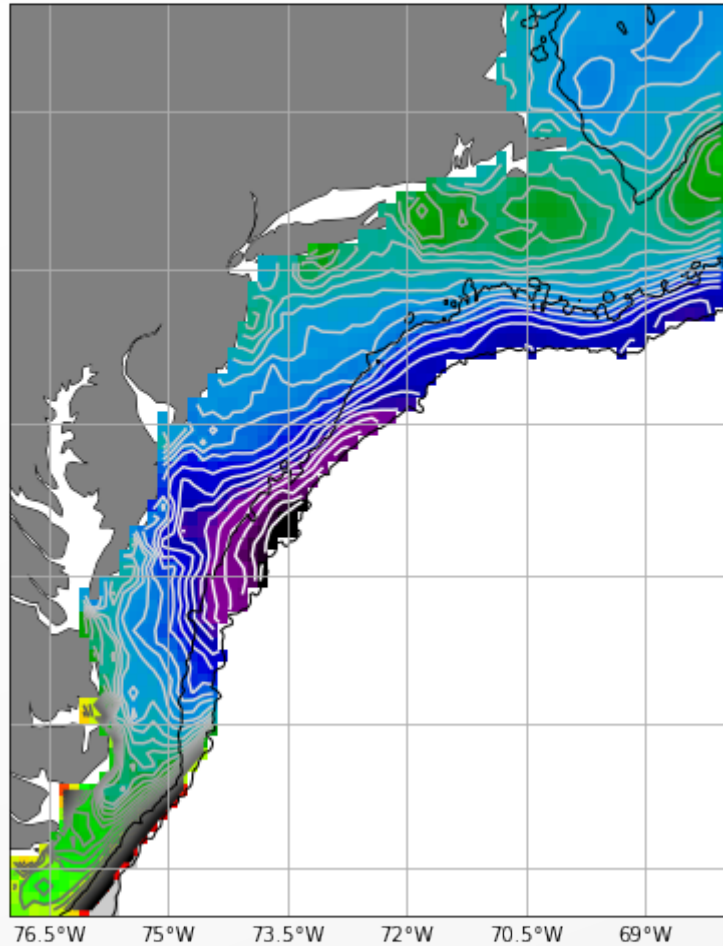
1. First-guess
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The new CNESCLS2022 β MDT vs the CNESCLS-18 MDT

CNES-CLS18

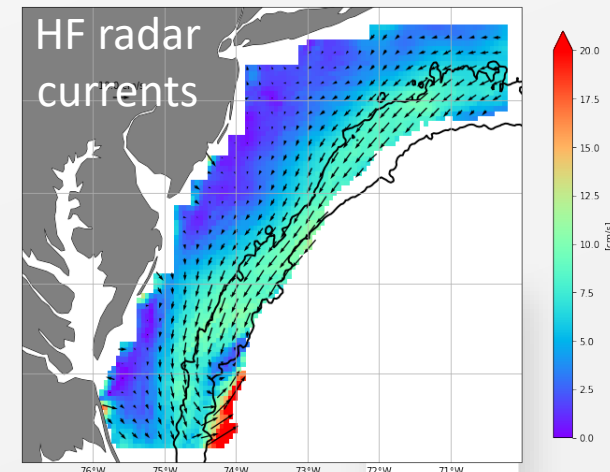
CNES-CLS 2022 β



No appreciable across-shelf gradient near the coast but very weak currents > very influenced by the first-guess

A more organized across-shelf gradient following the shelf-break, suggestive of a more continuous mean flow along this region from 70W to 74W, which is an improvement over the MDT CNES-CLS18 thanks to HF radar currents.

Sharp gradient, behavior related to the first-guess because no data close to the coast



The contours are drawn every 1cm

1. First-guess
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Conclusions



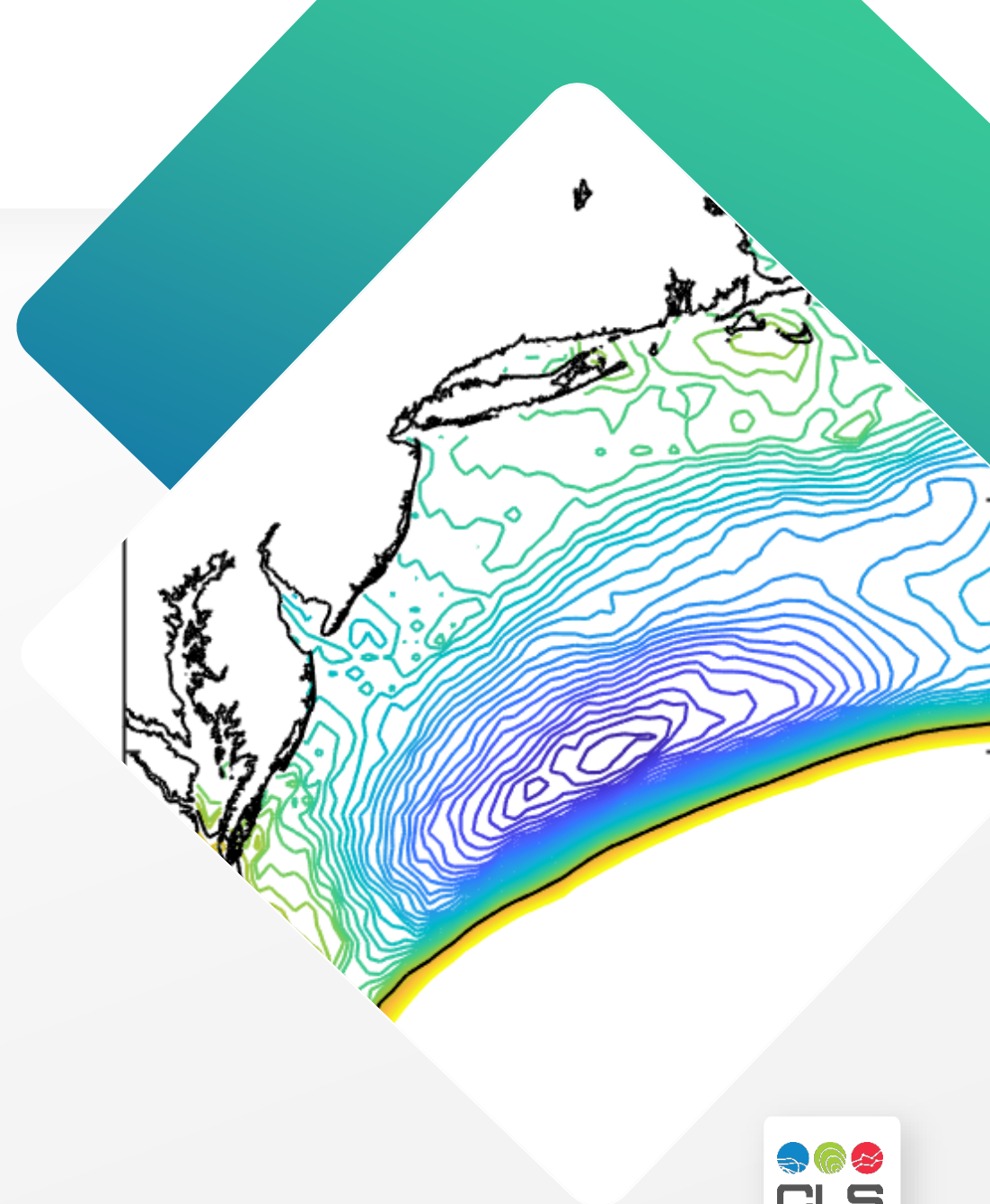
HF radar currents (and drifters currents) are not able to correct the first-guess near the coast → **it is essential to improve the coastal first-guess**

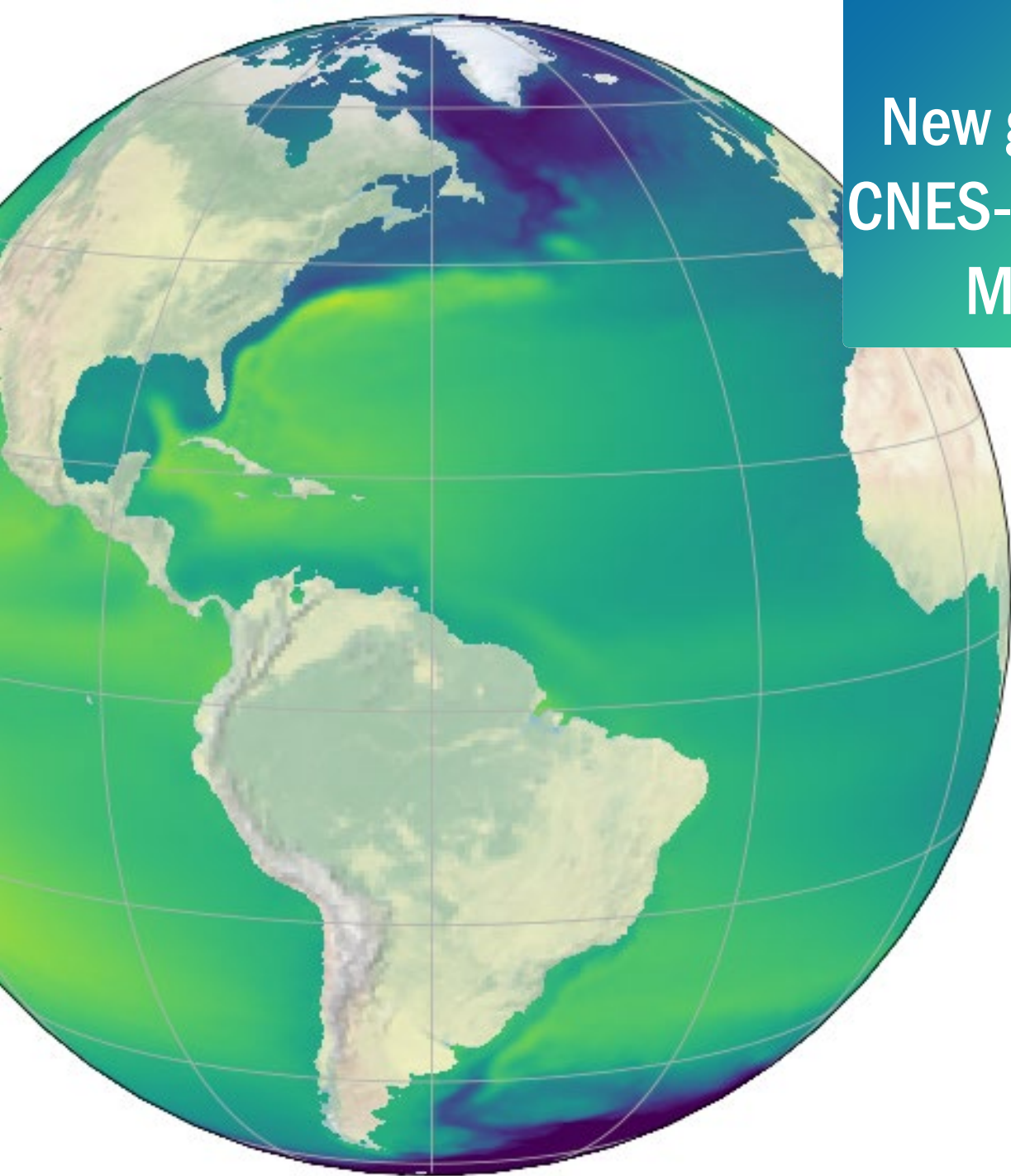


The contribution of HF radar data allows a **better representation of the shelf-break current**



Perspectives: using HF radar data globally
› **Substantial pre-processing** (here favourable case because data already detided, filtered and averaged)





New global CNES-CLS22 MDT

End of June 2022



Beta version



Validation/feedbacks by beta users

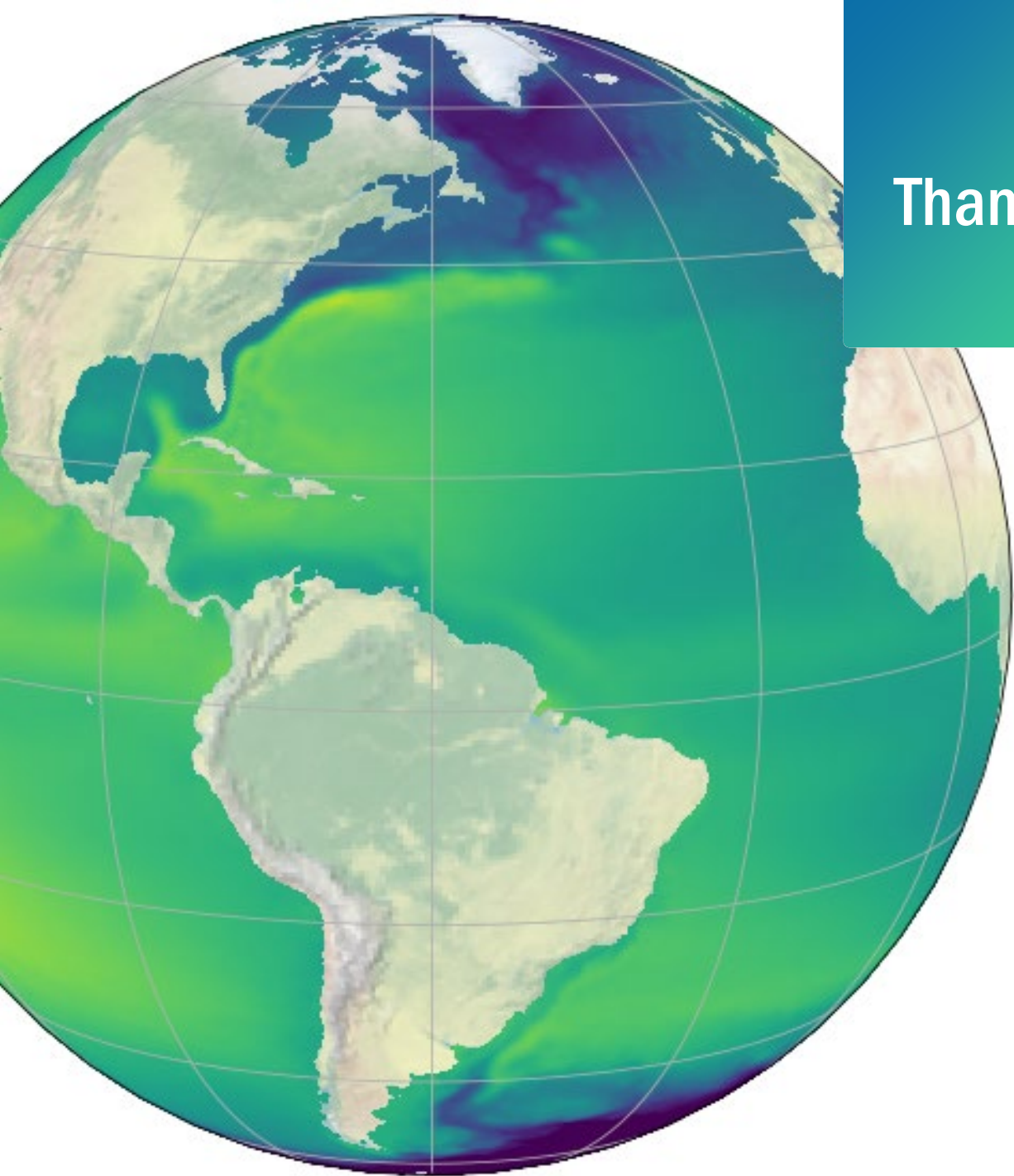
- If you are interested to be beta tester, let me know sjousset@groupcls.com

End of 2022



Final version end of 2022

sjousset@groupcls.com



Thank you

sjousset@groupcls.com

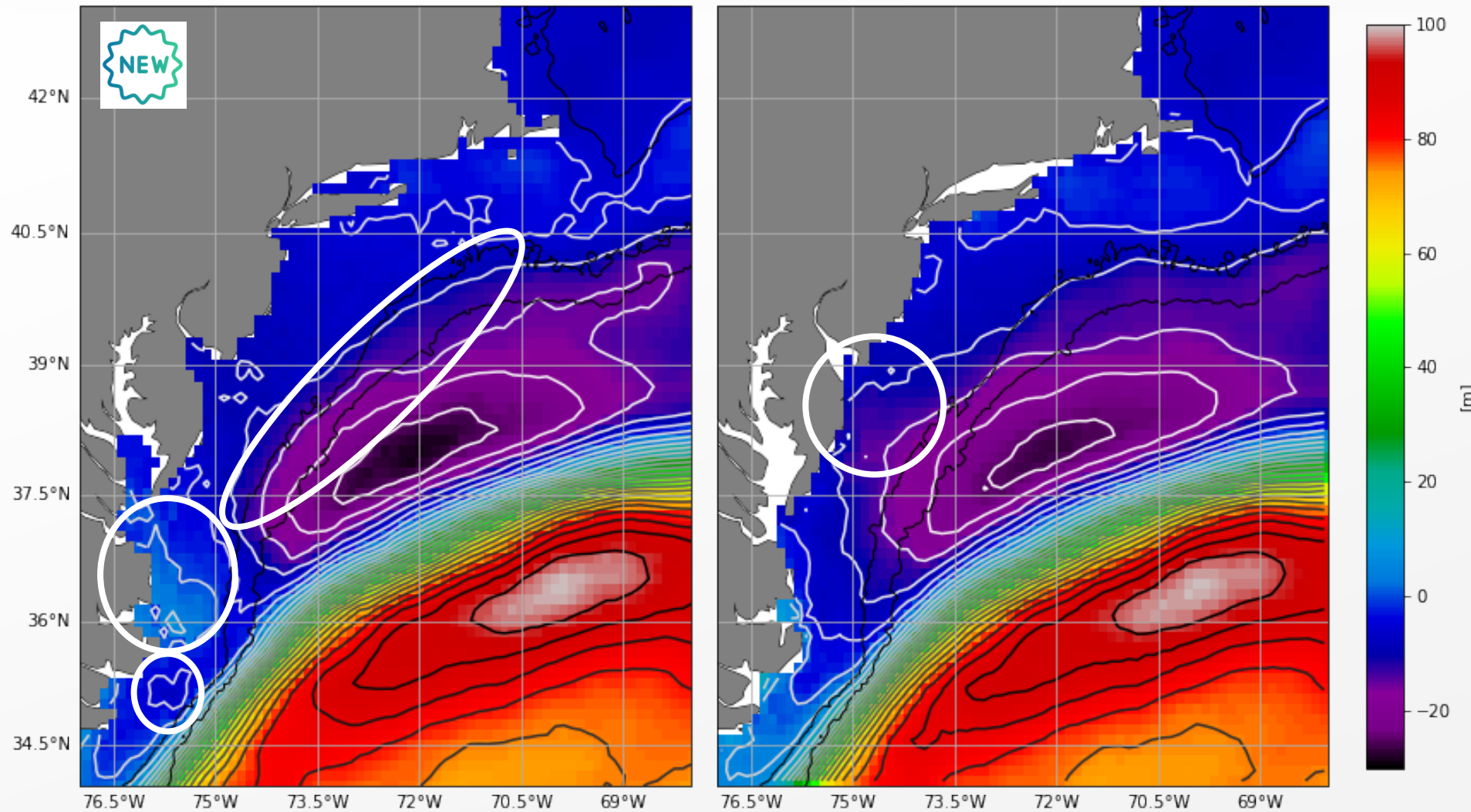


Backup
slides

The new CNESCLS2021 β MDT vs the CNESCLS-18 MDT

CNES CLS2021beta
min=-28.527, max=99.248, mean=22.435, delta=127.775

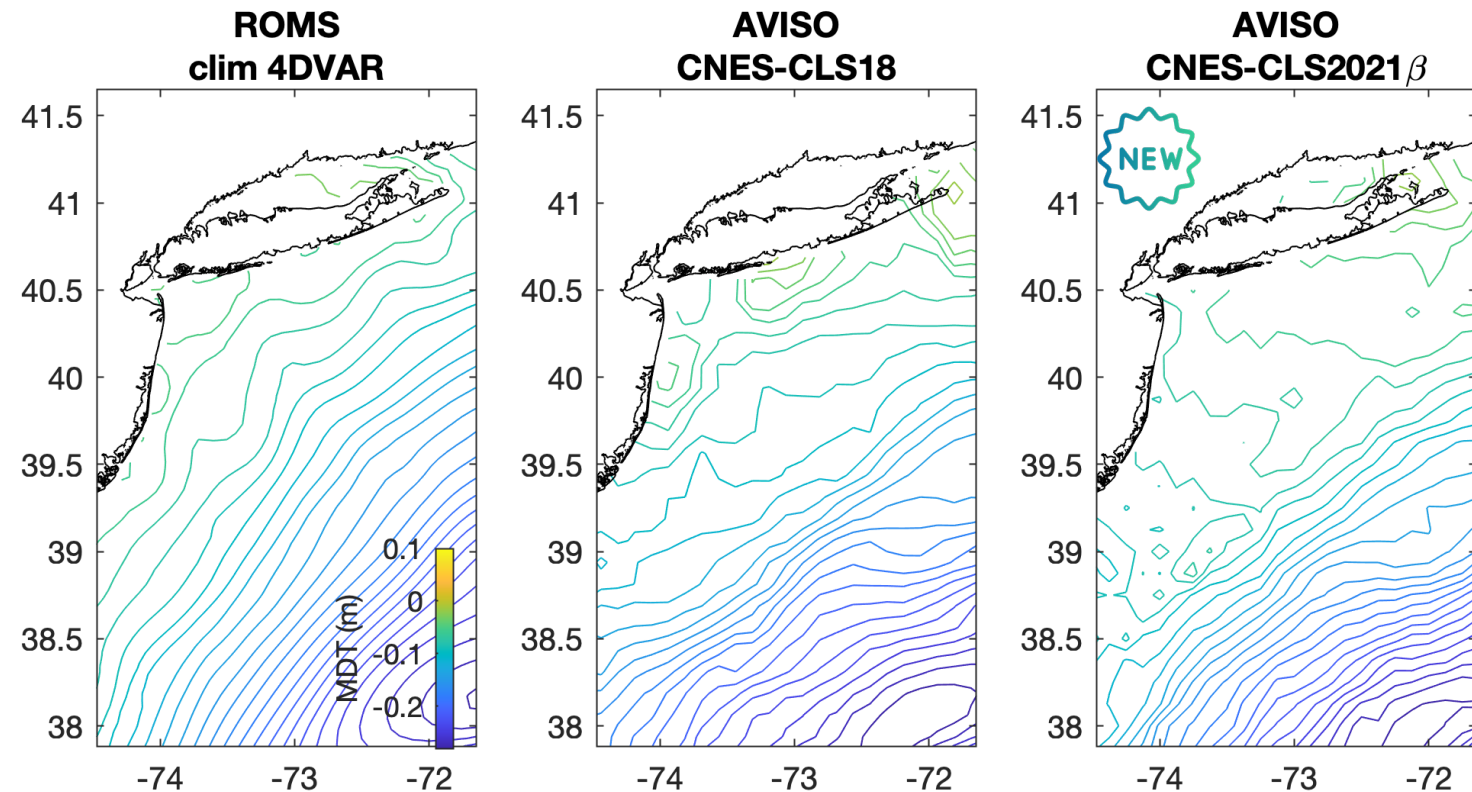
CNES CLS18
min=-26.900, max=99.080, mean=22.720, delta=125.980



■ Differences on the continental shelf

The contours are drawn every 5cm

The new CNESCLS2021 β MDT vs the CNESCLS-18 MDT



"ROMS clim 4DVAR" is the MDT used in the operational forecast system, calculated using the same methodology described in Levin* et al. (2018) but for a larger model domain that includes the Gulf of Maine.

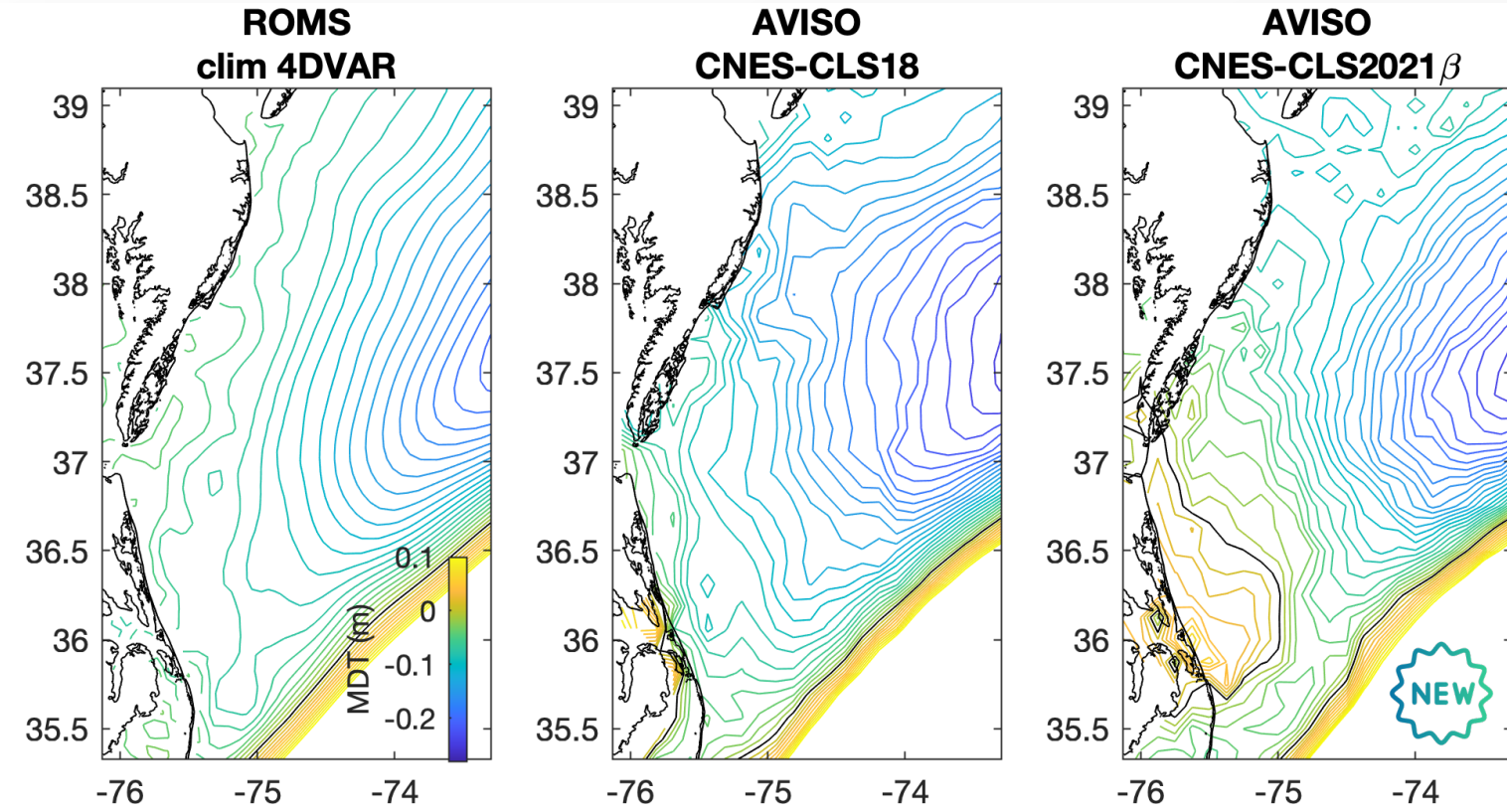
- NORTH inland plateau (bathy<30m):

There is no gradient perpendicular to the coast, but there should be, since the mean flow is always southwest. [J. Wilkin]

This should be visible if the aeostrophic signals are well suppressed from the HF radar.

- Improving near-shore radar processing!
The Ekman model used is not efficient enough in this area.
- Make a model from HF-radar

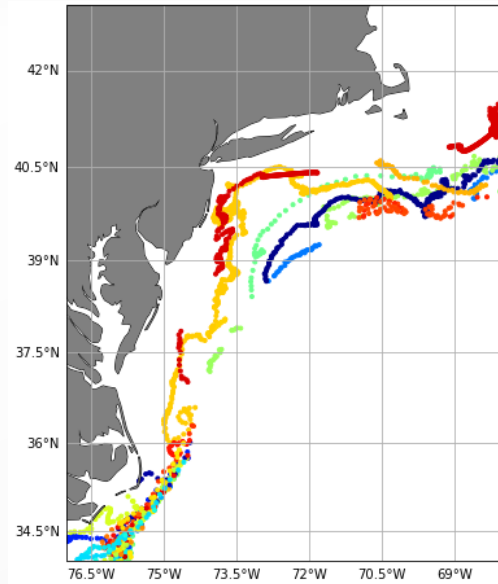
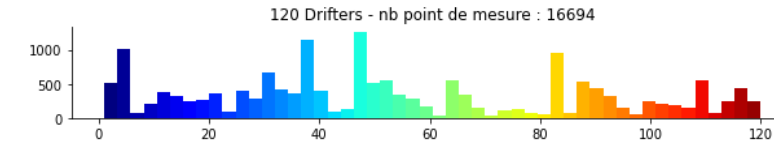
The new CNESCLS2021 β MDT vs the CNESCLS-18 MDT



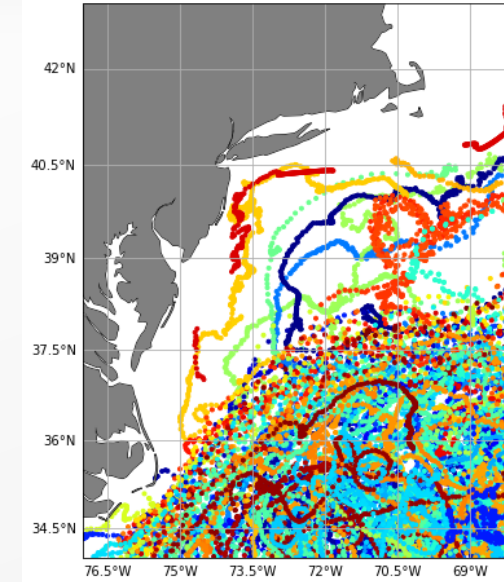
■ In the south:

- Sea level CNES-CLS2021 β takes a local maximum north of Cape Hatteras, which does not seem dynamically reasonable.
- Recent work by the PEACH program has added mooring data and repeated glider transects in this region and suggests that MAB waters are moving offshore at about 36-36.5N. -> on this point, the CNES-CLS18 seems better than the CNES-CLS2021 β [J. Wilkin]

Validation with independant drifters [2017-2019]



Drifters number	60	Measurement number	2094		
name	U rmsd [cm/s]	U corr	V rmsd [cm/s]	V corr	
CNESCLS18	19.297	0.759	20.663	0.797	
CNESCLS2021be					
ta	19.413	0.755	20.913	0.792	



nb drifter	120	nb points	16735		
name	U rmsd [cm/s]	U corr	V rmsd [cm/s]	V corr	
CNESCLS18	21.629	0.886	21.509	0.827	
CNESCLS2021be					
ta	21.649	0.885	21.584	0.826	

- No real differences between the new MDT and the global MDT compared to independent drifters
- Bias of this comparison: on the continental shelf we trust more the HF radars which give a mean current different from the drifters