

living planet symposium | BONN

23-27 May
2022

TAKING THE PULSE
OF OUR PLANET FROM SPACE



Spatio-temporal data fusion of Sentinel-2 and Sentinel-3 ocean color products using a hybrid reconstruction-based and learning-based approach

Olivier Regniers¹, Rémi Budin¹, Thibaut Voirand², Pedro Ribeiro³, Virginie Lafon¹

1. i-Sea 2. Telespazio France 3. CoLAB +ATLANTIC

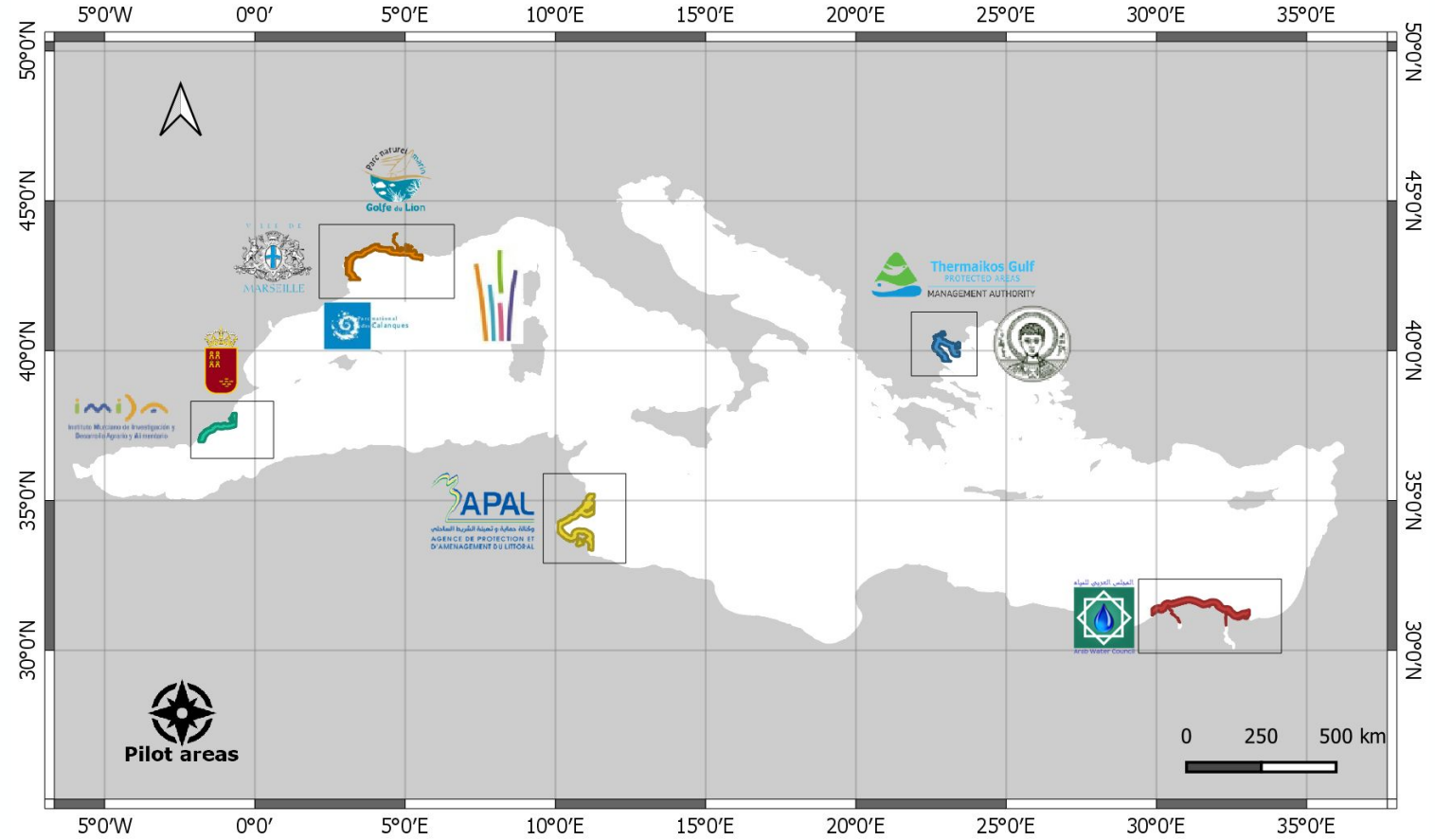
23/05/2022

MEDITERRANEAN Regional Initiative

LAND-BASED POLLUTION ASSESSMENT & MONITORING IN THE MEDITERRANEAN COASTAL WATERS

Main objective

Develop and produce **daily high-resolution, gap-free** maps of EO **water quality** products by using **data fusion** techniques to combine the high temporal resolution of **S3-OLCI** and high spatial resolution of **S2-MSI** data



<https://medeos.deimos.pt/>

MedEOS is a project funded by ESA Mediterranean Regional Initiative within Future-EO - Science for Society programme (2020-2022), under the Grant Reference: AO/1-10376/20/I-EF

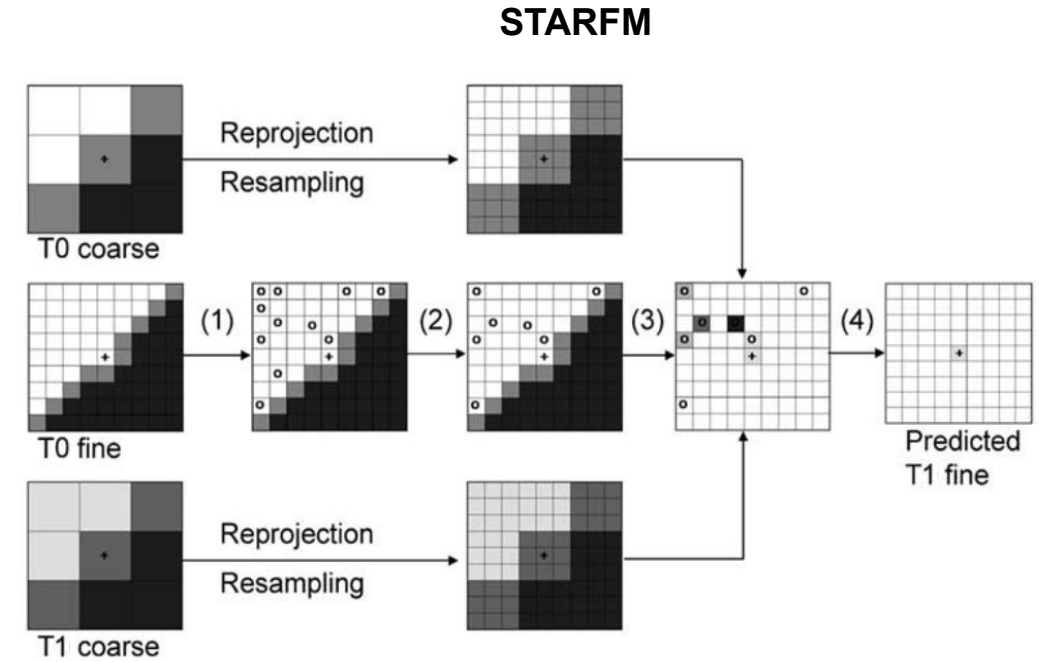
T0 : Fine Resolution (T0 fine) & Coarse Resolution (T0 coarse) images acquired on the same day

T1 : Only Coarse Resolution images acquired (T1 coarse)

STARFM decision rules

T1 fine pixels predicted with a weighted set of decision rules based on:

- spectral difference between S2 and S3
- temporal difference between S3 T0 and S3 T1
- distance between central pixel and candidate pixel



Source: On the Blending of the Landsat and MODIS Surface Reflectance: Predicting Daily Landsat Surface Reflectance, Gao et al. 2006

Main hypothesis
Objects do NOT drastically change between T0 and T1



Sentinel-3 - 22/11/2020



STARFM decision rules

Main challenges

Highly dynamic environment

Lower reflectance values on water

↓

Higher sensitivity to atmospheric correction, BRDF, sunlint, noise

Differences between S2 and S3 spectral bands

Target high resolution (20m)

<<<

Input coarse resolution (300m)

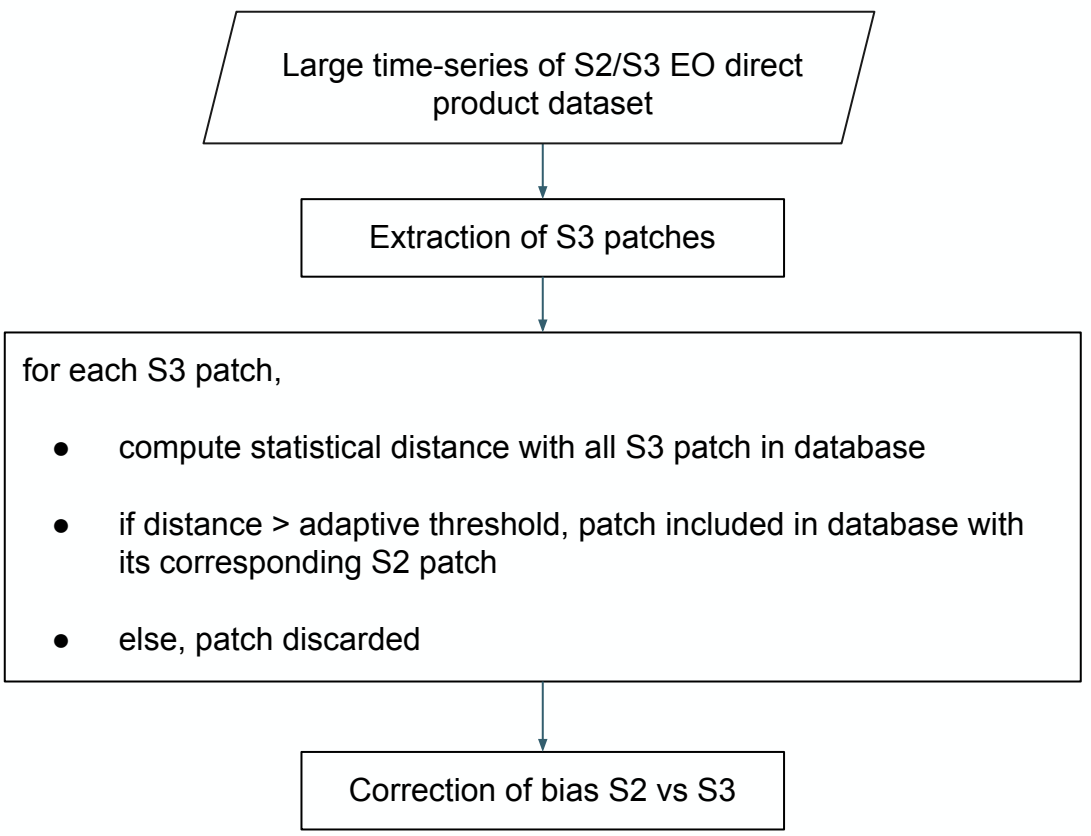
T1 fine pixels predicted with a weighted set of decision rules based on:

- spectral difference between S2 and S3
- temporal difference between S3 T0 and S3 T1
- distance between central pixel and candidate pixel

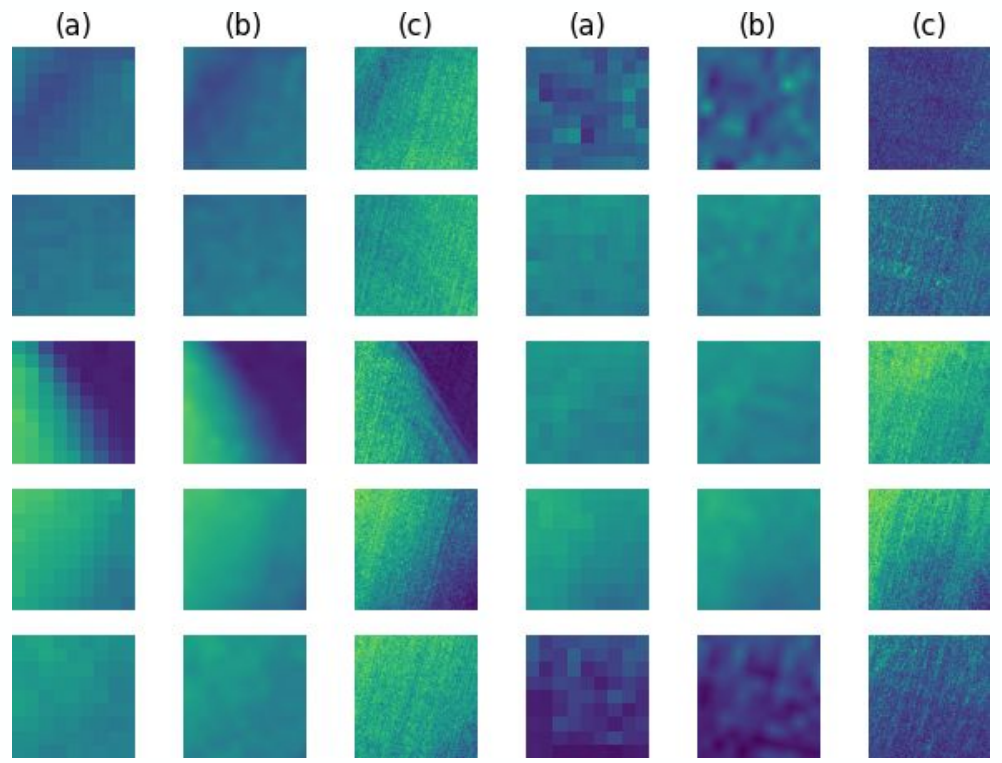
Data fusion performed on EO direct products to limit the impact of differences in water surface reflectance between S2 and S3

How can we trick data fusion reconstruction based approach to work in highly dynamic ocean environment ?

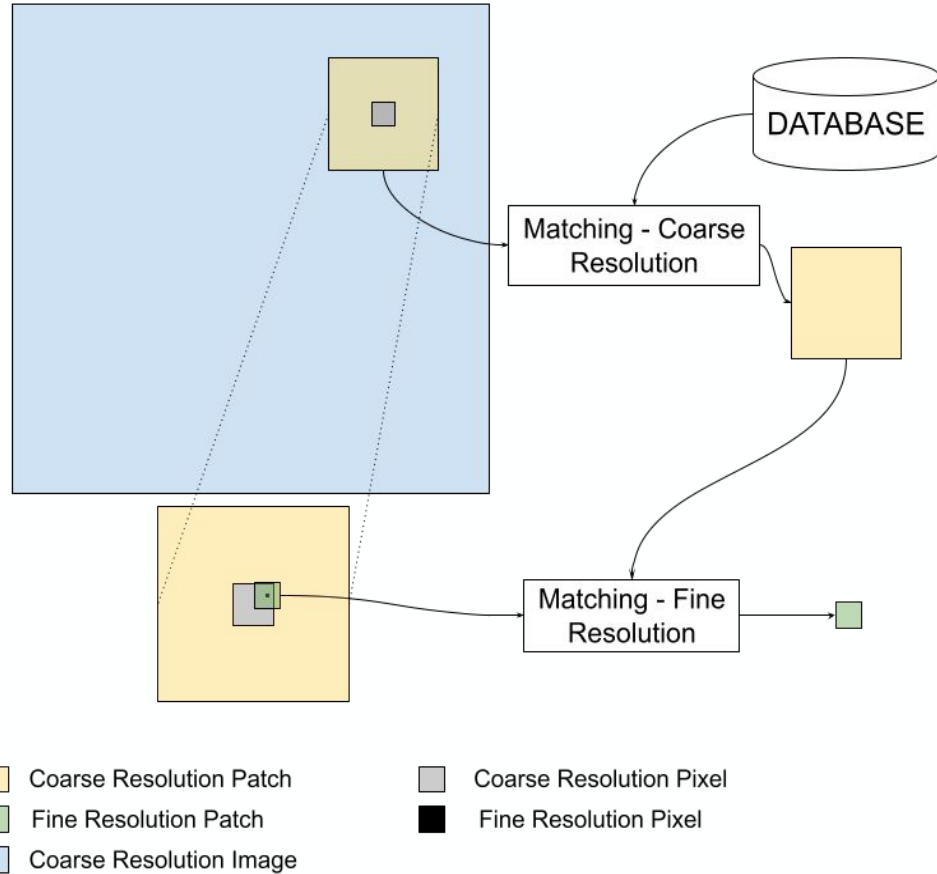
Data selection recursive process



pairs of S2/S3 reference database



Extract of the reference database built from pairs of S2 and S3 products. (a) S3 patches coarse resolution, (b) S3 patches fine resolution, (c) S2 patch the same day as S3 product.



Coarse and fine matching analysis

S3 product on targeted day T1

for each patch around pixels of S3 T1 product

- find S3 patch with most similar statistical content in reference database at coarse resolution → **Coarse matching analysis**

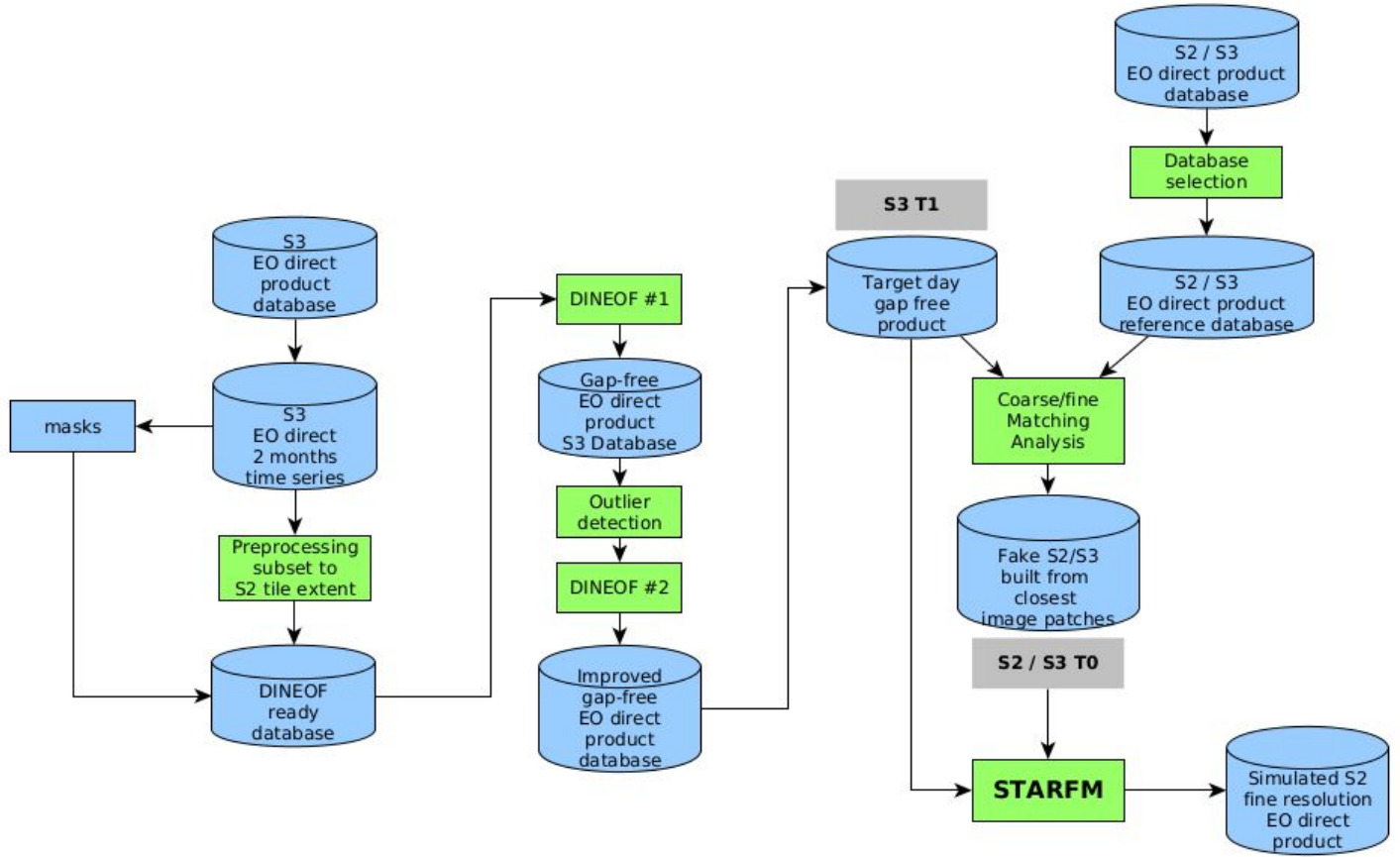
→ "S3 T0"

- New database is build from all patches derived from S3 patch 'coarse resolution' resampled at fine resolution
- find S3 patch with most similar statistical content in new database at fine resolution → **Fine matching analysis**

→ "S2 T0"

Triplets of "S3 T0", "S2 T0" and S3 T1

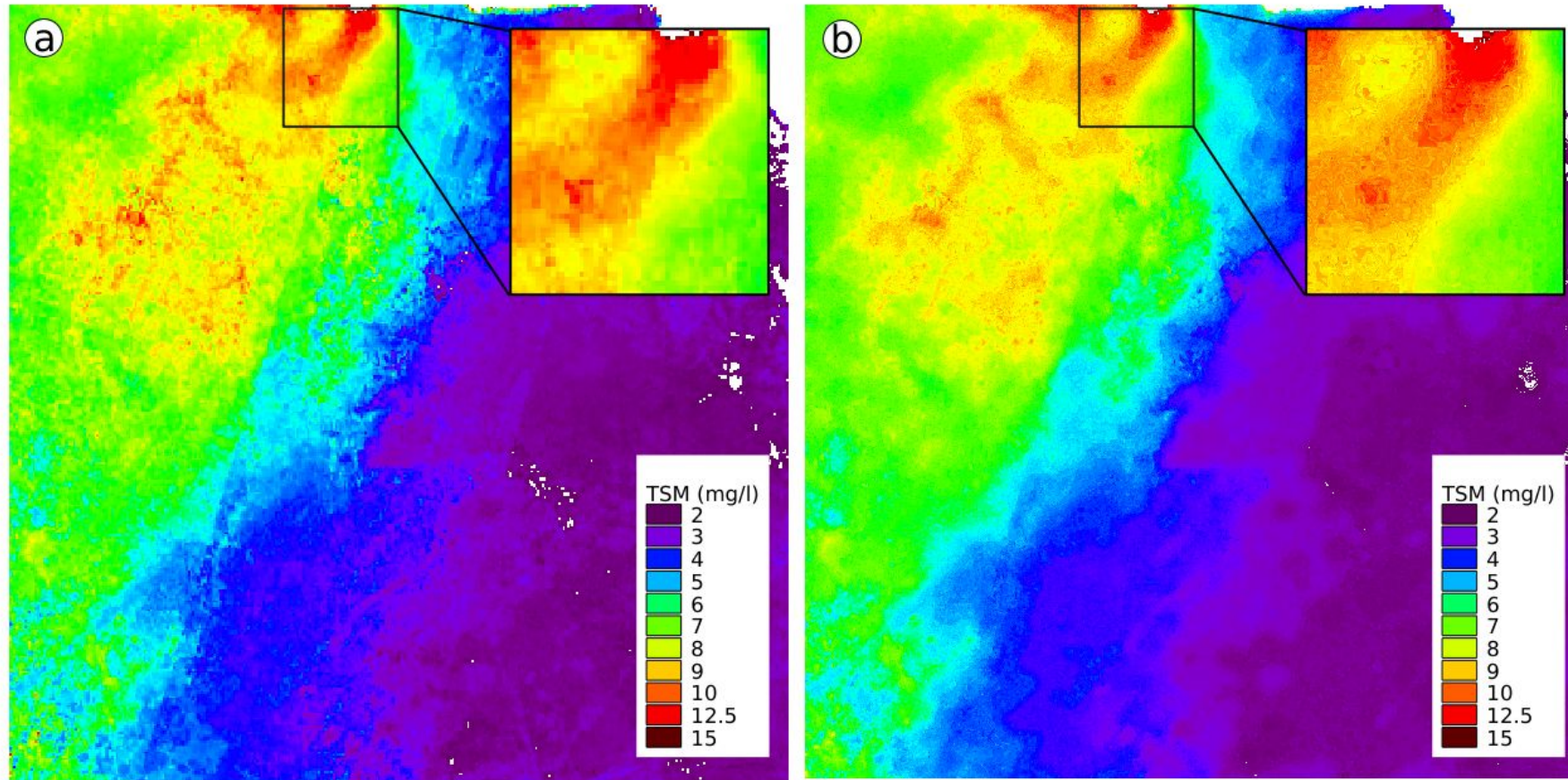
→ STARFM



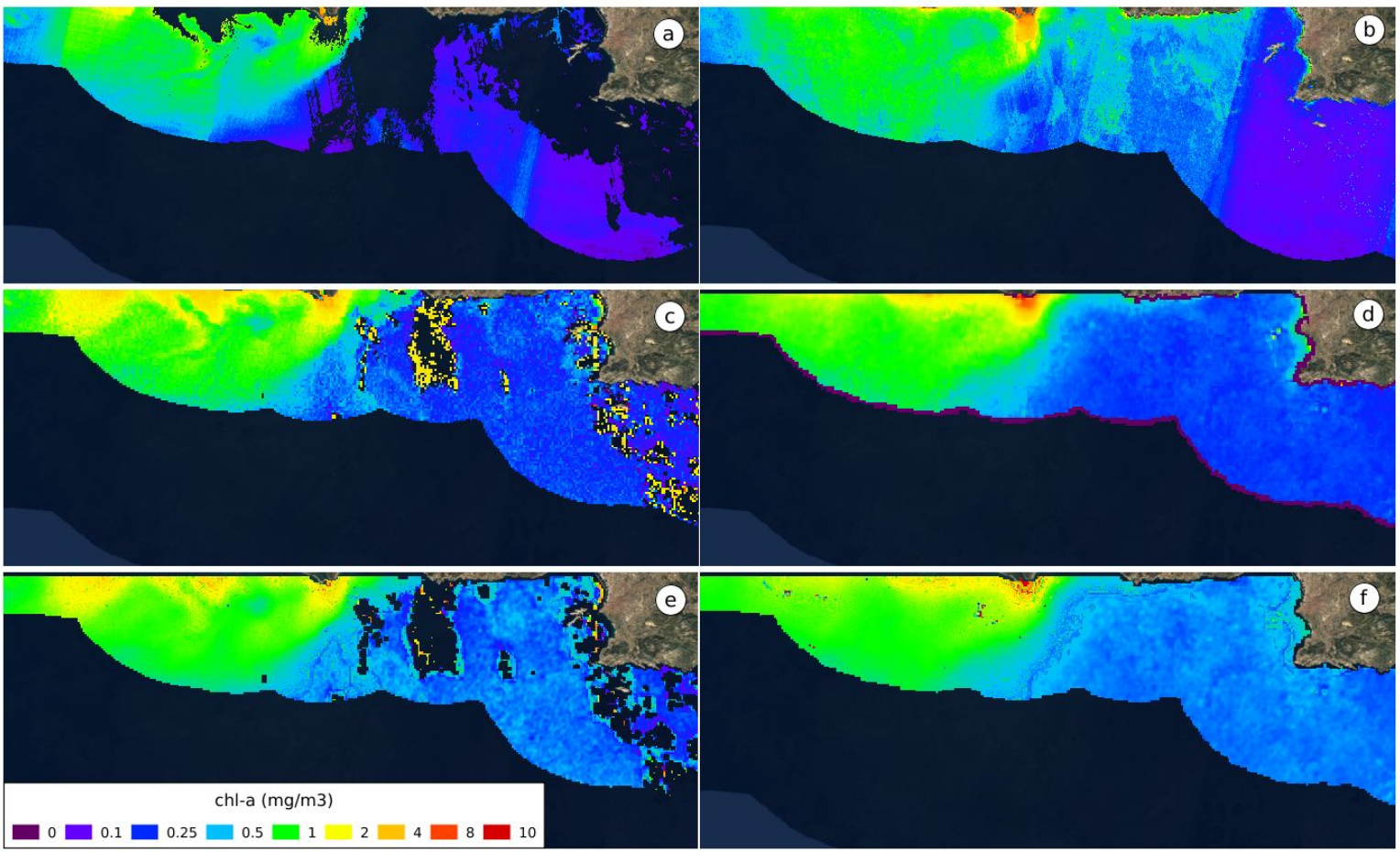
General workflow of the Gap-filling and Data Fusion processing chain

Main steps:

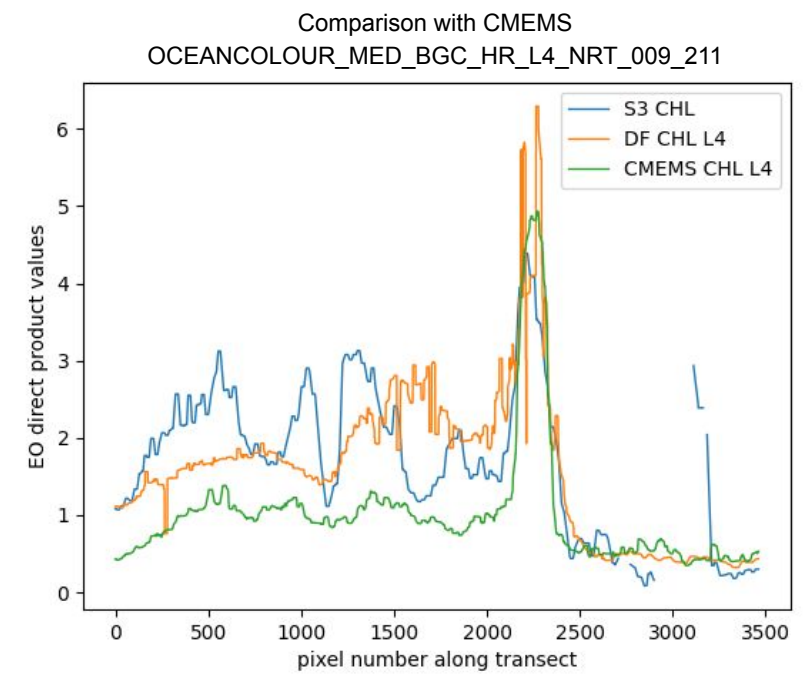
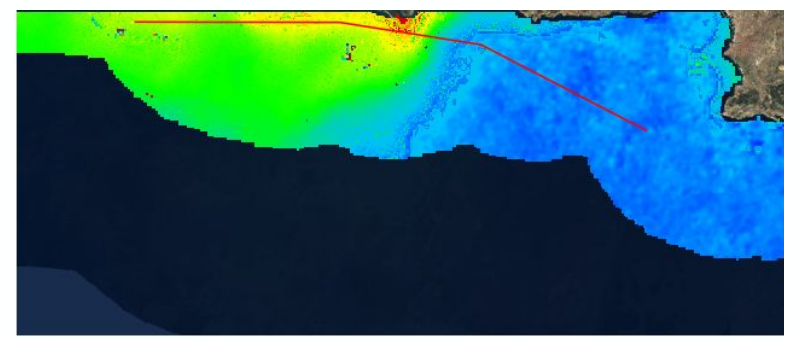
- **Gap-filling** (DINEOF) of S3 EO direct products with outlier detection
- **Data selection** on S2/S3 EO direct products dataset to build a reference database
- Coarse and fine **matching analysis** to derive artificial S2/S3 image pair
- **STARFM** to simulate S2 EO direct product at fine resolution



Example of preliminary results on TSM - (a) S3 derived TSM product after gap-filling at 300m, (b) TSM data fusion output at 20m



Visual comparison between (a) 100m CMEMS HR OC CHL L3, (b) 100m CMEMS HR OC CHL L4, (c) 300m S3 CHL, (d) 300m S3 CHL after DINEOF gap-filling, (e) 20m CHL product after data fusion without gap-filling, (f) 20m CHL product after data fusion with gap-filling.



Conclusions

Spatio-temporal data fusion for water applications is **not straightforward**

More efficient to apply data fusion **at the product level** rather than at the reflectance level

Tricking data fusion state-of-the-art approaches with proposed database and matching analysis is working

Computation time is compatible with operational application

BUT

Artefacts are present and results are not fully realistic



Next steps

Production phase I - **ongoing**

Pre-validation - **ongoing**

MTR → **July 2022 Go / no Go**

Production Phase II - starting **this summer**

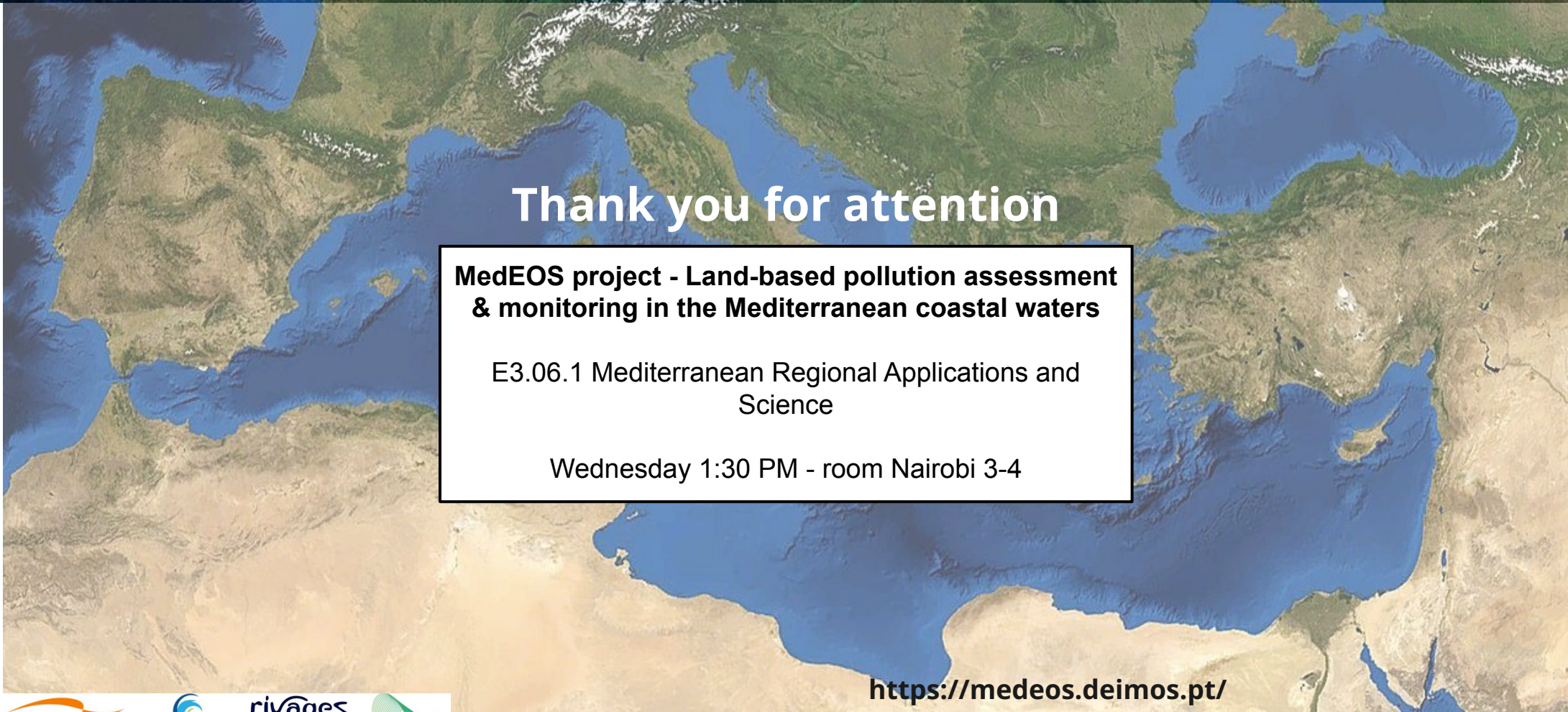
Larger scale validation with in-situ data

Refining of the output resolution

End-user's uptake

<https://medeos.deimos.pt/>

MedEOS is a project funded by ESA Mediterranean Regional Initiative within Future-EO - Science for Society programme (2020-2022), under the Grant Reference: AO/1-10376/20/I-EF



Thank you for attention

MedEOS project - Land-based pollution assessment & monitoring in the Mediterranean coastal waters

E3.06.1 Mediterranean Regional Applications and Science

Wednesday 1:30 PM - room Nairobi 3-4

<https://medeos.deimos.pt/>



MedEOS is a project funded by ESA Mediterranean Regional Initiative within Future-EO - Science for Society programme (2020-2022), under the Grant Reference: AO/1-10376/20/I-EF

