

A satellite night view of Earth showing city lights and coastlines. A large green rectangular box is overlaid on the right side of the image, containing the title and presenter information.

# PV-CC PDGS status & Cal/Val plan

Iskander Benhadj



## Outline

- PV-CC objectives
- PDGS development status
- PV-CC Cal/Val plan

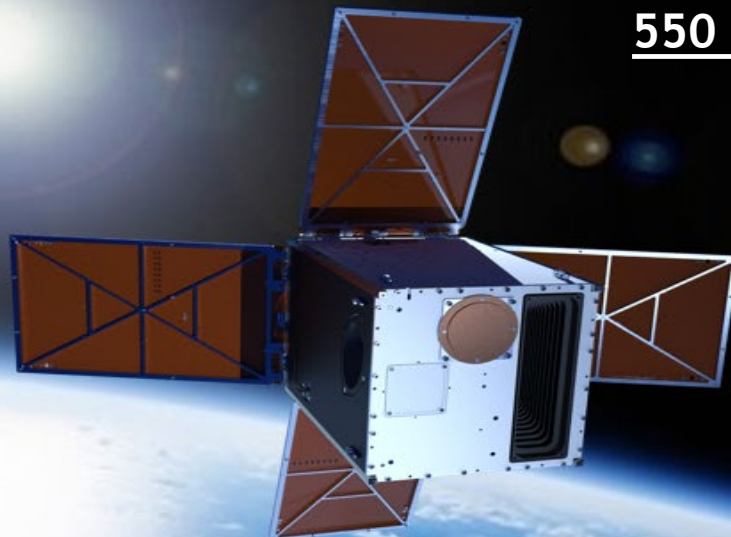
# PROBA-V Companion Cubesat (PV-CC)

AerospaceLab

Belgian Nanosat platform flying  
the spare PROBA-V Instrument

Sun-synchronous orbit 500-  
550 km altitude range

Global coverage 12 days



Cubesat mass 18kg

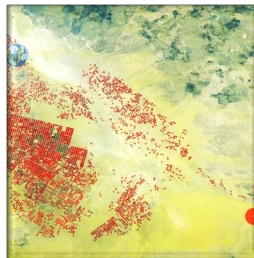
Re-use of PROBA-V ground  
segment for the IOD data

# PV-CC objectives



## Technology Objectives

- Demonstrate TRL level of the platform
- Verification of the ground station (control & command as well as downlink capacity)
- Cross calibration of PROBA-V with the companion Cubesat



## Application Objectives

- Studies on BRDF effects (allowing better modeling) thanks to different observation geometry (viewing and sun angles)
- Harmonization of datasets captured by different platforms, in a different orbit, but with the same sensor
- Improve Calibration / Validation for Cubesat and Small satellites



# PROBA-V vs PV-CC

|                                    | Proba-V                              | PVCC                                |
|------------------------------------|--------------------------------------|-------------------------------------|
| <b>Altitude (km)</b>               | 820                                  | 564                                 |
| <b>GSD at Nadir</b>                | VNIR : 97 m<br>SWIR : 186 m          | VNIR : 67 m<br>SWIR : 128 m         |
| <b>Ground Speed (km/s)</b>         | 6,6                                  | 7,0                                 |
| <b>Native sampling time (ms)</b>   | VNIR: 14,7<br>SWIR: 28,3             | VNIR: 9,6<br>SWIR: 18,4             |
| <b>Integration Time Range (ms)</b> | VNIR: 1,2 – 11,3<br>SWIR: 0,4 – 22,3 | VNIR: 1,2 – 6,2<br>SWIR: 0,4 – 12,4 |
| <b>Satellite Mass (kg)</b>         | 158                                  | 18                                  |



2022-May-20 08:00:00.000 UTC

Lat :

2022-May-20 08:00:00.000

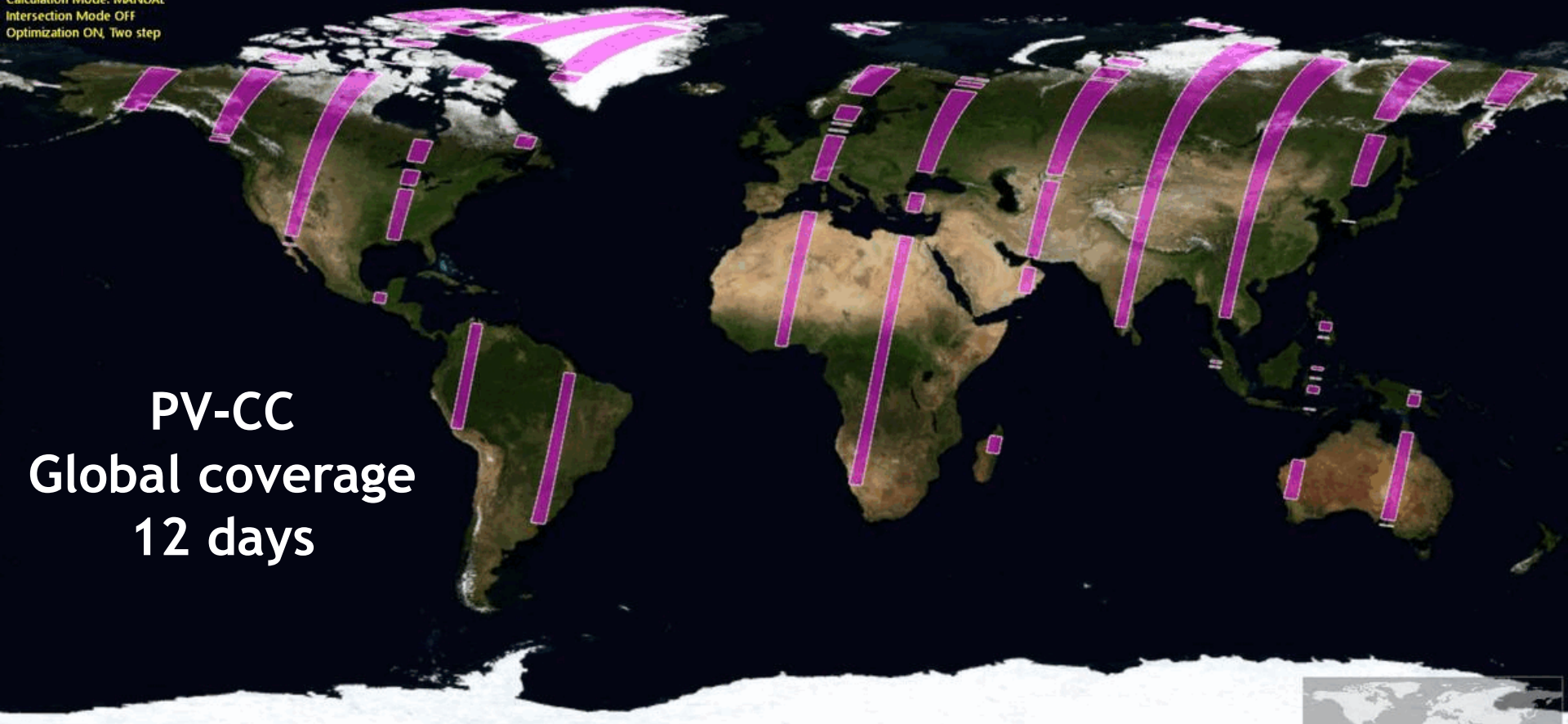
Lon :

Sat 21-May-2022 < + - > ⇄

Calculation Mode: MANUAL

Intersection Mode OFF

Optimization ON, Two step



**PV-CC**  
**Global coverage**  
**12 days**

**Day 1**

Image courtesy of NASA (earth.nasa.gov)

SAVOIR - Multisatellite Swath Planner - © TAITUS SOFTWARE



2022-May-20 08:00:00.000 UTC

Lat :

Lon :

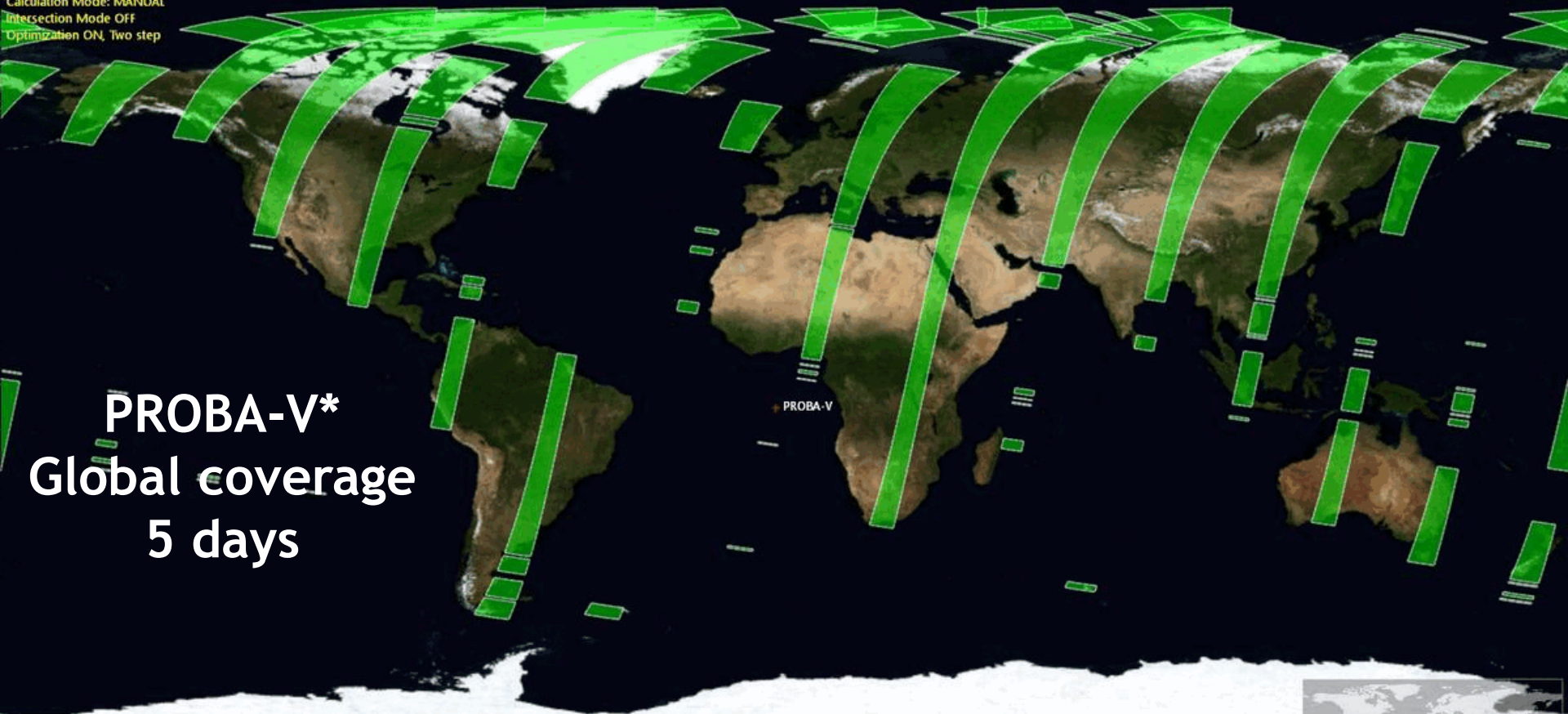
Calculation Mode: MANUAL

Intersection Mode OFF

Optimization ON, Two step

2022-May-20 08:00:00.000

Sat 21-May-2022



**PROBA-V\***  
Global coverage  
5 days

PROBA-V

**Day 1**

Image by [esa/sa \(credit: earth.nasa.gov\)](https://earth.nasa.gov)

SAVOIR - Multisatellite Swath Planner - © TAITUS SOFTWARE



\*center camera



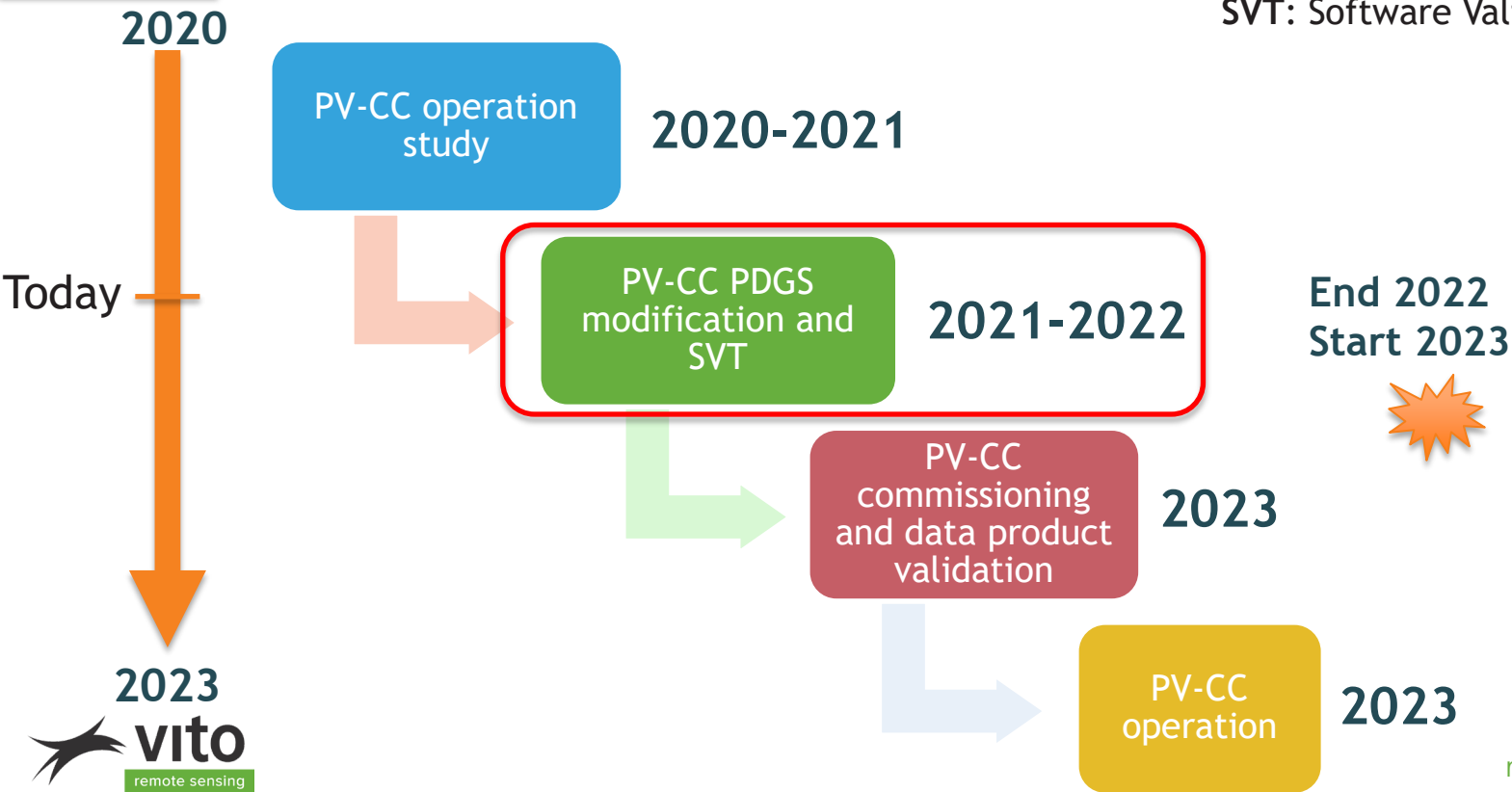
# PDGS DEVELOPMENT STATUS





# PV-CC PDGS phases/contracts

PDGS: Payload Data Ground Segment  
SVT: Software Validation and Testing



Launch



# PDGS overview and updates

- Analysis of PV-CC high-level mission requirements and impact assessment on PDGS

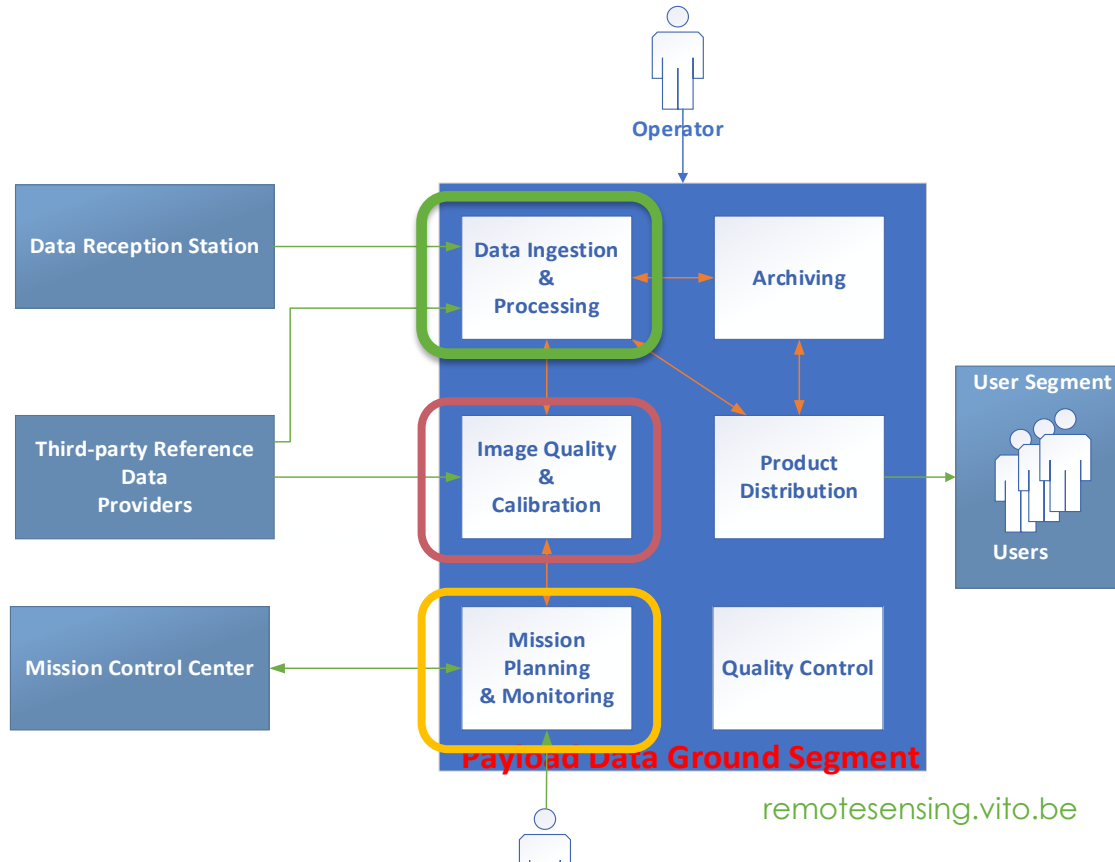
✓ The definition of RAW data products

✓ The MCC - User Segment interface

✓ MCC tasking and commanding vs. land-sea mask imaging

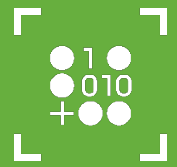
✓ Update of calibration to accommodate for Cubesat low performance

## Re-use of PROBA-V ground segment ground segment

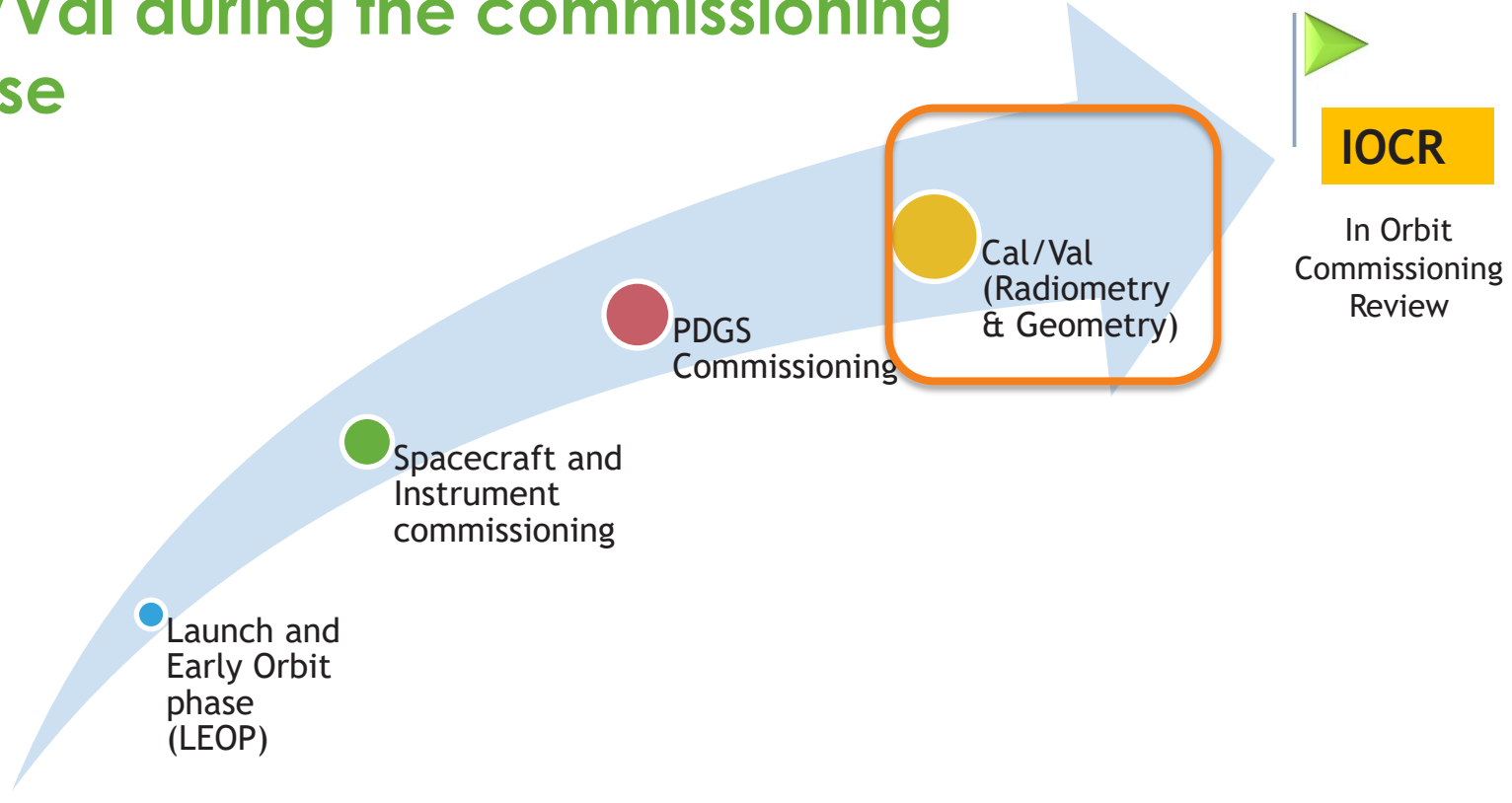




**PV-CC  
CAL/VAL  
PLAN**



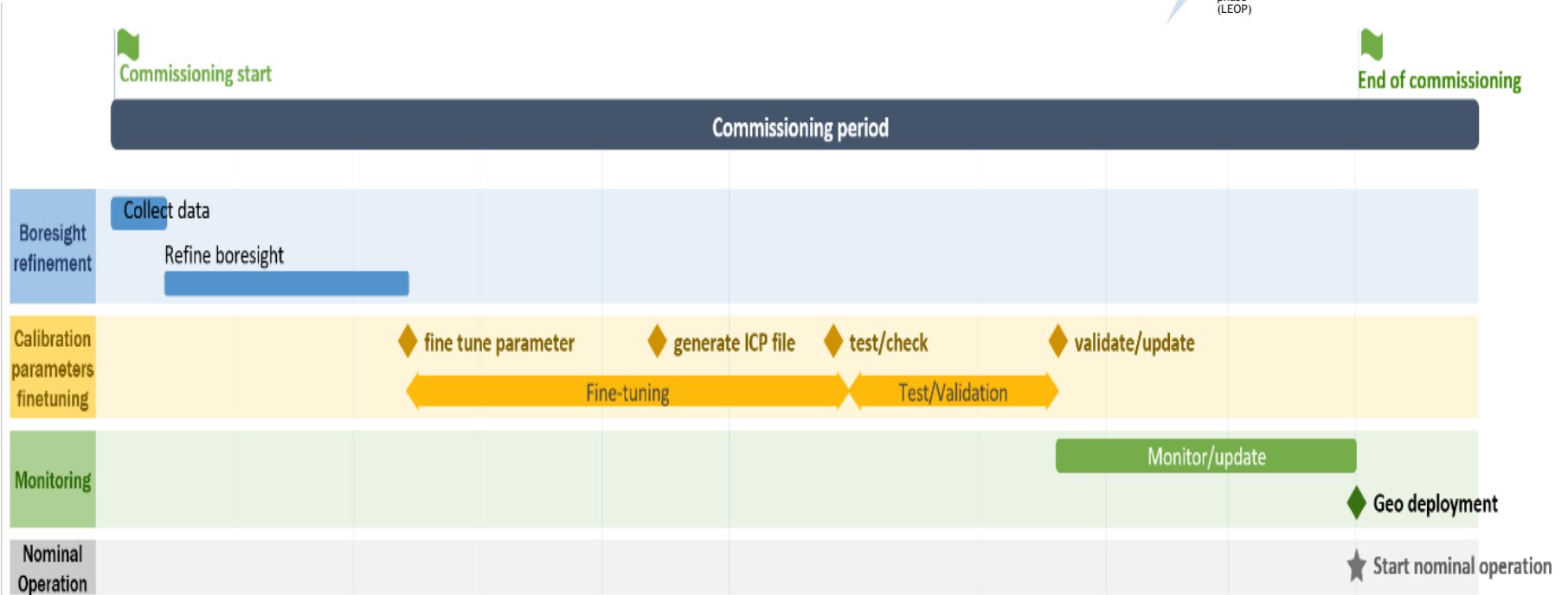
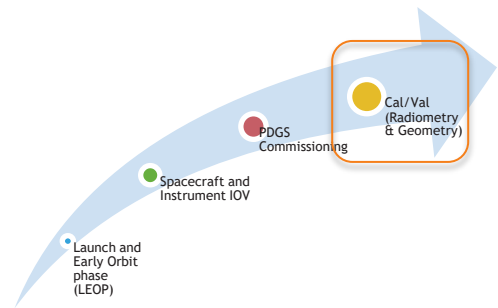
# Cal/Val during the commissioning phase



**PV-CC launch**

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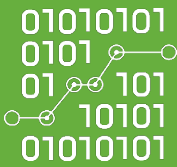
# Cal/Val plan (geometry)





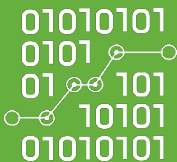
# Cal/Val plan (geometry)

- GCP database from Landsat/Sentinel2 is prerequisite
- GCP distortion calculation (chip matching + cross correlation)
- Parameter inversion based on robust Least square fitting and outliers removal
  - **Interior orientation** (focal length, CCD polynomial distortions)
  - **Exterior orientation** (boresight angles)
- Band to band co-registration
- Co-registration with other sensors (Landsat/Sentinel2, etc..)
- Generation of geometric ICP file

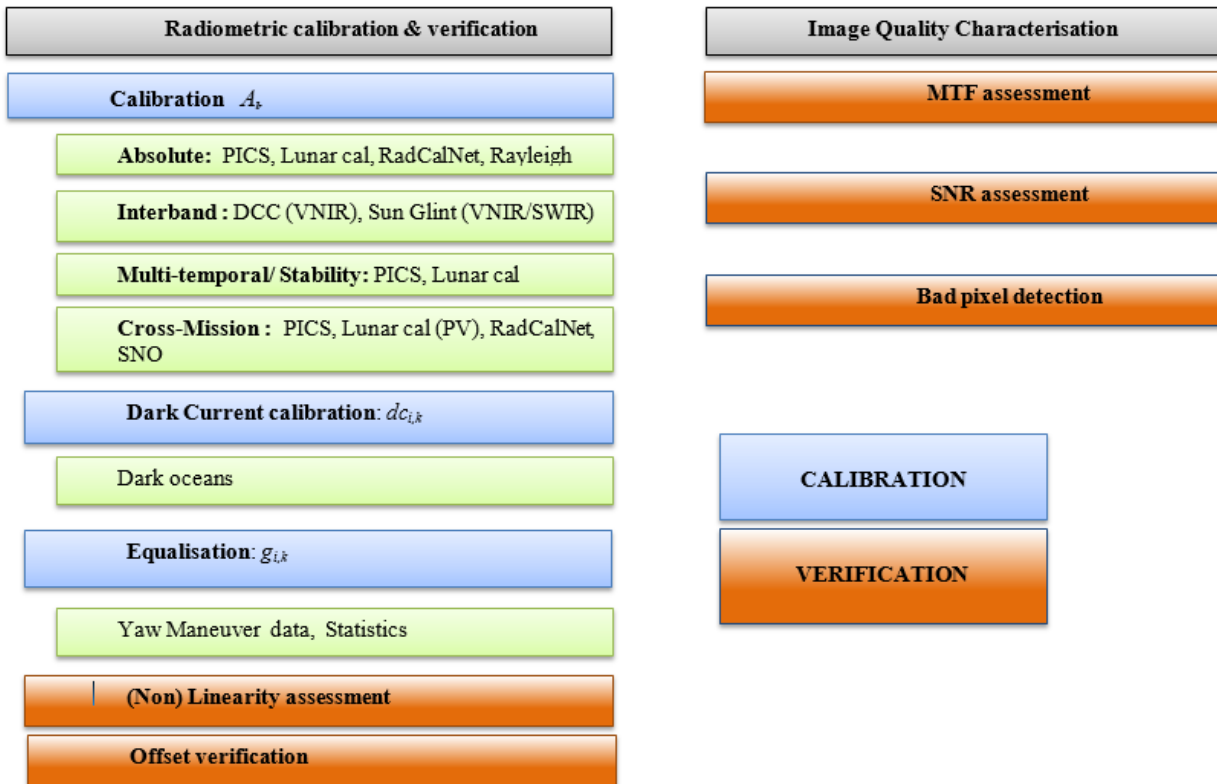


# Cal/Val plan (radiometry)

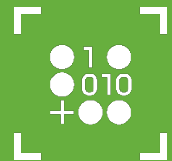
- PROBA-V heritage
- Differences wrt PROBA-V commissioning
  - Availability of Landsat8, Sentinel-2, Sentinel-3
  - Availability of RadCalNet sites
  - LIME lunar model (very good absolute accuracies)
  - Yaw maneuvers
- Complexities
  - the longer revisit time at nadir (approximately 12 days, TBC)
  - possible larger sensitivity to thermal environment changes



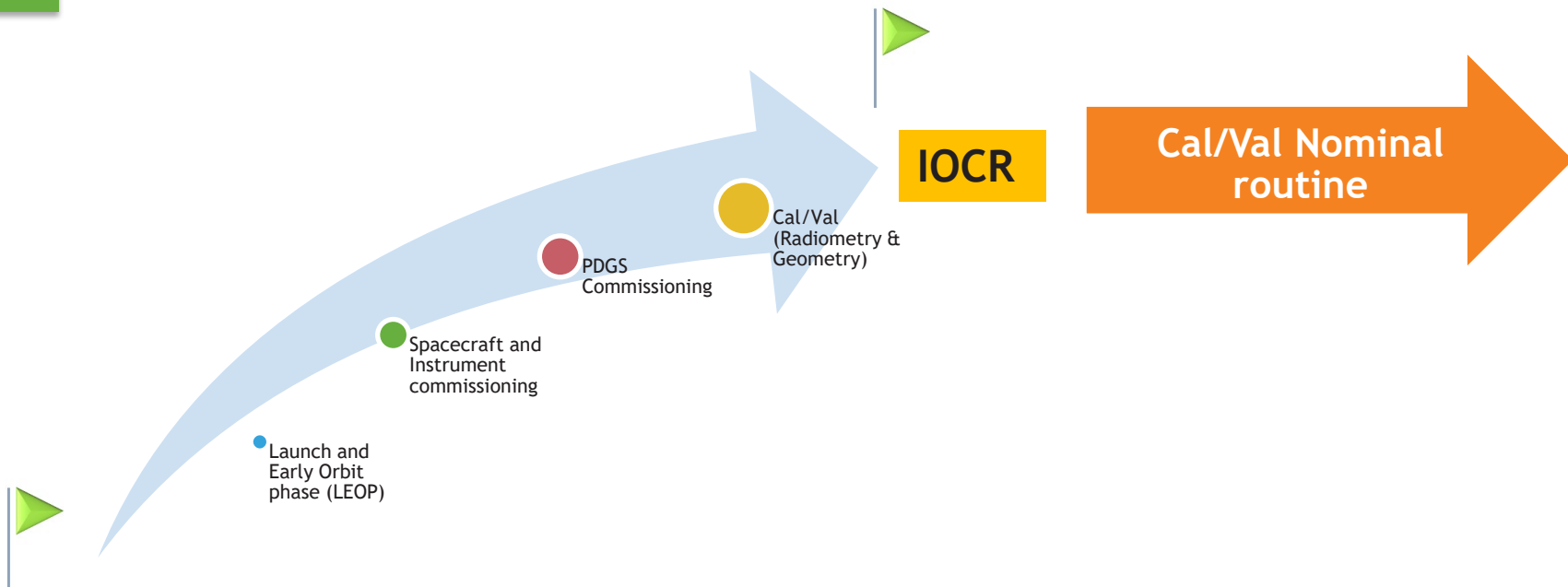
# Cal/Val plan (radiometry)







# Cal/Val during the nominal operation



PV-CC launch



# Cal/Val activities (geometry)

- » **Daily operations**

- » From nominal data, selected ROI's are automatically processed

- » **Weekly operations**

- » Verification of the L1C geometric accuracy

- » Verification of the L2 geometric accuracy

- » **Monthly update (if needed) of the ICP-GC**

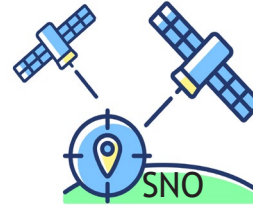
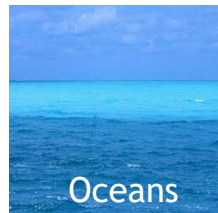
- » Update frequency can be reduced if stability is further confirmed

- » Update frequency can be increased (e.g. once a week) in the very unlikely event of rapid degradation

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# Cal/Val activities (radiometry)

- Use of **tasking** interface to acquire :



- Priority will be given to calibration over PICS and RadCalNet sites, Lunar calibration, and dark current acquisitions.
- Automatic radiometric processing will be performed:
  - to continuously **monitor the instrument** calibration parameters
  - to **compensate for drifts** caused by systematic changes such as ageing of the instruments

to **update the ICP file** as needed to maintain the accuracy of the calibration and continuity of product quality



THANK YOU

[remotesensing.vito.be](http://remotesensing.vito.be)