

Soil Moisture “re-processing” activities

Presentation to
SCIRoCCO project team
ESA

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scirocco

scatterometer instrument
competence centre

- Introduction to WARP and WARP NRT
 - Different processing approaches
 - SM product differences
 - Software evolution
- Current available ERS ESCAT SM products
 - Who are the users of the different products?
- Proposed “re-processing” plan
- Achievements since PM#1
- Outlook

Water Retrieval Package (WARP) Near Real Time (NRT)

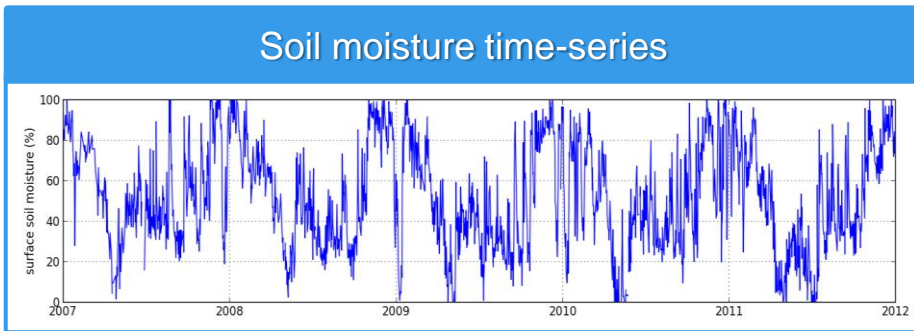
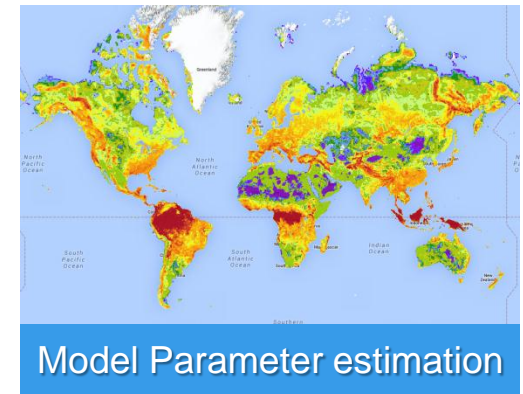
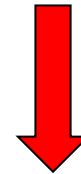
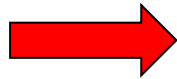
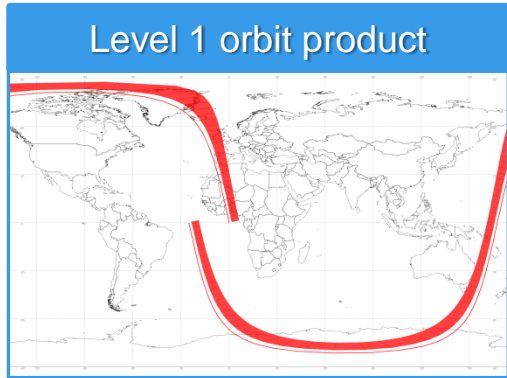


- Processing of L1 data archives
- Time-series based processing on a discrete global grid (DGG)
- Outputs
 - SM model parameter
 - SM time-series on DGG

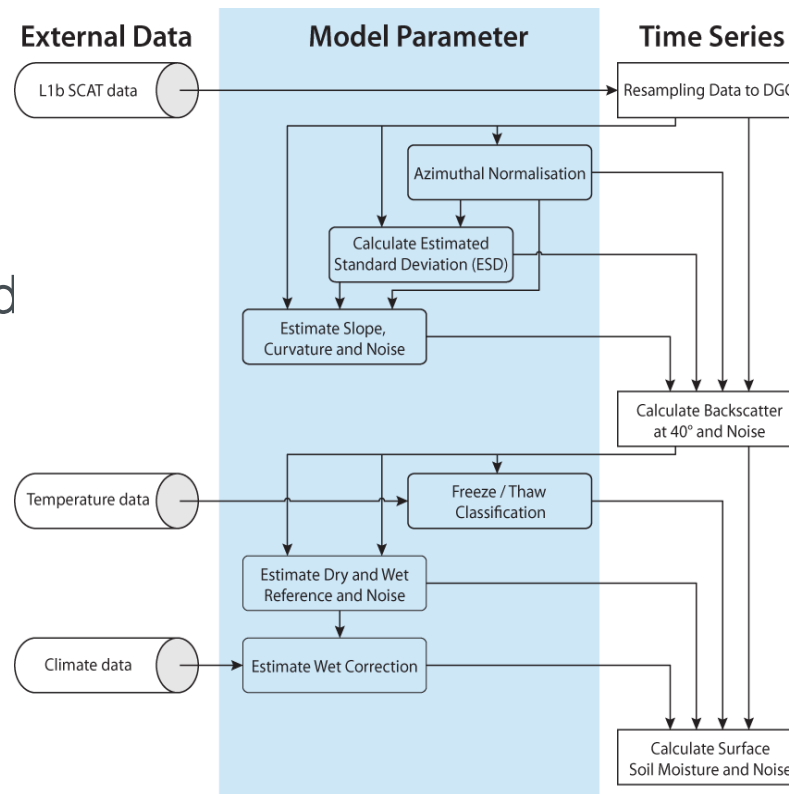


- Operational processing of L1 data
- Orbit based processing on swath grid
- Outputs
 - SM in orbit (swath grid)

WARP processing approach



- Model Calibration
 - Estimation of **Model Parameter**
 - Time consuming task
- All operations are performed in the time-domain
- 9 processing steps required to retrieve SM



- WARP 5.0 (IDL, new implementation)
 - New definition of the **Discrete Global Grid (DGG)**
 - Spatial resampling using “Hamming-Window”
 - Initial implementation of **error modelling**
 - Experimental use of **MetOp ASCAT EPS data**
 - New/improved **Slope/Curvature** estimation
- WARP 5.1 (IDL)
 - Improvements related to error modelling
 - First tests between **ESCAT and ASCAT**



- WARP 5.2 (IDL)
 - Improved resampling (lookup-table, buffer handling with bugs removed)
 - Code entirely adopted to **ASCAT**
- WARP 5.3 (IDL)
 - Implementation of **freeze/thaw (F/T) thresholds** estimation
 - Calculation of **Surface State Flag (SSF)**
 - Improvements in **Dry- and Wet- Reference** calculation
 - Output of global binaries (WARP NRT)

■ WARP 5.4 (IDL)

- Generic I/O routines fully implemented (data-structure)
- New cell-structure (partitioning) for DGG
- New resampling step with different methods (Hamming Window, Inverse Distance Weighting, Lanczos filtering)
- ESCAT processing capability re-introduced partly
 - ▶ F/T thresholds and SSF missing

■ WARP 5.5 (IDL, **latest version**)

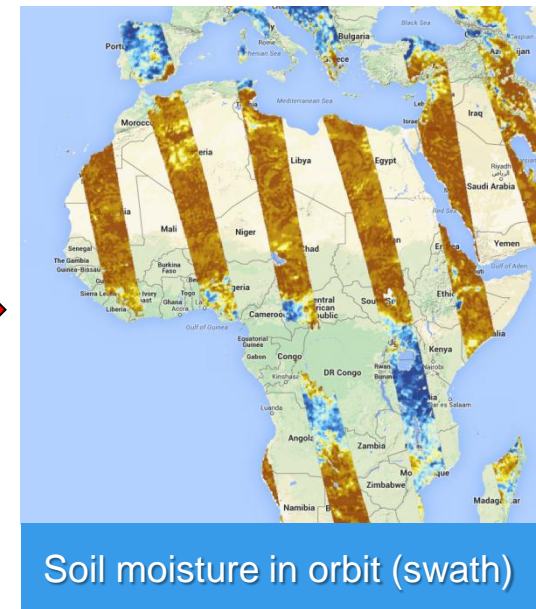
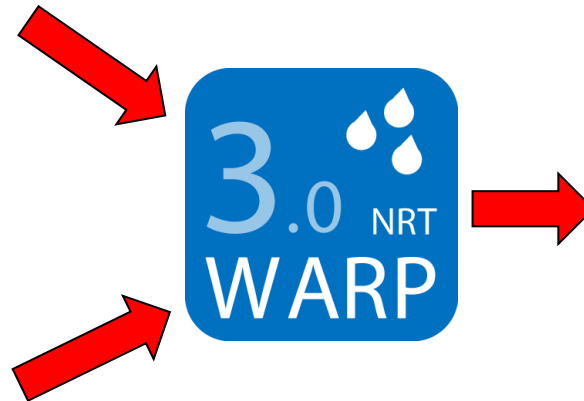
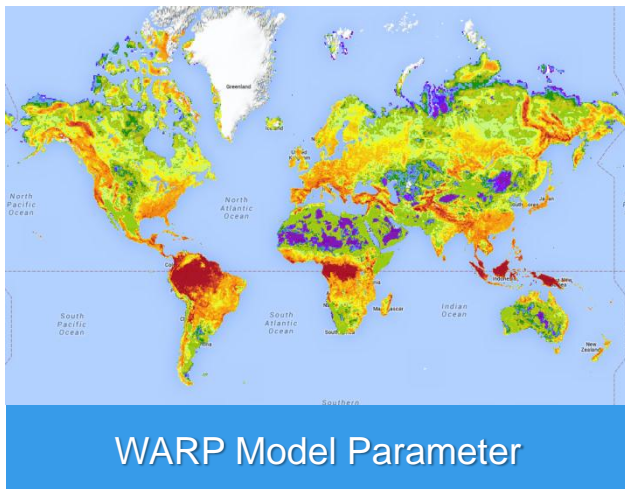
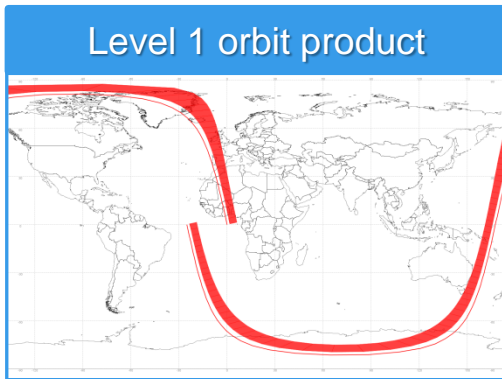
- Revisions/Changes in SSF processing
- Capabilities of parallel processing
- Sensor **intra- and inter-calibration** of ESCAT and ASCAT

- WARP 6.0 (Python, planned version)
 - **Daily Slope/Curvature** estimation (ASCAT and ESCAT)
 - Improved Dry- Wet-Reference estimation (**Cross-over angle optimisation**)
 - Improved Wet-Correction
 - **NetCDF IO** instead of GenericIO
 - Revision of sensor intra- and inter-calibration
 - **Noise estimate** based on Kp-value
 - Complete **ESCAT and ASCAT** processing capability



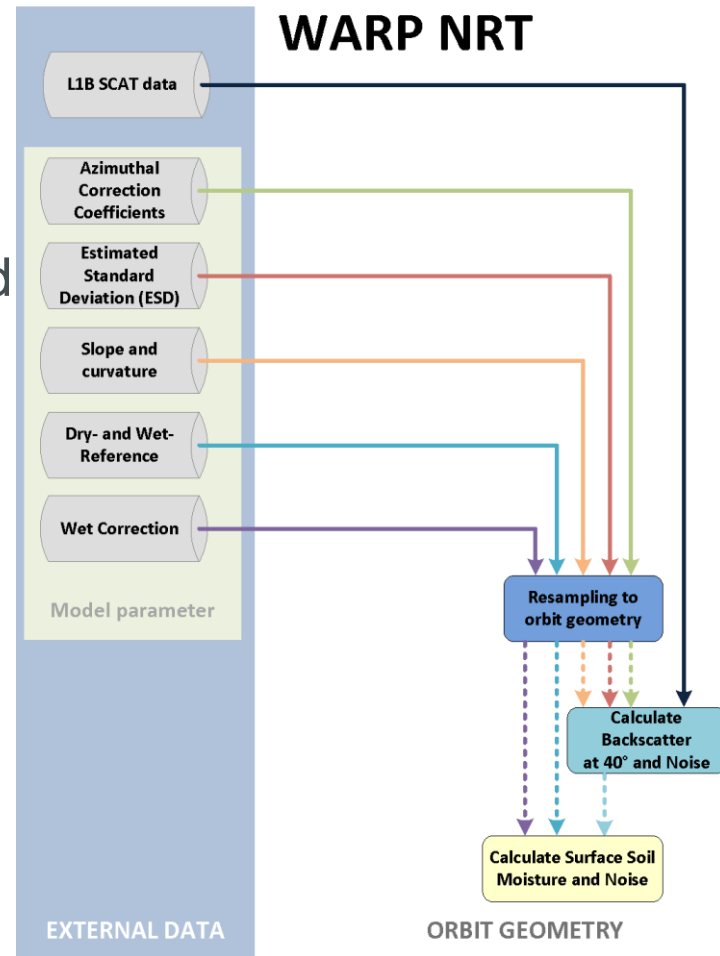
WARP NRT processing approach

standalone and simplified implementation of TU-Wien SM model



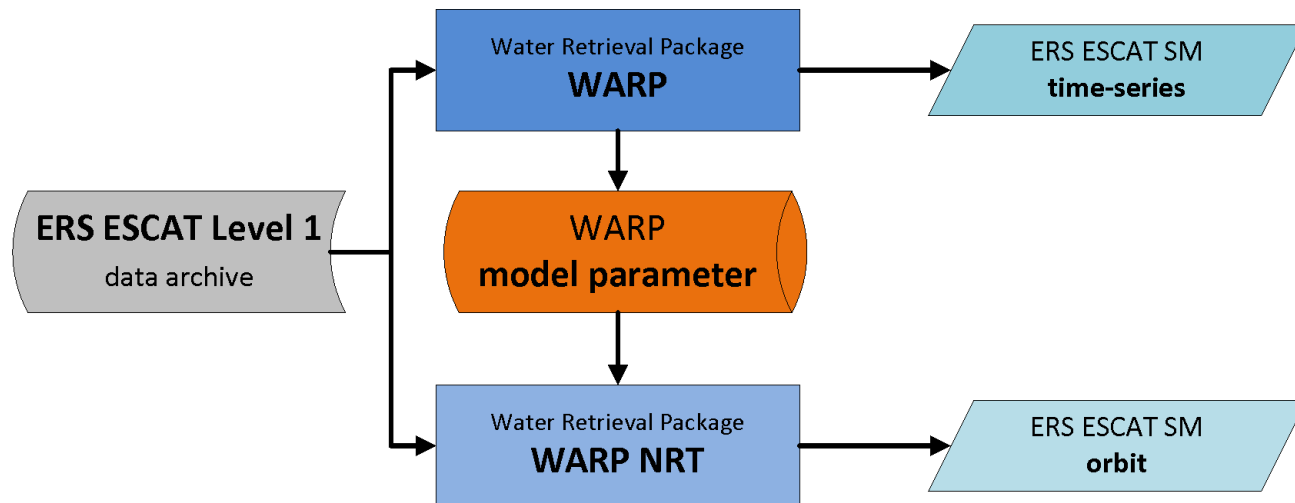
WARP NRT processing steps

- NRT processing take full advantage of pre-computed model parameters
- Model parameters are resampled to orbit (swath grid)
 - Fast computation of SM



From WARP to WARP NRT

- WARP and WARP NRT are individual software packages
 - Dependency because of required “model parameter”
 - Model parameter are related to the utilised WARP version



- WARP NRT 1.0 and 1.1 (IDL and C++)
 - Initial implementation
 - **ERS-2 UWI data** handling
 - First tests with MetOp ASCAT EPS data
 - **WARP 4.0** model parameters
- WARP NRT 2.0 (C++, latest ASCAT version)
 - **Operational SM processor @ EUMETSAT**
 - Adaptions to **WARP 5** processing steps and model parameters
- WARP NRT 2.4 (IDL, latest ESCAT version)
 - IDL implementation of version 2.0
 - Adaptions to **WARP 5.4**
 - **ERS-2 ASPS_H** data handling

- WARP 3.0 (Python, planned version)
 - **Processor encapsulated** from input data
 - ▶ Common interface for European scatterometer data (**ESCAT and ASCAT**)
 - **Adaptations to WARP 6.0** processing steps and model parameters
 - ▶ Noise estimate based on Kp-value
 - ▶ Integration of F/T threshold model parameters
 - ▶ Estimate of SSF, ...
 - Sensor intra- and inter-calibration capabilities
 - Improved Processing Flags
 - Revised Advisory Flags
 - Standardised **NetCDF** Level 2 soil moisture product output



- 4 different products available
 - Time-series vs. Orbit products
 - Different processor versions (model parameters)
 - Various input data (formats) with different spatial resolutions
 - ▶ Temporal coverage (data gaps)
 - ▶ Data consistency

“re-processing” demanded

Product Name	Processor	Input data	Temporal Coverage	Spatial Coverage
ERS-1/2 ESCAT Soil Moisture Time-Series	WARP 5.0	ERS-1/2 WNF, UWI 50 km	1991-08-05 to 2007-05-31, data gap between 2001-01 and 2003-08	Global coverage until 2001, from 2003 onwards regional coverage
ERS-2 ESCAT ASPS_H Soil Moisture Time-Series	WARP 5.4	ERS-2 ASPS_H	1997-05-20 to 2003-02-17	Global coverage
ERS-2 ESCAT ASPS_H Soil Moisture	WARP NRT 2.4	ERS-2 ASPS_H	1997-05-20 to 2003-02-17	Global coverage
ERS-1/2 ESCAT Soil Moisture Time-Series	WARP 5.5	ERS-1/2 WNF, UWI 50 km	1991-08-05 to 2007-05-31, data gap between 2001-01 and 2003-08	Global coverage until 2001, from 2003 onwards regional coverage

- Who are (will be) the users of the different products?
 - **Orbit product** (operational product, close as possible to L1 measurements)
 - ▶ Meteorological Offices
 - ECMWF
 - Met Office (UK)
 - Météo France
 - ZAMG (Austria)
 - ...
 - **Time-series product** (research product)
 - ▶ Universities
 - ▶ Other research institutions
 - Climate change research

**ESA CCI SM project
requires consistent
ERS-1/2 ESCAT SM**



Contribution from SCIRoCCo

“Re-processing” activities

- Re-processing activity plan outlined in a Technical Note
- Proposed activities were split in two phases
 - **Phase 1:**
 - ▶ **“Completion of ERS-2 ESCAT ASPS data archive”**
 - ▶ Extend ERS-2 ESCAT **ASPS_H** SM orbit product
 - ▶ Creation of ERS-2 ESCAT **ASPS_N** SM orbit product (**WARP 5.4 and WARP NRT 2.4**)
 - **Phase 2:**
 - ▶ **“Generation of the most complete and consistent ERS-1/2 ESCAT products”**
 - ASPS_H and ASPS_N
 - ▶ Incorporating all achieved SM-model improvements
 - ▶ Set of model parameters based on ERS-1/2

Phase 1 (revision request)

- Products generated within Phase 1
 - Products become **obsolete** after a few month
 - Improved products will be released in Phase 2
- Request for revision of “Phase 1”
 - Neglect product generation within Phase1
 - Use freed resources for
 - ▶ proper implementation / documentation of WARP NRT 3.0
 - Implementation tests
 - Output verification (WARP NRT 2.4 vs. 3.0)
 - Product validation (QC)
 - ▶ Concentrate on algorithmic improvements demanded in Phase 2

- Transition from IDL to Python
 - **ASPS reader** implemented in Python
 - **NetCDF** reader/writer for orbit data
 - **WARP** processor ported to Python
 - ▶ Python vs IDL processor (WARP 5.5)
 - First implementation tests of proc. steps were successful
 - Output verification indicates insignificant differences
 - **WARP NRT** processor ported to Python (package)
 - ▶ Processor encapsulated from input data
 - ▶ Resampling different to IDL version (Kd-tree) [pyresample]
 - ▶ Interface to run processor with ESCAT and ASCAT data (70%)

- Phase 1 “re-processing” products required ?
 - If yes, delivery of data (ASPS_H/N) end of August 2015?
- Phase 2 outlook (timeframe end of 2015)
 - WARP NRT 3.0
 - ▶ Implementation tests
 - ▶ Output verification (WARP NRT 2.4 vs. 3.0)
 - ▶ Adaptations of NetCDF writer
(identical format for ESCAT and ASCAT)
 - WARP NRT 3.0 improvements
 - ▶ Surface State Flag from F/T-thresholds
 - ▶ Improved error characterisation using Kp-value
 - First validation study

Questions or Comments