Aeronomy Level 2 data products

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The following outlines the format and storage of the various data products from the Level 2 processing software. Level 2 is basically any data product derived from Level 1b. Data in a Level 2 file is stored by orbit.

SMR Aeronomy Level 2 data will be stored using the HDF-EOS 4 Point object data format. HDF-EOS is an extension of NCSA (National Center for Supercomputing Applications) HDF (Hierarchical Data Format) selected by NASA as the baseline standard for EOS (Earth Observing System).

The version of the HDF-EOS library used is 2.5. For more information download the documents "HDF-EOS Library User's Guide for the ECS Project, Volume 1: Overview and Examples; Volume 2: Function Reference Guide". This document is available on the web at http://hdfeos.gsfc.nasa.gov.

Scientific product file name convention

The official product from MISU will have the filename,

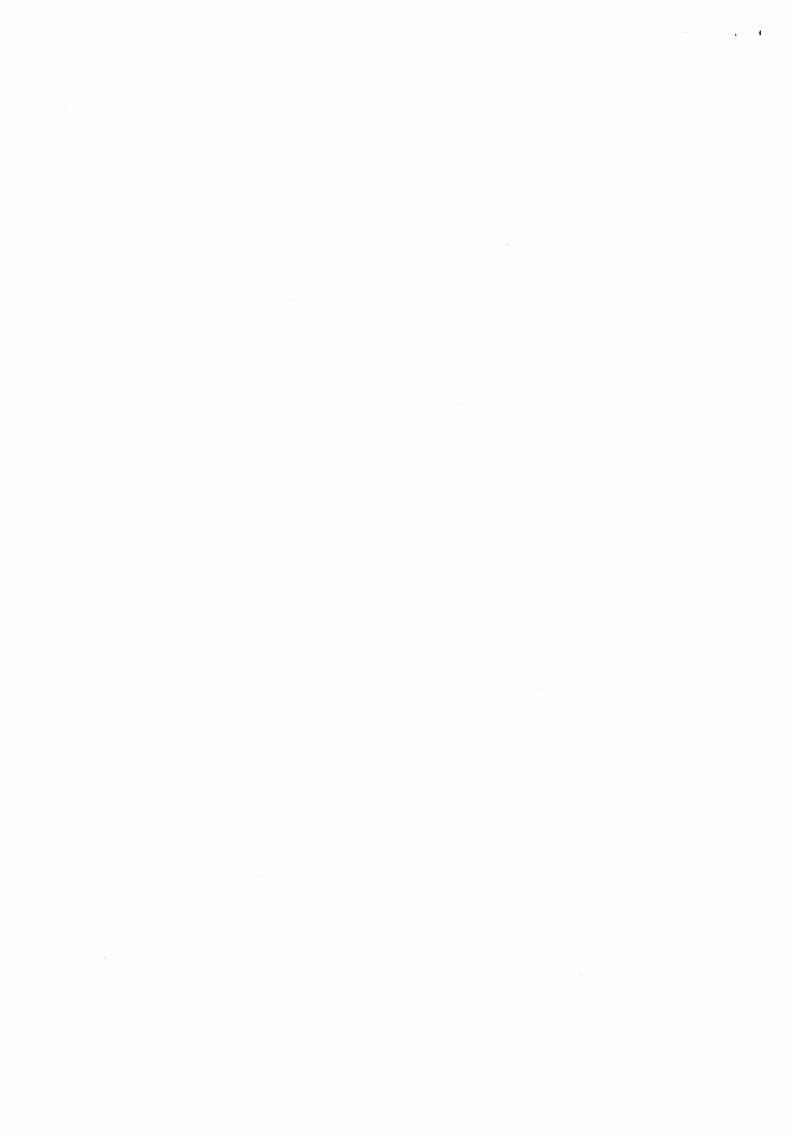
$SMR_XXXX_MPPPP_VVJ.L2P$

- SMR means sub-millimeter instrument¹.
- XXXX is a four digit number in GHz representing the center frequency
 of the band that was used in the retrieval. e.g. 5014 is read as 501.4
 GHz. In the case of both sub-bands inverted together, the centre frequency is defined as the centre of the band considering both sub-bands,
 e.g. 5018 for a simultaneous inversion of 501.4 GHZ and 502.2 GHz bands.
- MPPPP, here M is the spectrometer that was used (A, B or C) and PPPP is the 4 digit hexadecimal number of the orbit.
- VVJ is the version number of the product. VV is the major version number and J is the minor.
- version number. e.g. 013 is read as version one point three.
- The extension .L2P means level two product. This level two product is what is known as the scientific product.

Level 2 Retrieved Profiles Data Product Structure

Reading an SMR Level 2 data product retrieves the data needed to write the Level 2 Retrieved Profiles Data Product Structures. The history implementation of the structure, the structure fields with some commnets about their HDF-EOS coding, and a description of the fields follow. See next section for further explanations about the HDF-EOS coding.

 $^{^1\}mathrm{For}$ the validation institues of Bordeaux and Chalmers the filename will be the same except that SMR is replaced by SOB and SCH respectively



```
#ifndef SMRLEVEL2_H
#define SMRLEVEL2 H
          History:
          First version created March 11 1999
          Version 0.2
          August 16 1999
          Major changes concerning new and removed structure members.
          Version 0.3
          August 3 2000
          More fields added.
          Version 0.4
          March 21 2001
          Changes made after retrieval group meeting 1 at MISU
          Constituents field changed to Profiles
Field double Orbit changed to char *OrbitFileName
Variances field is removed.
          AprioriContr field is removed.
          Added field ZPTSource.
          Added field ZPT
          Added fields NullSpaceError, MeasError, MeasResp and TotalError. Added fields StartTan and EndTan.
          Version 0.5
          March 26 2001
          Removed fields Level1Bfile, ClimTP
          Added fields Nzpt, ZPTNames and ZPT.
Changed NullSpaceError to SmoothingError
          Changed AprioriUncert from a vector to a matrix.
          Version 0.6
July 17 2001
          Added #define MAXSTRING 32, all strings in the structure are now of length MAXSTRING
          Changed AprioriUncert from float to a double.
          Changed SmoothingError from float to a double.
          Added field NzptParam
          Fields Day, Month, Year, Hour, Min and Secs changed from int to short
          Version 0.7
          Aug 30 2001
          Extra parameters added to the diagnostic product.
          (see diagnostics product below)
          Version 0.8
          Jun 27 2002
          Revision of fields before implementatioon of Level2 files
          in Bdx and Chalmers.
          Remove AprioriUncert
          Change all double fields to float.
          Version 0.9
          Sep 5 2002
Adding modified julian date field
          Version 1.0
          Changing char to short for fields Nspecies and NzptParam Changing float to double for field MJD and LST
          Version 1.1
Sep 30 2002
          Changing short to char for fields Version1b and Version2
Specifying latitude and longitude in ranges [-90,90] [-180,180] and adding Time field, all changes to comply with reserved field names
          for geolocation
Changing units of LST to hours.
```



```
Especyfing units for altitude to km, pressure in hPa and temperature
          in Kelvin.
          Version 1.2
          ZPT is from now our best knowledge of these quantitites, not the pure
          apriori data.
#define VERSION_L2 0x0008 /* read: version (high byte).(low byte), here: 0.6 */
#define L2VERSION "080"
#define MAXSTRING 32
#define UNDEFINED 0
struct SMRLevel2Data {
          char Version1b;
                                          // level O, Retrieval point grid
                                          // level 0, Retrieval point grid
// level 0, Retrieval point grid
          char Version2;
          unsigned long Quality;
          char *Source;
                                          // level O, Retrieval point grid
          char *ZPTSource;
                                          // level O, Retrieval point grid
                                          // level O, Retrieval point grid
          char *OrbitFilename;
                                          // level 0, Retrieval point grid
// level 0, Retrieval point grid
          float SunZD:
          double LST;
          int ScanNo;
                                          // level O, Retrieval point grid also T/P point grid
                                          // level 0, Retrieval point grid
// level 0, T/P point grid
          short Nspecies;
          short NzptParam;
                                          // level 0, Retrieval point grid
// level 0, Retrieval point grid
          short Day;
          short Month:
                                          // level O, Retrieval point grid
          short Year;
          short Hour;
                                          // level 0, Retrieval point grid
                                          // level 0, Retrieval point grid
// level 0, Retrieval point grid
          short Min;
          short Secs;
          float Ticks;
                                          // level O, Retrieval point grid
          float Latitude;
                                          // level O, Retrieval point grid also T/P point grid
                                          // level 0, Retrieval point grid also T/P point grid
// level 0, Retrieval point grid
// level 0, Retrieval point grid
          float Longitude;
          float StartLat;
          float EndLat;
                                          // level 0, Retrieval point grid
// level 0, Retrieval point grid
          float StartLong;
          float EndLong;
          float StartTan;
                                          // level O, Retrieval point grid
                                          // level 0, Retrieval point grid
// level 0, Retrieval point grid
          float EndTan;
          double MJD;
          double Time;
                                          // level O, Retrieval point grid
          char **Species;
                                          // level 1, Retrieval point grid
                                          // level 1, Retrieval point grid
// level 1, T/P point grid
// level 1, T/P point grid
          short *Naltitudes;
          char **ZPTNames;
          short *Nzpt;
                                          // level 2, Retrieval point grid
// level 2, Retrieval point grid
          float **Altitudes:
          float **Profiles;
float **MeasError;
                                          // level 2, Retrieval point grid
// level 2, Retrieval point grid
          float **MeasResp;
          float **TotalError;
                                           // level 2, Retrieval point grid
          float **SmoothingError;
                                          // level 2, Retrieval point grid
// level 2, T/P point grid
          float **ZPT;
1:
#endif
```

• char Version1b

The version number of the level 1b processing chain that was used to create the level 1b file.

• char Version2



The version number of the level 2 processing chain that was used to create the level 2 file.

· unsigned long Quality

Up to 32 bit of status information for various error, warning or informative purposes. Quality = 0 means a good retrieval. i.e. no problems. Quality = 1 means a bad retrieval. i.e. should not be used.

• char *Source

The observation mode. e.g Stratospheric, Odd Hydrogen, Odd Nitrogen, Water Isotope.

• char *ZPTSource

A character string containing the source of the temperature and pressure

• char *OrbitFileName

The full orbit filename (excluding the extension .HDF) including the spectrometer that was used.

e.g. OB1B13A4

• float SunZD

The average solar zenith angle for the scan. Taken from the log file. Unit: degrees.

• double LST

The average local (mean) sidereal time for the scan. Calculated from the values of the scan in the level 1b file.

$$LST = \frac{(LST \text{ from the start of the scan} + LST \text{ at the end of the scan})}{2}$$
(A-1)

Unit: hours.

• double MJD

The average modified julian date for the scan. Calculated from the values of the scan in the level1b file.

$$MJD = \frac{(MJD \text{ from the start of the scan} + MJD \text{ at the end of the scan})}{2}$$
(A-2)

Unit: days.

• double Time

A time field based on average modified julian data. Calculated as TAI93: seconds until(-)/since(+) midnight,1/1/93.

Time =
$$24 * 60 * 60 * (MJD - 48988)$$
 (A-3)

Unit: seconds.

• int ScanNo

The scan number within this orbit. This number always refers to complete scans, it is taken from the log file.



• short Nspecies

The number of species that were retrieved. If temperature is a retrieval product, Nspecies is the number of species plus one, see below the field Species.

• short NzptParam

The number of ZPT parameters. At the moment this is set to 3. i.e. Altitude, Pressure and Temperature.

• short Day

Day of observation. Calculated from the average MJD in the log file.

• short Month

Month of observation. Calculated from the average MJD in the log file.

· short Year

Year of observation. Calculated from the average MJD in the log file.

• short Hour

Hour of observation. Calculated from the average MJD in the log file.

• short Min

Minute of observation. Calculated from the average MJD in the log file.

· short Secs

Seconds of observation. Calculated from the average MJD in the log file.

• float Ticks

Ticks of observation. Calculated from the average MJD in the log file.

• float Latitude

Reference latitude for the scan. Calculated as,

$$Latitude = \frac{(Latitude from the start of the scan + Latitude at the end of the scan)}{2}$$
(A-4)

Calculated from the values in the log file.

Unit: decimal degrees on the range [-90,90].

• float Longitude

Reference longitude for the scan. Calculated as,

Latitude = $\frac{\text{(Attitude from the start of the scan + Latitude at the end of the scan)}}{2}$ (A-5)

Calculated from the values in the log file.

Unit: decimal degrees on the range [-180,180].

• float StartLat

The geodetic latitude of the tangent point for the first spectra in the scan.

Taken from the log file.

Unit: degrees on the range [-90,90].



• float EndLat

The geodetic latitude of the tangent point for the last spectra in the scan. Taken from the log file.

Unit: degrees on the range [-90,90].

• float StartLong

The geodetic longitude of the tangent point for the first spectra in the scan. Taken from the log file.

Unit: degrees on the range [-180,180].

• float EndLong

The geodetic longitude of the tangent point for the last spectra in the scan. Taken from the log file.

Unit: degrees on the range [-180,180].

• float StartTan

The start tangent altitude of the scan. Taken from the log file.

Unit: Kilometers.

• float EndTan

The end tangent altitude of the scan. Taken from the log file.

Unit: Kilometers.

• char **Species

The name of each retrieved species. The convention here is to write the species name followed by the center frequency number of the band. e.g O3_5014, this is read as ozone using the frequency band with center frequency 501.4 GHz. If temperature is a retrieval product, the field can also have the string TEMP followed by the center frequency as before, e.g TEMP_5014. The string is of length MAXSTRING

• short *Naltitudes

The number of retrieval grid altitude points for each retrieved species.

• char **ZPTNames

This is an array that contains the following strings:

ZPTNames[0] = "Altitude";

ZPTNames[1] = "Pressure";

ZPTNames[0] = "Temperature";

They are always called this and always in the same order. The strings are of length MAXSTRING.

• short *Nzpt

The number of altitude points for the *a priori* temperature, pressure and altitude grid. This should be equal to the number of retrieval layers that was used in the inversion.

• float **Altitudes

A two dimensional array, where each row corresponds to the retrieval altitude grid for each retrieved species.

Unit: Kilometers.



• float **Profiles

The molecular volume mixing ratio (VMR) for each retrieved constituent. If temperature is a retrieval product, it can also be the temperature distribution in K. A two dimensional array, where each row corresponds to the VMR of a retrieved species and the temperature if it is retrieved. Unit: VMR and Kelvin.

• float **ZPT

The best knowledge of the temperature and pressure after the retrieval process in the retrieval altitude grid. Whether this is the *a priori* pressure and temperature used during the inversion or not depends on the retrieval procedure. For instance, if temperature is retrieved the temperature here corresponds to the retrieved temperature.

Unit: Kilometers, hPascal and Kelvin.

• float **SmoothingError

This is the retrieval error covariance matrix (S_n) due to the error between the true and a priori states. It is calculated as,

$$S_n = (A - I)S_x(A - I)^T \tag{A-6}$$

here A is the averaging kernels matrix, I is the identity matrix, S_x is the a priori covariance matrix that was used when performing the inversion and T means transpose. Only the diagonal terms are kept.

• float **MeasError

This is the retrieval error covariance matrix (S_m) due to errors in the measurement. It is calculated as,

$$S_m = D_y S_y D_y^T (A-7)$$

here D_y are the contribution functions, S_y is the error covariance matrix, and T means transpose. Only the diagonal terms are kept.

• float **MeasResp

This is defined as,

$$w^{p}(i) = \sum_{j} A(i,j) \frac{x_{a}(i)}{x_{a}(j)}$$
 (A-8)

Here A(i,j) describes the submatrix from species j to i. Only the rows of the submatrices from species i to j are stored.

float **TotalError

This is the total retrieval error covariance matrix (S_{δ}) , given by

$$S_{\delta} = S_n + S_m \tag{A-9}$$

Only the diagonal terms are kept.

Data Format with HDF-EOS

The SMR data is stored in a HDF-EOS file containing two point grid structures. One point grid structure is used to represent the data retrieved from a particular

frequency band, the other Point Grid structure holds the *a priori* temperature and pressure profiles. The point grid structure name for the retrieved profiles is given by the frequency band name, see table 1. For example '501.180 - 501.580 GHz' will be the Point Grid name for all the retrieved parameters in this band 2 . The *a priori* temperature and pressure Grid Point regardless of the frequency band is always called "T/P apriori".

Each point grid structure is implemented with 3 levels. Tables 2 - 4 illustrate the hierarchical table structure for the profiles grid-structure. Level 0 contains all the information on a per profile basis. The next level, Level 1, contains the information on the species that were retrieved. Level 0 and 1 are linked through the ID1 field. Level 2 contains the actual retrieved data. Level 1 and 2 are linked through the ID2 field. Similar hierarchical structure is implemented for the a priori point grid structure, see Tables 5 - 8.

	Frequency Bands			
ID	Point grid name			
1	501.180 - 501.580 GHz			
2	501.980 - 502.380 GHz			
3	501.180 - 502.380 GHz			
4	544.202 - 545.002 GHz			
5	488.950 - 489.350 GHz			
6	488.350 - 488.750 GHz			
7	488.350 - 489.350 GHz			
8	556.598 - 557.398 GHz			
9	576.062 - 576.862 GHz			
10	489.950 - 490.750 GHz			
11	556.550 - 557.350 GHz			

Table 1: Frequency modes, also used as point grid names.

Geolocation			
Latitude	Longitude	NSpecies	ID1
у1	x1	3	0
y2	x2	4	1
у3	x3	3	2

Table 2: Level 0, retrieved parameters (product/diagnostics) point grid

²Only the frequency bands used presently during the observations are listed here. If further bands are used, the table and document will be consequently updated. Notice that bands with IDs 3 and 7 correspond to a joint retrieval of bands with IDs 1-2 and 5-6 respectively

Retrieval			
ID1	Species	Naltitudes	ID2
0	O3_501	2	0
0	NO2_501	3	1
0	H2O_501	2	2
1	O3_501	2	3
1	NO2_501	6	4
1	BrO_501	4	5
1	OClO_501	5	6

Table 3: Level 1, retrieved parameters product point grid

Data				
ID2	Altitude	Profiles	SmoothingError	
0	20	5.4	2	
0	30	6.3	6	
1	20	5.2	4	
1	40	7.9	3	
1	50	5.8	1	
2	50	4.9	7	
2	60	6.9	7	

Table 4: Level 2, retrieved parameters product point grid

Geolocation				
ScanNo	Latitude	Longitude	NzptParam	ID1
1	у1	x1	3	0
2	у2	x2	3	1
3	у3	x3	3	2

Table 5: Level 0, a priori temperature and pressure point grid



	Retrieval			
ID1	ZPTNames	Nzpt	ID2	
0	Altitude	2	0	
0	Pressure	2	1	
0	Temperature	2	2	
1	Altitude	2	3	
1	Pressure	2	4	
1	Temperature	2	5	
2	Altitude	2	6	
2	Pressure	2	7	
2	Temperature	2	8	

Table 6: Level 1, a priori temperature and pressure point grid

ZPTinfo			
ID2	ZPT		
0	20		
0	30		
1	20		
1	40		
2	50		
2	60		
3	20		
3	30		
4	20		
4	40		
5	50		
5	60		
6	20		
6	30		
7	20		
7	40		
8	50		
8	60		

Table 7: Level 2, a priori temperature and pressure point grid



Tem	TemperatureBrightness			
ID2	TB	Frequencies		
0	200	501		
0	300	502		
1	250	501		
1	100	502		
2	120	501		
2	180	502		
3	200	490		
3	250	491		
3	204	492		
4	100	490		
4	150	491		
4	260	492		
5	320	490		
5	301	491		
5	160	492		

Table 8: Level 2, Measurement or Fit point grid

