

# Detecting and monitoring the time-variable gravity field of Greenland

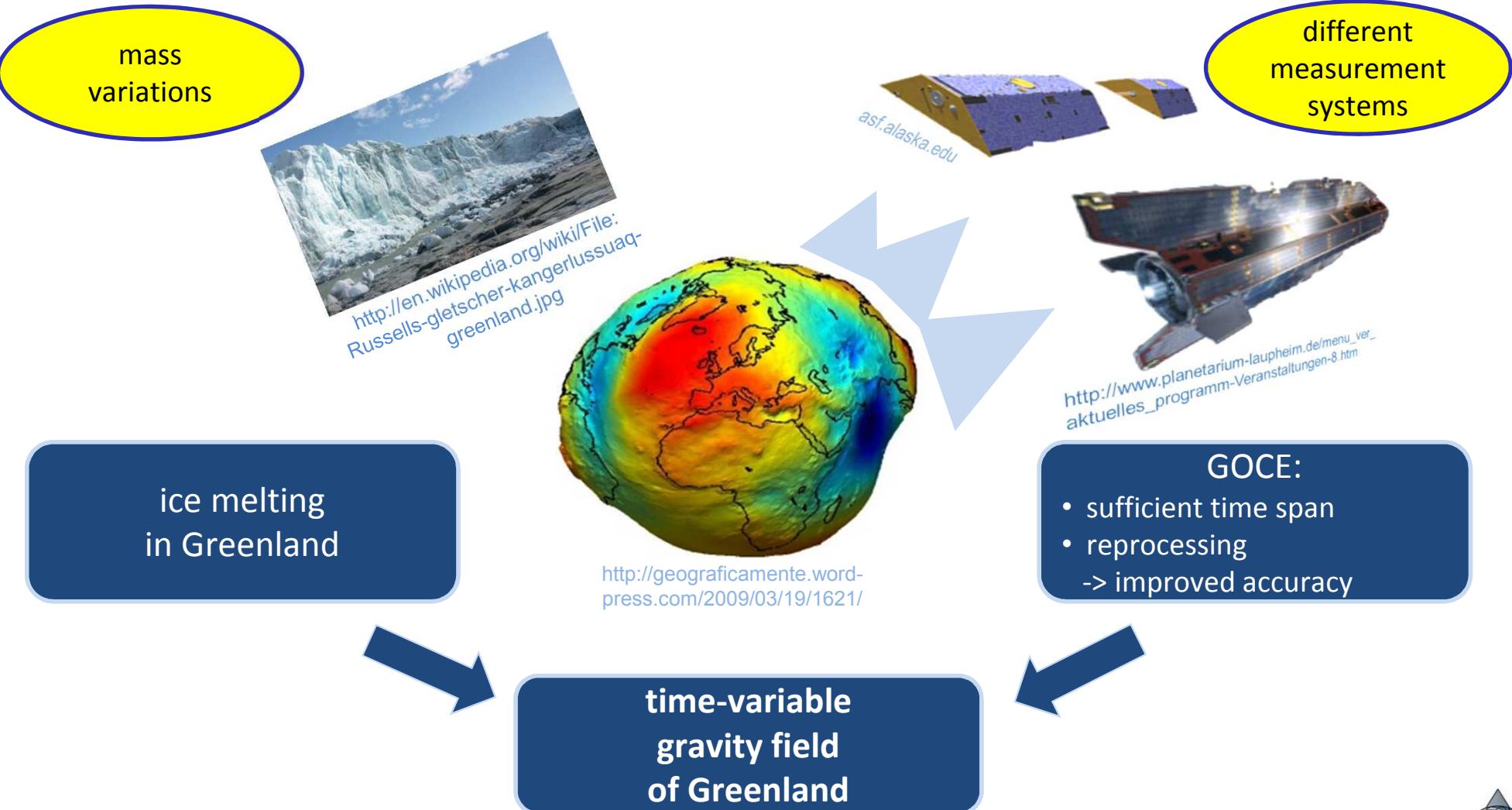
## - using reprocessed GOCE gradients -



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# 0. Motivation



# 1. Spectral sensitivity

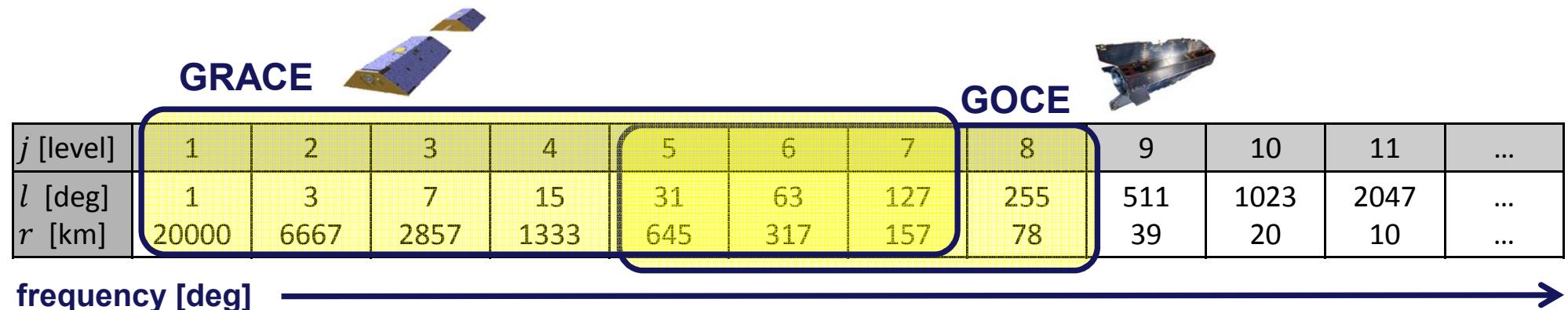
- **resolution levels  $j$**  split spectrum into frequency bands
- upper boundary corresponds to the **maximum degree  $l$**  in a series expansion
- relation to the **spatial resolution  $r$**  on the Earth's surface
- GOCE covers higher frequencies than GRACE

MBW: 5 ... 30 mHz

$j = 5 \dots 8$

$l = 2^j - 1$

$$r = \frac{20,000}{l} \text{ [km]}$$



## 2. GOCE data set

Measuring:

Vzz

GRF;  $Vzz \approx Vrr$

Modifying:

$Vzz\_mod = (Vzz - Vxx - Vyy)/2$

40% noise reduction

Filtering:

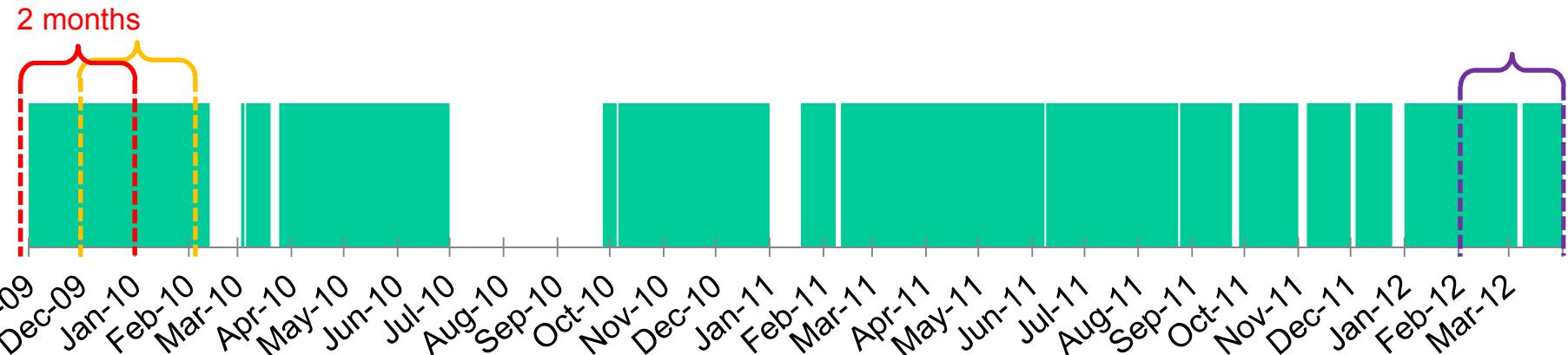
MBW: 5 ... 30 mHz

low frequencies: GOCO03S

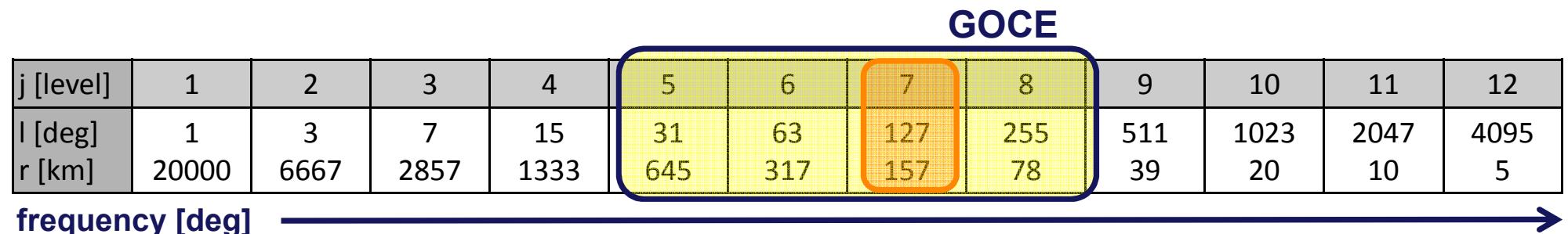
Creating 2-month data sets:

time span:  
11/2009 - 03/2012  
1 month overlap

repeat cycle: ~ 61 days



### 3. Regional gravity field modeling



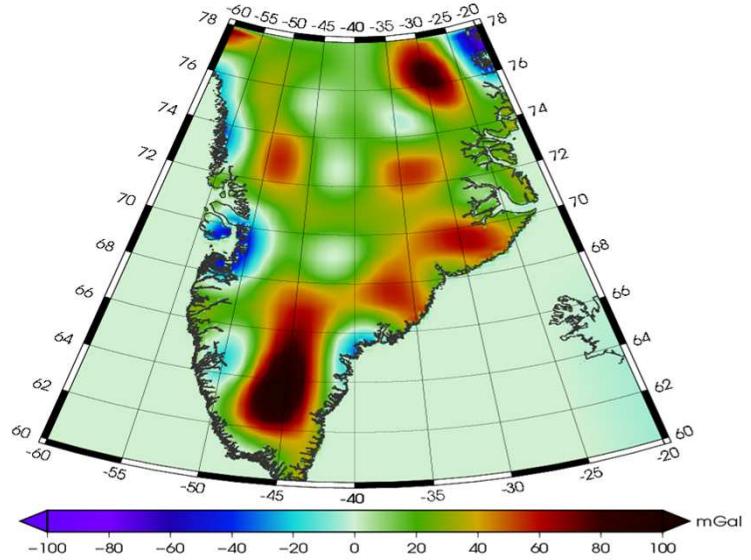
1) Subtracting background model:  $\Delta V_{zz} = V_{zz} - V_{back}$

V<sub>back</sub>: GOCO03S  
d/o 127

... the same as used for filling up low frequencies  
... according to modeling resolution (j = 7)  
(reduce static part completely)



### 3. Regional gravity field modeling



**background model:**

GOCO03S  
Dg [mGal], d/o 127 (j=7)

### 3. Regional gravity field modeling

- 1) Subtracting background model:  $\Delta V_{zz} = V_{zz} - V_{back}$

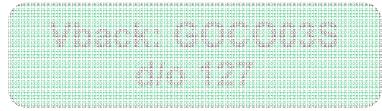
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- 2) Analysis: series expansion in terms of **reproducing kernel**

krepro  
d 140

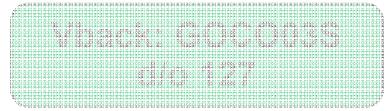
... estimating unknown scaling coefficients  $d_6$   
... avoiding omission errors

$$\Delta V_{zz}(P) + e_{Vzz}(P) = \sum_{q=1}^{N_6} d_{6,q} \tilde{k}_{repro}(P, Q)$$

$$\tilde{k}_{repro}(P, Q) = \sum_{l=0}^{140} \frac{2l+1}{4\pi R^2} \frac{(l+1)(l+2)}{r_p^2} \left(\frac{R}{r_p}\right)^{l+1} P_l(P, Q)$$

### 3. Regional gravity field modeling

- 1) Subtracting background model:  $\Delta V_{zz} = V_{zz} - V_{\text{back}}$



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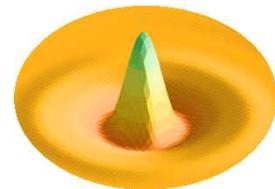
- 3) Synthesis: series expansion in **scaling functions**

Blackman  
d 127

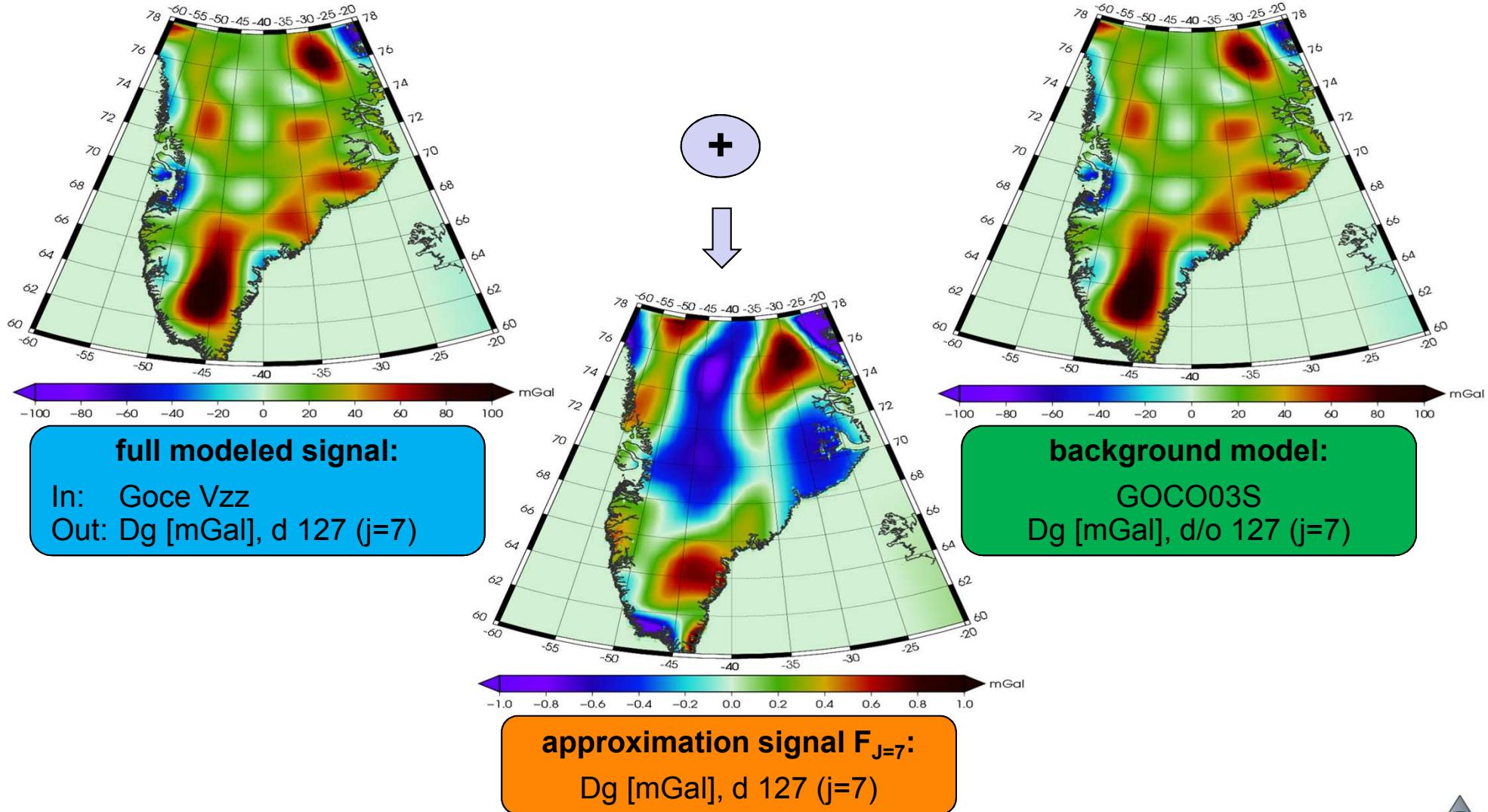
... modeling approximation signal  $F_7$   
... low-pass filter

$$F_7(P) = \sum_{q=1}^{N_6} \hat{d}_{6,q} \tilde{\phi}_7(P, Q)$$

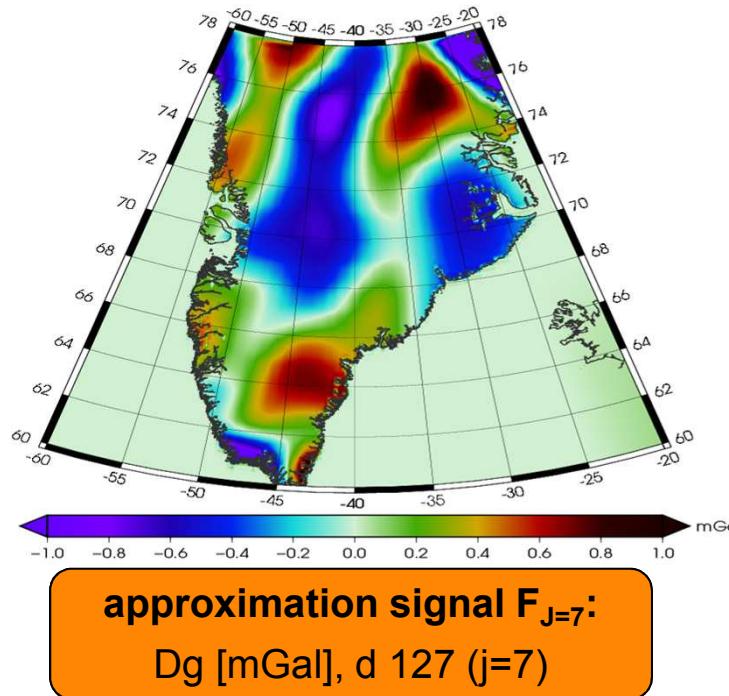
$$\tilde{\phi}_7(P, Q) = \sum_{l=0}^{127} \frac{2l+1}{4\pi R^2} \frac{(l-1)}{r_p} \left(\frac{R}{r_p}\right)^{l+1} \Phi_{7,l} P_l(P, Q)$$



### 3. Regional gravity field modeling

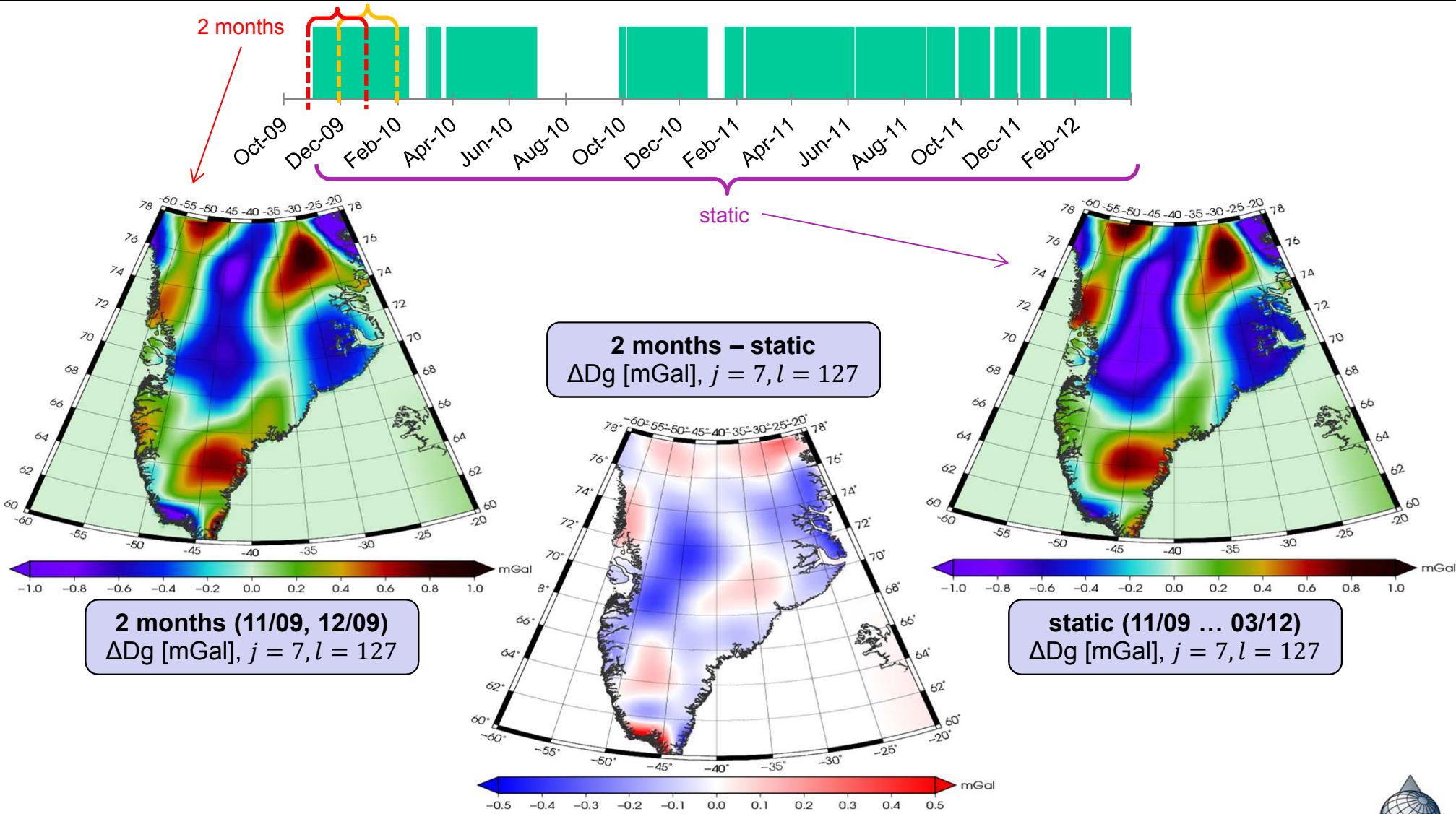


### 3. Regional gravity field modeling



## 4. Time series

- i. Regional approach – GOCE
- ii. Regional approach – GRACE

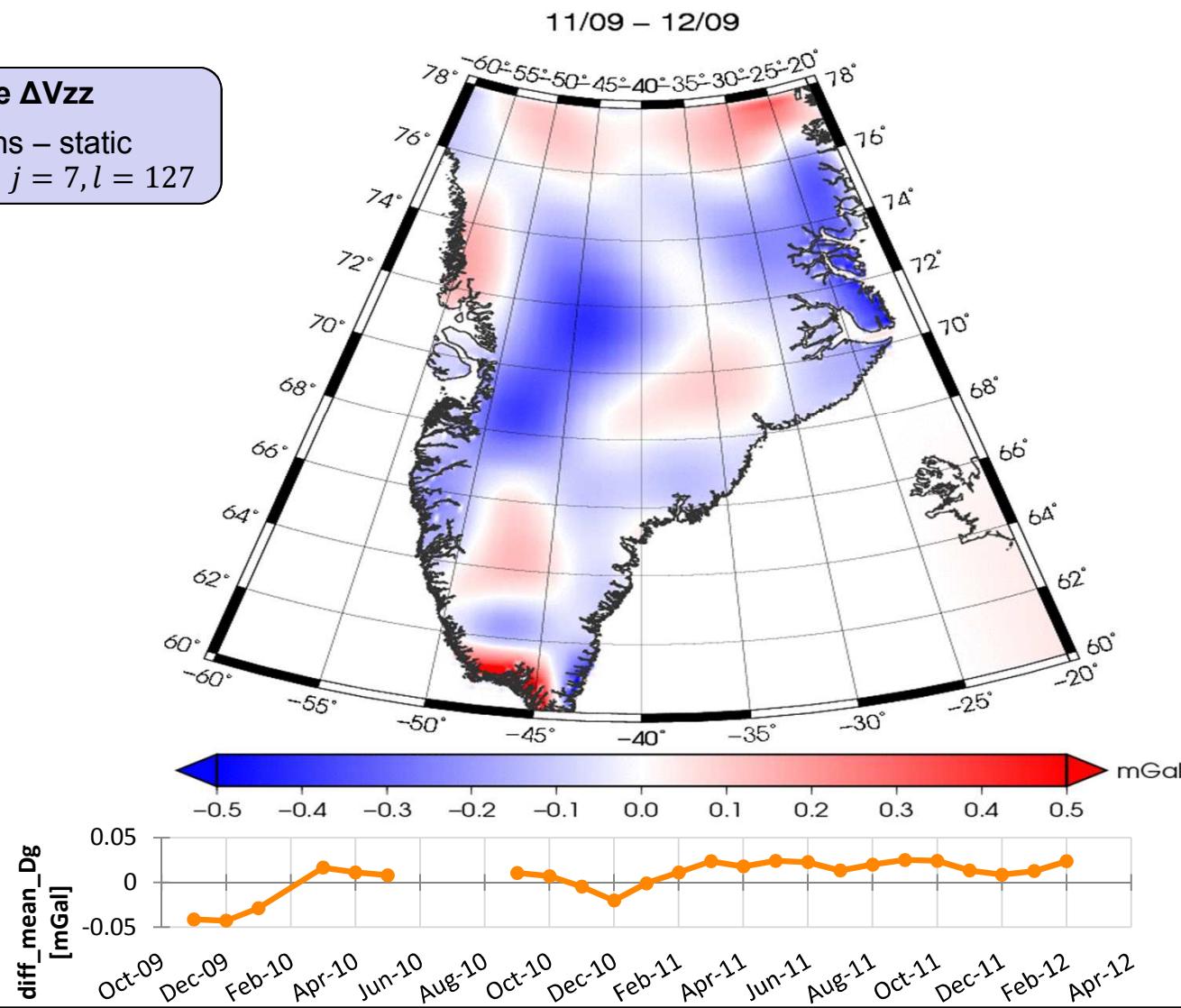


## 4. Time series

- i. Regional approach – GOCE
- ii. Regional approach – GRACE

Goce  $\Delta V_{zz}$

2 months – static  
 $\Delta Dg$  [mGal],  $j = 7, l = 127$



## 4. Time series

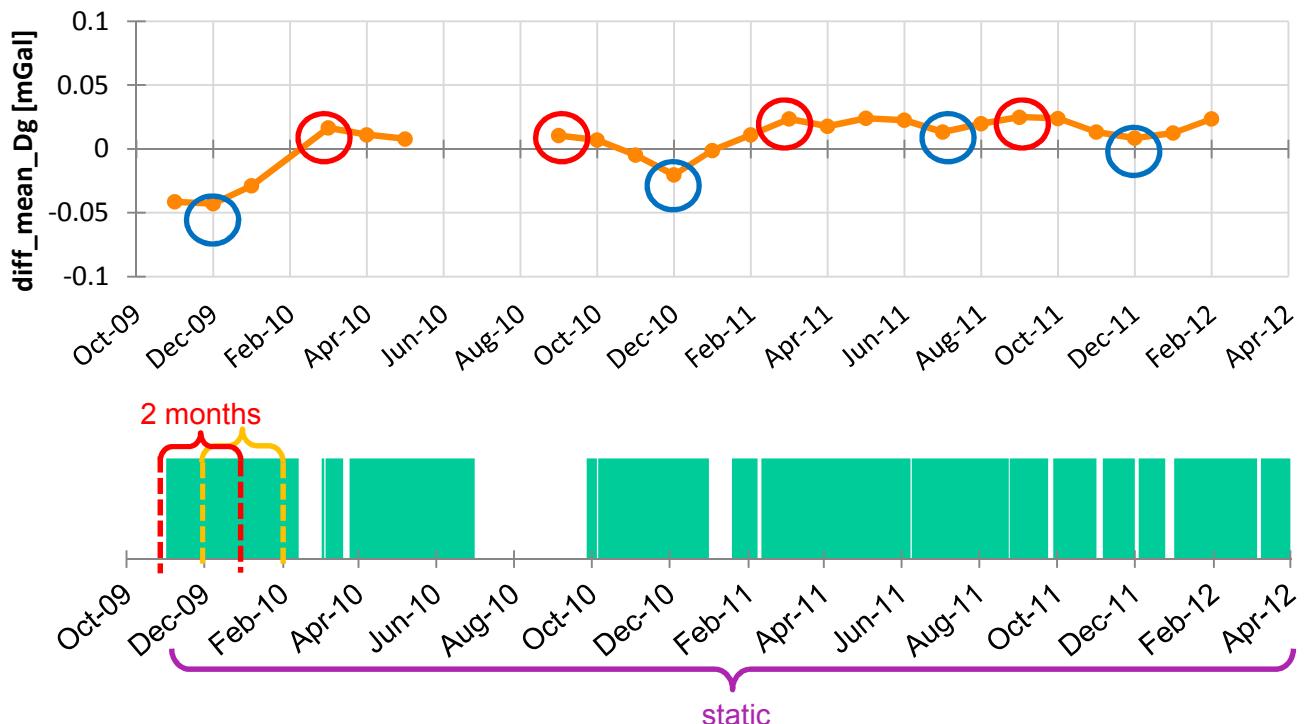
i. **Regional approach – GOCE**  
ii. **Regional approach – GRACE**

### Regional approach - GOCE ( $j = 7$ )

**Goce  $\Delta V_{zz}$**   
2 months – static  
 $\Delta g$  [mGal],  $j = 7, l = 127$



- variation:  $\sim 30 \mu\text{Gal}$
- seasonal variations
- max: Mar/Apr, Sep/Oct
- min: Dec/Jan, Jul/Aug
- no trend

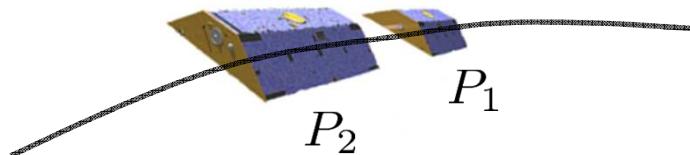


## 4. Time series

- i. Regional approach – GOCE
- ii. Regional approach – GRACE

### Regional approach – GRACE ( $j = 6$ )

- 1) Computing the potential differences  $\mathbf{dV}(\mathbf{P}_1, \mathbf{P}_2) = \mathbf{V}(\mathbf{P}_1) - \mathbf{V}(\mathbf{P}_2)$  from GSM potential fields



- 2) Subtracting a background model:  $\Delta dV(\mathbf{P}_1, \mathbf{P}_2) = dV(\mathbf{P}_1, \mathbf{P}_2) - dV_{back}(\mathbf{P}_1, \mathbf{P}_2)$



#### GRACE

$j$ [level]	1	2	3	4	5	6	7	8	9	10	11	...
$l$ [deg]	1	3	7	15	31	63	127	255	511	1023	2047	...
$r$ [km]	20000	6667	2857	1333	645	317	157	78	39	20	10	...

frequency [deg] →

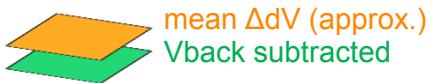


## 4. Time series

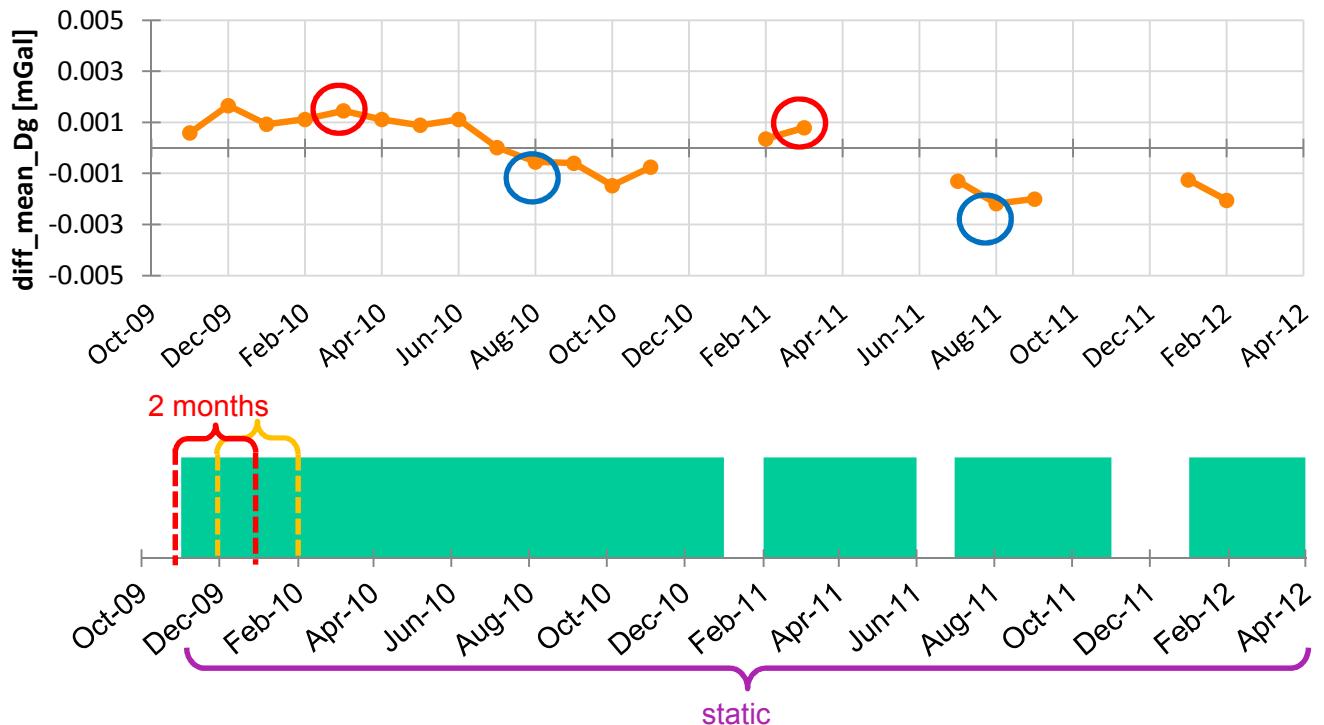
i. Regional approach – GOCE  
 ii. Regional approach – GRACE

### Regional approach – GRACE ( $j = 6$ )

**Grace  $\Delta dV$**   
 2 months – static  
 $\Delta Dg$  [mGal],  $j = 6, l = 63$

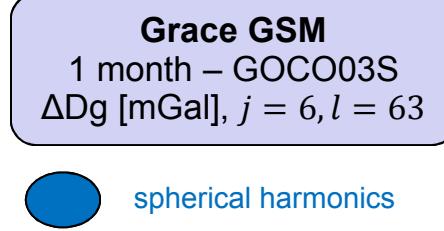
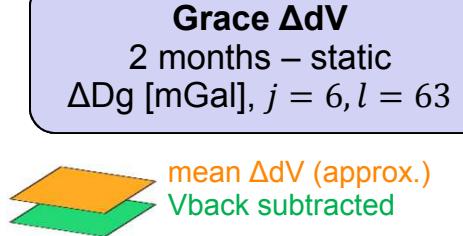


- variation:  $\sim 5 \mu\text{Gal}$
- seasonal variations
- max: Mar/Apr
- min: Aug/Sep
- descending trend ?

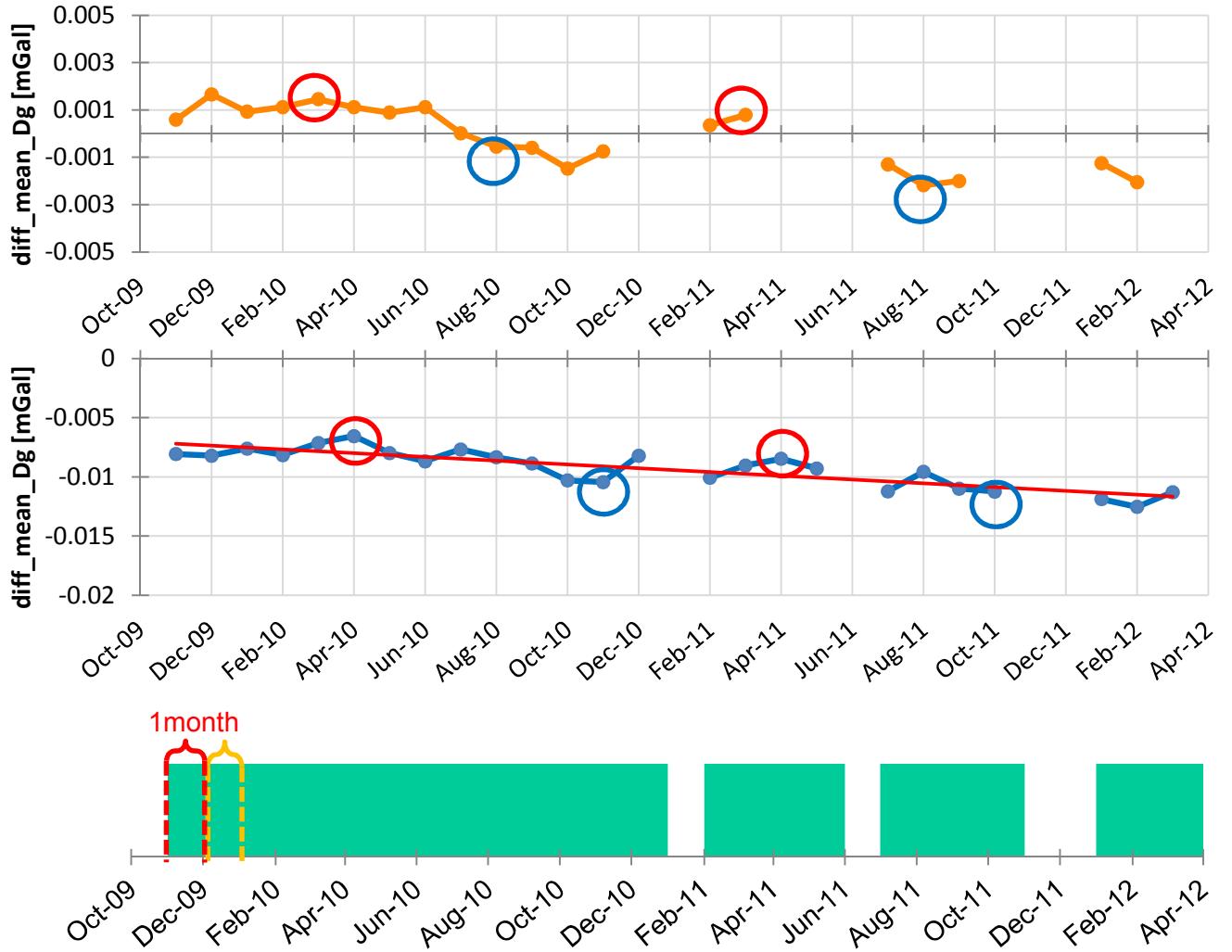


## 4. Time series

- i. Regional approach – GOCE
- ii. Regional approach – GRACE
- iii. Comparison: regional vs. global

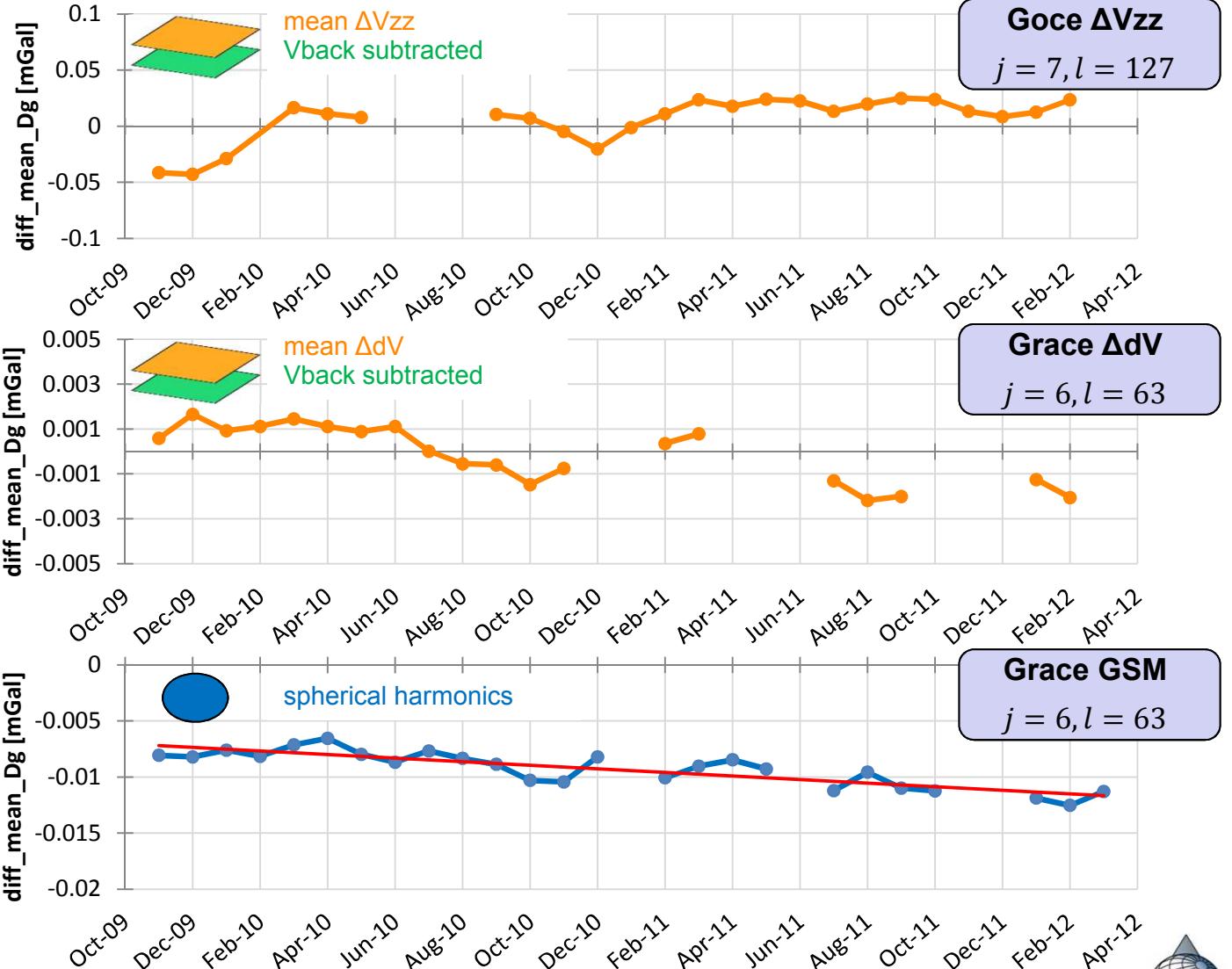


- variation: 5  $\mu$ Gal
- seasonal variations (not so clear)
- max: Apr
- min: Oct
- descending trend: 5  $\mu$ Gal
- > parallels detectable

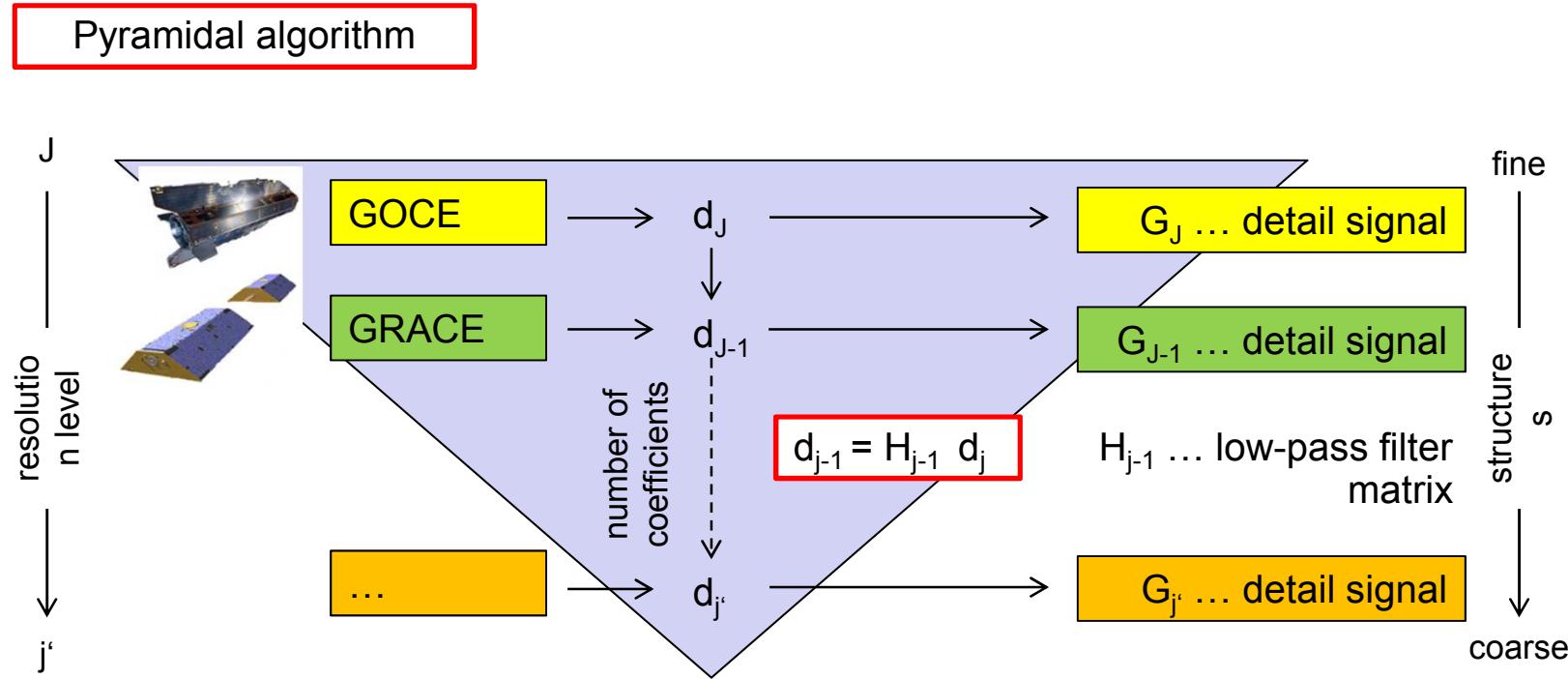


## 5. Aim: combination

**regional:  $j=7$  vs.  $j=6$**   
consistent maxima and minima



## 5. Aim: combination



# Summary

GOCE: originally planned to observe the Earth's static gravity field, but...

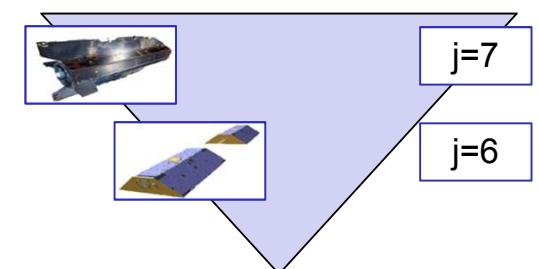


... time variations visible??

- 2-months solutions compared with static solution
- semi-seasonal variations detected with high sensitivity by GOCE
- good consistency to GRACE
- combination of GOCE + GRACE
- exploit highest degree of information from each measurement technique

## Open questions:

- consistent data sets (2-months GOCE vs. 1-month GRACE-GSM)?
- $V_{zz\_mod}$ : systematic errors caused by  $V_{yy}$ ?
- using full GOCE gradient tensor information?
- combination by pyramidal algorithm  
(step-by-step introducing new observation techniques)?



# Appendix

### 3. Regional gravity field modeling

- With all these assumptions we obtain the observation equation for the **modified GOCE gravity gradient**  $V_{zz} = V_{rr}$  with  $\Delta V_{zz}(\mathbf{x}(t)) = V_{zz}(\mathbf{x}(t)) - V_{zz,\text{GOCE03S}}(\mathbf{x}(t))$

$$\Delta V_{zz}(\mathbf{x}(t)) + e_{zz}(\mathbf{x}(t)) = \Delta V_{zz,7}(\mathbf{x}(t)) = \sum_{q=1}^{N_6} d_{6,q} \tilde{\phi}_7(\mathbf{x}(t), \mathbf{x}_q)$$

(globally the condition  $N_6 \geq 16,384 = 128^2$  ( $19,881 = 141^2$ ) has to be fulfilled).

The **modified scaling functions**  $\tilde{\phi}_7(\mathbf{x}(t), \mathbf{x}_q)$  are defined as

$$\tilde{\phi}_7(\mathbf{x}(t), \mathbf{x}_q) = \sum_{l=0}^{l'_{127}} \frac{2l+1}{4\pi R^2} \frac{(l+1)(l+2)}{r(t)^2} \left( \frac{R}{r(t)} \right)^{l+1} \Phi_{7,l} P_l(\mathbf{r}(t)^T \mathbf{r}_q) .$$

- With the  $N_6 \times 1$  vectors  $\mathbf{a}^T(\mathbf{x}) = [\tilde{\phi}_7(\mathbf{x}, \mathbf{x}_1), \tilde{\phi}_7(\mathbf{x}, \mathbf{x}_2), \dots, \tilde{\phi}_7(\mathbf{x}, \mathbf{x}_{N_6})]$  and  $\mathbf{d}_6^T = [d_{6,1}, d_{6,2}, \dots, d_{6,N_6}]$  the **general observation equation** reads

$$\Delta V_{zz}(\mathbf{x}(t)) + e_{zz}(\mathbf{x}(t)) = \mathbf{a}^T(\mathbf{x}(t)) \mathbf{d}_6 .$$

### 3. Regional gravity field modeling

- Considering the prior information  $E(\mathbf{d}_J) = \boldsymbol{\mu}_d$  and  $D(\mathbf{d}_J) = \boldsymbol{\Sigma}_d$  for the expectation vector and the covariance matrix of the vector  $\mathbf{d}_J$  the linear model

$$\begin{bmatrix} \mathbf{y} \\ \boldsymbol{\mu}_d \end{bmatrix} + \begin{bmatrix} \mathbf{e} \\ \mathbf{e}_d \end{bmatrix} = \begin{bmatrix} \mathbf{A} \\ \mathbf{I} \end{bmatrix} \mathbf{d}_J \quad D\left(\begin{bmatrix} \mathbf{y} \\ \boldsymbol{\mu}_d \end{bmatrix}\right) = \sigma_y^2 \begin{bmatrix} \mathbf{P}_y^{-1} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} + \sigma_d^2 \begin{bmatrix} \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{P}_d^{-1} \end{bmatrix}$$

results, wherein  $\sigma_y^2$  and  $\sigma_d^2$  are unknown variance components,  $\mathbf{P}_y$  is the given positive weight matrix of the observations.

- Variance component estimation** yields the estimation

$$\hat{\mathbf{d}}_J = \left( \frac{1}{\hat{\sigma}_y^2} \mathbf{A}^T \mathbf{P}_y \mathbf{A} + \frac{1}{\hat{\sigma}_d^2} \mathbf{P}_d \right)^{-1} \left( \frac{1}{\hat{\sigma}_y^2} \mathbf{A}^T \mathbf{P}_y \mathbf{y} + \frac{1}{\hat{\sigma}_d^2} \mathbf{P}_d \boldsymbol{\mu}_d \right)$$

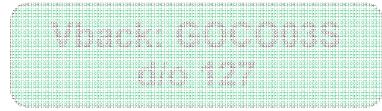
of the coefficient vector and its covariance matrix  $D(\hat{\mathbf{d}}_J)$ .

Introducing the parameter  $\lambda = \hat{\sigma}_y^2 / \hat{\sigma}_d^2$  the solution can be rewritten as

# 3. Regional gravity field modeling

i. General approach  
ii. MRR

- 1) Subtracting background model:  $\Delta V_{zz} = V_{zz} - V_{\text{back}}$



- ... the same as used for filling up low frequencies
- ... according to modeling resolution ( $J = 7$ )  
(reduce static part completely)



- 2) Analysis: series expansion in terms of reproducing kernel

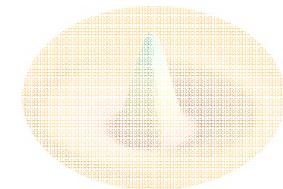


- ... estimating unknown scaling coefficients  $d_s$
- ... avoiding omission errors

- 3) Synthesis: series expansion in scaling functions



- ... modeling approximation signal  $F_j$
- ... low-pass filter



- 4) MRR: series expansion in wavelet functions

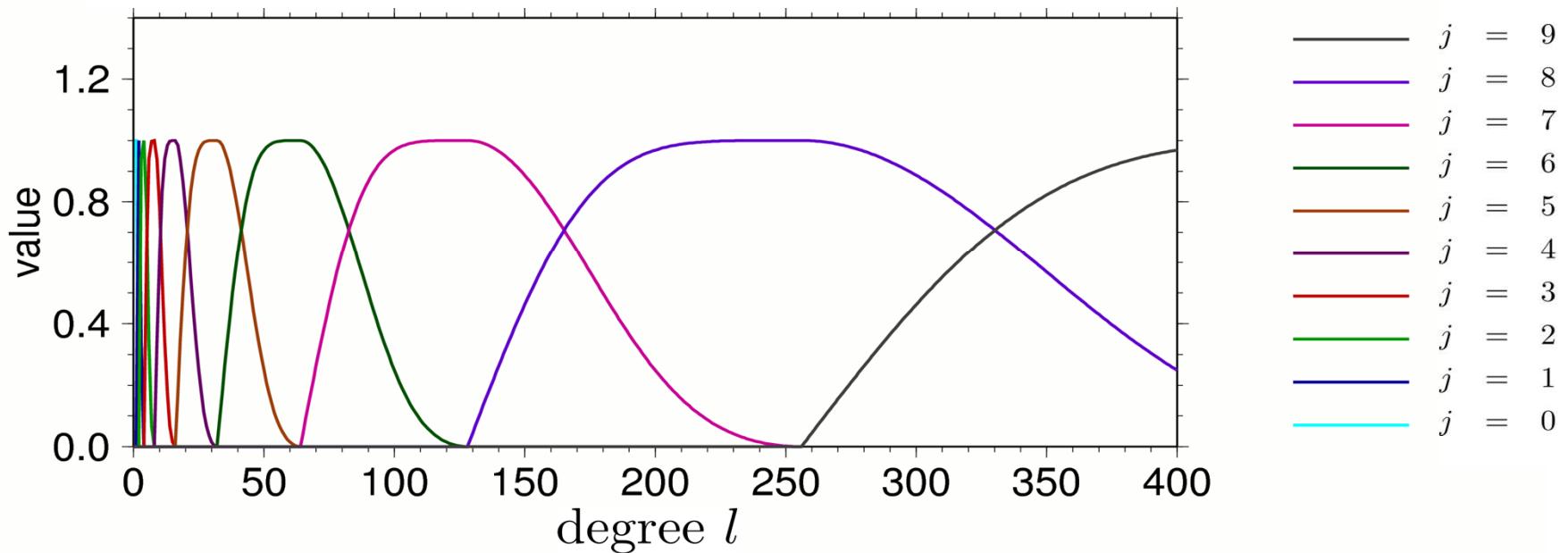
Vback: GOCO03S  
d/o 127

- ... splitting approximation signal into detail signals  $G_{j=0,\dots,6}$
- ... using Blackman wavelet functions
- ... band-pass filter



### 3. Regional gravity field modeling

i. General approach  
ii. MRR



#### 4) MRR: series expansion in **wavelet functions**

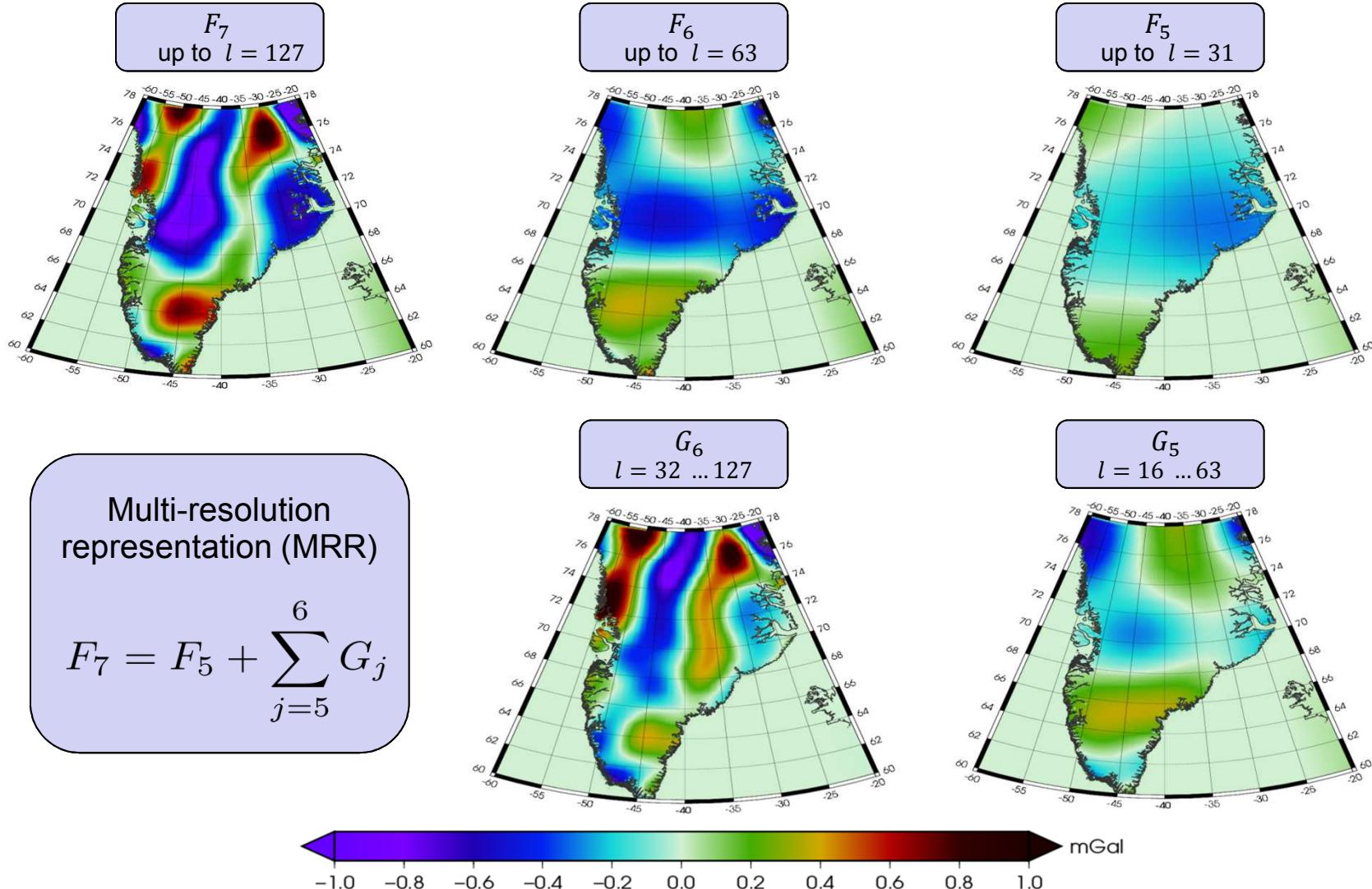
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### 3. Regional gravity field modeling

i.  
ii.

General approach  
MRR

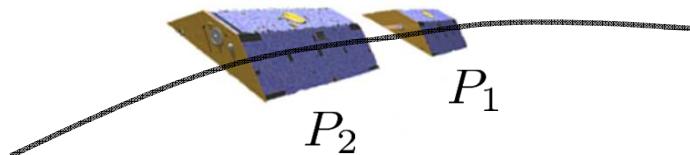


## 4. Time series

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### Regional approach – GRACE ( $j = 6$ )

- 1) Computing the potential differences  $dV(P_1, P_2) = V(P_1) - V(P_2)$  from GSM potential fields



- 2) Subtracting a background model:  $\Delta dV(P_1, P_2) = dV(P_1, P_2) - dV_{back}(P_1, P_2)$



#### GRACE

$j$ [level]	1	2	3	4	5	6	7	8	9	10	11	...
$l$ [deg]	1	3	7	15	31	63	127	255	511	1023	2047	...
$r$ [km]	20000	6667	2857	1333	645	317	157	78	39	20	10	...

frequency [deg]

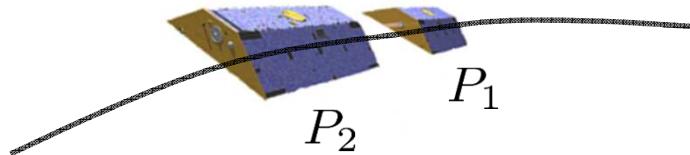


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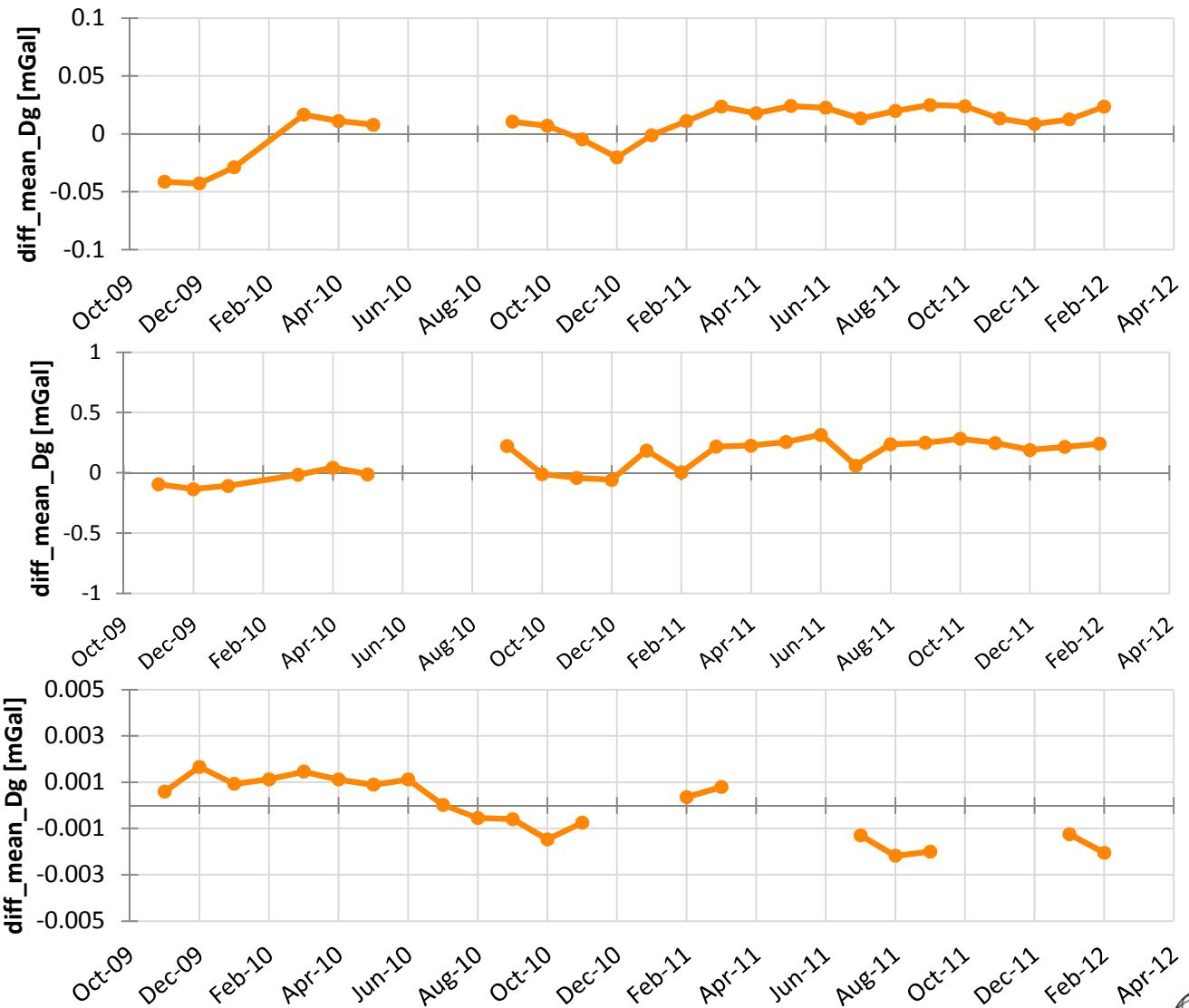
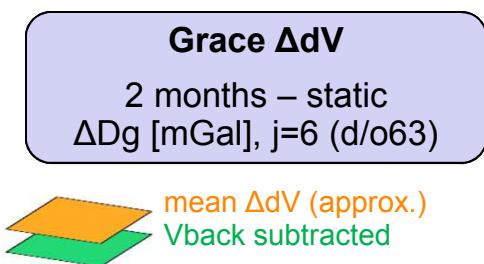
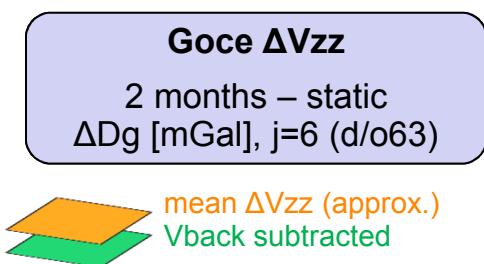
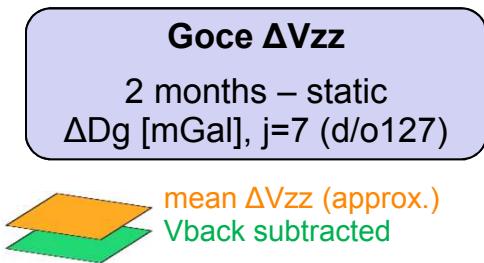
- 3) Analysis: series expansion in terms of **reproducing kernel** (up to degree  $l = 75$ )

$$\Delta dV(\mathbf{P}_1, \mathbf{P}_2) + e_{dV}(\mathbf{P}_1, \mathbf{P}_2) = \sum_{q=1}^{N_5} d_{5,q} \tilde{k}_{repro}(\mathbf{P}_1, \mathbf{P}_2, Q)$$

$$\tilde{k}_{repro}(\mathbf{P}_1, \mathbf{P}_2, Q) = k_{repro}(\mathbf{P}_1, Q) - k_{repro}(\mathbf{P}_2, Q)$$

## 4. Time series

i.      Regional approach – GOCE  
 ii.     Regional approach – GRACE



## 5. Aim: combination

