The ENVISAT Atmospheric-Chemistry mission (GOMOS, MIPAS and SCIAMACHY) – Instrument Status and Mission Evolution F. Niro, L. Saavedra de Miguel, A. Dehn, T. Fehr, G. Barrot, H. Bovensmann, M. Canela, H. Laur, P. Lecomte, G. Lichtenberg, G. Perron, P. Raspollini, P. Vogel and GOMOS, MIPAS, SCIAMACHY Quality Working Groups (QWG)



GOMOS

Afterwards, the range becomes a sliding window of 30°.

The Atmospheric-Chemistry instruments

GOMOS, Global Ozone Manitoring by Occultation of Stars, is a spectrameter that works in the UV, visible and near infrared wavelength ranges. The wavelength coverage allows monitoring 03, Core productions duration by proceedings of size, is a percentaint rule were all to y, rules durate durate many development rules are all to y, rules durate durate many development rules are all to y rules durate durate many development. The many development rule were all to y rules durate durate rules are all to y rules are

MPAS, Michelson Interferometer for Passive Atmospheric Sounding, is a Fourier transform spectrometer that measures the atmospheric limb emission in the mid-R (4.15 - 14.5 µm). It can perform elevation scan sequences through different sections of the etmosphere, from the upper troposphere to the mesosphere. MIPAS can scan in the anti-flight direction and in the perpendicular direction. It allows to retrieve profiles of several trace gases, in particular operational products include profiles of: 03,1420, CH4, N20, HN03 and N02 as well as temperature and ressure scientific products include: NO N205 HNO4 CION02 CIO CO CECS NH3 C2H6 HDO 03 isotopomers and others (more than 25 parameters

backstend end reflected from the etmosphere is recorded or relativity high resolution over the rouge 240 nm to 1700 nm, and in subcod regions however 2000 nm and 2400 nm. The longe werelength region to deally solid for the detection of above and encode. The three different viewing generative (eagle, link), and is sup/mon exclutionally yield: to how total column values or well as distribution publics the strategiment of the same concentration for the same concentration of the same table column.



* March 2004: owing to increased number of Interferometer Drive Unit (IDU) anomalies, the

Spatial (horizontal and vertical) resolution increased owing to the shorter slide movement
 Duty cycle decreased to around 35% to allow self-healing of instrument

mission was standed and several tests were made in order to arree a new measurement scenario

★ Jon 2005: the MIPAS mission restarted operationally with the Optimized Resolution scenario:

The IDU is a mechanical part with limited redundancy. IDU velocity error occurs when slide velocity is 20% higher than nominal. At this point instrument stops, the measurements need

to be restarted from on-ground operator. High number of INT velocity errors were still observed during 2005 – 2006 when the Optimized Resolution mission restarted. The errors

type was analyzed in details it was found that it depends on Temp (beam-splitter), frictio

identify the source of problems and corrective actions were undertaken. These

reduce the number of IDU errors that have now almost disappeared, see picture below

(bearings) and # of initialization (start-up). The investigations on IDU performances allow to

IDU velocity errors per month of operations (autor of ktig

ENVISAT extension beyond 2010

The main principle is to change the current (altitude and inclination) control by altitude control only in order to minimize the fuel consumption and extend the mission lifetime. ENVISAT will loose the repeat orbit track away from the equator and a drifting Mean Local Solar Time (MLST); in about 13,5 month, ENVISAT would reach the MLST of 21:55, and 6 Month later ENVISAT would reach MLST = 21:50.

ie **second principle** is to advance the altitude reduction, required at End of Mission. This will have 3 effec The altitude reduction is achieved during the mission, and an eventual failure of the platform will net endanger achieving this altitude.
* The altitude reduction is achieved without using the available fuel margin. The fuel margin will be used later for altitude maintenance. * A Menn Local Solar Time drift towards 22:05 will be induced

Adopting the principles explained above, the following two phases will be implemented chronologically. * Phese E3: The current mission plan is continued, i.e. nominal operations with no change in the Orbit maintenance strategy based on

MIPAS availability since the beginning of mission

inclination and ellitude control, up to about end 2010 (milestone II).
* Phase 64 (free inclination drift in lower ellitude - from milestone II to milestone IV): The satellite altitude is lowered to the one of the disposal orbit, and the satellite operation continues in "altitude control only" until fuel is exhausted. This point will mark the end of the ENVISAT Missi (possibly up to end 2013).

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Selected Orbit Control Strategy

08,5° inclination

22:10

35 / 501 AR

35/501, monitod control

Details on the mission status are regularly provided via the SCIAMACHY Operations Support Team (SOST, http://atmos.caf.dlr.de/projects/scops/

★ SCLAMACHY is operated in four main Science measurement observation modes: (i) Nadir, (ii) Limb, (ii Sun occultation. (iv) Moon Occultation: in addition Calibration and Monitorina measurements are serformed

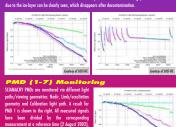
★ Modifications (test scenarios or permanent changes) to the operational scenario are introduced ar tracked via Operation Change Requests (OCR). e.g. regular limb mesosphere/thermosphere measurements

The SCIAMACHY instrument health and performance is monitored by SOST and ESA (via Instrument Data quality Evaluation and Analysis Service, IDEAS). On the right an overall status on the instrument or platform availability is shown, including also decontamination periods. Besides this, a major part of the monitoring is dedicated to analyze any instrument degradation and calibration - the results are used for data correction with m-factors starting with the next processor version. Main long-term monitoring Thermal Operations * Spectral Light Path Monitoring (SOST)

PMD monitoring (SOST) * Dead and bad Pixel Mask monitoring (SRON)

Spectral Light Path monitoring

White Light Source (WLS). In order to monitor the different SCIAMACHY light paths, solar measurements are taken in various viewing geometries: e.g. In limb/occultation geometry (via ASM and ESM mirrors) Below the current status for channels 1 and 8 as examples are shown. The throughput loss in channel 8 due to the ice-laver can be clearly seen, which disappears after decontamination.



Courtesy of SROW Scan Mirror Degra Analysis of the Absorbing gerosol data, Nadir stati MARAL measurements and science nodir rents show a scan angl - Courtery of SIGN

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Bad and dead Pivel Mask

http://www.sron.nl/index.php?option=com_conten

mid-100 The current status is shown in the picture below.

SRON analysis the had nixels of the detector array using criteria based on the

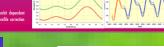
dark signal model, transmission gain and noise of pixel. As a result for

channels 6-8 pixels are flagged as unreliable or not usable for data retriev

Courtesy of SOSTOLR

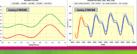
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dependent degradation. Th chnical Note by SRON. The effe rated on the right. Mission Extension – Impact on

Timelines and mission scenarios are analysed by SOST. The lowered ENVISAT orbit of shorte memore and mixing stemmes are unopeen y 2001, not lowere evident evident downlow will be complet inpact the inter-Sight (GS) delinities (ciambi/devition, see plots below). Impacts on scheduling of specific measurements (e.g. diffuse) or the limb/node matching access trackcomponent, will be addressed via instrument yew steering correction (Astronom). Along toxic cospects will be addressed via instrument yew steering correction (Astronom). Along toxic cospects will be addressed via instrument yew steering correction (Astronom). Along toxic cospects will be addressed via instrument yew steering correction (Astronom). Along toxic cospects will be addressed via instrument yew steering toxic controls and the steering toxic cospects will be addressed via instrument yew steering toxic costs and toxic costs and the steering toxic costs and to be addressed via instrument yew steering toxic costs and toxic costs a





★ March 2003: Major anomaly in Azimuth angle of the Steering Front Mechanism (SFM)→ Instrument Control Unit (ICU) and Mechanism Drive Electronics (MDE) configured to side '8' since 17-JUL-2003. GOMOS unavailability since the beginning of mission \star January 2005: Major anomaly affecting the Elevation angle of the SFM o Since 29-AUG-2005, a tent in an azimuth range of [-10,+10] End December 2008: mirror vibrations in elevation anale during tracking phase, measured by the SATU 111---(Star and Acquisition Tracking Unit) 'Y' axis, cause the profiles to stop high in the atmosphere. As the main mission target (ozone profiling) is at risk, the GOMOS mission is interrupted on 03-FEB-2009 *2 March 2009 the instrument is put in operations again. The azimuth is kept fixed to a window of

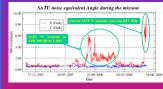
Currently GOMOS is experiencing an anomaly which is under investigation. The main issues

subject to intense monitoring are: *Tracking performance: unexpected SATU 'Y' fluctuations since end December 2008 that

monsted the overall data quality * Most Illuminated Position (MIP): bios in detection position on SATU since January 2005

* Increase of detector temperatures at expected rate due to ageing of radiators

 \bigstar Increase of the dark charge signal on all detectors due to non-protons radiation (expected) and due to protons (higher than expected before launch but linear in time). ★ UV radiometric sensitivity ratio has decreased 30% since the beginning of the mission which is slightly higher than the predicted value of 20-25%



Tracking performance

The Star Acquisition and Tracking Unit noise equivalent angle (SATU NEA) is the statistical angular variation of the SATU data above the atmospher

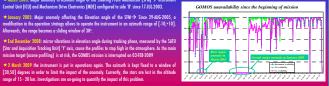
al increase (April 2006 – October 2007) due to fluctuations in the SATU 'Y' data above the atmosphere. The data availity was not affected

nt anomaly; sudden increase (from 29th December 2008) due to fluctuations on the Following a quick degradation, on 3rd February 2009 the stars were lost at 80 km and thus the instrument was placed in "PAUSE" mode until 2 March 2009

Life-limited items (LLI)

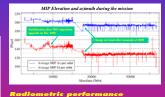
The most critical life limited item is the Steering Front Mechanism. The whole mechanism has been qualified for 1.5 million cycles. The number of movements will be around 990 000 at end October 2010. An estimation given by industry points to a 66% chance o having at least a GOMOS degraded mission at the end of 2010.

Assuming that the SATU Υ will return to stable conditions, the most critical performance parameter is the dark charge signal which is increasing due to temperature increase and due to high energy protons impacts. In October 2010 the signal will be around 4500e-which means that for given stars the signal noise will be lower than the DC signal (for SPA2). However, the performance degradation in 2010 is not drastic and only for a reasonable number of stars

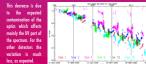


Acquisition and detection

The percentage of stars lost in detection and centering phases is less than 0.4%, much less than the warning value set to 15%. The Most Illuminated Pixel (star position on the SATU CCD in detection mode) should be at the SATU center (pixel 145 in elevation , pixel 205 in azimuth). The elevation MIP was stable since the end 2003 when the activation of a new algorithm reduced the deviations of the ENVISAT platform attitude with respect to the nominal one. The change in trend observed after the 2005 anomaly is acceptable but, at the moment the reason is not understood.



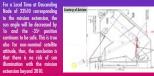
The monitoring consists of the calculation of the radiometric sensitivity of each of the four CCDs (UV, Visible, IR1 and IR2) and for the two photometers, by computing the ratio between parts of the reference spectrum using specific stars. For spectrometer A1 (UV) the ratio has decreased ~30% (slightly higher than expected) during the 7 years of mission.



Sun bafflina

COSA Earthnet Online

The problem could appear during Orbit Control Manoeuvres when the SFM is moved to the Sun Shade Position (-45°) in order to avoid any sun illumination in the detectors. Th position presents some margin and any mirror position below -35° (or even -31°) is safe.



Sun entering the FOV

Data quality disclaimers provide information on known deficiencies in processing, and on transient degradations, see:

on ENVISAT and for accessing atmospheric products, please contact ESA's SO Helpdesk;

The unavailability intervals of the ENVISAT instrument are available on line

Due to the updated ENVISAT oblit scenario with lowering of the orbit by 25 km and inclination drift, the MIPAS mission may be impacted due to sun illumination on the ASU (orange part on the right). The sun illumination into the instrument may damage seriously the detector, therefore it should be avaided with extreme care. A detailed analysis has shown that sun illumination on the ASU is dependent on the veriation of the Mid-Local Solar Time (MLST) induced by the updated ENVISAT orbit scenario.

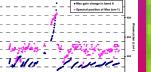


ENVISAT daily/monthly reports inform about calibration and processing configuration, anomalies, Product Control Service

Casa

The MIPAS focal plane (cooled to 70K) is affected by ice contamination that causes signal loss at the detector. This is weekly monitored as gain variation in band A. Increase of gain mean-signal less due to ice. Warm up of fecal plane with switch off of the cooler (decontamination allows to release ice. Decontaminations are now planned 2-3 times/year, this has strongly improved instrument performances in the last years. Outgassing is increasing with increases temperatures and it is decreasing along the mission as demonstrated by gain curve. Position of maximum is around 880 cm¹ corresponding to maximum of ice absorption in band A However spectral position of maximum may change due to other ice effects (e.g., scattering

Gain long term variation in band A



5 min for each orbit (before solar eclipse), during this time slat the ASU shutter should be closed and the instrument put to H/R mode.









MIPAS

The following main events characterize the MIPAS mission since Jounch:

Spectral Resolution reduced to 41% of the original one

The main issues in this paragraph, they are:

* Pointing performances

t Instrument Drive Unit (IDII) performance

*Radiometric calibration performance

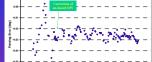
IDU performance

The mispointing of MIPAS is determined by looking at stars with the slides fixed. We measure the time of a star passing through the FOV and we compare it to the expected time in order to retrieve the pointing error. The long term series of mispointing shows that after the correction of on-board software (Dec 2003), the pointing has changed slightly with seasonal fluctuations around a mean value of about -25 mdeg. It should be stressed that mispointing is less critical for MIPAS since pressure is retrieved from the spectro in the 12 procession

Life-limited Items (LLI)

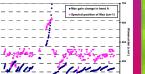
mechanism (ASU/FSU). There is no specific limiting factor for the number of interferometer strokes. Since the instrument performances are very stable there is no indication at the moment of INT or ASU/FUS degradation. Other important LLI are the cooler and the losse. No degradation is observed in the cooler parameters, while for the loser power we still have a lot of margin to operate for next 10 years. Finally long term analysis of the overall thermal conditions shows that there is no specific trend and the long term variations of house-keeping data are as expected.

★ Since Oct 2006: following the improved instrument performances the duty cycle has bee progressively increased from 35% of Oct 2006 to 100% since Dec 2007. The increase of duty cycle did not affect instrument performances. it at at at at at a at at at at at a MIPAS mispointing variations along the mission



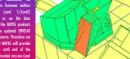
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Radiometric performance

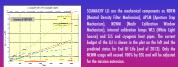


Dec-82 Jan-64 Feb-65 Mar-64 Apr-67 Jan-68

Following this analysis the sun illumination on the ASU may be present for MLST of 22:03 - 22:10 in the period 8 May to 11 July 2012 over the southern hemisphere. This critical condition may lest about



yielding an effective throughput for the different PMD light paths. Since the PMDs are broadband Source and Source devices, no spectral averaging is required. Life-limited Items (LLI)





anner Control System

n, and performance, they can be accessed for the atmospheric chemistry missions at:

tp://earth.esa.int/pcs/envisat/gomos/re

http://earth.esg.int/pcs/envisat/mipgs/reports.

A special analysis on the scanner control algorithms was performed by Astrium to analyze orbit dependent parameters and soft ware codes. The basic scan profile parameters and a part of the scan profile correction rs need to be updated

Source) and SLS and cryogenic heat pipes. The current budget of the LLI is shown in the plot on the left and the predicted status for End Of Life (end of 2013). Only th NCWM usage will exceed 100% by EOL and will be adjuste

Courtery of SOST/FE