

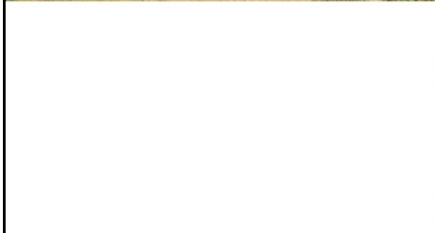
Soil moisture & Water Resource Applications

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What is the difference?



What is Drought ?

Dry Condition: No transpiration



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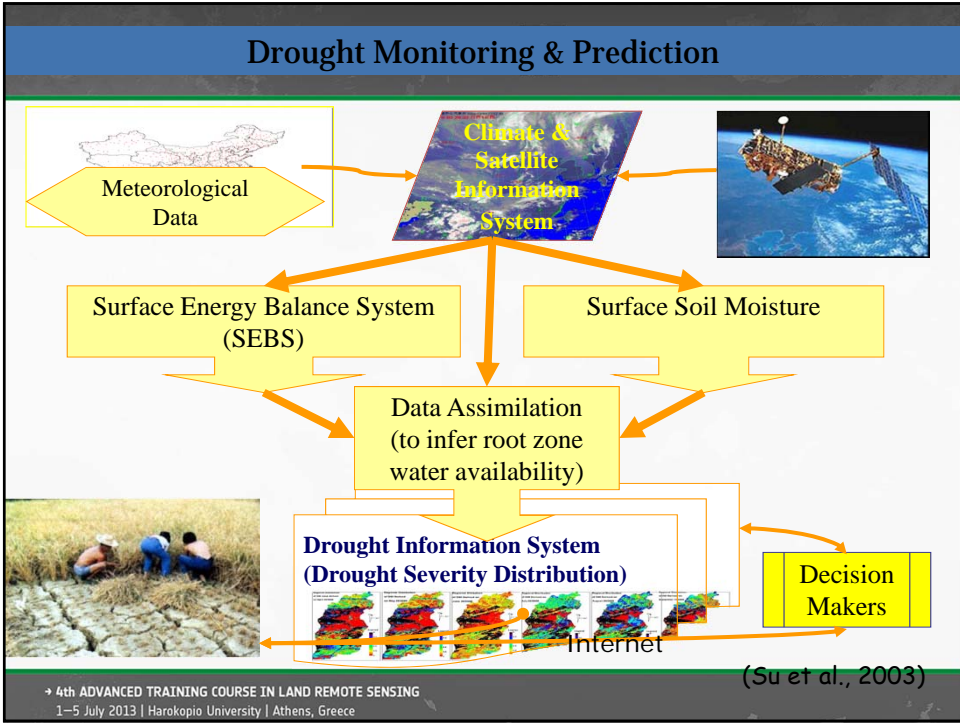
Approaches for Drought Monitoring and Prediction

- Approach 1: Surface Energy Balance
 - To derive relative evaporation & relative soil moisture in the root zone from land surface energy balance
 - To define a quantitative drought severity index (DSI) for large scale drought monitoring
- Approach 2: Soil Moisture Retrieval
 - To determine surface soil moisture
 - To assimilate surface SM into a hydrological model to derive root zone soil moisture

To validate the methodologies on the basis of large scale field experiments

(Su et al., 2003)

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Microwave remote sensing of soil moisture

- Retrieval with Radiative Transfer Equation (Wen and Su, 2003a, Phy. Che. Earth)
- Retrieval with change detection method (Wen and Su, 2003b, Geophys. Res. Letter)

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Retrieval with Radiative Transfer Equation

For the three antennae forward (45°), sideways (90°), and afterward (45°), we have

$$\sigma^0(\theta) = [1 - F_c(1 - T^2(\theta))] \sigma_{soil}^0 + F_c(\sigma_{int}^0 + \sigma_{veg}^0)$$

$$\sigma_{soil}^0(\theta) = \frac{|\Gamma(0)|^2 \exp\left(-\frac{\tan^2 \theta}{2s^2}\right)}{2s^2 \cos^4 \theta}$$

$$\sigma_{veg}^0(\theta) = \frac{\kappa_s \cos \theta}{2\kappa_e} [1 - \exp(-2\kappa_e \sec \theta)] = \frac{1}{2} \omega_s \cos \theta [1 - T^2(\theta)]$$

Where:

$\sigma^0(\theta)$ is observed backscattering coefficient,

θ is incidence angle,

F_c is vegetation fractional coverage,

$T^2(\theta)$ is canopy transmittance in two ways of incoming and outgoing path,

σ_{soil}^0 is contribution of soil, σ_{veg}^0 is vegetation volumetric contribution,

σ_{int}^0 is the contribution from land surface-vegetation interaction.

κ_s and κ_e are scattering and extinction coefficient of vegetation discrete elements.

ω_s is the single scattering albedo of the vegetation scatters.

$s = \sqrt{2\sigma} / l$ is the root mean square (RMS) slope of surface height,

σ is standard deviation of the surface height,

l is horizontal distance between two different points on the surface using a Gaussian correlation function,

$\Gamma(0)$ is soil Fresnel reflectivity at normal incidence of a half-space.

from above eqs, we solve for F_c , $\Gamma(0)$, s or T (with some additional input for vegetation)

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Retrieval with Radiative Transfer Equation

Radar backscatter of tree antennae
(three azimuth angles)

Vegetation
fractional coverage

Vegetation transmissivity,
Reflectivity at nadir,
Roughness slope

Given $\Gamma(0)$, we solve for the
dielectric constant, ϵ , (real part, $\epsilon = \epsilon_r - j\epsilon_i$)

Dielectric constant
(dielectric mixing model)

Soil texture
(percentage of
sand and clay)

$$\Gamma(0) = \left| \frac{1 - \sqrt{\epsilon_r}}{1 + \sqrt{\epsilon_r}} \right|^2$$

From ϵ_r , we solve for soil
moisture M_v , using the dielectric
mixing model of Dobson (1986),
Peplinski (1998).

Soil moisture

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Tibetan Soil Moisture Experiments at location of CAMP/Tibet sites (in collaboration with Y. Ma, J. Wen, K. Yang, Z. Hu, CAS)

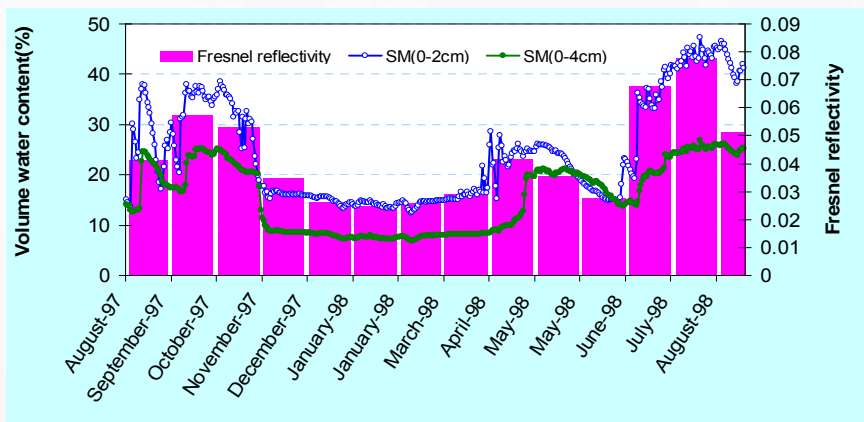
GEWEX Asian Monsoon Experiment (GAME) in the Tibet Plateau (GAME/Tibet, 1996-2000)

CEOP (Coordinated Enhanced Observing Period) Asia-Australia Monsoon Project in the Tibetan Plateau (CAMP/Tibet, 2001-2005)

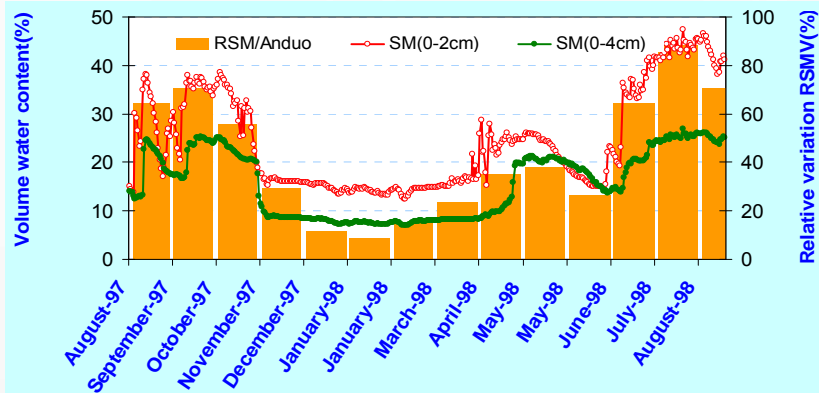
Coordinators: Y.M.Ma & T.D.Yao, K.Ueno & T.Koike



Estimated Fresnel reflectivity and ground measured volume soil water content



Retrieval with change detection method (Wen and Su, 2003b, Geophys. Res. Letter)



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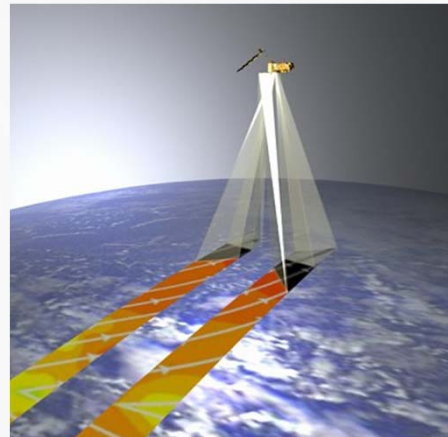


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ASCAT Scanning Principle

- 5.255 GHz C-band radar scatterometer with three dual-swath (2 x 500 km width, offset 384 km left/right of ground track) antennas (fore/mid/aft)
- Radar backscatter at three azimuth angles to provide surface wind vectors of 4-24 m/s with accuracy ± 2 m/s & $\pm 20^\circ$
- Spatial resolution 50 km (25 km experimental)
- 0.57 dB radiometric accuracy
- Incidence angle range 25-65°



ASCAT's two 500km swaths, global coverage every 5 days, data acquired irrespective of daylight and cloud conditions

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Global soil moisture maps (pixel size:15' by 15')

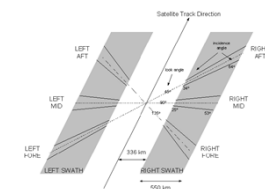
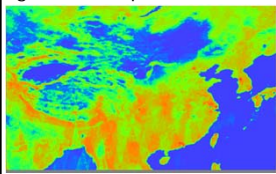
Retrieved using ASCAT data (the smoothed 12.5 km spatial resolution)
temporal coverage from 1-7 July 2007.

Input data:

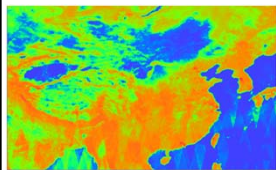
- ASCAT sigma triplet values (fore, mid, aft).
- Percentage of sand and clay maps obtained from ecoclimap website:
http://www.cnrm.meteo.fr/gmme/PROJETS/ECOCLIMAP/page_ecoclimap.htm
[reterived](#) derived from FAO (1988) soil texture database
- Land cover map also obtained from ecoclimap project
- Vegetation cover converted from LAI data using : $F_c = 1 - \exp^{-0.5 \cdot LAI}$,
where LAI is MODIS leaf area index 8-day global 1km product, temporal
coverage 01-08 July 2007, obtained from:
<https://wist.echo.nasa.gov/~wist/api/imswelcome/>

Some results with ASCAT data (CEOP-AEGIS WP4)

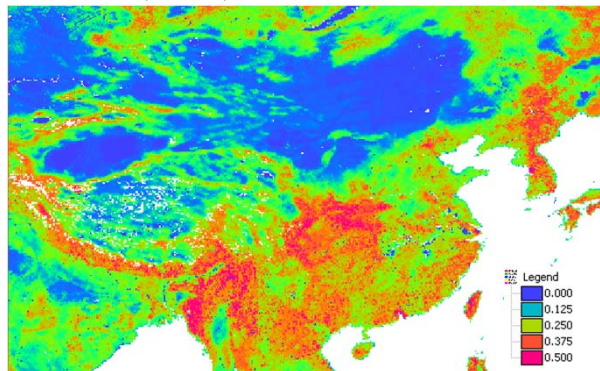
sigma zero triplet for values (dB)



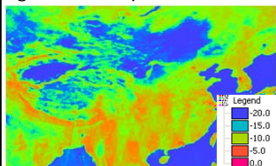
sigma zero triplet mid values (dB)



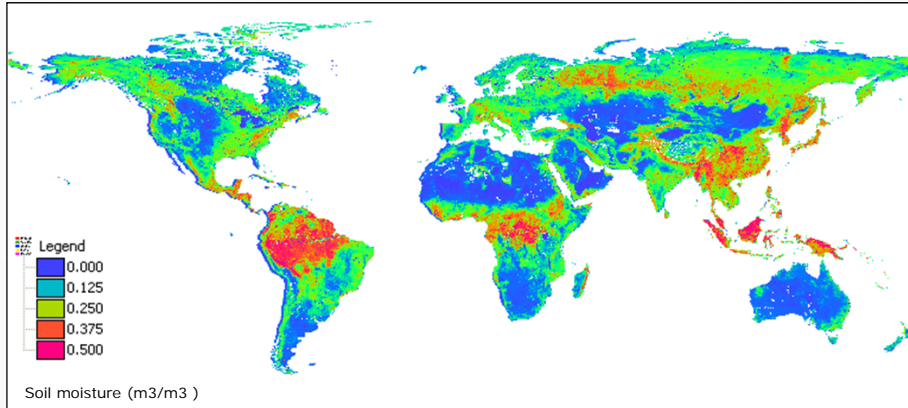
Soil moisture (m3/m3)



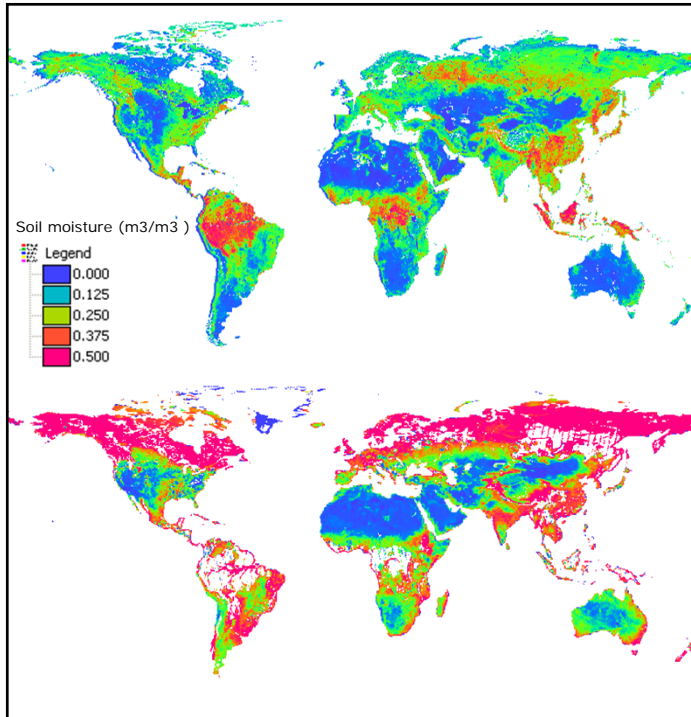
sigma zero triplet after values (dB)



Volumetric soil moisture, ASCAT data, 1-7 July 2007

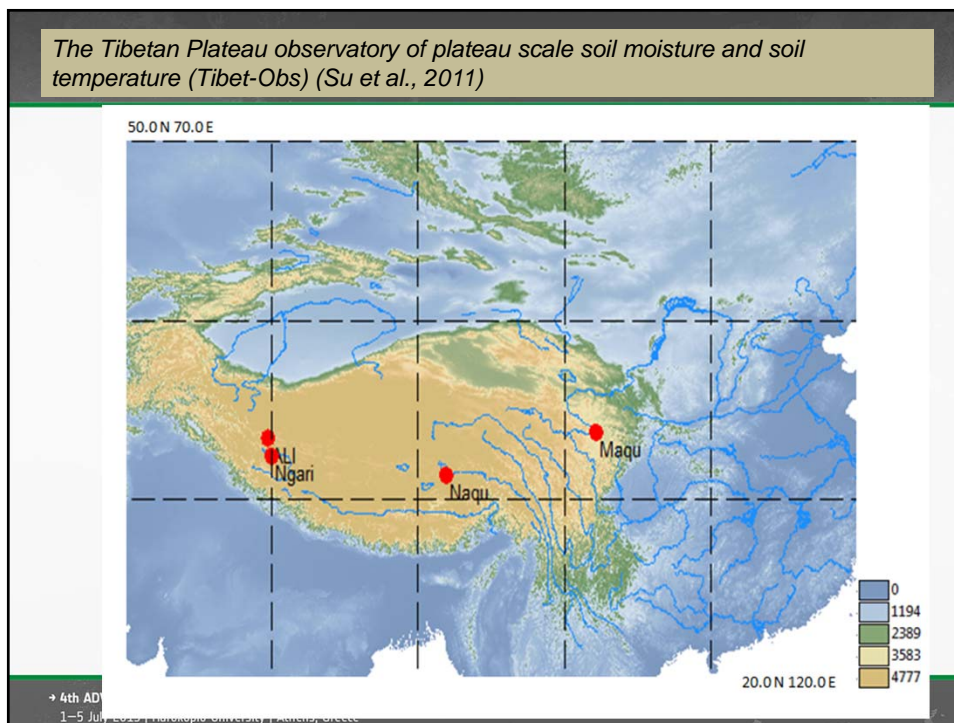
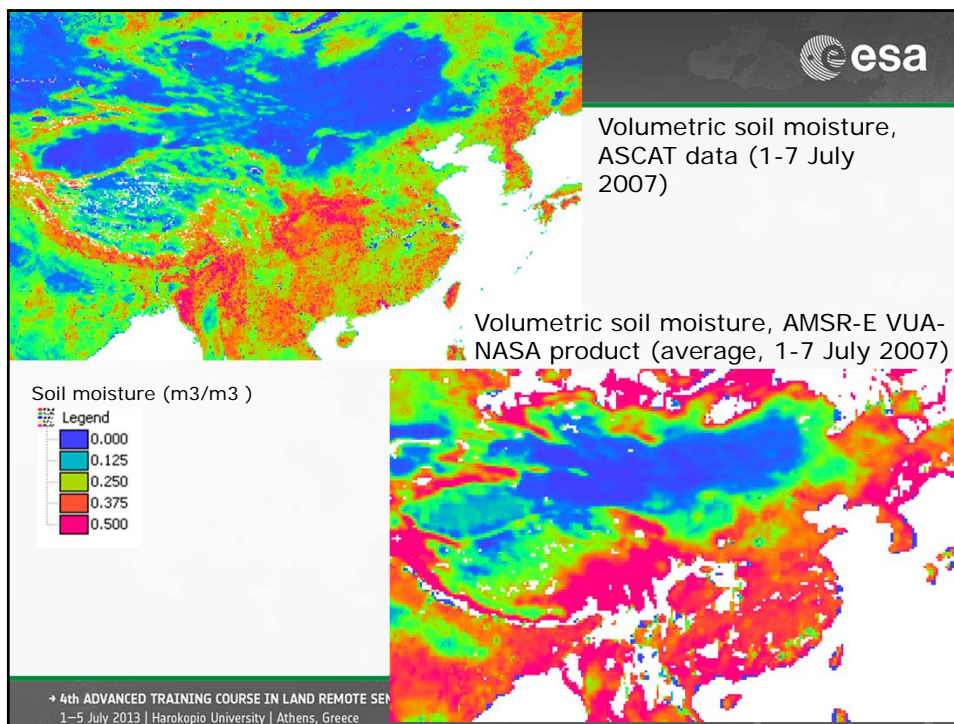


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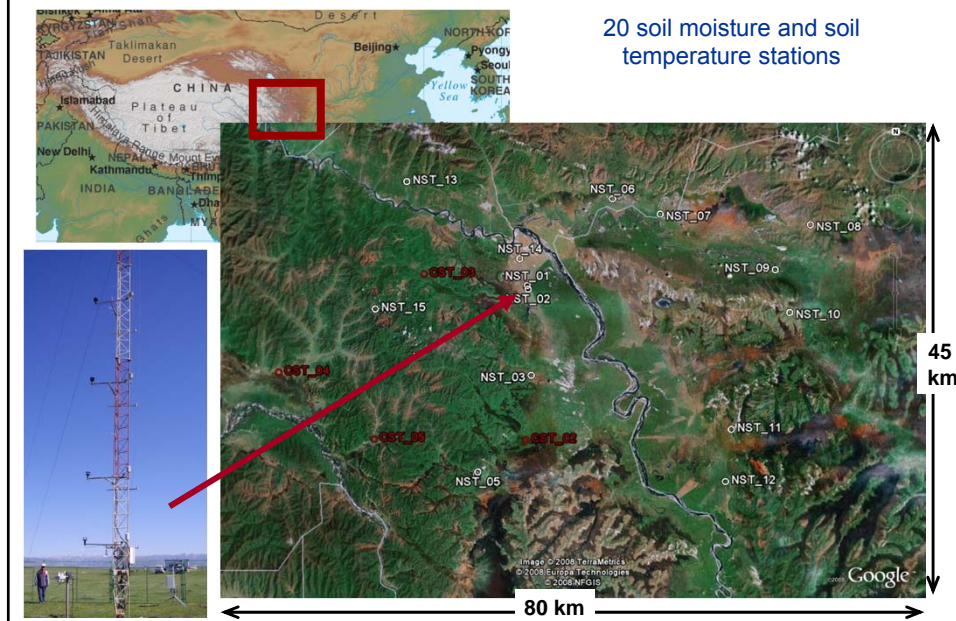


Volumetric soil moisture, ASCAT data, 1-7 July 2007

Volumetric soil moisture, AMSR-E VUA-NASA product, average 1-7 July 2007 (Pixel size 0.25°, White pixels = flag values = sea, ice, forest)

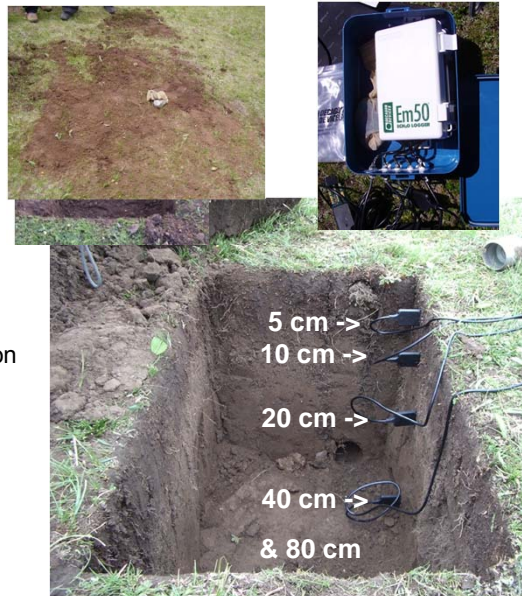


Maqu soil moisture network

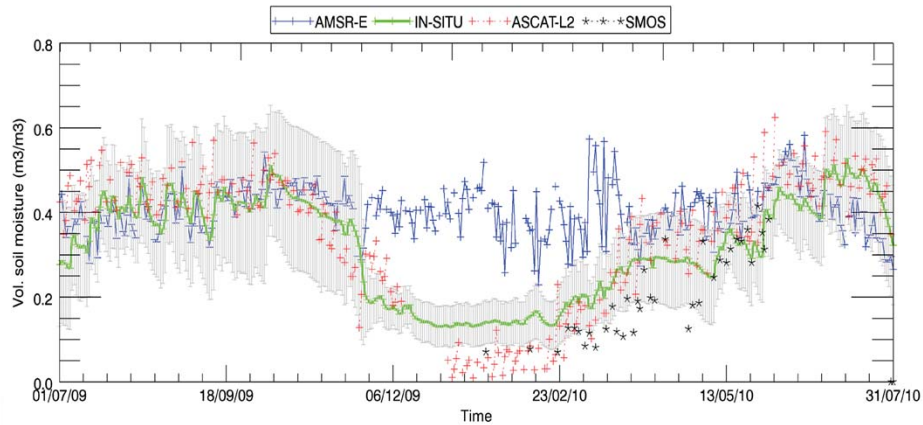


Maqu: station description

- 2/3 soil moisture & temperature probes
- 5, 10 & 20 cm deep (few profiles deep 80 cm)
- 1 datalogger
- data collected every 15 min
- memory capacity of 1 year
- completely buried
- site revisit to download data:
 - beginning and end of monsoon season in Maqu



The Tibetan Plateau observatory of plateau scale soil moisture and soil temperature (Tibet-Obs) – validation and calibration of global soil moisture data products (Su et al., 2011)



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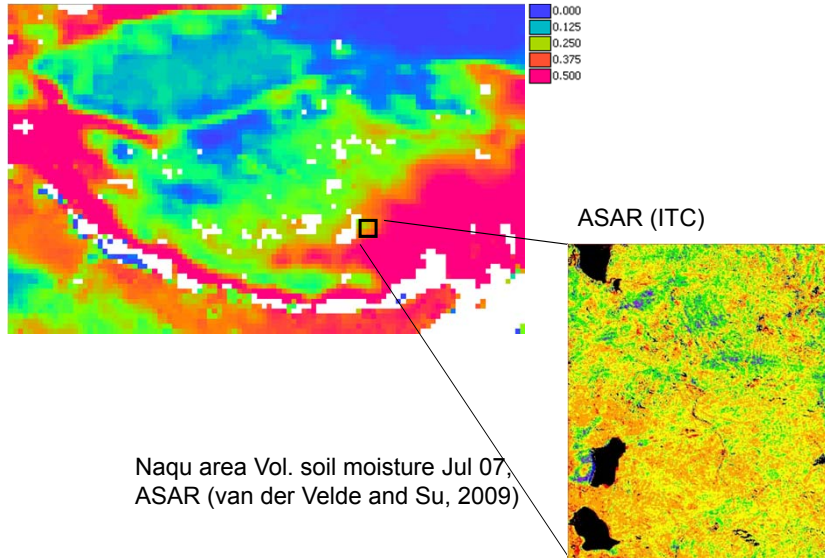
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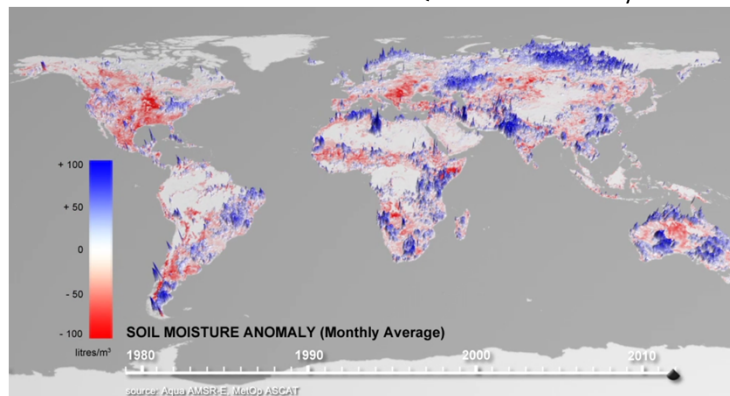
Tibetan Plateau Average vol. soil moisture 1-7 July 2007 AMSR-E VUA-NASA



The WACMOS global soil moisture product

<http://www.esa-soilmoisture-cci.org/node/127>

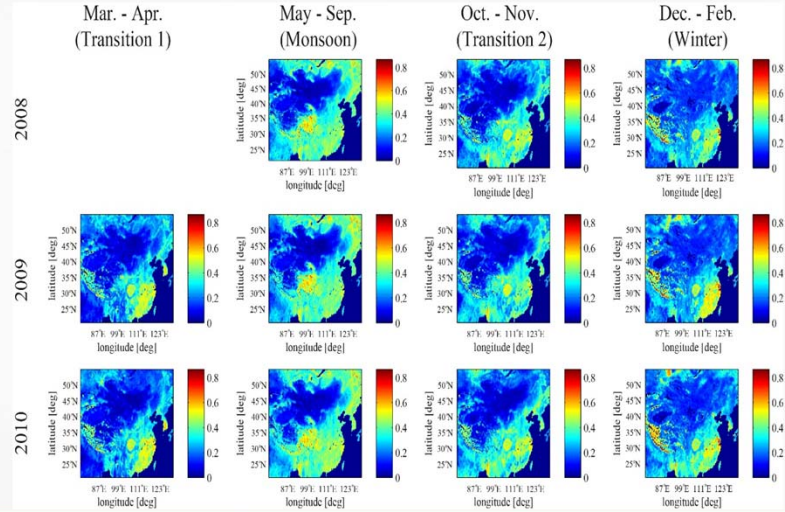
Global monthly averages of soil moisture in the early 1980s in litres per m³, followed by changes in global soil moisture to present. Major anomalies are highlighted, such as the 1992 flooding in Afghanistan, the 2005 drought in the central US, Russia's heatwave in 2010 and Australia's floods in Queensland in January 2011.



NEW: A Combined Soil Moisture Product over China Using Different Sensors (AMSR-E & ASCAT)

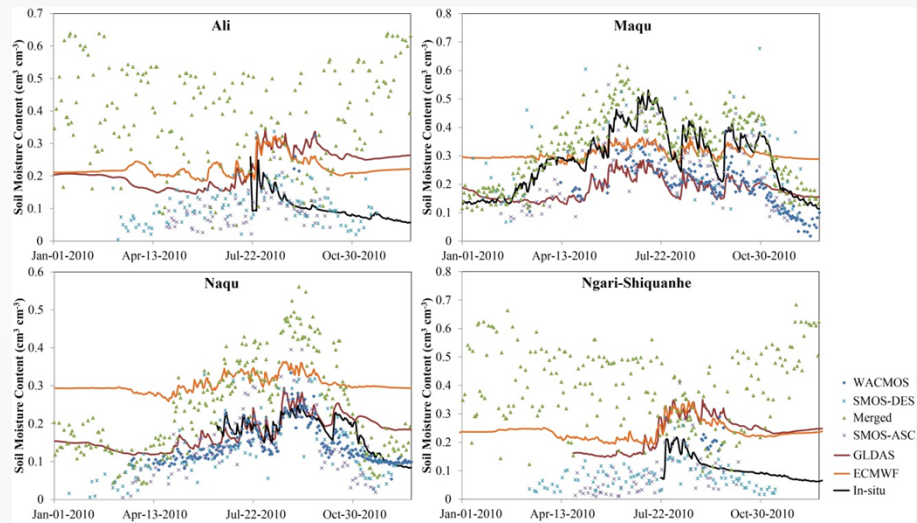
(Y. Zeng, L. Dente, L. Wang, J. Wen, Z. Su)

A simple Bayesian based method is used (bias correction, & variational method)



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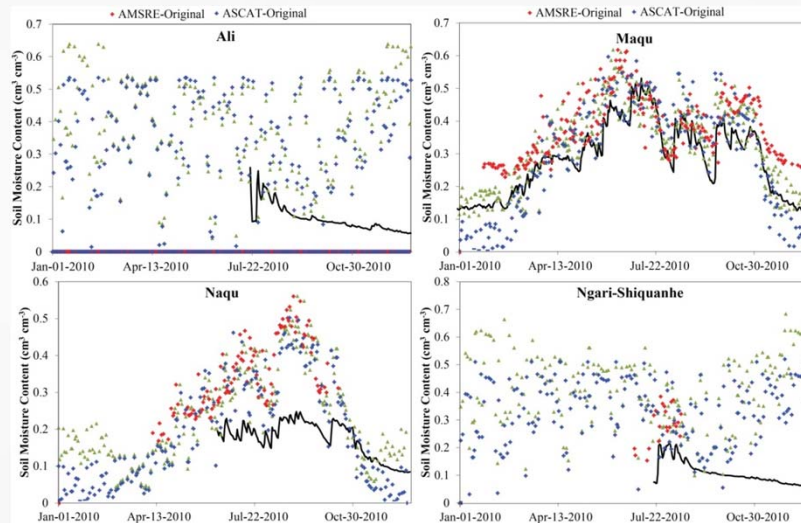
How good are the different products? Comparison of different soil moisture products with the in-situ observation



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Where is the problem?

Comparison among different original satellite soil moisture products with the in-situ observation



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Conclusions & outlook

1. Many soil moisture products are now available.
2. It is recommended to validate the accuracy of these products, with in-situ data, before routine applications.
3. In-situ observations remain crucial, especially in places where little observational evidence exists.
4. Accurate retrieval of soil moisture remains a challenge.

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Practical – soil moisture retrievals

Objectives

1. To retrieve soil moisture using the ITC retrieval model (an example of using METOP ASCAT L1B data).
2. To get familiar with soil moisture product retrieved from AMSR-E data.
3. To get familiar with EUMETSAT soil moisture product retrieved from ASCAT L2 data.
4. To get familiar with the SMOS soil moisture product.
5. To compare the soil moisture products.

Materials (Prepared by Lichun Wang, ITC)

– Exercise : Practical on analysis of soil moisture products

Software

– ILWIS & BEAM

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References/Further Readings

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