# On the Combination of Terrestrial Data and GOCE Based Models in Earth's Gravity Field Studies: Compatibility and Optimization 

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## 1. Introduction - Integral Kernels

When dealing with the relationship between the disturbing potential $T$ and gravity disturbances $\delta g$, we known that

$$
T(x)=R \sum_{n=0}^{\infty}\left(\frac{R}{r}\right)^{n+1} \frac{1}{n+1} \delta g_{n}, \quad r=|x|
$$

and that for $r=R$

$$
T=\frac{R}{4 \pi} \int_{\sigma} K(\psi) \delta g d \sigma \quad \text { with } \quad K(\psi)=\sum_{n=0}^{\infty} \frac{2 n+1}{n+1} P_{n}(\cos \psi)
$$

which sometimes is called Hotine-Koch function.
Naturally, global gravity field models allow a modification, e.g.

$$
T(x)=\frac{R}{r} T_{0}+\left(\frac{R}{r}\right)^{2} T_{1}+\cdots+\left(\frac{R}{r}\right)^{N} T_{N-1}+R \sum_{n=N}^{\infty}\left(\frac{R}{r}\right)^{n+1} \frac{1}{n+1} \delta g_{n}
$$

where we compute the disturbances $\delta g$ with respect to an adopted model, put $T_{n}=0$ for $n=0,1,2, \ldots, N-1$ and
subsequently work with the reduced Hotine-Koch kernel

$$
K_{r e d}^{(N)}(\psi)=\sum_{n=N}^{\infty} \frac{2 n+1}{n+1} P_{n}(\cos \psi)
$$

Graphically the kernel is illustrated in the following figures.



The approach as above is straightforward, but not the only possible.

GOCE data and terrestrial gravity measurements are two different sources of information. Their combination has a tie to potential theory and boundary value problems.

In the sequel $\Omega$ means a solution domain bounded by two surfaces. We can even suppose that $\Omega$ is bounded by two spheres of radius $R_{i}$ and $R_{e}, R_{i}<R_{e}$.

in Holota and Nesvadba (2007)

## 2. Boundary Value Problem

If we continue in our considerations, we e.g. can formulate the following problem

$$
\begin{gathered}
\Delta T=0 \text { in } \Omega \\
\frac{\partial T}{\partial r}=-\delta g \text { for } r=R_{i} \quad \text { and } \quad T=t \text { for } r=R_{e}
\end{gathered}
$$

where $\delta g$ is the gravity disturbance and $t$ means the input from an available satellite-only model .

The domain $\Omega$ is bounded. $\Rightarrow$ Therefore, the solution $T=(r, \varphi, \lambda)$, we are looking for, has generally the following form

$$
\begin{gather*}
T=T^{(i)}+T^{(e)}  \tag{3}\\
T^{(i)}=\sum_{n=0}^{\infty}\left(\frac{R_{i}}{r}\right)^{n+1} T_{n}^{(i)}(\varphi, \lambda) \quad \text { and } \quad T^{(e)}=\sum_{n=0}^{\infty}\left(\frac{r}{R_{e}}\right)^{n} T_{n}^{(e)}(\varphi, \lambda)
\end{gather*}
$$

where $T_{n}^{(i)}$ and $T_{n}^{(e)}$ are the surface spherical harmonics.

Using the orthogonality of spherical harmonics, we obtain a linear system for $T_{n}^{(i)}$ and $T_{n}^{(e)}$, that for and individual $n$ yields

$$
\begin{equation*}
T_{n}^{(i)}=\frac{R_{i} \delta g_{n}+n q^{n} t_{n}}{D_{n}} \tag{4a}
\end{equation*}
$$

and

$$
\begin{equation*}
T_{n}^{(e)}=-\frac{R_{i} q^{n+1} \delta g_{n}-(n+1) t_{n}}{D_{n}} \tag{4b}
\end{equation*}
$$

where

$$
D_{n}=n\left(1+q^{2 n+1}\right)+1 \text { is the determinant, } q=R_{i} / R_{e}
$$

while $\delta g_{n}$ and $t_{n}$ are surface spherical harmonics in the developments of $\delta g$ and $t$, respectively, i.e. in

$$
\delta g(\varphi, \lambda)=\sum_{n=0}^{\infty} \delta g_{n}(\varphi, \lambda) \quad \text { and } \quad t(\varphi, \lambda)=\sum_{n=0}^{\infty} t_{n}(\varphi, \lambda) .
$$

## 3. Compatibility

The solution $T$ is harmonic in $\Omega$. However, the continuation of $T$ for $r>R_{e}$ need not be regular at infinity, i.e., if analytically extended, then for $r \rightarrow \infty$ it does not decrease as $c / r$ ( $c$ is a constant) or faster.

This is a consequence of errors in data.

- The data given for $r=R_{i}$ are enough to determine a harmonic function in $\Omega_{\text {ext }} \equiv\left\{\boldsymbol{x} \in \boldsymbol{R}^{3} ; r>R_{i}\right\}$ and thus in $\Omega \subset \Omega_{\text {ext }}$.
- The data for $r=R_{e}$ have the nature of excess data and give rise to the ("internal") term $\left(r / R_{e}\right)^{n} T_{n}^{(e)}$ not regular at infinity.

Thus

$$
T=T^{(i)}+T^{(e)}, \quad T^{(i)}=\sum_{n=0}^{\infty}\left(\frac{R_{i}}{r}\right)^{n+1} T_{n}^{(i)}, \quad T^{(e)}=\sum_{n=0}^{\infty}\left(\frac{r}{R_{e}}\right)^{n} T_{n}^{(e)}
$$

is a general solution in the domain $\Omega$, but from the physical point of view its justification rests on a formal basis.

Nevertheless the term $T^{(e)}$ gives a possibility to confront the two data sources considered. To see an example suppose that,

$$
\begin{equation*}
T^{(E G M)}=\sum_{n=0}^{\infty}\left(\frac{R_{i}}{r}\right)^{n+1} T_{n}^{(E G M)}(\varphi, \lambda) \tag{9}
\end{equation*}
$$

and

$$
\begin{equation*}
T^{(G O C)}=\sum_{n=0}^{\infty}\left(\frac{R_{i}}{r}\right)^{n+1} T_{n}^{(G O C)}(\varphi, \lambda) \tag{9b}
\end{equation*}
$$

are the disturbing potentials related to the EGM2008 and to a GOCE based satellite-only model, respectively.

Subsequently, we can simulate the input surface spherical harmonics $\delta g_{n}$ and $t_{n}$ in the following way

$$
\delta g_{n}=\frac{n+1}{R_{i}} T_{n}^{(E G M)} \quad \text { and } \quad t_{n}=q^{n+1} T_{n}^{(G O C)}
$$

Hence from Eq. (4b) we get that

$$
T_{n}^{(e)}=c_{n}\left[T_{n}^{(G O C)}-T_{n}^{(E G M)}\right] \quad \text { with } \quad c_{n}=\frac{(n+1) q^{n+1}}{n\left(1+q^{2 n+1}\right)+1}
$$

and the coefficient $c_{n}$ is illustrated in the following Fig. 1

Figure 1.


A better insight offers a plot of degree variances $\operatorname{var}\left\{T_{n}^{(e)}\right\}$. Recall, therefore, that

$$
\begin{aligned}
& T_{n}^{(E G M)}(\varphi, \lambda)=\sum_{m=0}^{n}\left[\delta \bar{C}_{n m}^{(E G N)} \cos m \lambda+\delta \bar{S}_{n m}^{(E G N)} \sin m \lambda\right] \bar{P}_{n m}(\sin \varphi) \\
& \text { and }
\end{aligned}
$$

$$
T_{n}^{(G O C)}(\varphi, \lambda)=\sum_{m=0}^{n}\left[\delta \bar{C}_{n m}^{(G O C)} \cos m \lambda+\delta \bar{S}_{n m}^{(G O C)} \sin m \lambda\right] \bar{P}_{n m}(\sin \varphi)
$$

where, $\delta \bar{C}_{n m}^{(E G N)}, \delta \bar{S}_{n m}^{(E G N)}$ and $\delta \mathcal{C}_{n m}^{(G O C)}, \delta \bar{S}_{n m}^{(G O C)}$ are coefficients of fully normalized surface spherical harmonics. Hence

$$
\begin{gathered}
\operatorname{var}\left\{T_{n}^{(e)}\right\}=M\left\{\left[T_{n}^{(e)}\right]^{2}\right\}= \\
=\left[c_{n}\right]^{2} \sum_{m=0}^{n}\left\{\left[\delta \bar{C}_{n m}^{(G O C)}-\delta \bar{C}_{n m}^{(E G M)}\right]^{2}+\left[\delta \bar{S}_{n m}^{(G O C)}-\delta \bar{S}_{n m}^{(E G M)}\right]^{2}\right\}
\end{gathered}
$$

Here $M$ stands for the average over the whole unit sphere.

Figure 2. Two parts of this figure now show:
(Left) the diagram of $\sqrt{\operatorname{var}\left\{T_{n}^{(e)}\right\}}=\left|c_{n}\right| \sqrt{\operatorname{var}\left\{T_{n}^{(G O C)}-T_{n}^{(E G M)}\right\}}$ (Right) the diagram of $\sqrt{\operatorname{var}\left\{T_{n}^{(G O C)}-T_{n}^{(E G M)}\right\}}$ - for comparison computed for 3 subsequent GOCE gravity field solutions (TIM)



> We also add a global charts of $T^{(e)}$ and of $T^{(G O C)}-T^{(E G M)}$ for gravimetry (EGM 2008) and GO_CONS_GCF_2_TIM_R5 model.


Figure 3a. $T^{(e)}$ for $r=R_{i}$

Figure 3b. $T^{(e)}$ for $r=R_{e}$.


Figure 4a.
$T^{(G O C)}-T^{(E G M)}$ for $r=R_{i}$
Here the scale is 75 times as large.

Figure 4b.

$$
T^{(G O C)}-T^{(E G M)} \text { for } r=R_{e} .
$$



## 4. Optimization

In solving the incompatibility (overdetermined problem) above, we will look for a harmonic function $f$, regular at infinity that minimizes the functional

$$
\Phi(f)=\int_{\Omega}(f-T)^{2} d x
$$

We suppose that $f \in H_{2}\left(\Omega_{\text {ext }}\right)$, where $H_{2}\left(\Omega_{\text {ext }}\right)$ is a space of harmonic functions with inner product

$$
(f, g) \equiv \int_{\Omega_{\text {ett }}} \frac{1}{r^{2}} f g d x
$$

The functional $\Phi$ attains its minimum in $H_{2}\left(\Omega_{\text {ext }}\right)$. Hence, assuming $\Phi$ has its minimum at a point $f \in H_{2}\left(\Omega_{\text {ext }}\right)$, its Gâteaux' differentials equals zero at $f$. This yields

$$
\begin{equation*}
\int_{\Omega} f v d x=\int_{\Omega} T v d x \tag{18}
\end{equation*}
$$

for all $v \in H_{2}\left(\Omega_{\text {ext }}\right)$.

Eq. (18) represents Euler's necessary condition for $\Phi$ to have a minimum at $f$. It is a starting point for obtaining the function $f$.

We put $v_{n m}=\left(R_{i} / r\right)^{n+1} Y_{n m}(\varphi, \lambda)$, denoting by $Y_{n m}$ Laplace' surface spherical harmonics.

Subsequently, $f=\Sigma_{n=0}^{\infty} \Sigma_{m=-n}^{m=n} f_{n m} v_{n m}$, while $f_{n m}$ are scalar coefficients. After some algebra we easily obtain

$$
f=\sum_{n=0}^{\infty}\left(\frac{R_{i}}{r}\right)^{n+1}\left[T_{n}^{(i)}+\alpha_{n} T_{n}^{(e)}\right] \text { with } \quad \alpha_{n}=\frac{(2 n-1)\left(1-q^{2}\right)}{2\left(1-q^{2 n-1}\right)} q^{n-2}
$$



Figure 5. Values of $\alpha_{n}$ for

$$
R_{i}=6378,136 \mathrm{~km}
$$

and

$$
R_{e}=R_{i}+224 \mathrm{~km}
$$

i.e., for

$$
q=0.966071588
$$

The optimized solution $f$ is partially generated by $T_{n}^{(e)}$, but in contrast to the original Eq. (3), i.e., $T=T^{(i)}+T^{(e)}$ the influence of $T_{n}^{(e)}$ is now attenuated by the factor $\alpha_{n}$.

This is illustrated for GO_CONS_GCF_2_TIM_R5 model in Fig. 6.


Figure 6


Figure 2 - for comparison

## 5. Optimized Solution - Influence of Input Data

To see the influence of the input data $\delta g$ and $t$ on the optimized solution $f$ we have to return to the original structure of the harmonics $T_{n}^{(i)}$ and $T_{n}^{(e)}$.

Therefore, we insert from Eqs (4a) and (4b) and subsequently obtain

$$
\begin{equation*}
f=\sum_{n=0}^{\infty}\left(\frac{R_{i}}{r}\right)^{n+1}\left[A_{n}^{(i)} \frac{R_{i}}{n+1} \delta g_{n}+A_{n}^{(e)} t_{n}\right] \tag{20}
\end{equation*}
$$

with

$$
\begin{equation*}
A_{n}^{(i)}=\frac{(n+1)\left(1-\alpha_{n} q^{n+1}\right)}{D_{n}} \quad \text { and } \quad A_{n}^{(e)}=\frac{n q^{n}+\alpha_{n}(n+1)}{D_{n}} \tag{21}
\end{equation*}
$$

where

$$
D_{n}=n\left(1+q^{2 n+1}\right)+1
$$

The values of $A_{n}^{(i)}$ and $A_{n}^{(e)}$ are in Fig. 7 that follows.


Figure 7. The coefficients $A_{n}^{(i)}$ and $A_{n}^{(e)}$ for $q=0.966071588$ (i.e. $R_{e}=R_{i}+224 \mathrm{~km}$ ) in case that gravity disturbances $\delta g$ are combined with $t$ representing the input from a satellite-only model.

## 4. Optimization in $H_{2}^{(1)}$ - Energetic Concept

Let $H_{2}^{(1)}\left(\Omega_{\text {ext }}\right)$ be the space of harmonic functions on $\Omega_{\text {ext }}$ which is equipped with inner product

$$
(f, g)_{1}=\int_{\Omega_{e t t}}\langle\boldsymbol{g r a d} f, \operatorname{grad} g\rangle d x
$$

where $\langle.,$.$\rangle is the scalar product of two vectors in R^{3}$. We look for a function $f \in H_{2}^{(1)}\left(\Omega_{\text {ext }}\right)$ that minimizes the functional

$$
\Psi(f)=\int_{\Omega}|\operatorname{grad}(f-T)|^{2} d x
$$

Similarly as above the functional $\Psi$ attains its minimum in $H_{2}^{(1)}\left(\Omega_{\text {ext }}\right)$ and $f$ is defined by the integral identity

$$
\int_{\Omega}\langle\boldsymbol{g r a d} f, \boldsymbol{\operatorname { g r a d }} v\rangle d \boldsymbol{x}=\int_{\Omega}\langle\boldsymbol{\operatorname { g r a d }} T, \boldsymbol{\operatorname { g r a d }} v\rangle d \boldsymbol{x}
$$

which holds for all $v \in H_{2}^{(1)}\left(\Omega_{e x t}\right)$.

Interpreting the identity in terms of our function basis, we again write $f=\Sigma_{n=0}^{\infty} \Sigma_{m=-n}^{m=n} f_{n m} \nu_{n m}$, but now we arrive at

$$
f=\sum_{n=0}^{\infty}\left(\frac{R_{i}}{r}\right)^{n+1} T_{n}^{(i)}
$$

which is considerably more simple. Subsequently we obtain

$$
f=\sum_{n=0}^{\infty}\left(\frac{R_{i}}{r}\right)^{n+1}\left[A_{n}^{(i)} \frac{R_{i}}{n+1} \delta g_{n}+A_{n}^{(e)} t_{n}\right]
$$

with

$$
A_{n}^{(i)}=\frac{n+1}{D_{n}} \quad \text { and } \quad A_{n}^{(e)}=\frac{n q^{n}}{D_{n}}
$$

where

$$
D_{n}=n\left(1+q^{2 n+1}\right)+1
$$

The values of $A_{n}^{(i)}$ and $A_{n}^{(e)}$ are in Fig. 8 that follows.



Figure 8. The coefficients $A_{n}^{(i)}$ and $A_{n}^{(e)}$ for $R_{e}=R_{i}+224 \mathrm{~km}$ in case that gravity disturbances $\delta g$ are combined with $t$ representing the input from a satellite-only model and (Left) an energetic norm is applied in the optimization concept.

## 6. Terrestrial Term and the Integral Kernel

Recall that we obtained the following result - optimized solution:

$$
f=\sum_{n=0}^{\infty}\left(\frac{R_{i}}{r}\right)^{n+1}\left[A_{n}^{(i)} \frac{R_{i}}{n+1} \delta g_{n}+A_{n}^{(e)} t_{n}\right]
$$

Our aim is to find an integral representation for

$$
f_{\text {terr }}=\sum_{n=0}^{\infty}\left(\frac{R_{i}}{r}\right)^{n+1} A_{n}^{(i)} \frac{R_{i}}{n+1} \delta g_{n}, \quad A_{n}^{(i)}=\frac{(n+1)\left(1-\alpha_{n} q^{n+1}\right)}{n\left(1+q^{2 n+1}\right)+1}
$$

which is the terrestrial term in the structure of the optimized solution. We get

$$
f_{\text {terr }}=\frac{R_{i}}{4 \pi} \int_{\sigma} K^{*}(r, \psi) \delta g d \sigma
$$

with

$$
K^{*}(r, \psi)=\sum_{n=0}^{\infty} A_{n}^{(i)} \frac{2 n+1}{n+1}\left(\frac{R_{i}}{r}\right)^{n+1} P_{n}(\cos \psi)
$$

Of course, we are interested in a closed form of the kernel

$$
K^{*}(r, \psi)=\sum_{n=0}^{\infty} A_{n}^{(i)} \frac{2 n+1}{n+1}\left(\frac{R_{i}}{r}\right)^{n+1} P_{n}(\cos \psi)
$$

Here we confine ourselves just to an illustration showing how the kernel $K^{*}(r, \psi)$ depends on the angle $\psi$ in case that $r=R_{i}$. The dependence is shown in the two figures below.



The kernel was used practically. The dominant part of the terrestrial term $f_{\text {terr }}$ (with respect to EGM2008) was computed for data from the territory of the Czech Republic and it is plotted in the following figure.


## The composition of

$$
f_{\text {sat }}=\sum_{n=0}^{\infty}\left(\frac{R_{i}}{r}\right)^{n+1} A_{n}^{(e)} t_{n}
$$

and

$$
f_{\text {terr }}=\sum_{n=0}^{\infty}\left(\frac{R_{i}}{r}\right)^{n+1} A_{n}^{(i)} \frac{R_{i}}{n+1} \delta g_{n}
$$

is then here.

$$
f=f_{t e r r}+f_{\text {sat }}
$$



## Thank you for your attention !

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