

MEETC2 : Bayesian & multiscale analysis atmospheric corrections for the sentinels 2&3



coastal tep | GeoBrowser

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Please test yourself the MEETC2 algorithm:
<https://www.coastal-tep.eu/geobrowser/>

esa
European Space Agency

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- ❖ *Saulquin B. et al. Multi-scales atmospheric corrections for the Sentinels 2, In writing process.*



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MEETC2: Ocean color atmospheric corrections in coastal complex waters using a Bayesian latent class model and potential for the incoming sentinel 3 — OLCI mission

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MeetC2 = Meet case 2 waters

➤ **Targeted long term improvement**

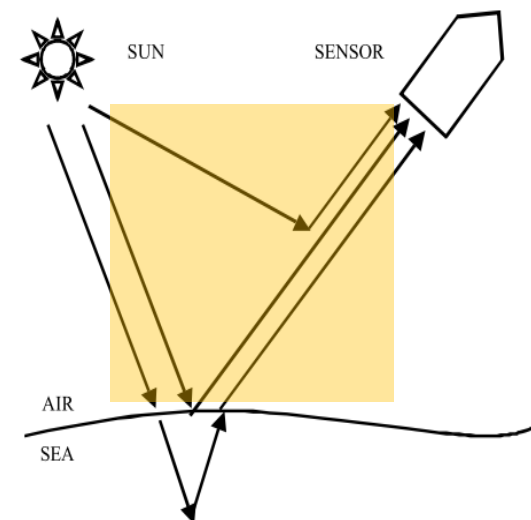
❖ **Major improvements in atmospheric corrections will lead to the end of the historical case 1 / case 2 issues in oceanography including tens of regional algorithms and the corresponding nightmare for end users.**

Opportunities: improve the atmospheric corrections with the introduction of spatial / temporal information

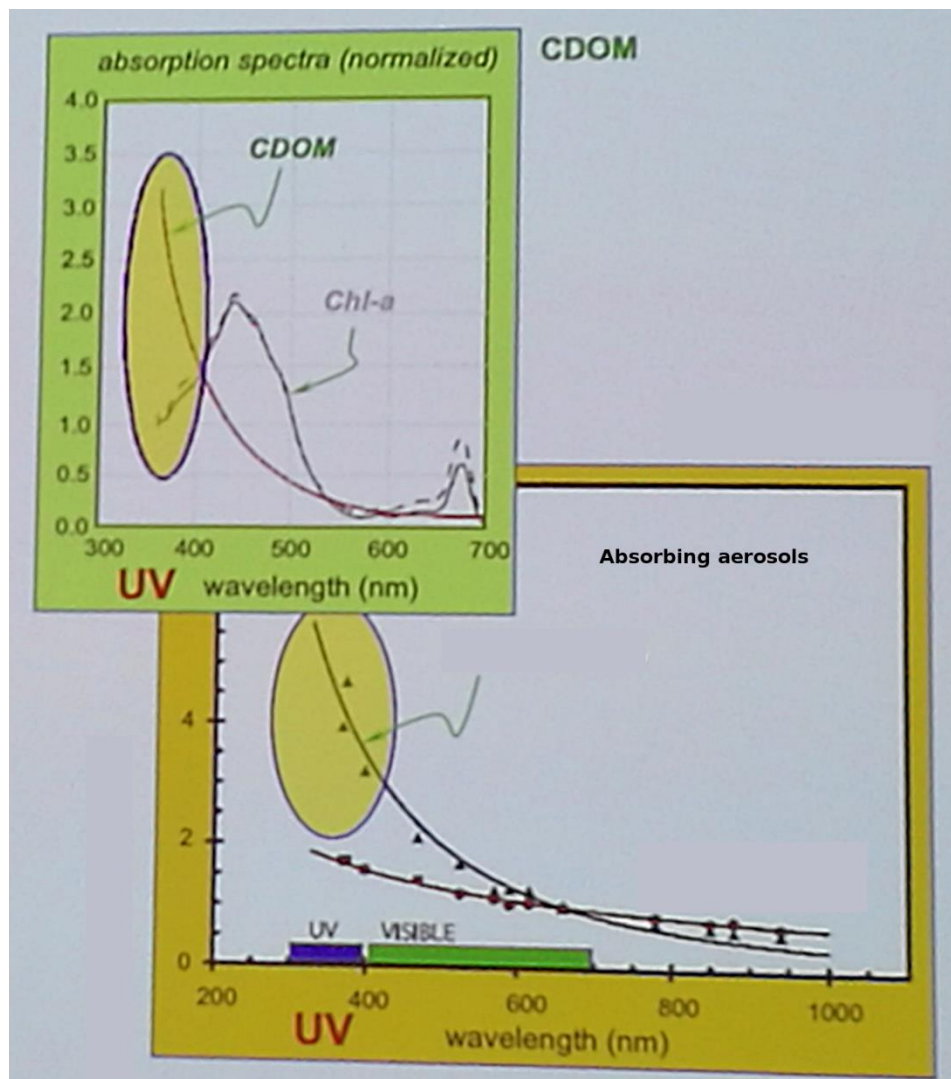
$$\underbrace{\rho_w(\lambda)}_{\text{HR}} = \underbrace{[\rho_{TOA}(\lambda)]}_{\text{HR}} / \underbrace{T_g(\lambda)}_{\text{LR}} - \underbrace{\rho_{path}(\lambda)}_{\text{LR}} - \underbrace{t_{up}(\lambda)t_{down}(\lambda)}_{\text{LR}} \underbrace{\rho_{glint}(\lambda)}_{\text{HR}} / \underbrace{T_{up}(\lambda)T_{down}(\lambda)}_{\text{LR}}$$

Signal	Coastal areas	Open waters
$T_g(\lambda)$	10 to 30 kms*	> 100km*
$\rho_{path}(\lambda)$	10 to 30 kms	> 100km
$T_{up}(\lambda)T_{down}(\lambda)$	10 to 30 kms	> 100km
$\rho_w(\lambda)$	Few meters	> 10km
$t_{up}(\lambda)t_{down}(\lambda) \rho_{glint}(\lambda)$	Few meters	Few meters

*Seinfeld, J. H., & Pandis, S. N. (2016)



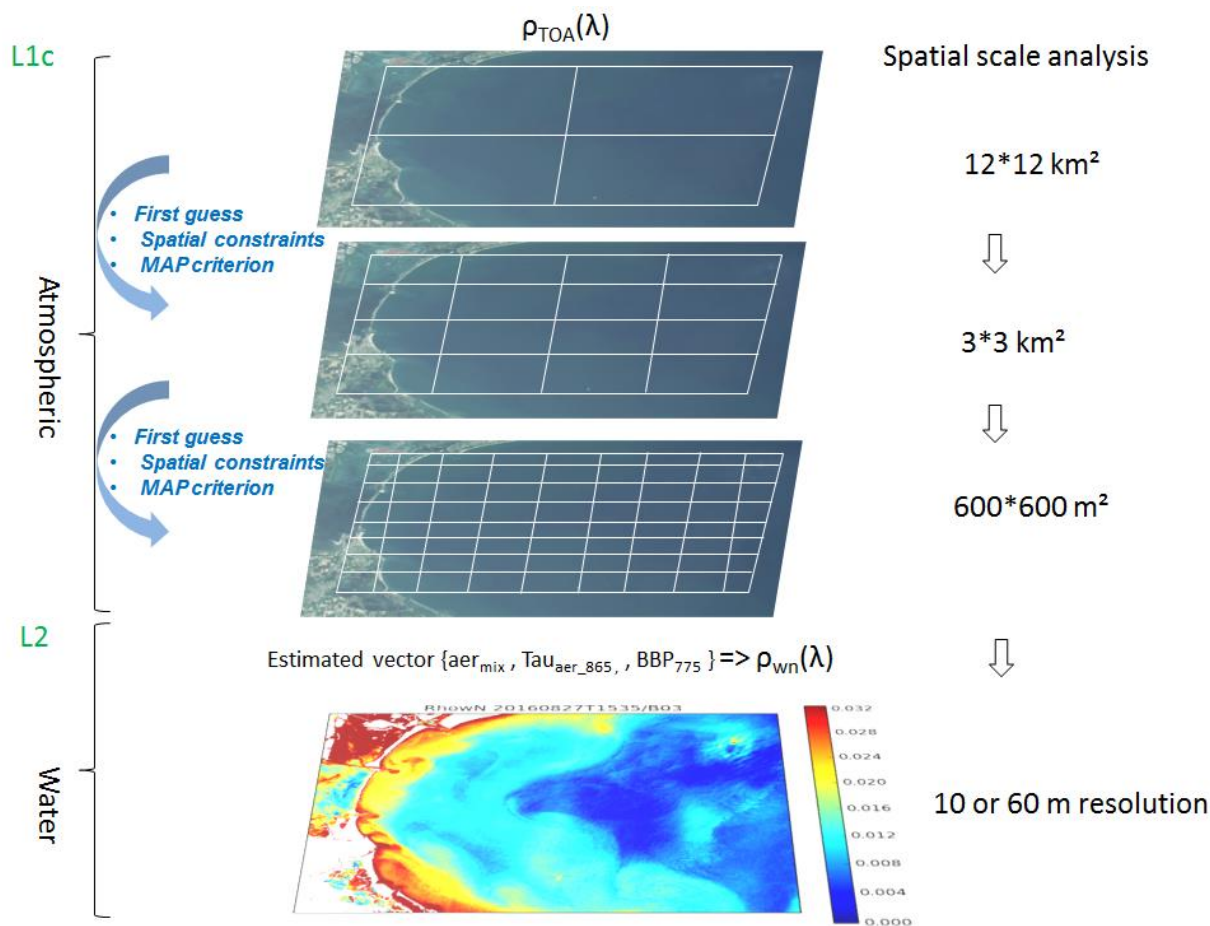
The spatial continuity of the aerosols is an information as the spectral signature



Spectral approach is not always deterministic

Need of:

- External variables (assimilation...)
- Change your inversion scheme to include e.g temporal or spatial information



Our cost function (expressed here using bayesian notation):

$$P(V_a, V_w | \rho_{TOA}) \propto P(\rho_{TOA} | V_a, V_w) \cdot P(V_a, V_w) \cdot P(\nabla V_{a,i,i+1})$$

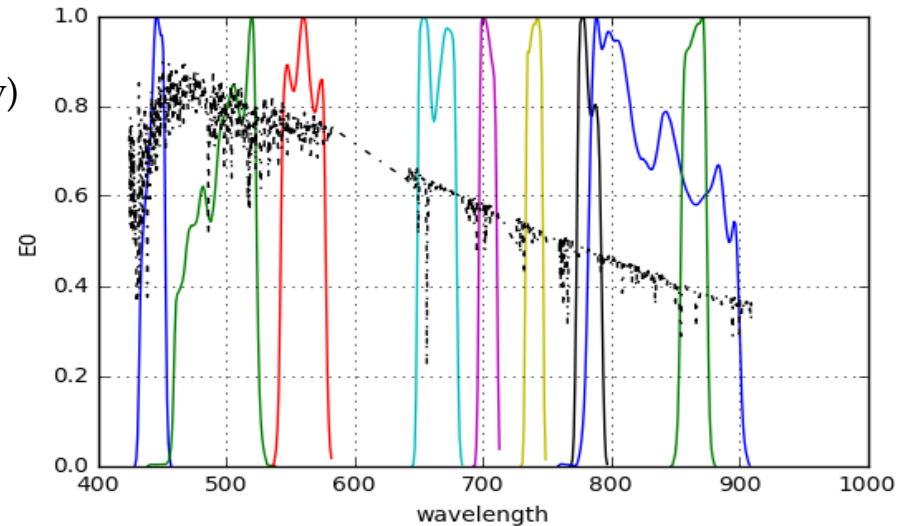
Spatial and/or
Temporal term

Residuals of the observation
model

A priori onto parameters

6 precomputed LUTs from **Smart-g or OSOAA coupled water + atmosphere RTMs** (integration using reptran & the S2 spectral response):

- $Td_{\text{gaz}}(\lambda, \theta, O_3)$
- $Rho_{\text{path}}(\lambda, WV, P_0, \theta_s, \text{aer_type}, \tau_{\text{aer_865}}, \Delta\varphi, \theta_v)$
- $Td_{\text{diff}}(\lambda, WV, P_0, \theta_s, \text{aer_type}, \tau_{\text{aer_865}}, \Delta\varphi, \theta_v)$
- $TD_{\text{direct}}(\lambda, WV, P_0, \theta_s, \text{aer_type}, \tau_{\text{aer_865}})$
- $Rho_{\text{glint}}(\lambda, \theta_s, WS, \Delta\varphi, \theta_v)$
- $Rho_{\text{water}}(\lambda, \theta_s, WS, \text{bbp_775}, \Delta\varphi, \theta_v)$



Reptran & S2A spectral response

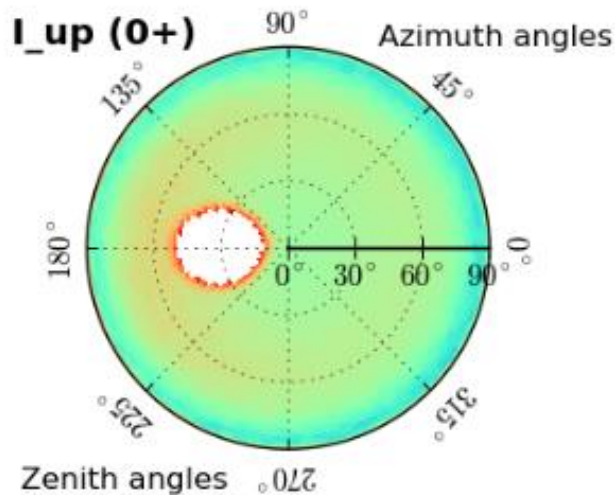
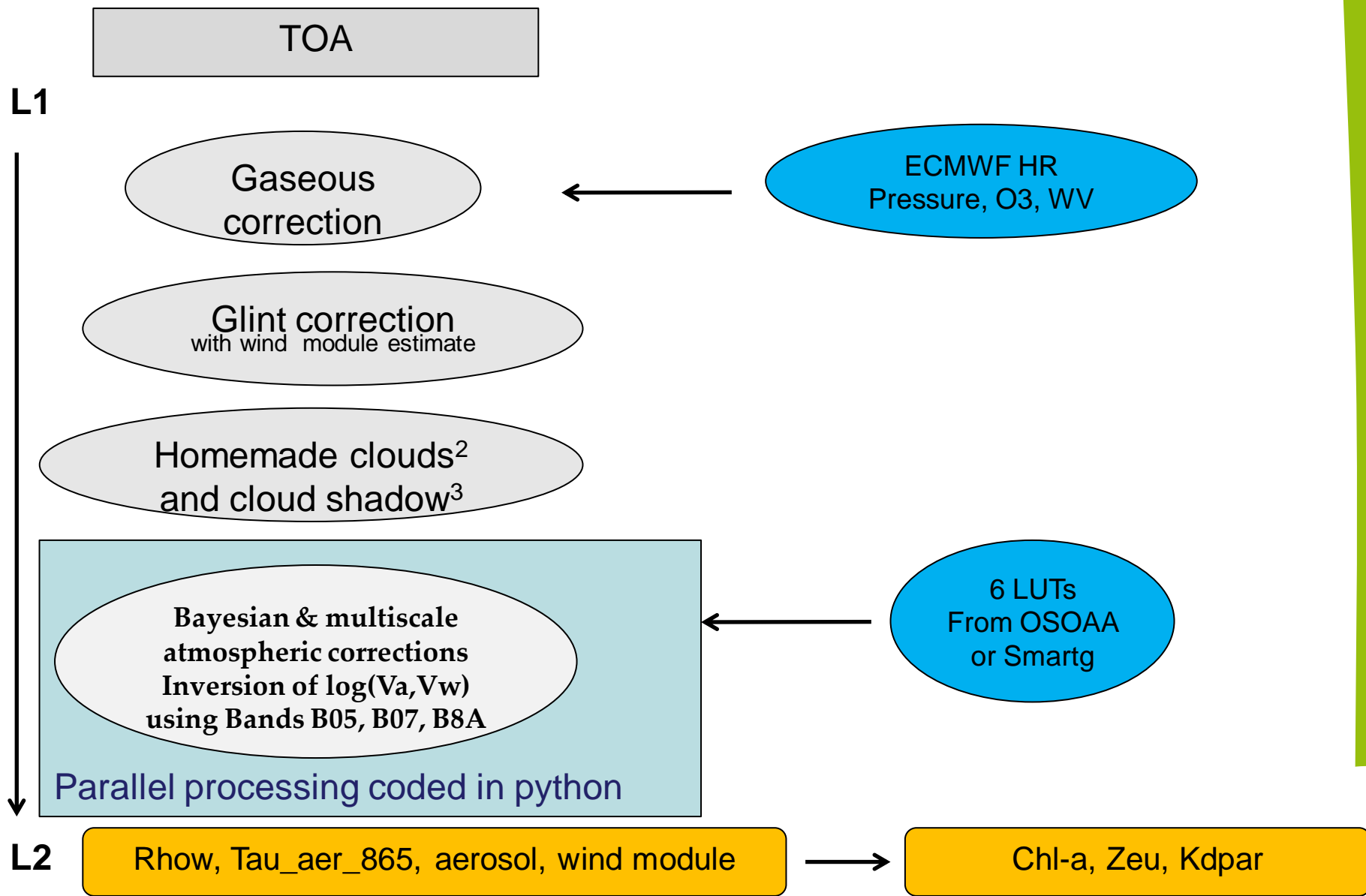


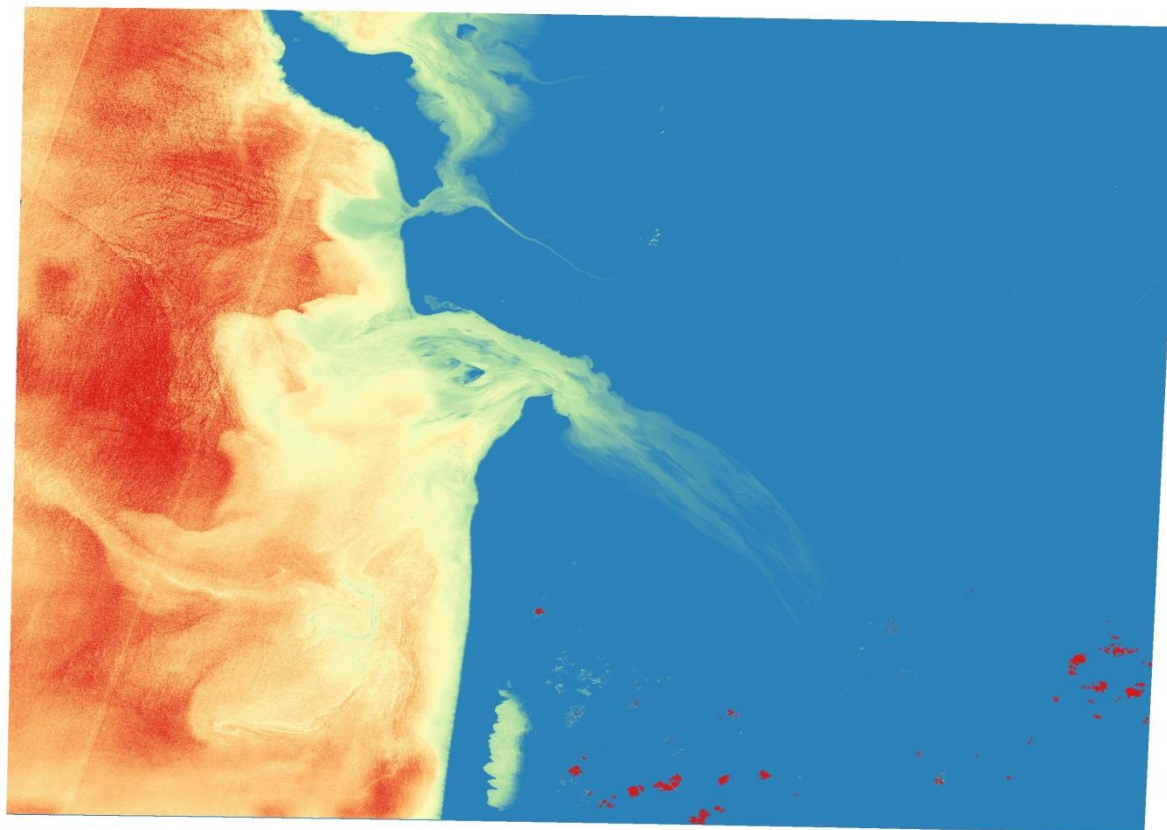
Figure: Example of Rho_w simulation using **Smart-G*** ($\text{bbp_775}=0.1, \theta_s=30^\circ$)

A dedicated water model derived from hydrolight simulations

MeetC2 functional scheme



- Normalised water reflectances + **total uncertainty per pixel**
- Chl-a
- Euphotic depth
- RGB L1
- RGB L2
- Cloud mask.



Légende

zeu_20180822T132540

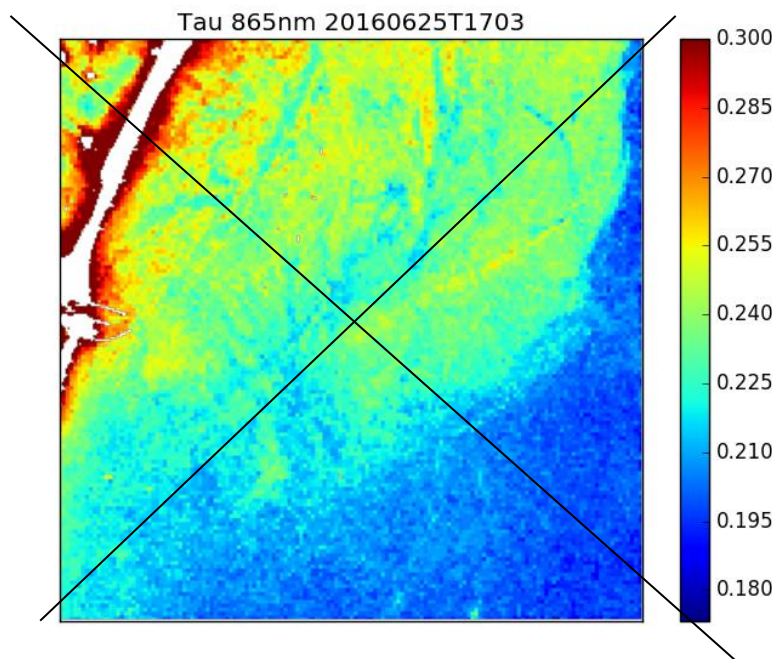
2.602690
4.161122
5.719554
7.277986
8.836418
10.394851
11.953283
13.511715
15.070147
16.628579
18.187011
19.745443
21.303875
22.862307
24.420739
25.979172
27.537604
29.096036
30.654468
32.212900

➤ **Methodological improvements in the inversion lead to:**

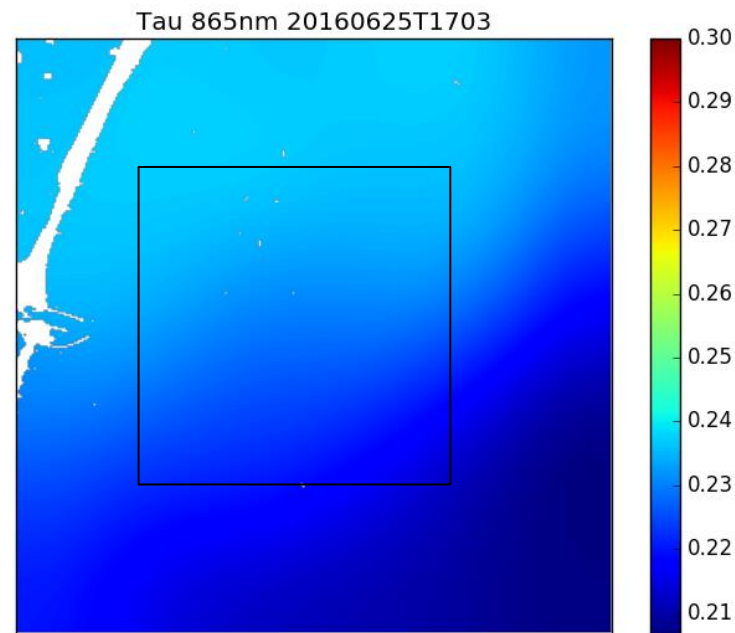
- ❖ Increase the unmixing capability of the algorithm for the atmospheric corrections:
The shape of the aerosol and water reflectance spectra are similar in coastal areas and infrared regions leading to inversion issues. The inclusion of constraints onto the gradients of the atmospheric variables help to unmix the two contributions compared to a single pixel approach.
- ❖ Reduce uncertainties onto the estimates: Case of a non linear minimisation $\widehat{V_a}, \widehat{V_w} = \operatorname{argmin}(\widehat{\rho_{TOA}} - \rho_{TOA})$.
- ❖ Increase the speed of the processing : you do not need to do an inversion pixel by pixel

Single approach vs multi-pixels approaches

← 1,8 km → **Tau_aer_865**



Single pixel inversion



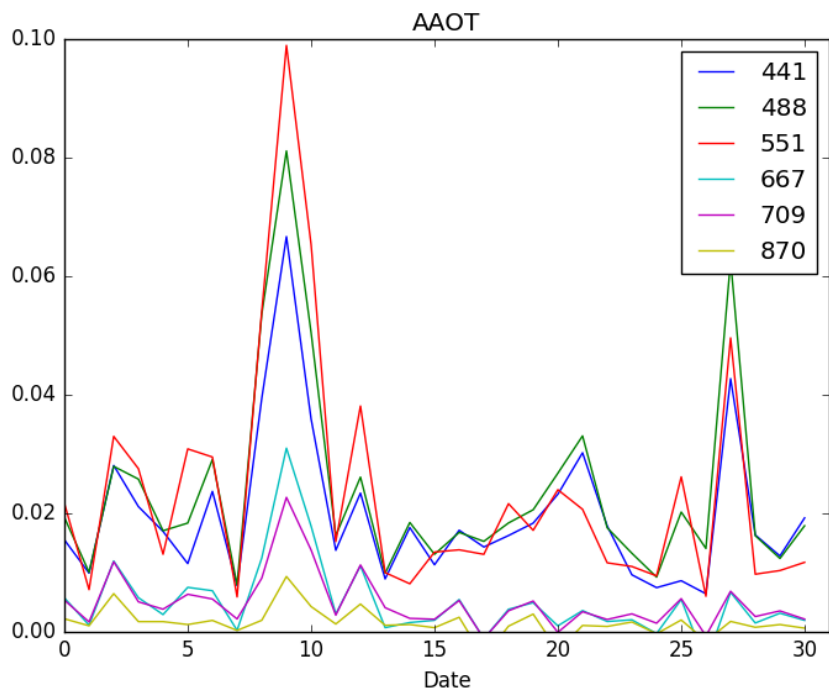
Multi-pixels inversion

Signature of sediments onto the retrieved AOT=> need to introduce spatial regularisation terms onto the atmospheric parameters

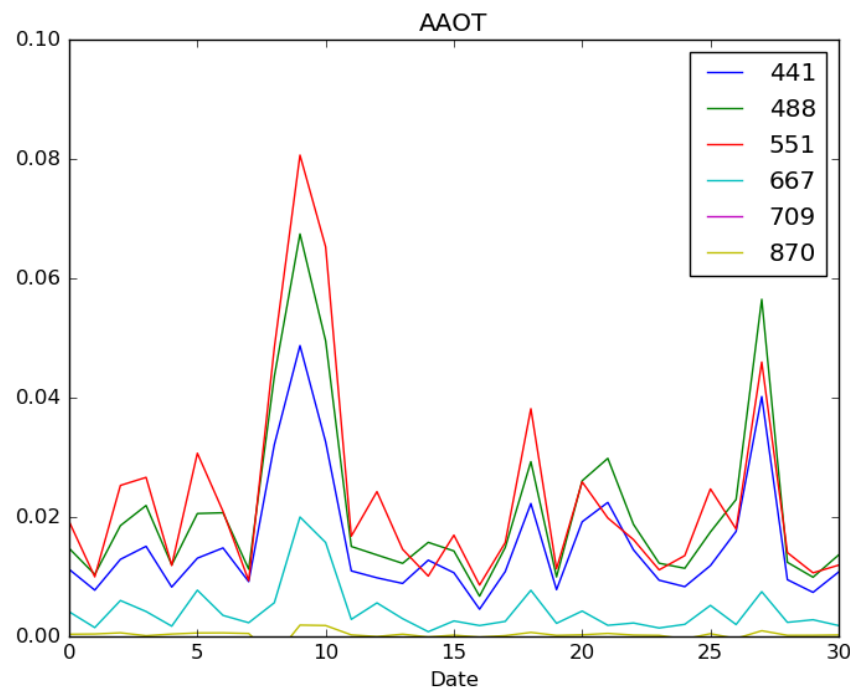
Venice laguna

Temperate Site: Venice [Italy]

- A proposition to integrate the ACIX Intercomparaison exercise



Satellite

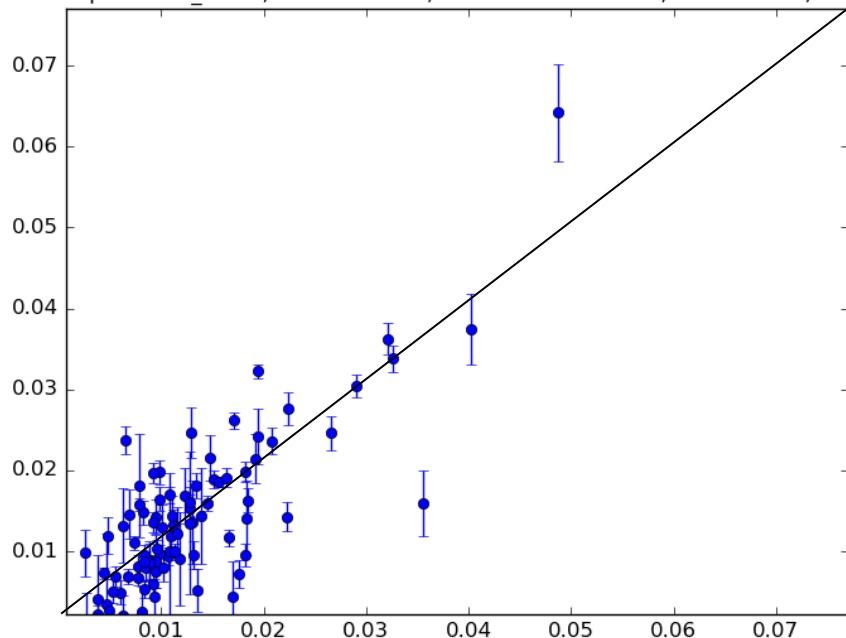


In-situ



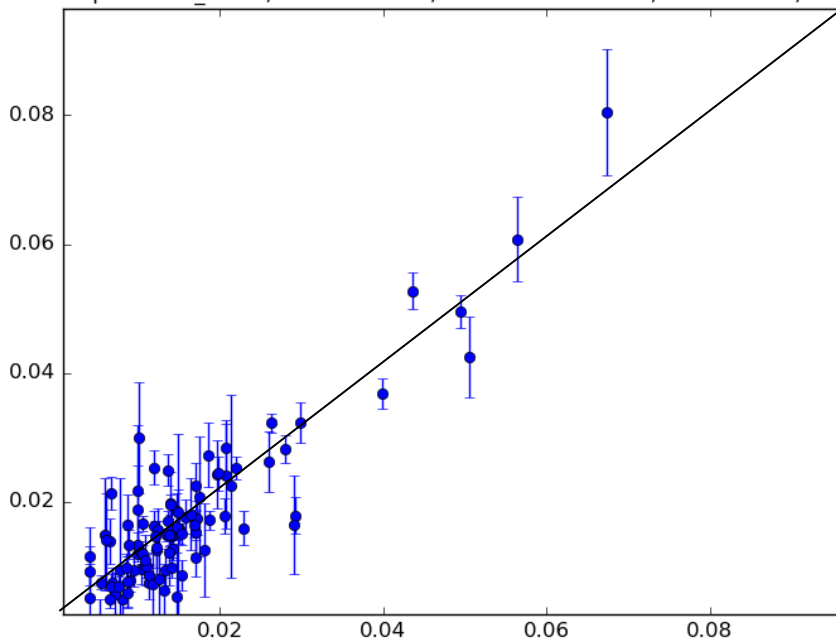
Scatterplots, all sites: rhown estimated using S2A&B

matchups Rhown_443.0;nb match= 97 ; median bias=0.0007; std=0.0029 ;r2 =0.64



443

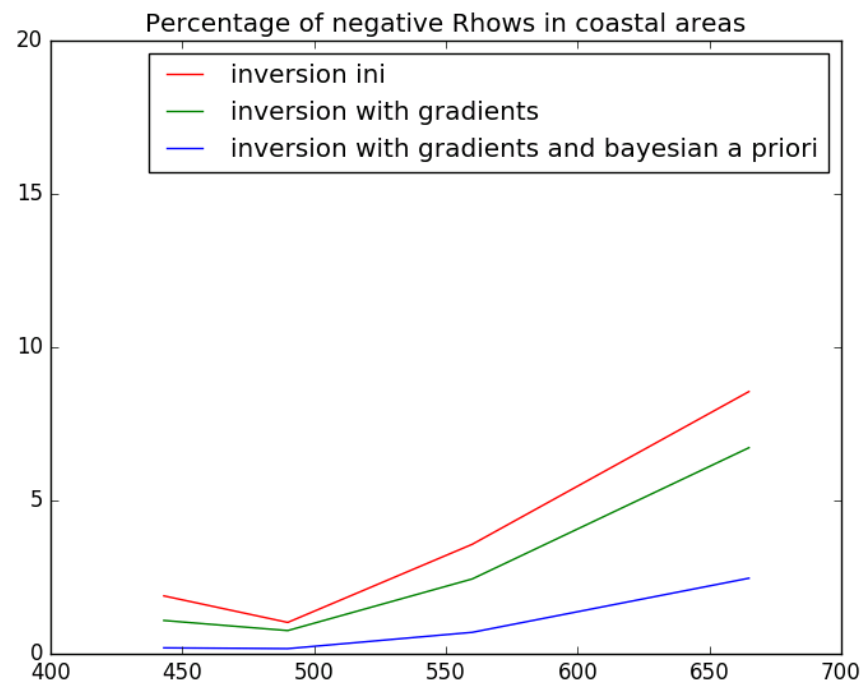
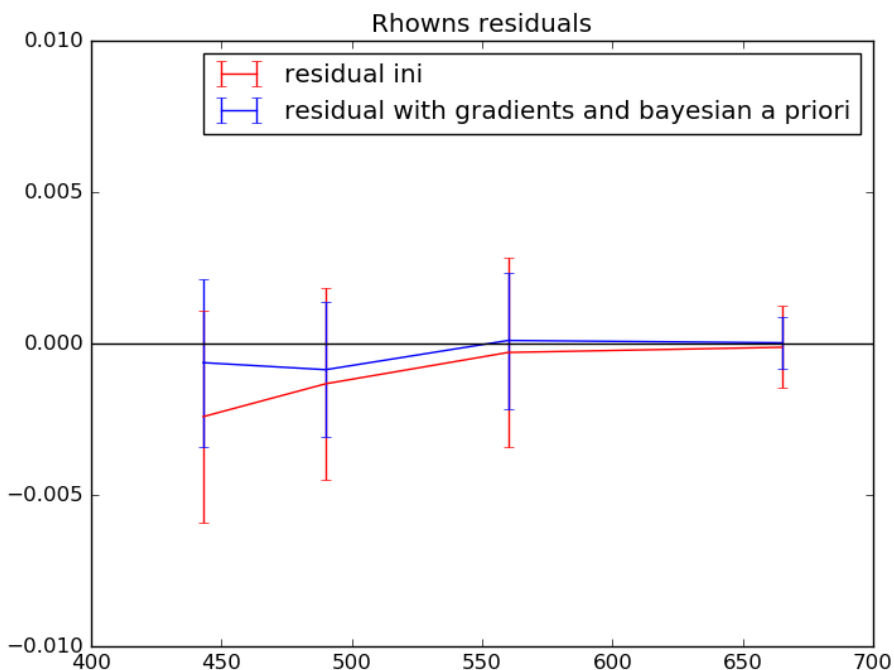
matchups Rhown_490.0;nb match= 97 ; median bias=0.001; std=0.0027 ;r2 =0.79



490



$$P(V_a, V_w | \rho_{gc}) \propto P(\rho_{gc} | V_a, V_w) \cdot P(V_a, V_w) \cdot P(\nabla V_{a_{i,i+1}})$$



➤ Less bias and decrease of the uncertainties onto the Rhows

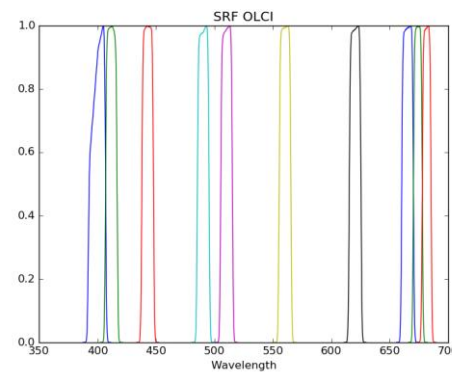
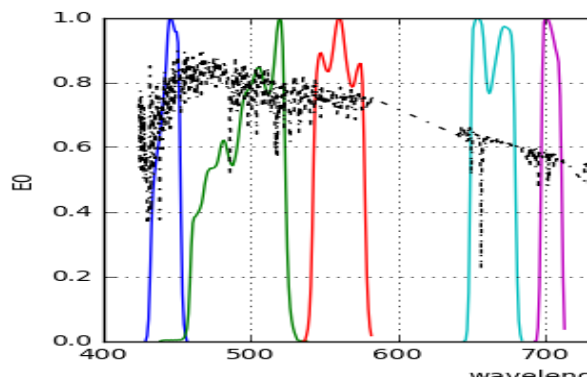
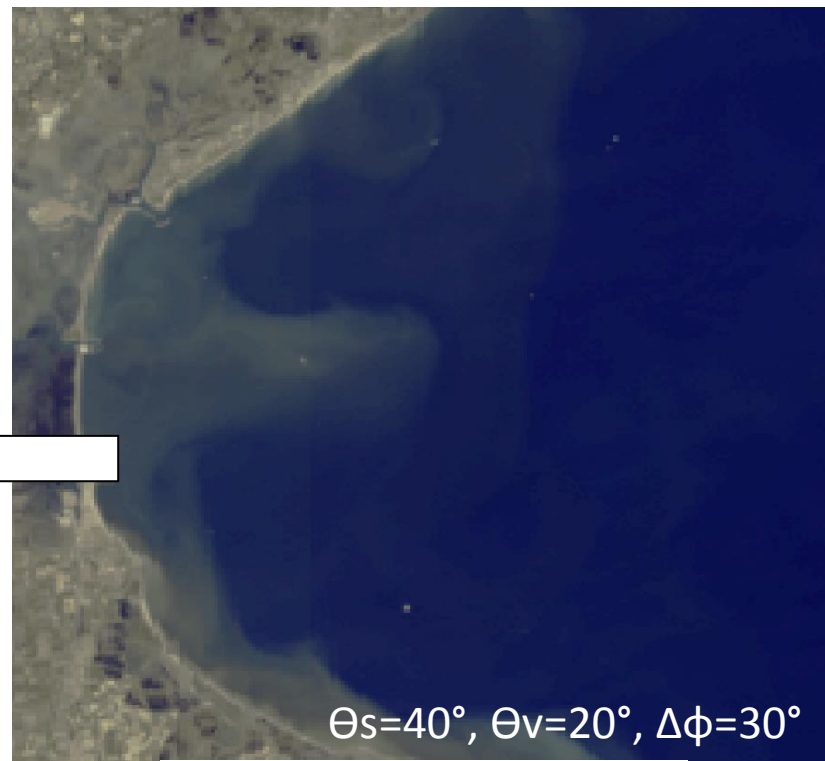
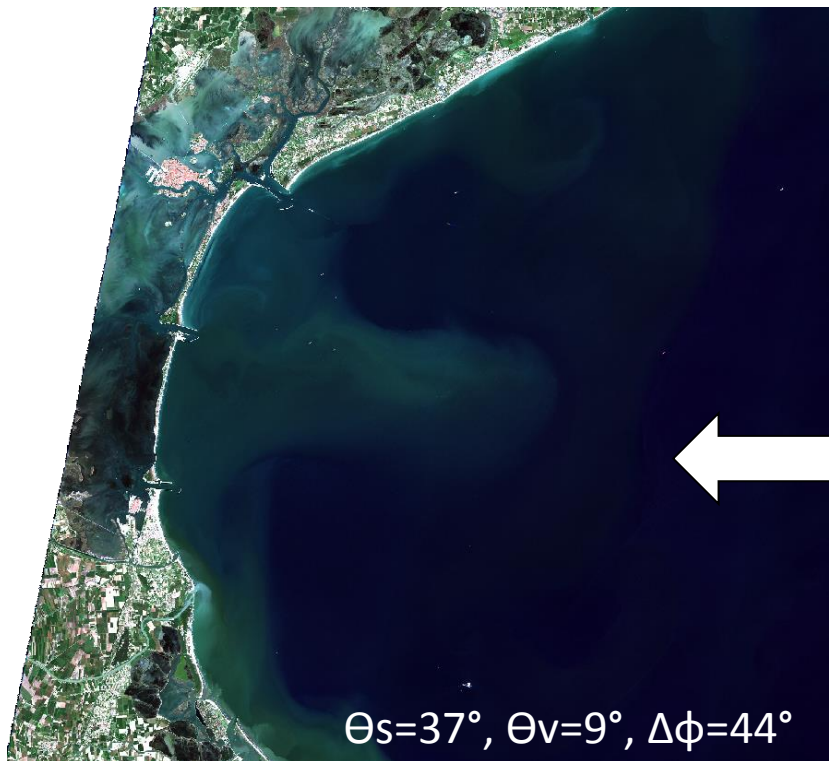
➤ Less negative reflectances = optimisation of the L2

Comparisons with OLCI OL2

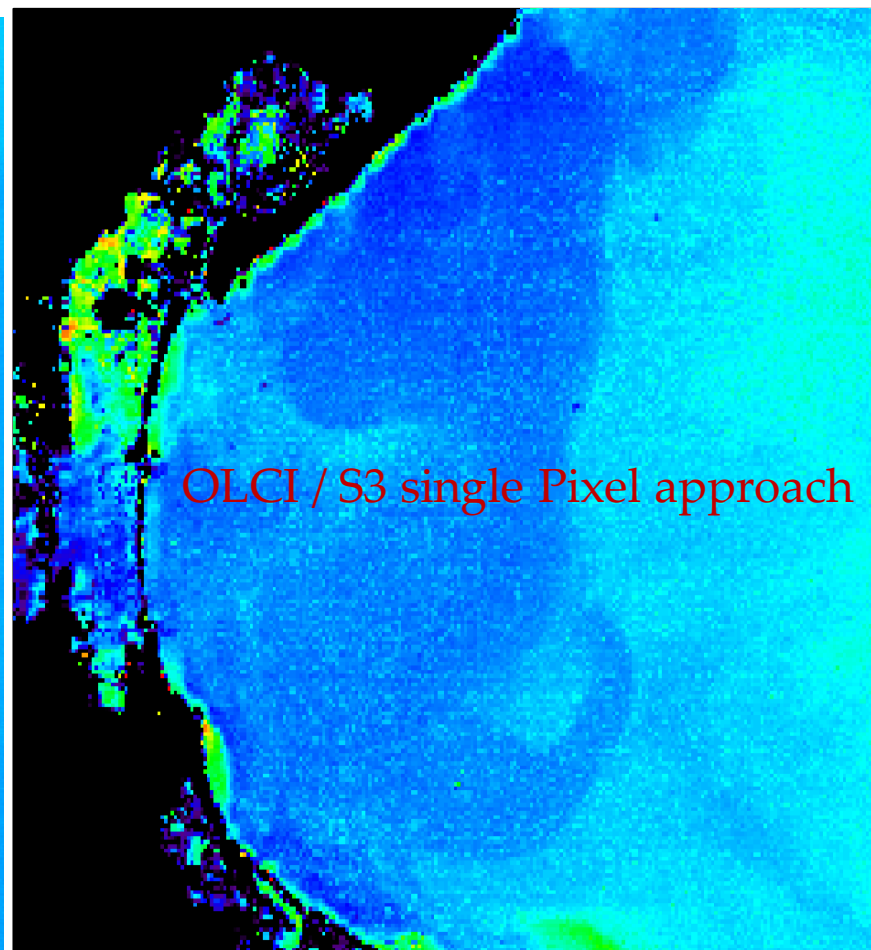
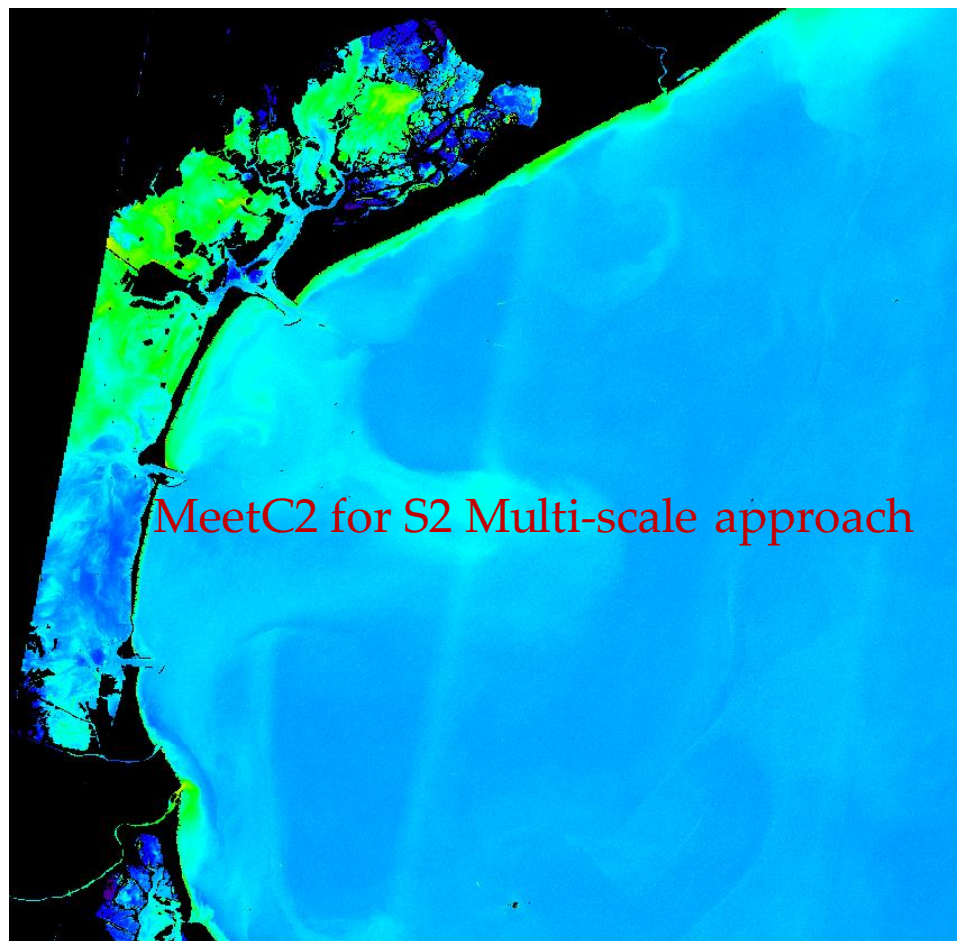
20160824 Venice Laguna (similar geometry of observation)

Level 1 S2 RGB

Level 1 OLCI RGB

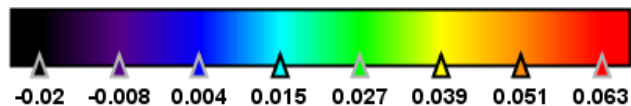


20160824 Venice Laguna

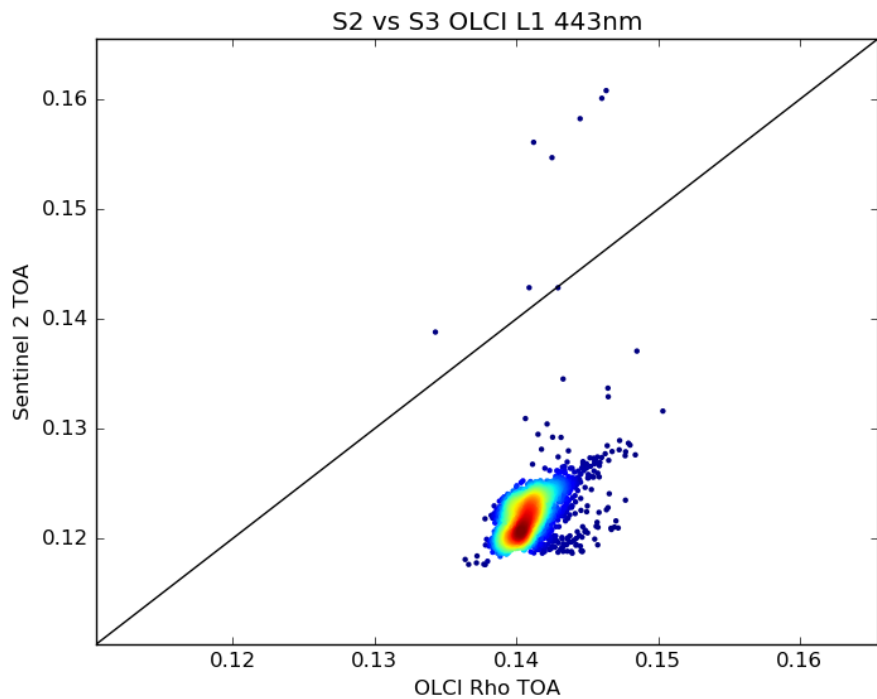


MeetC2 Level 2 S2 Rhown 443 nm

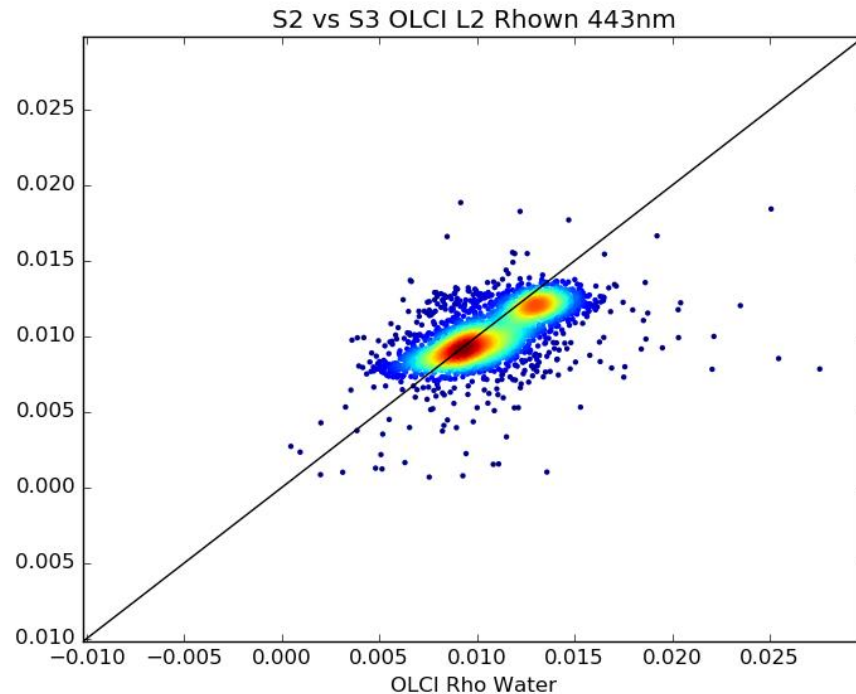
Level 2 443 nm OLCI



20160824 Venice Laguna



L1 ρ TOA OLCI vs S2



L2 ρ_w OLCI vs S2

Without spectral adjustment

- ❖ *Saulquin B. et al. Multi-water & multi-scales atmospheric corrections for the Sentinels 2, In writing process.*
- ❖ *Saulquin, B., Fablet, R., Bourg, L., Mercier, G., & d'Andon, O. F. (2016). MEETC2: Ocean color atmospheric corrections in coastal complex waters using a Bayesian latent class model and potential for the incoming sentinel 3—OLCI mission. Remote Sensing of Environment, 172, 39-49.*
- ❖ *Saulquin, B., Hamdi, A., Gohin, F., Populus, J., Mangin, A., & d'Andon, O. F. (2013). Estimation of the diffuse attenuation coefficient KdPAR using MERIS and application to seabed habitat mapping. Remote Sensing of Environment, 128, 224-233.*
- ❖ *Seinfeld, J. H., & Pandis, S. N. (2016). Atmospheric chemistry and physics: from air pollution to climate change. John Wiley & Sons.*
- ❖ *Ramon, D. et al., 2017 “ Ocean-Atmosphere Polarized Radiative Transfer with the GPU-Accelerated SMART-G*
- ❖ *Monte Carlo Code”, J. Quant. Spec. Rad. TransferChami, M., Lafrance, B., Fougny, B., Chowdhary, J., Harmel, T., & Waquet, F. (2015). OSOAA: a vector radiative transfer model of coupled atmosphere-ocean system for a rough sea surface application to the estimates of the directional variations of the water leaving reflectance to better process multi-angular satellite sensors data over the ocean. Optics express, 23(21), 27829-27852.*

MeetC2 available onto the Coastal TEP Web facility

CTEP GeoBrowser

coastal tep | Geobrowser

Processors

Approved | My Processors | **Other**

- Ecobaw Céline@esa.int
- Altimetry Match-up ctep1@esa.int
- sen3cor ngilles@esa.int
- WQ Spatial Statistics ext. shape Giulio.Ceriola@esa.int
- Meet_C2, v2 of Atmospheric corrections above waters for the Sentinels 2**
- bsaulquin@esa.int
- WQ Temporal Statistics Giulio.Ceriola@esa.int
- WQ Spatial Statistics Giulio.Ceriola@esa.int

Search results | AOIs | Uploaded Files | Processing results | Shared Files | Input Data:

- rhow_B03_20180414T122253_R022_T33TUL_data.tif
- rhow_B05_20180414T122253_R022_T33TUL.tif
- rhow_B02_20180414T122253_R022_T33TUL.tif
- zeu_20180414T122253_R022_T33TUL_data.tif
- rhow_B01_20180414T122253_R022_T33TUL.tif
- zeu_20180414T122253_R022_T33TUL.tif
- S2A_MSIL1C_20180405T103021_I
- L3m_20180101-20180131_GLOB
- S2B_MSIL1C_20180112T144719_I

1: select the good tab

2: the good processor

Please test yourself the MEETC2 algorithm:
<https://www.coastal-tep.eu/geobrowser/>

If it is not clear please contact bertrand.saulquin@acri-st.fr