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Mapping glacial and periglacial environments with optical and radar data

At all latitudes, field research in glacial and periglacial regions encounters limitations in terms of accessibility, expenses and repeatability.

The Reintal in southern Germany and Austfonna on Svalbard are considered here (Fig. 1). Located at similar longitudes, they represent two extremes in terms of (peri-)glacial environments: a high alpine, steep rugged valley versus a smooth ice cap with low optical contrast.

Remote sensing techniques represent a valuable additional dimension for feature monitoring. They operate at global scales

use globally uniform data sets and methods provide long-term, comparable measurement

al, horizontal, total curvatur

data base DEM. ASTER Two independent methods are assessed to handle the gradients involved with respect to topography and climate: *A.* an object-oriented approach for alpine landform detection *B.* a combination of optical and radar data for subpolar glacier mapping



Synthetic aperture radar (SAR) has the following advantages over optical data (e.g. ASTER used in A) • independence of cloud cover and daylight (Fig. 5)

- the radar signal penetrates the ground to a certain extent; it's amplitudinal backscatter depends on humidity amongst others dati
 - > information on ice melting conditions retrievable · coherence between the phases of two or more satellite
 - passes flying on the same orbit can be used for SAR interferometry (InSAR) and differential InSAR (Fig. 4) > DEMs and movements can thereby be derived even
- Combination of SAR and optical from areas with poor optical contrast like Austfonna ice cap (Figs. 5, 6, poster background).



Fig. 5: Austfonna ice cap. (a) SAR amplitude image. (b) Interferogram of 7./8.11.1995, amplitude image in the background. Fringe structures from "flat Earth", topography and movement. (c) Interferogram of 7./8.11.1995, "flat Earth" corrected. Remaining fringes from topography and movements. (d) Unwrapped interferogram where the fringes represent continuous values instead of modulo 2π. Marked areas indicate fringe deformation due to movement influence.



While optical data often lacks spectral contrast in (peri-)glacial environments, it can provide information which is less obvious in SAR data, e.g. the exact glacier outline (Fig. 6) and its variations over time. Besides, the optical spectral mass balance correlates with the volumetric glacier mass balance.

The analysis of combined optical and SAR data applied to glaciers leads to an increased gain of information: optical and radar analyses complement one another with their respective strengths.

Fig. 6: Landsat 7 composite of Austfonna (10.07.2001) in RGB 543; shown in RGB 321 in the poster background

The result of approach A coherently shows the geomorphic process units in the entire valley up to its inaccessible upper regions, which had not been mapped before.

In the visible spectral range, interpretations appear quite straightforward, because optical data depict the ground as it is perceived by the human eye. This helps understanding and represents an asset for methods to be widely spread.

For further information on the optical, objectoriented remote sensing applications and for geomorphic details, see Schneevoigt et al. (2006, 2008)

Conversely, SAR imagery delivers information beyond the visible: backscat-er, polarisation and interferometric phase bherence permit inferences on and below e surface, concerning roughness, melting conditions and snow facies amongst others.

"Flat Earth

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Fig. 4: InSAR principles. Left: coloured fringes with 2π wavelength and phase difference $\Delta \phi$ between the two passes. Right: InSAR geometry, "flat Earth" removal to obtain clear topography signals and the effect of movements.

biect-oriented approach workflow in object-oriented classification classificatio
hierarchy layer creation segmentation classification L4 strata mask strata mask L3 hollow forms landform 12 landforms L1 land cove multiscalar project

Fig. 2: Object-oriented classification. Top: Input data: an ASTER satellite scene (29.05.2001, 15m resolution), a digital elevation model (DEM, 5m resolution) generated in Topogrid from data by the Bavrian L and Survey, and five DEM derivatives generated in ArcInfo. Bottom left: Segmentation on four hierarchical levels L1 to L4. Bottom right: Classification process flow.

- In the segmentation on four levels (Fig. 2), ...a small scale parameter conveys the spectral
- ground information of the Reintal (L1, Fig. 2) ...the mask of three altitudinal subsystems (L4)
- requires a very high scale parameter ...a high scale parameter is needed for cirgues
- and hanging valleys (L3) ...an intermediate level serves as final level L2
- (for details, see Schneevoigt et al., 2008).

In a second, separate step, classification is done on level L1, L4 and L3 individually. All information then merges into the final classification on L2, mostly based on fuzzy membership functions.

Level L1 classification renders ground land cover, level L4 the strata mask, level L3 eastern and western walls of cirques and hanging valleys (see Schneevoigt & Schrott, 2006).

This leads to a sound L2 landform classification (Fig. 3); a kappa coefficient of 0.915 in eCognition confirms the good fit of the results to ground truth.

