

# Sensor-Independent Deep Learning for Cloud Masking

#### **Alistair Francis**

Imaging Group, MSSL, University College London

ESA PhiLab

## ESA Φ-Lab

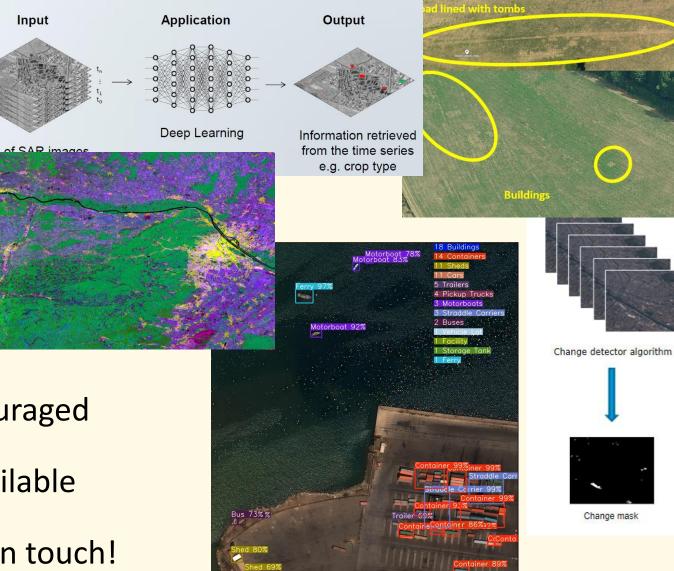


- Researching and investing in 'disruptive' technologies in Earth Observation
- In-house focus on Machine Learning and Computer Vision techniques
- Works with other ESA divisions, as well as wider European community

# **L**

## ESA Φ-Lab

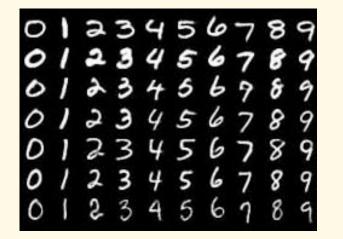
- Projects include:
  - Crop-type classification
  - Archaeological surveying
  - On-board convolutional models
  - Analysis-ready SAR data
  - Many more
- Collaborations like mine are encouraged
- Research Fellowship positions available
- Companies and researchers get in touch!



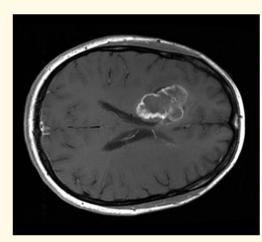


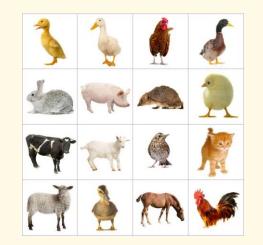
## Deep Learning's Promise

- Deep Learning offers remarkable performance
- Bespoke designs are unnecessary
- Applicable to wide range of problems and domains









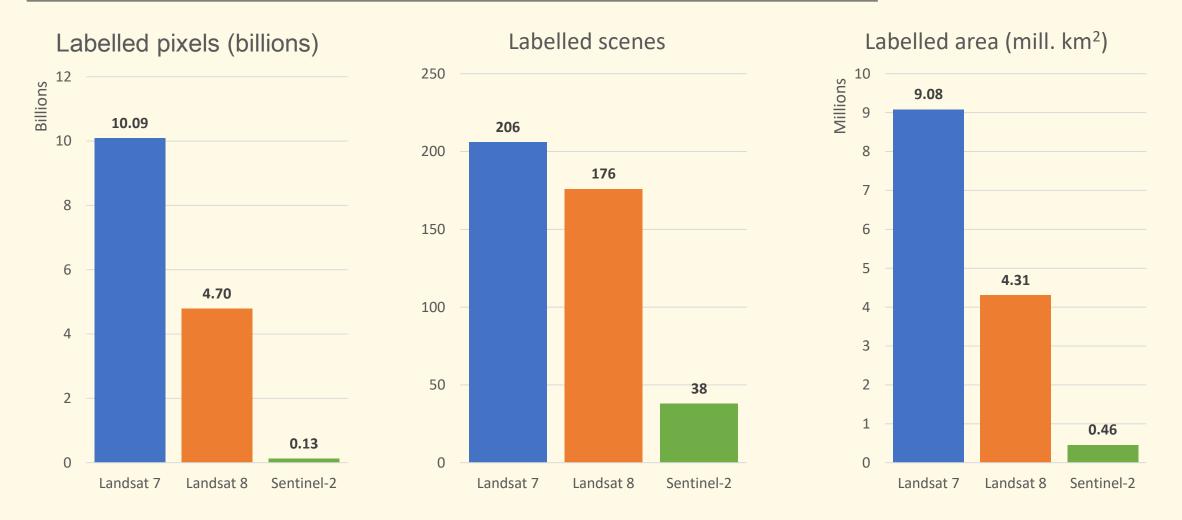


## Remote Sensing vs. other imaging domains

- Consumer cameras all look similar: datasets are **not** camera-specific
- What's special about multispectral satellites?
  - Different spectral responses
  - Different brightness scales and calibration
  - Different noise characteristics
- New dataset needed for every problem and for every sensor type.
- Amount of labelled data multiplied by number of sensors flown!
- Problem is only emphasised as more satellites are launched



## Cloud Masking datasets

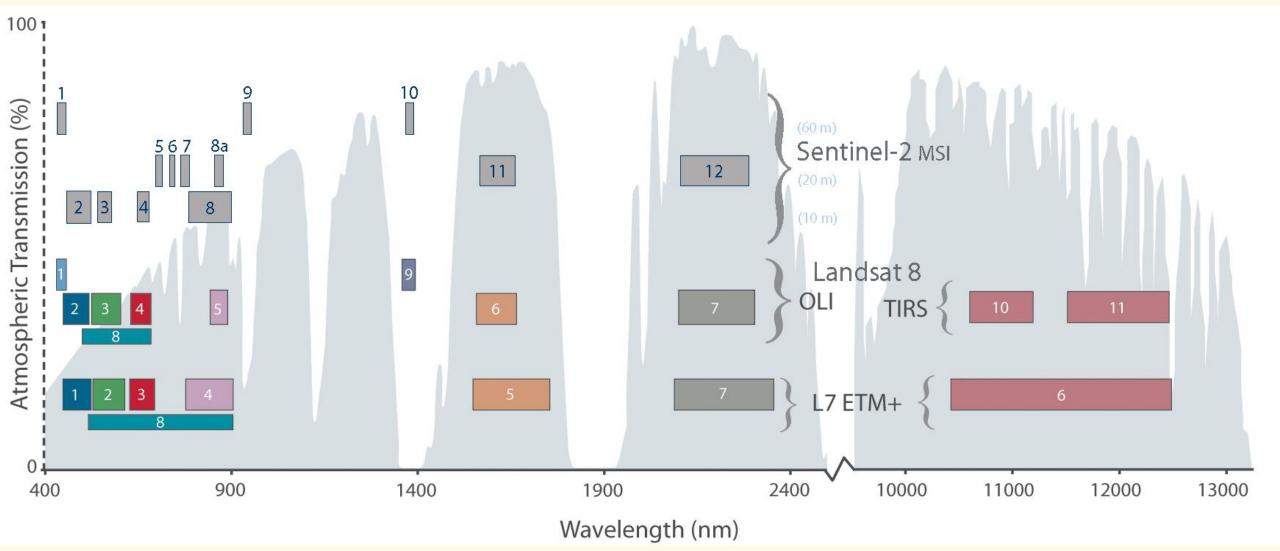


\*Aggregated from all publicly available datasets known to authors (not including single-pixel datasets).



# How do we get the **most** from the labelled data we **already have**?

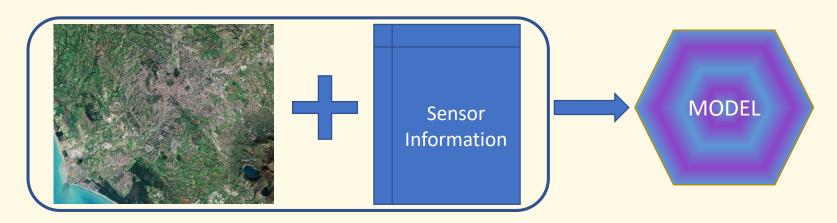
**UCL** 





## Sensor-Independent Model

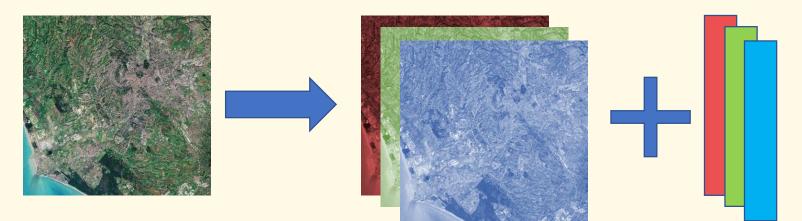
- Train model on all sensors: single unified dataset
- Model recognises and treat sensors in different ways
- Could be used on new satellite without retraining
- New convolutional model design needed





## Sensor-Independent Model

- Each spectral band treated as a member of the set of all possible bands
- Model takes as input any number of bands and their descriptors
- **Descriptor** is a vector parameterization of band characteristics e.g.:
  - central wavelength and bandwidth





## Experimental Setup

- Test across Landsat 7/8 and Sentinel-2
- Same model, trained three ways:
  - 1. Train on Sentinel Test on Sentinel
  - 2. Train on Landsat Test on Sentinel (only shared bands)
  - 3. Train on Landsat AND Sentinel Test on Sentinel
- Does data from other satellites help?
- Absolute performance less important than relative performance



LANDSAT 8 Biome – 96 scenes SPARCS – 80 subscenes

> Sentinel-2 CNES – 38 scenes

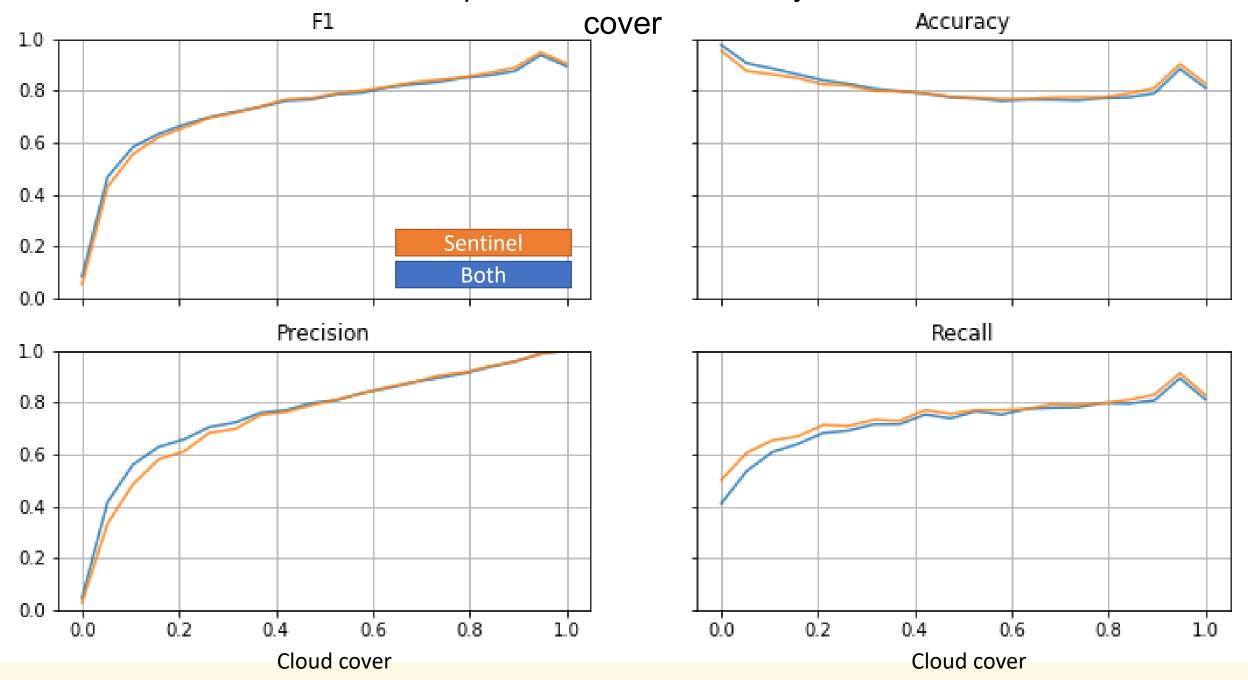


## Results

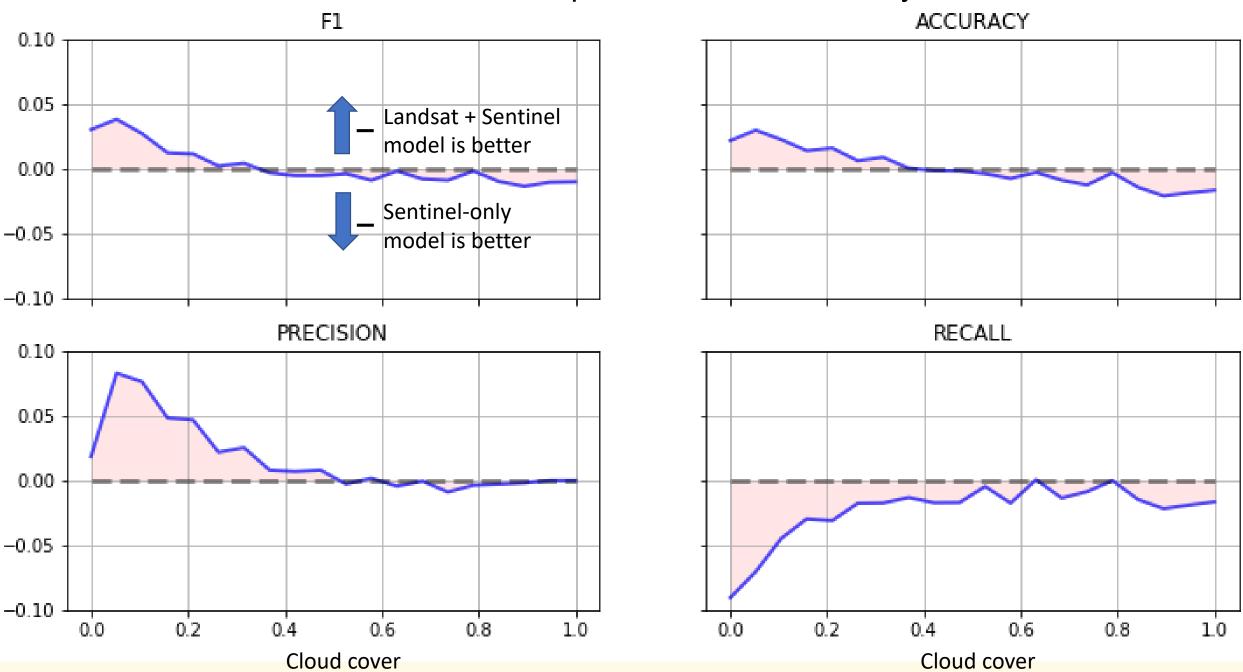
| MODEL              | Accuracy (%) | F1 (%) | Precision (%) | Recall (%) |
|--------------------|--------------|--------|---------------|------------|
| Landsat            | 88.6         | 69.8   | 86.9          | 58.4       |
| Sentinel           | 91.9         | 80.6   | 79.1          | 82.1       |
| Landsat + Sentinel | 92.4         | 82.7   | 85.1          | 80.4       |

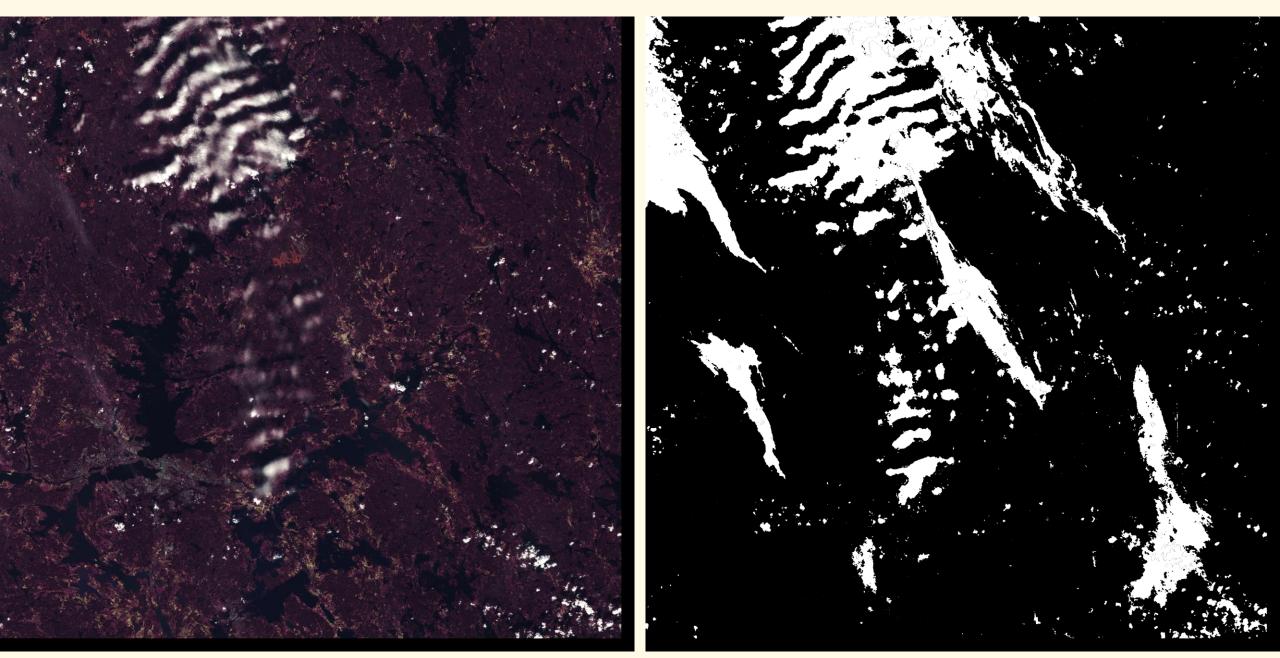
- Landsat-only model is not complete failure, but not good.
- Slight improvement in performance when using Landsat and Sentinel

Metrics per 128x128 window, by cloud



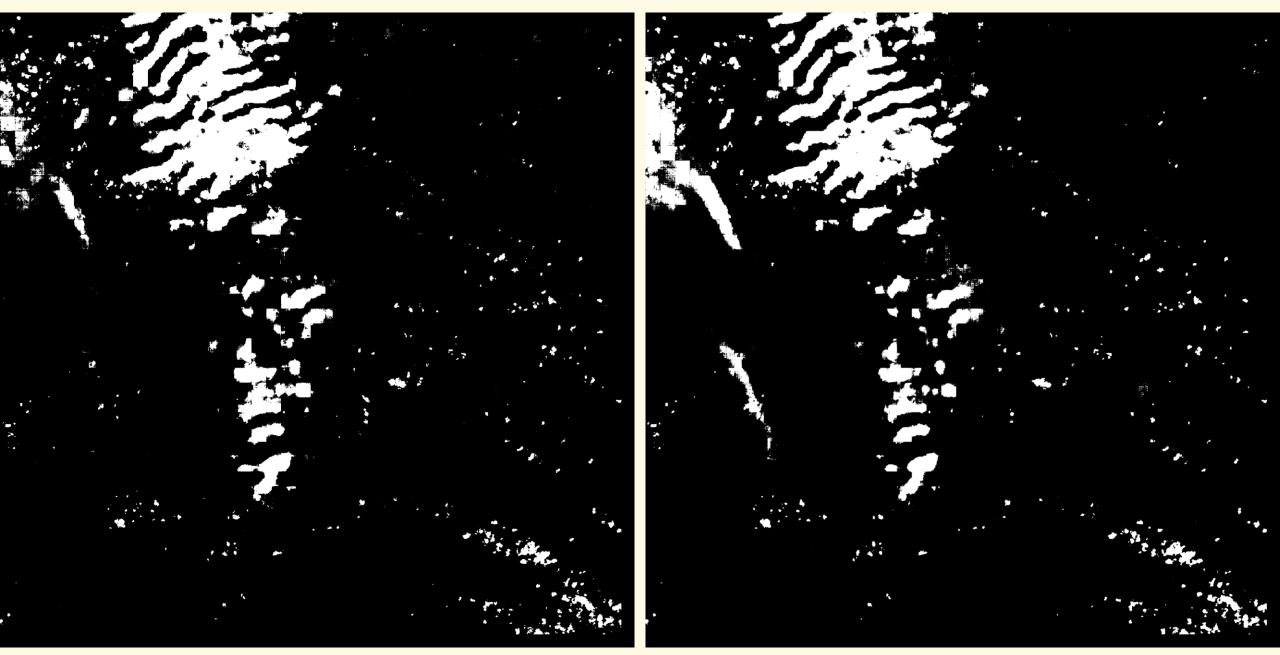
#### Difference between metrics per 128x128 window, by cloud cover





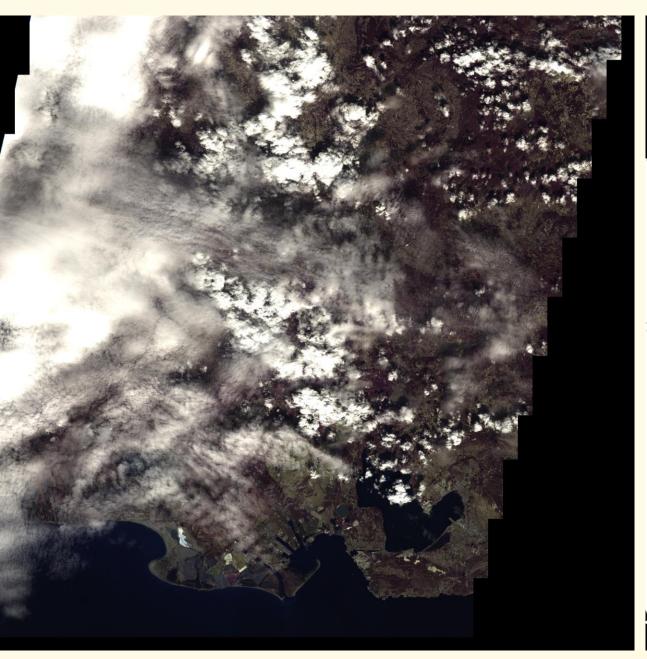
## **Central Finland**

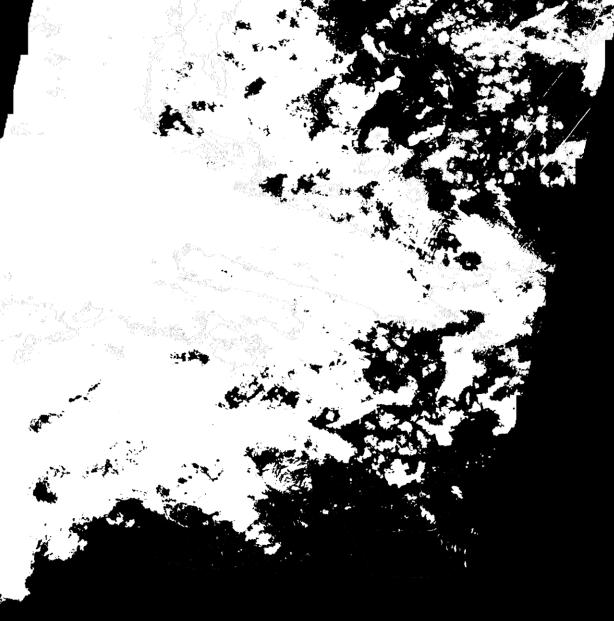
## Groundtruth



#### Landsat+Sentinel

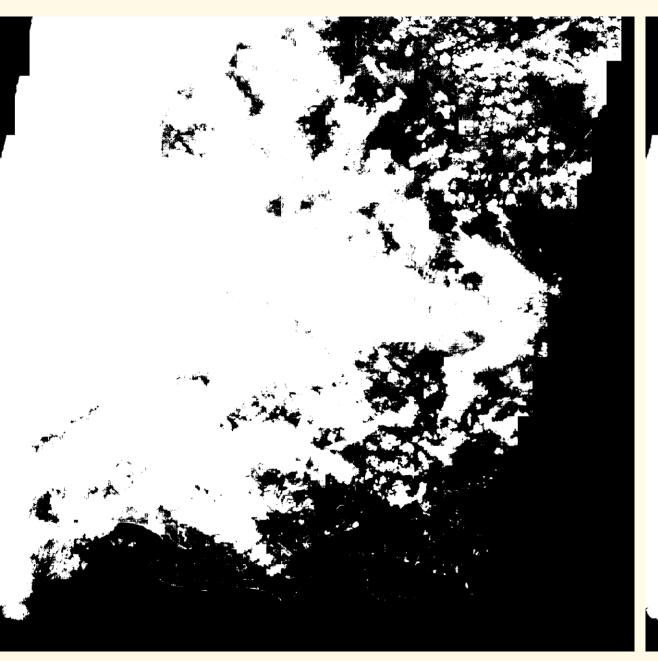






#### Arles, France

### Groundtruth





#### Landsat+Sentinel





## Takeaways

- Model is significantly worse if no data used from Sentinel-2.
  - Are there different sampling biases between Landsat and Sentinel datasets?
  - Are the shared bands as visually similar as we posit?
- (Very) tentative evidence that adding data from multiple satellites improves performance
  - Primary indicator of performance is **still** the amount of training data from the target satellite



## Conclusions

- Novel sensor-independent model has been developed
- Training across multiple sensors results in a somewhat better model
- More labelled data leads to better training and better validation
- More work is needed on understanding differences between sensors, and how the model is interpreting these differences



## Thanks!

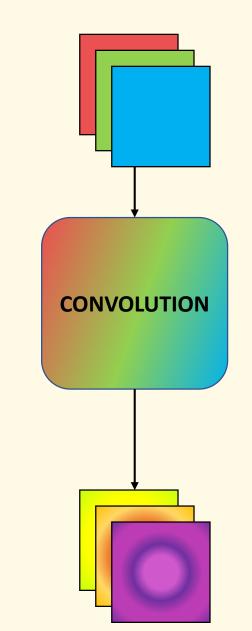


## Extra Slides...



## Sensor-Independent Model

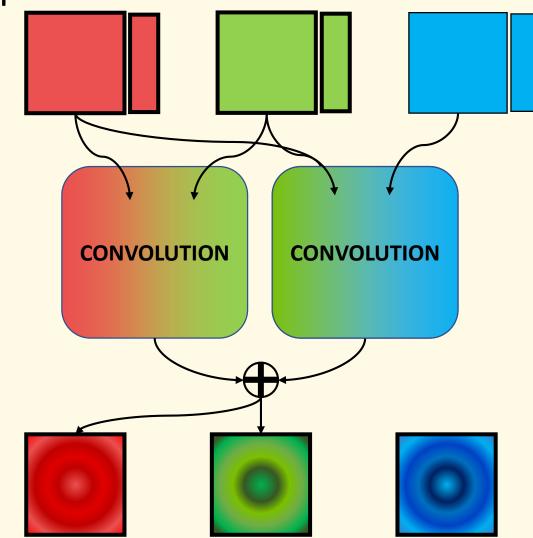
• Convolutional layer replaced by permutational convolutional layer





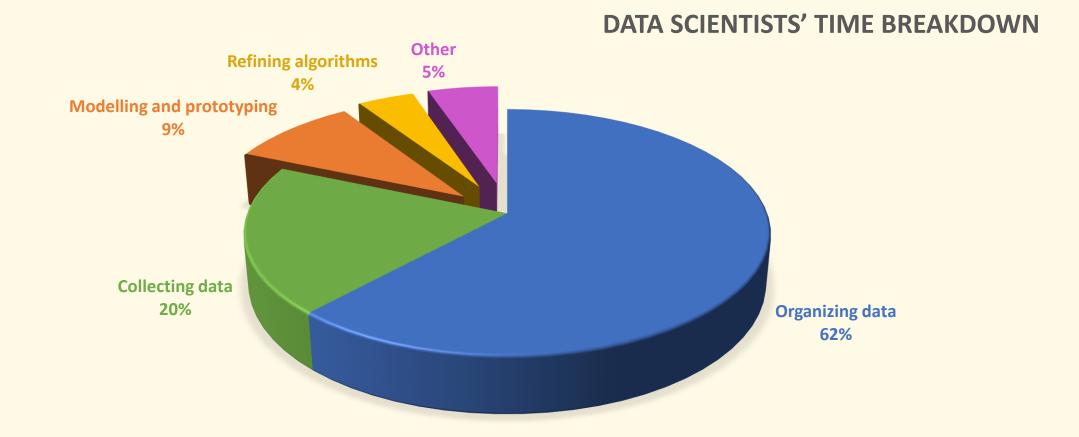
## Sensor-Independent Model

- Convolutional layer replaced by permutational convolutional layer
- Convolve each pair of bands
- Sum pairwise outputs.
- Allows for arbitrary input size, but O(n<sup>2</sup>) with number of bands
- Modular, can be substituted in for normal convolutions





## Deep Learning's Problem



#### >80% of time spent on problem-specific tasks

\*Data taken from CrowdFlower survey