

# Towards a Virtual Geostationary Ocean Colour Satellite Using Ocean Colour Constellation Data

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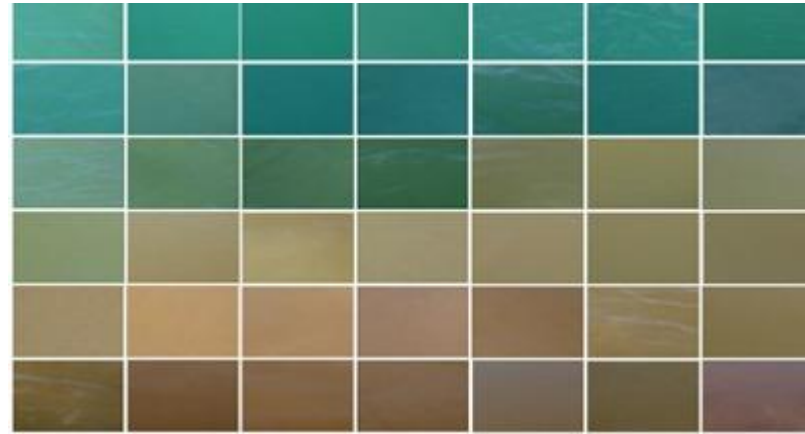
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<sup>3</sup> *Istituto di Scienze Marine (CNR-ISMAR), Arsenale-Tesa 104, Castello 2737/F, 30122 Venice, Italy*

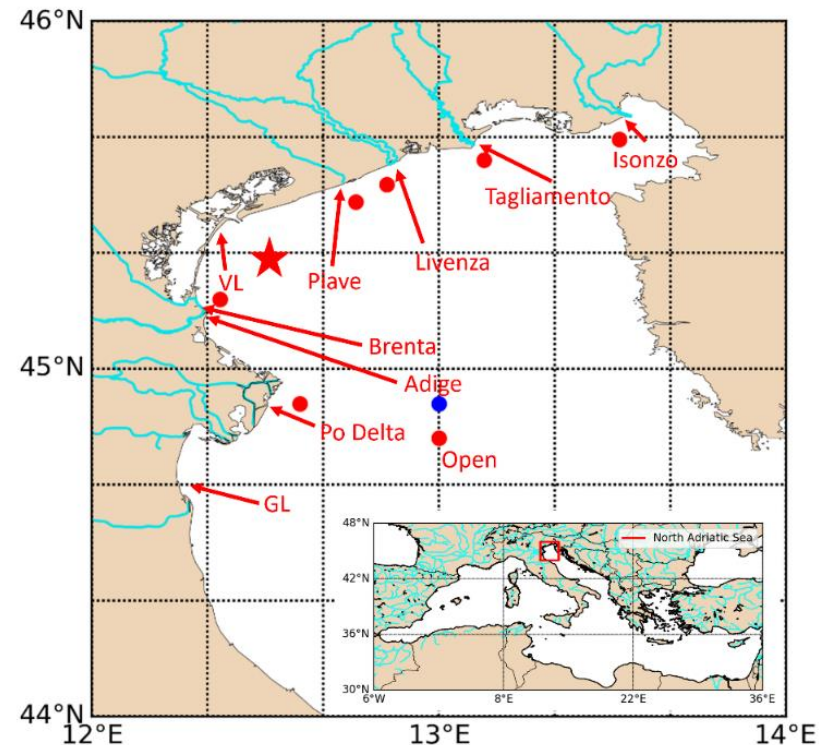


# Objective and study area

- In coastal areas the optical properties of the water components have a large variability on both spatial and temporal scale.
- Use of a single Ocean Colour (OC) polar sensor not sufficient to capture this variability, as it provides ~1 image a day of a basin at the middle latitudes.
- **OC geostationary sensors** provide multiple daily observations.
- Absent over the European Seas.
- **Objective:** Compensate the lack of an OC geostationary sensor over coastal environments, like the North Adriatic Sea (NAS), to have high temporal resolution observations of the optical properties.

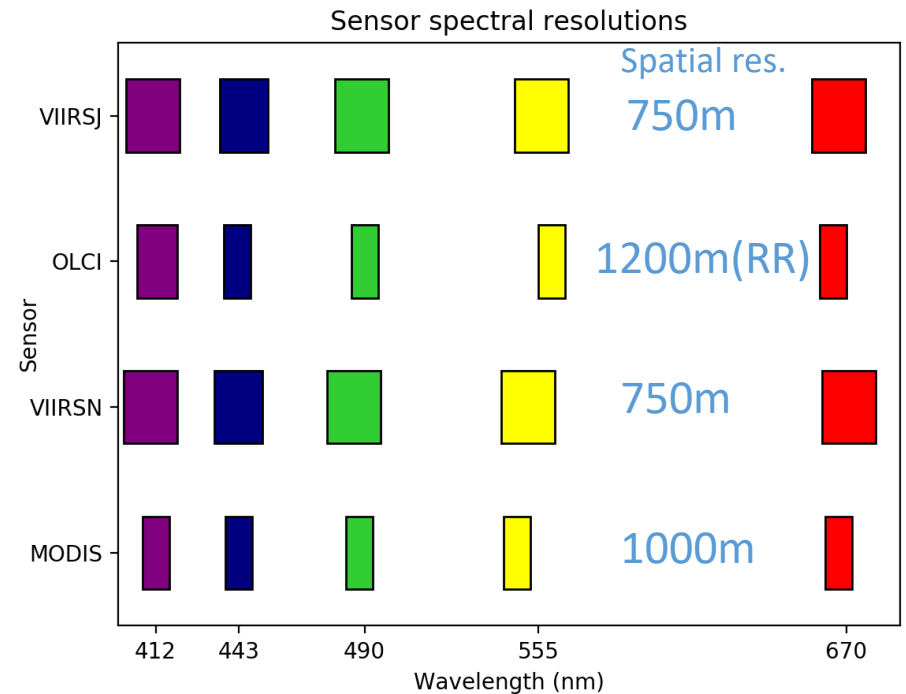
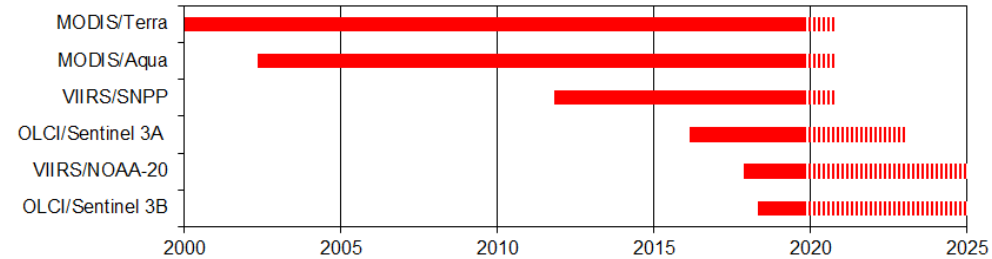


Map of the NAS with the rivers of the basin.



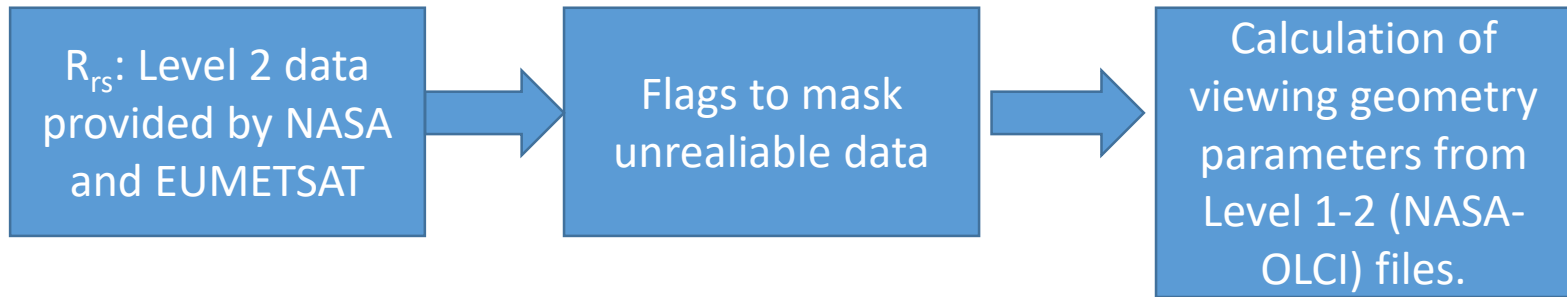
# The Virtual Geostationary Ocean Colour Sensor (VGOCS) dataset

- Analysis ready dataset that contains NAS observations from several OCR polar sensors (2002-2019).
- Multiple images during the same day, to approach the temporal resolution of a geostationary satellite.
- **Inter-sensor differences:**
  - Different spatial and spectral resolution.
  - Different processing.
  - Different calibration accuracy.
  - Different viewing geometry.
- Differences between different images are due to bio-optical processes or **artefacts?**
- **To reduce the inter-sensor differences: satellite  $R_{rs}$  adjustment** based on the Acqua Alta Oceanographic Tower (AAOT) in situ data.



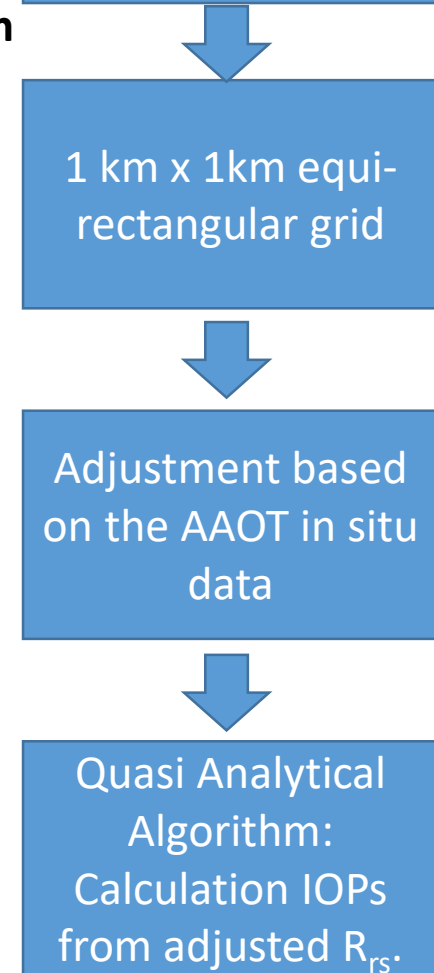
AQUA(A): MODIS-AQUA, TERRA(T): MODIS-TERRA, VIIRSN(V): VIIRS SUOMI-NPP, VIIRSJ(J): VIIRS NOAA-20, OLCI(O): OLCI S3A

# The VGOCS dataset



Based on the Copernicus Marine Environment Monitoring System (CMEMS) Product processing chain, with some differences.

	CMEMS	VGOCS
Temporal resolution	Daily: merging of different sensor images.	From 2 to 8 images a day: all images treated separately.
NASA flags	All standard flags.	All standard flags except for High Sensor Zenith (HSZ) and Stray-light (SL).
OLCI flags	All standard flags except for ANNOTATION (ANNOT_*).	All standard flags except for ANNOTATION (ANNOT_*).



# The VGOCS dataset

Filename format: VGOCS\_YYYYJJJHHMMSS\_X.nc

YYYY: year, JJJ: julian day of the year ,hh: hour, mm: minute, ss: second, X: sensor label

VGOCs_2013080110600_V.nc	VGOCs_2013080110600_V.nc
atmospheric_data	atmospheric_data
angstrom	angstrom
AOT	AOT
Geo_data	Geo_data
BOW	BOW
HISATZEN	HISATZEN
l2flags	l2flags
LAND	LAND
Minutes_from_scan	Minutes_from_scan
relative_azimuth	relative_azimuth
sensor_azimuth	sensor_azimuth
sensor_zenith	sensor_zenith
solar_azimuth	solar_azimuth
solar_zenith	solar_zenith
STRAYLIGHT	STRAYLIGHT
IOP_data	IOP_data
a0	a0
a555	a555
adg443	adg443
aph443	aph443
bbp0	bbp0
bbp443	bbp443
eta	eta
lambda0	lambda0
s	s
lat	lat
lon	lon
Orbital_cycle_day	Orbital_cycle_day
rrs_data	rrs_data
Rrs_410	Rrs_410
Rrs_443	Rrs_443
Rrs_486	Rrs_486
Rrs_551	Rrs_551
Rrs_671	Rrs_671
Sensor	Sensor
Time	Time

atmospheric\_data:

Aerosol optical thickness at 86X nm and angstrom coefficient.

Geo\_data:

Information about the flags, viewing geometry and time of the pixel observations.

IOP\_data:

All the IOPs estimated from the QAA.

rrs\_data:

All the  $R_{rs}$  bands used in the QAA at the native  $\lambda$ .

# Multi-linear regression (MLR) adjustment

Different adjustment coefficients for different sensors.

TRAINING DATASET: coefficient calculation.

VALIDATION DATASET: match-up analyses.

$$\Delta R_{rs}(\lambda) = R_{rs}^{is}(\lambda) - R_{rs}^{or}(\lambda)$$



Estimation of the coefficients



$$\langle \Delta R_{rs}(\lambda) \rangle = a_0^{sat} + \sum_{i=1}^5 a_i^{sat} R_{rs}^{or}(\lambda_i) + a_6^{sat} \theta_v + a_7^{sat} \theta_s + a_8^{sat} \phi$$



$$R_{rs}^{adj}(\lambda) = R_{rs}^{or}(\lambda) + \langle \Delta R_{rs}(\lambda) \rangle$$

$R_{rs}^{or}$ =original satellite  $R_{rs}$

$R_{rs}^{adj}$ =adjusted satellite  $R_{rs}$

$R_{rs}^{is}$ =in situ  $R_{rs}$

$\theta_v$ = sensor zenith angle.

$\theta_s$ = solar zenith angle.

$\phi$ = relative azimuth angle.



$R_{rs}$  in situ data acquired at the Acqua Alta Oceanographic Tower (AAOT), part of the Aeronet-OC network and representative of most of the optical variability of the basin.

Giuseppe Zibordi from the Joint Research Center of the European Commission is acknowledged for establishing and maintaining the AAOT AERONET-OC site.

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$R_{rs}^{or}$  = original satellite  $R_{rs}$

$R_{rs}^{ad}$  = adjusted satellite  $R_{rs}$

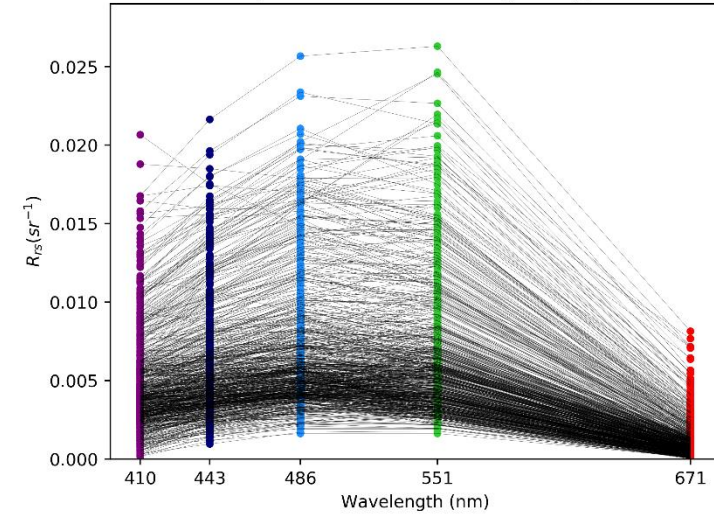
$R_{rs}^{is}$  = in situ  $R_{rs}$

$\theta_v$  = sensor zenith angle.

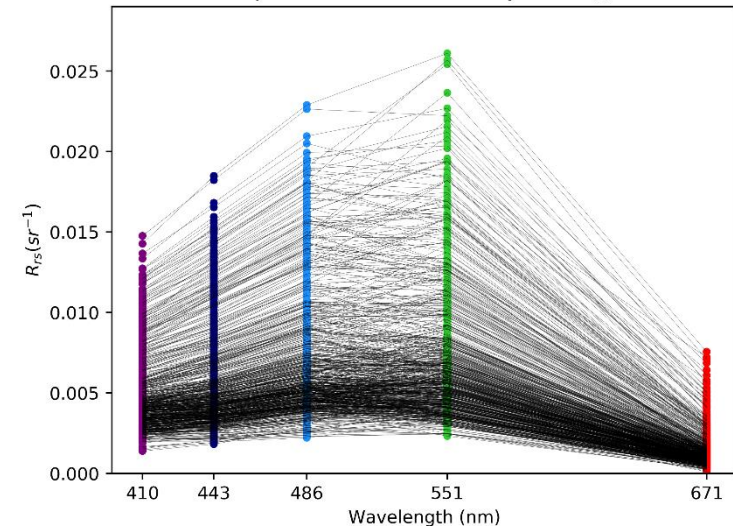
$\theta_s$  = solar zenith angle.

$\phi$  = relative azimuth angle.

Spectra for the VIIRS original  $R_{rs}$



Spectra for the VIIRS adjusted  $R_{rs}$



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Estimation of the coefficients



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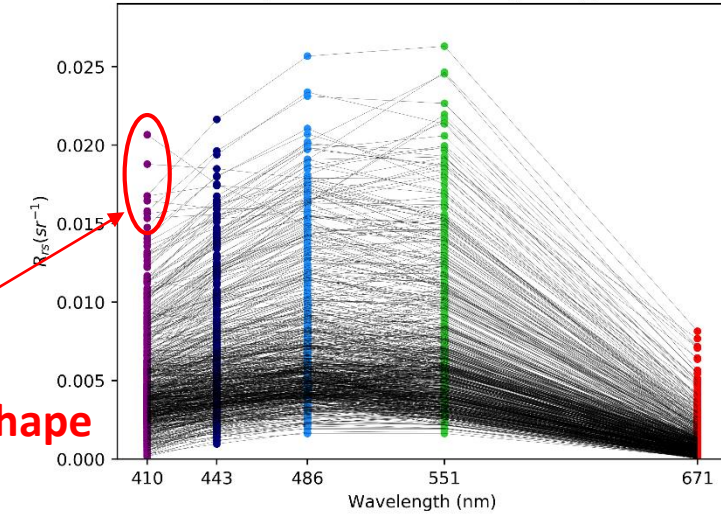
$\theta_v$  = sensor zenith angle.

$\theta_s$  = solar zenith angle.

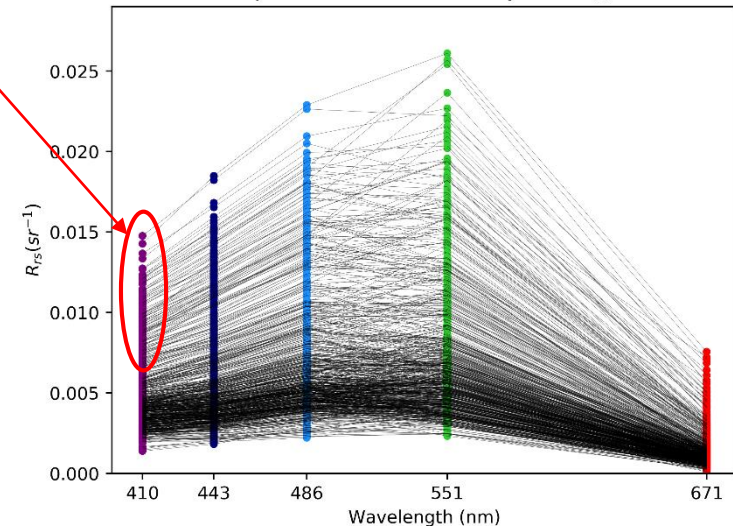
$\phi$  = relative azimuth angle.

**Anomalous spectral shape  
correction.**

Spectra for the VIIRS original  $R_{rs}$



Spectra for the VIIRS adjusted  $R_{rs}$

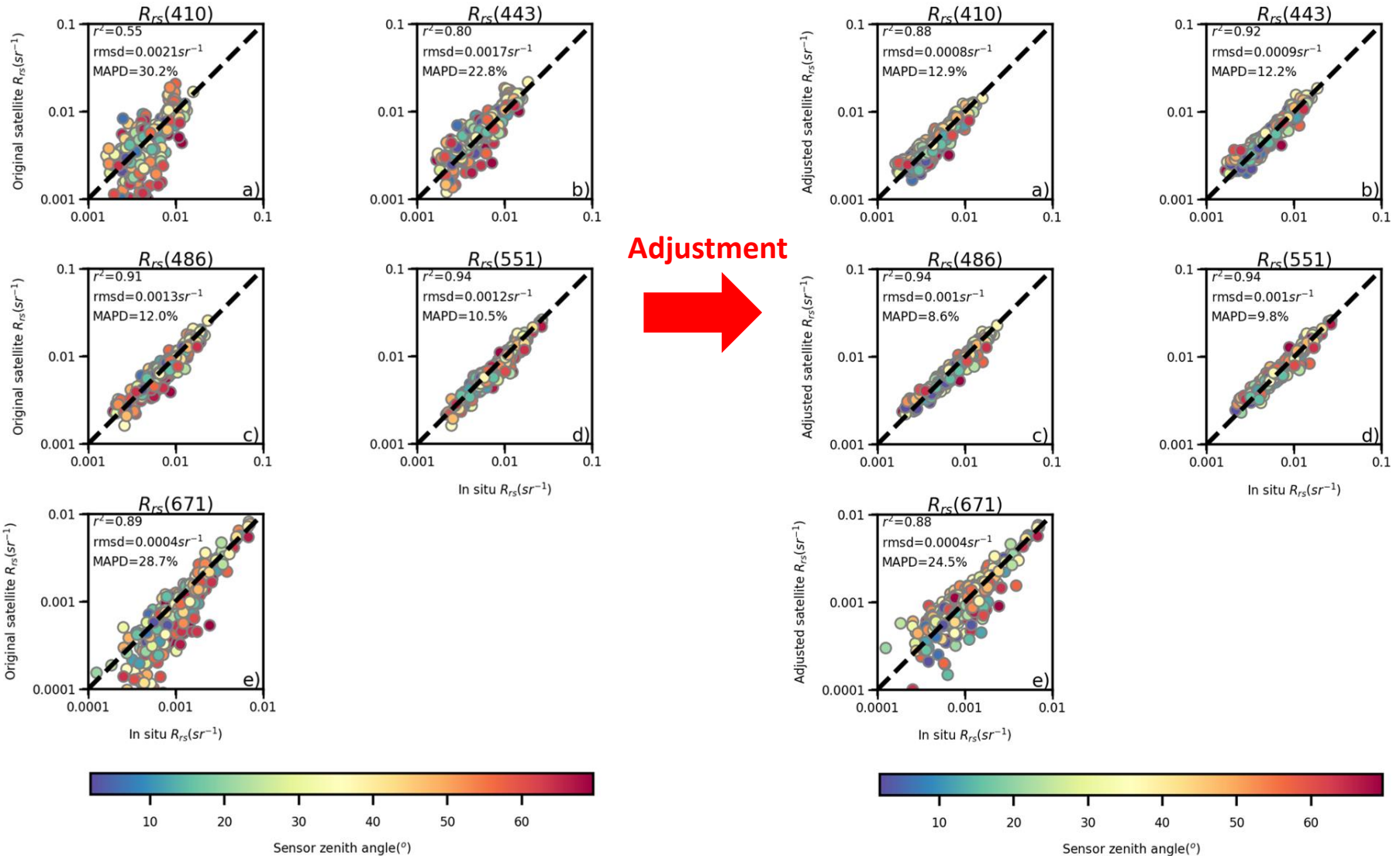




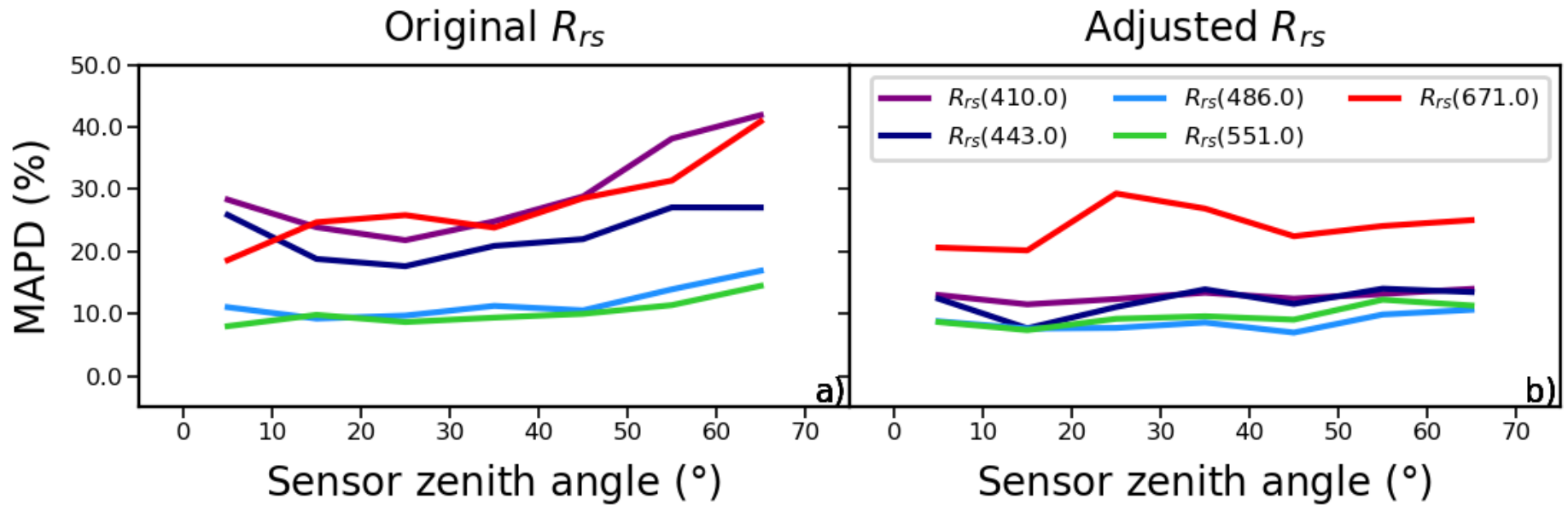
# VIIRSN match-up analysis

Training dataset (coefficient calculation): 02/01/2012 - 31/08/2015

Validation dataset (match-up analysis): 01/09/2015 - 28/02/2019



# HSZ flag and sensor zenith angle ( $\theta_v$ ) dependence



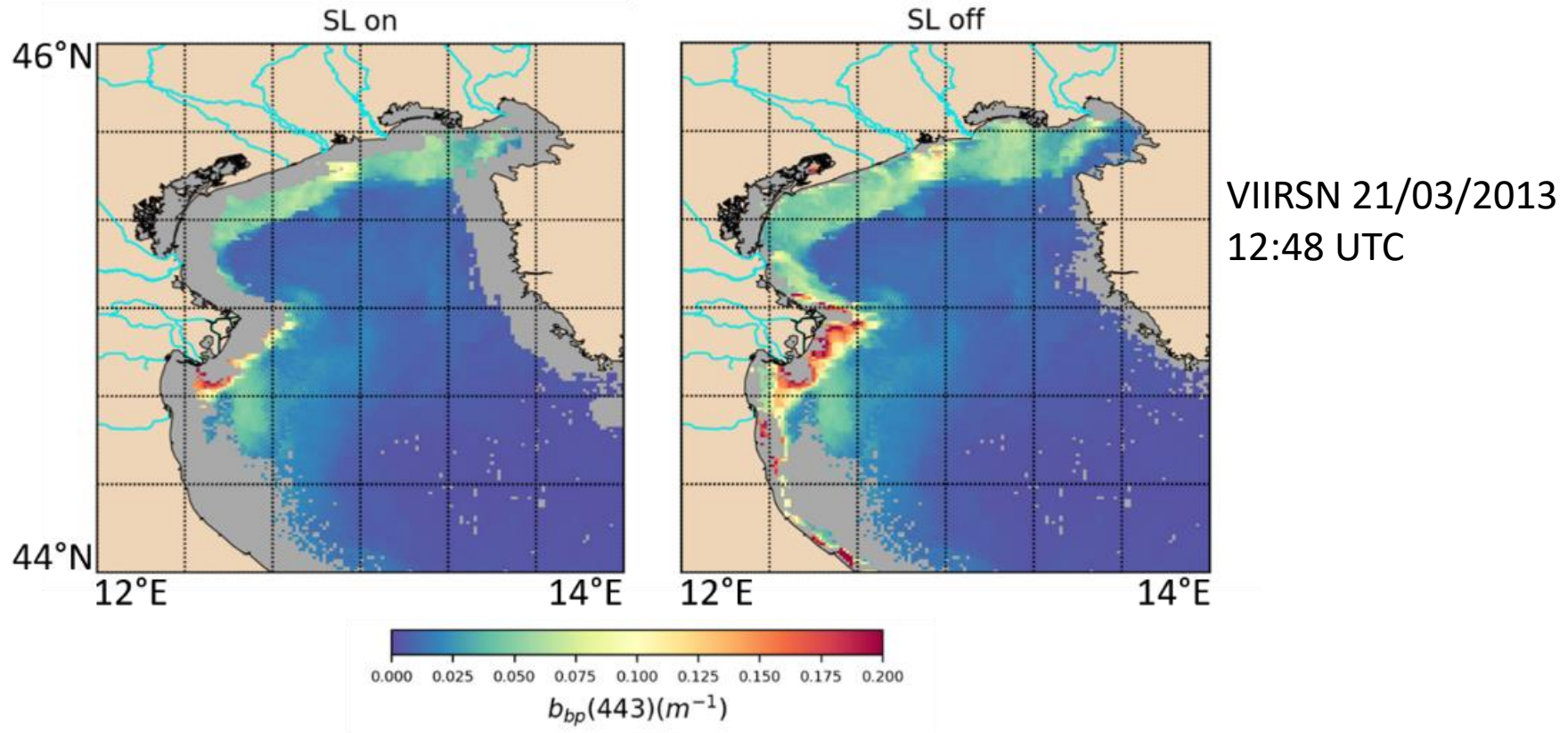
- No application of the High Sensor Zenith flag (HSZ,  $\theta_v > 60^\circ$ ).
- Large number of images masked by this flag.
- Calculation of MAPD for different range of  $\theta_v$ .
- For the original  $R_{rs}$  larger uncertainty for MAPD  $> 50^\circ$ .

Adjustment



- Reduced  $\theta_v$  dependence.
- Data with  $\theta_v > 50^\circ$  same order of MAPD of those at  $\theta_v < 50^\circ$ .
- Increase of the VGOCS temporal coverage.
- **Up to 3 additional images available during the same day.**

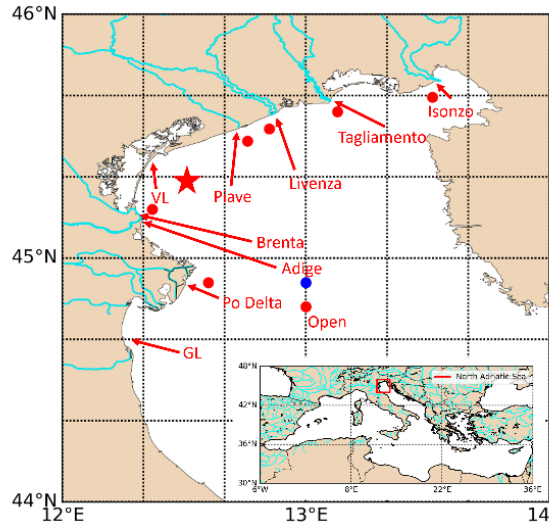
# Flag and spatial coverage: SL and ANNOT\_\*



- Similar effect on spatial coverage with **large number of masked coastal pixels**.
- ANNOT\_\* data in **good agreement** with the in situ spectra in coastal areas (Zibordi et al., 2018).
- SL uncertainty **strongly reduced by the adjustment**.
- **Notable increase of VGOCS spatial coverage**.
- **SL: 42.4%** additional coastal pixels for NASA sensors.
- **ANNOT\_\*: 61.6%** additional coastal pixels for OLCI.

# Inter-sensor differences

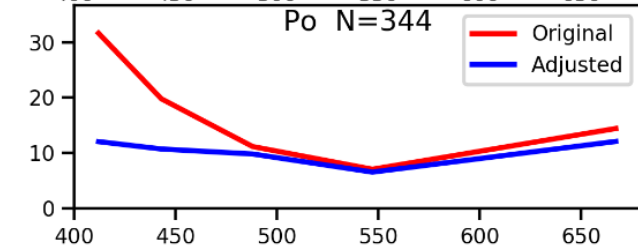
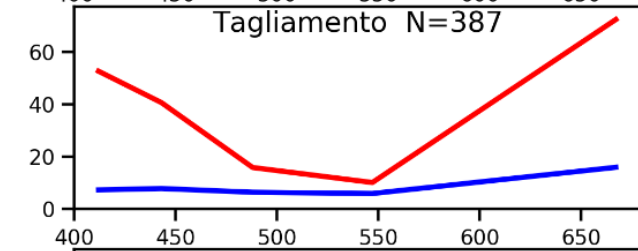
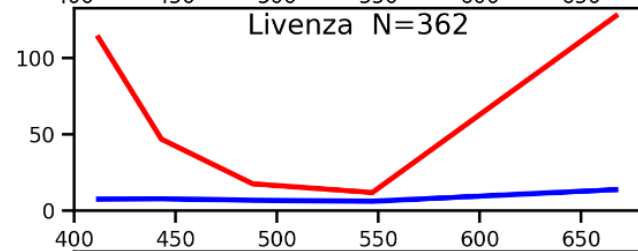
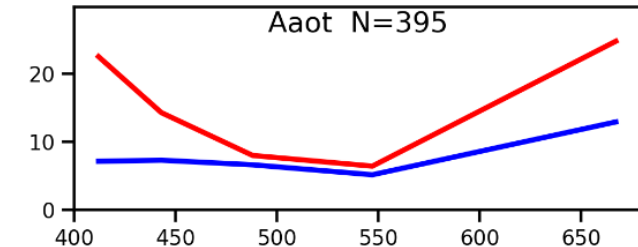
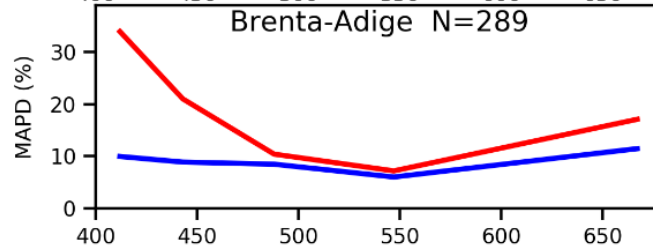
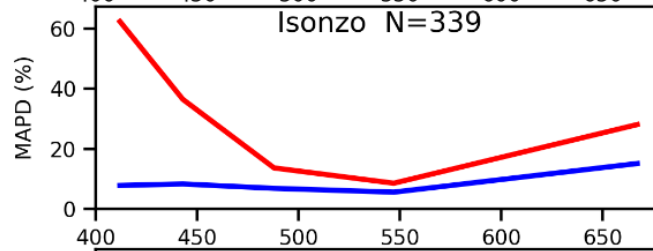
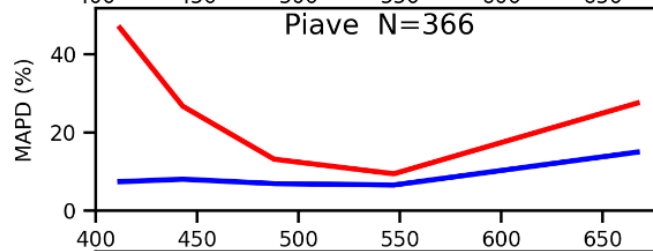
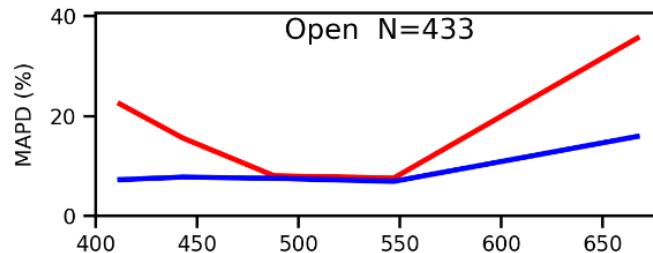
- Virtual buoys (red dots and red star).
- Hypothesis:
  - $\Delta R_{rs} \approx 0sr^{-1}$  for  $\Delta t < 20$  min.
  - $\Delta R_{rs}$  between couple images acquired with  $\Delta R_{rs} < 20$  mins are mostly due to artefact.



After the adjustment  
MAPD is reduced  
spectrally at each virtual  
buoy.



**Reduction of the inter-sensor differences.**

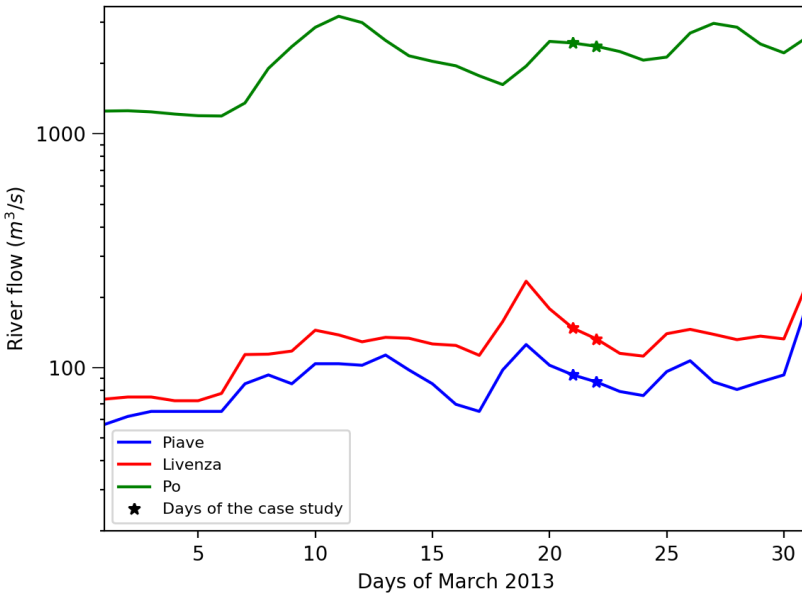


Wavelength (nm)

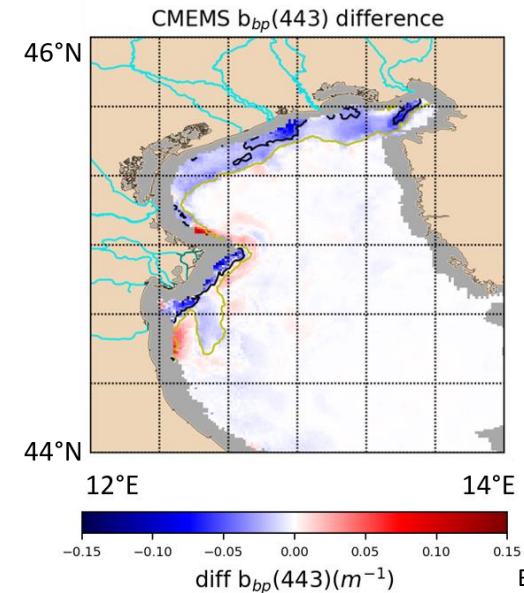
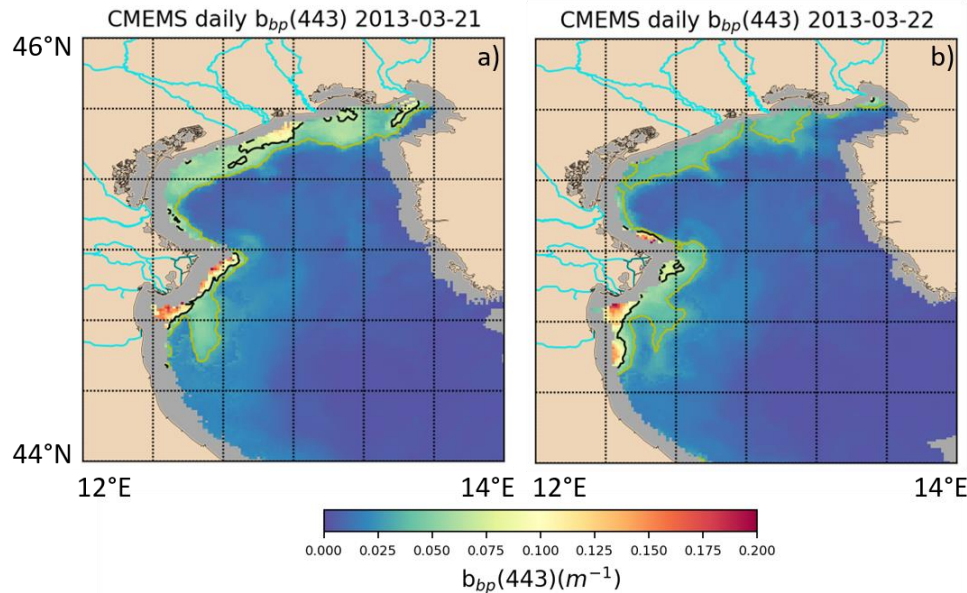
Wavelength (nm)

# 21st and 22nd of March 2013 case study

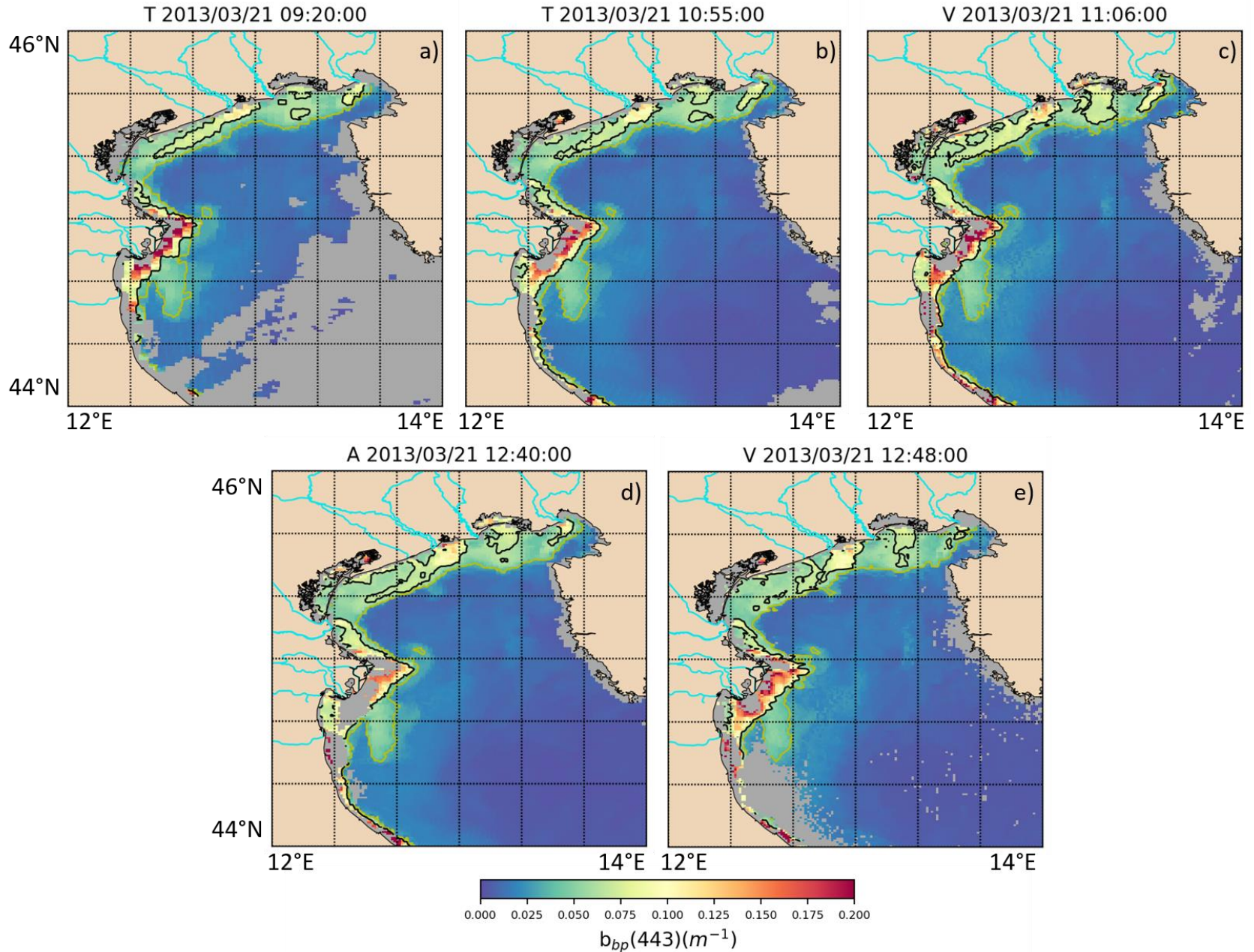
River Flows for March 2013



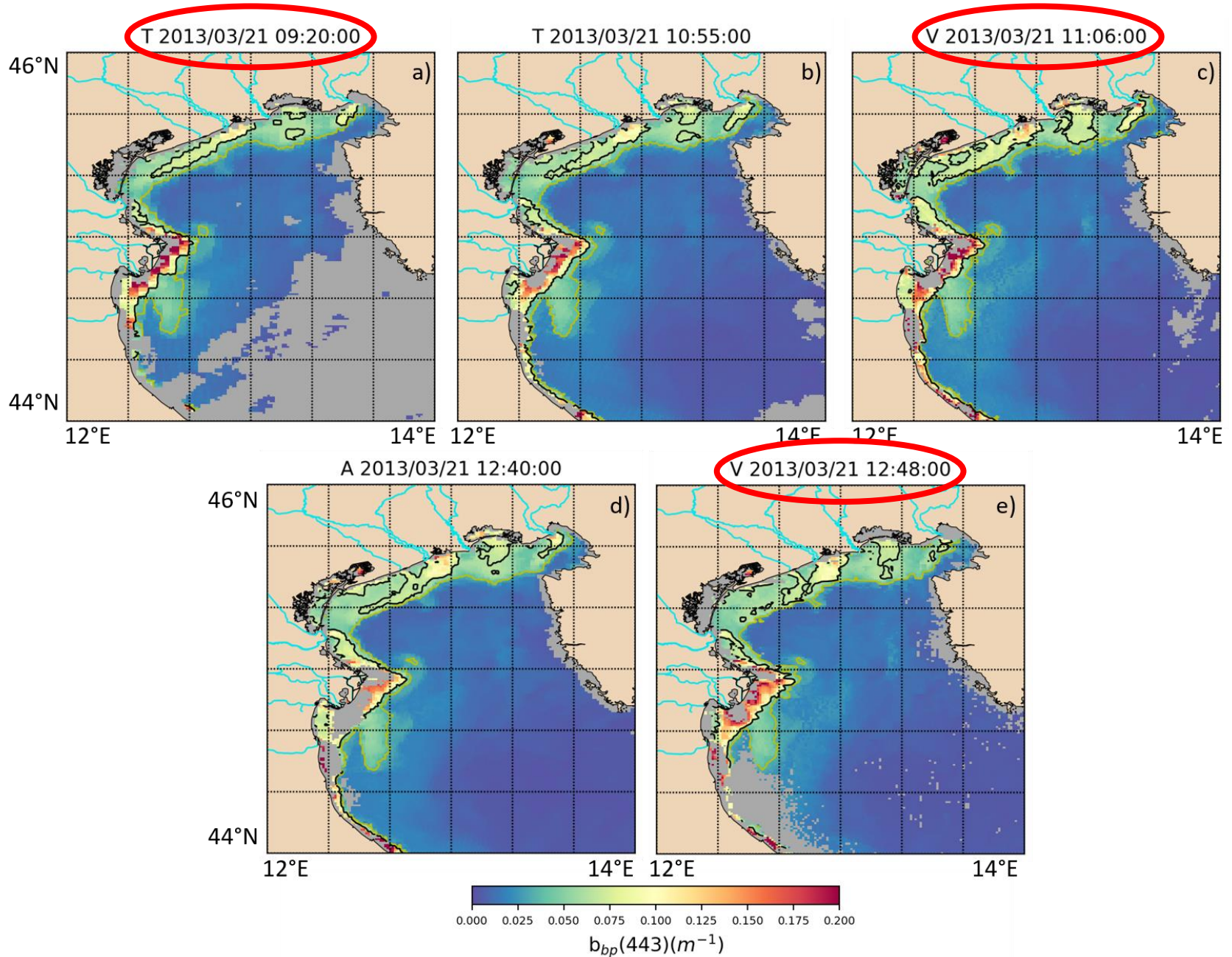
- Analysis of the variability of the particulate backscattering at 443 nm ( $b_{bp}(443)$ ) in the northern part of the basin, using first the CMEMS and then the VGOCS images.
- **High river discharges** for Livenza e Piave during 19th of March; strong reduction in the following days (ARPA data).
- **Strong  $b_{bp}(443)$  reduction** between 21st and 22nd of March.
- How and when did this reduction take place during the 24 hours?
- **No information close to the shore (stray-light flag).**



# VGCOS images: 21st of March

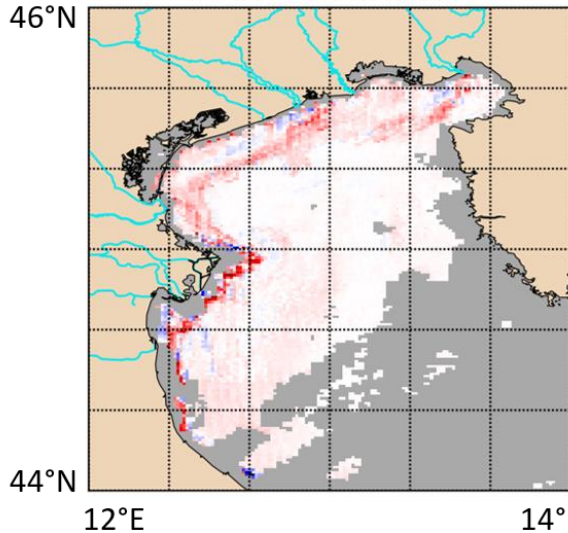


# VGCOS images: 21st of March

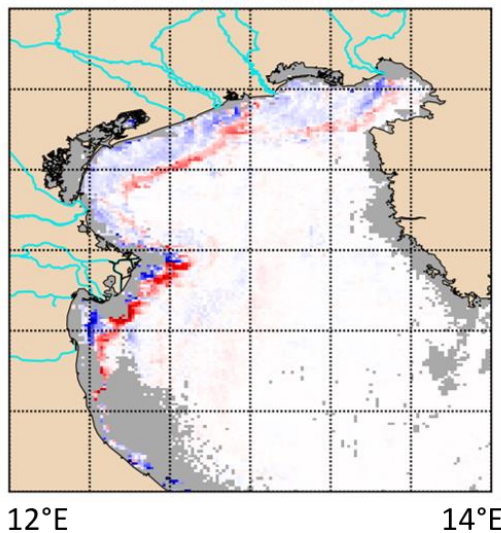


# VGOCs: 21st of March variability

Evolution between 09:20 and 11:06 UTC

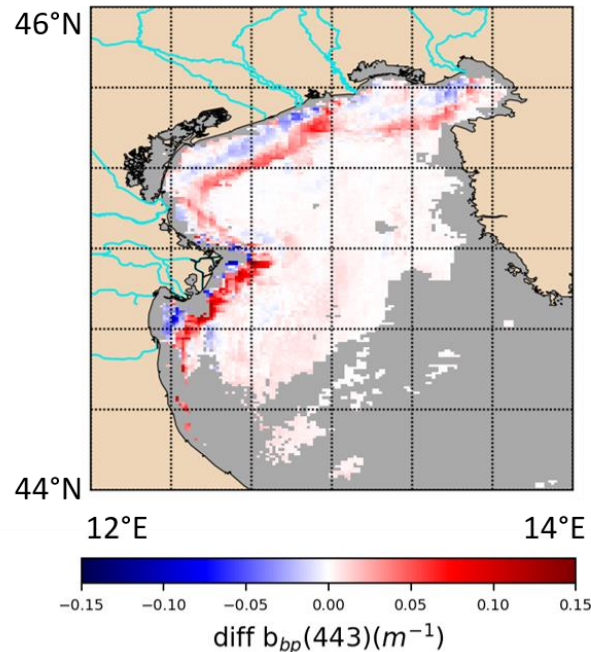


Evolution between 11:06 and 12:48 UTC



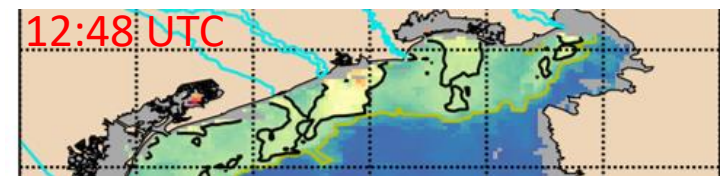
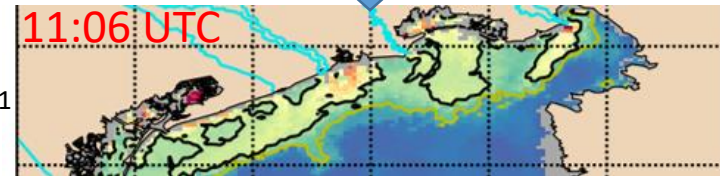
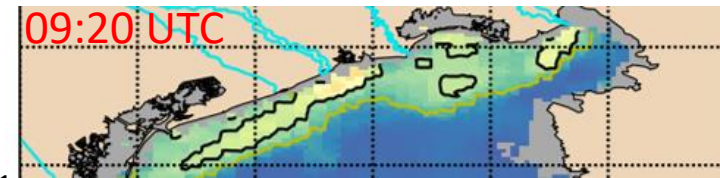
- Increase of  $b_{bp}(443)$  between 09:20 and 11:06 UTC due to the particulate matter carried by the river.
- After 11:06 strong reduction close to the river mouths.
- In 3 hours and half: reduction close to the river mouths, increase far from the shore for southward advection of the particulate matter.

Evolution between 09:20 and 12:48 UTC



Black isolines:  
 $b_{bp}(443)=0.065m^{-1}$

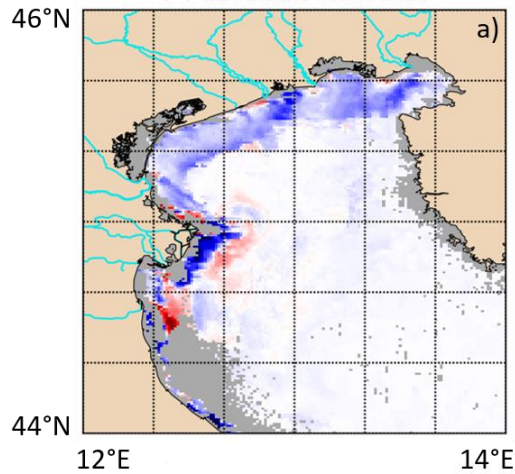
Yellow isolines:  
 $b_{bp}(443)=0.035m^{-1}$



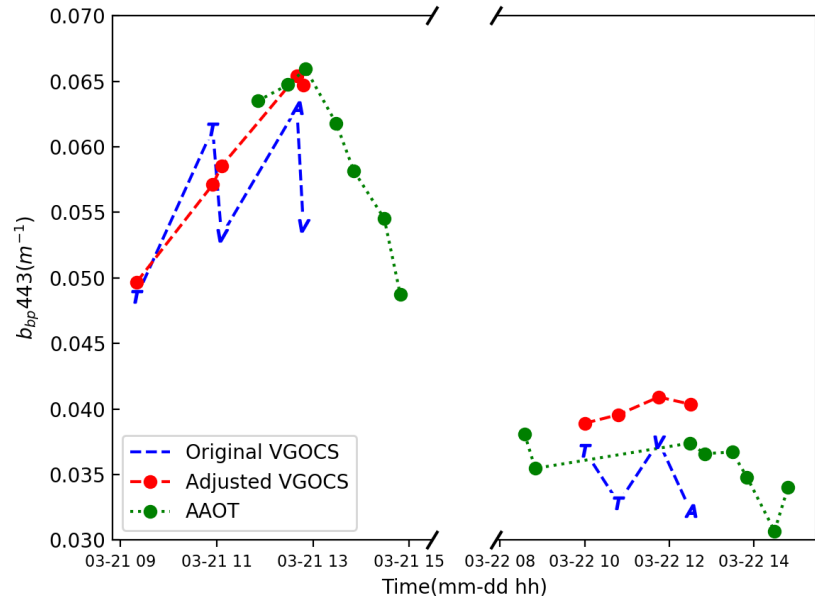
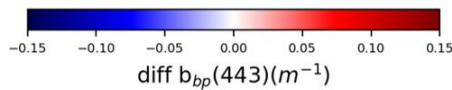
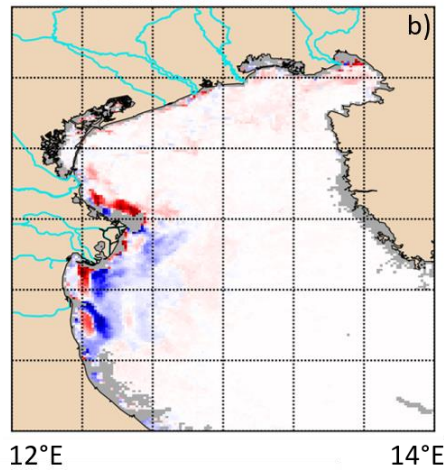


# VGCOS: inter-daily and 22nd of March variability.

Evolution between 12:48 UTC of the 21<sup>st</sup> of March and 10:00 UTC of 22<sup>nd</sup> of March



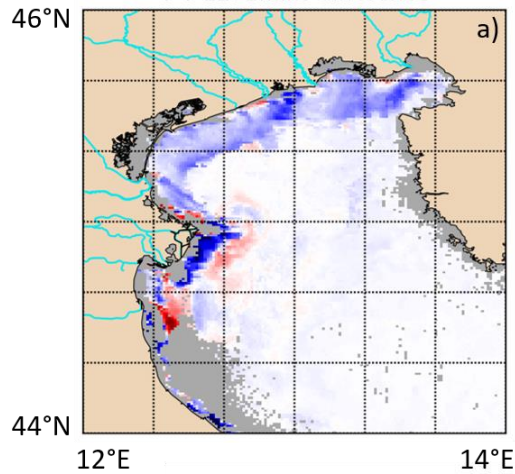
Evolution between 10:00 and 13:06 UTC of 22<sup>nd</sup> of March



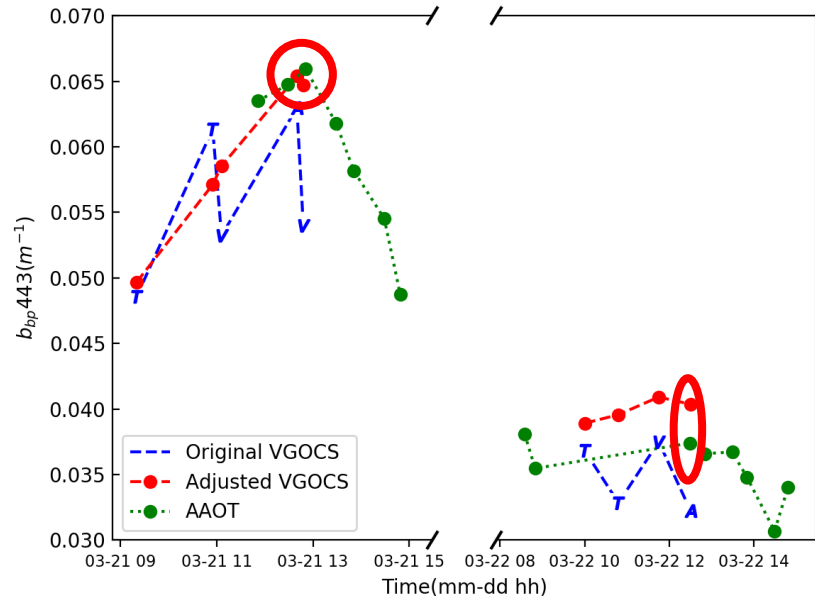
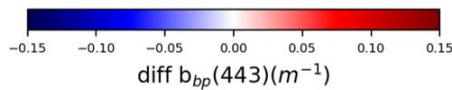
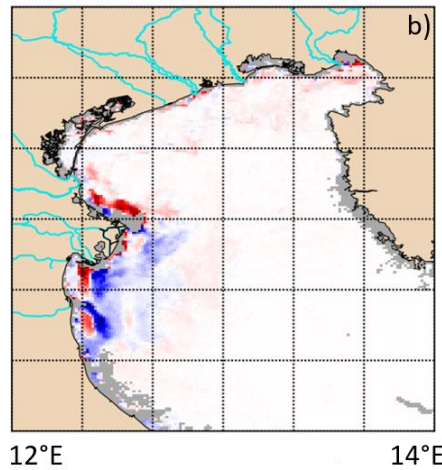
- Strong reduction between the two days, as for the CMEMS product.
- Multiple images allowed to capture most of the optical variability during the two days.
- Information about the dynamics and the dispersion of the particulate matter into the basin, not feasible with a daily product.
- Information close to the river mouths due to unmasking for SL.
- Better agreement for the adjusted  $b_{bp}(443)$  with the one retrieved from the in situ data.
- Lower  $b_{bp}(443)$  difference for the adjusted product for observations acquired in temporal proximity.

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Evolution between 12:48 UTC of the 21<sup>st</sup> of March and 10:00 UTC of 22<sup>nd</sup> of March



Evolution between 10:00 and 13:06 UTC of 22<sup>nd</sup> of March

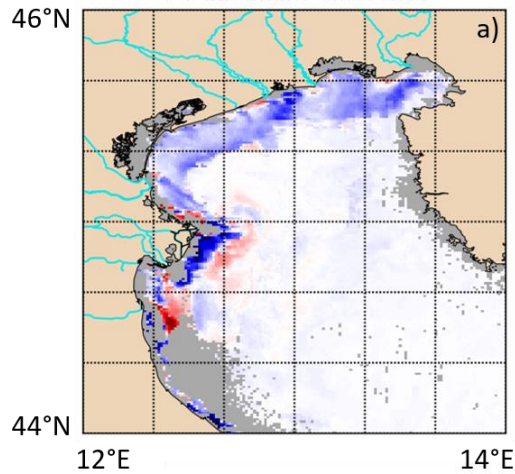


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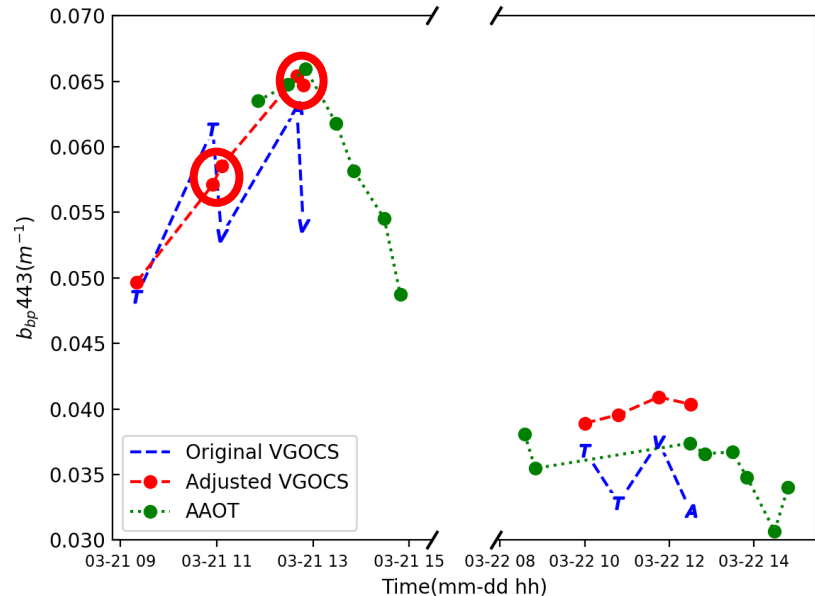
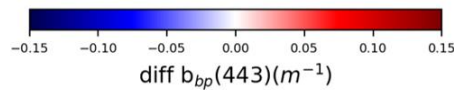
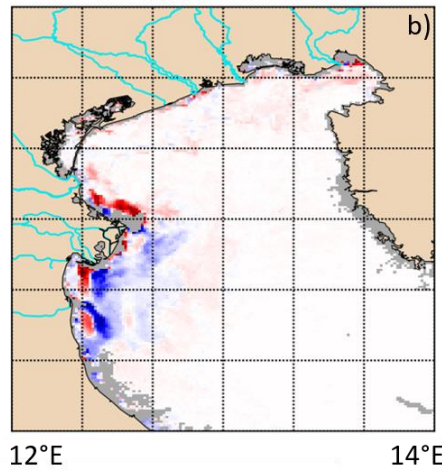
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- Information about the dynamics and the dispersion of the particulate matter into the basin, not feasible with a daily product.
- Information close to the river mouths due to unmasking for SL.

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- Lower  $b_{bp}(443)$  difference for the adjusted product for observations acquired in temporal proximity.

# Conclusions

- Adjustment improved the agreement with the in situ data, reduced the inter-sensor differences and allowed to use data generally masked in the standard processing chains:
  - No HSZ flag make available up to 3 additional images of the basin.
  - No SL flag for NASA (+ 42.4%) and no ANNOT\_\* flag for OLCI (+61.6%) allow to have information on coastal pixels.
- Need of an OC geostationary sensor over the european seas, partially compensated by our datasets.
- VGOCS analysis ready dataset allows to have at disposal more images of the basin during the same day, approaching a geostationary sensor temporal resolution.

# Conclusions and future perspectives

- VGOCS analysis ready dataset allows the users to:
  - Use OC data without a pre-processing, in order to have a quick access to field such  $R_{rs}$  spectra and various IOPs.
  - Calculate IOPs and component concentration using different algorithms, with the adjusted  $R_{rs}$  spectra as input.
  - Perform analysis exploiting products usually not provided in standard L3 files, such flags and viewing geometry parameters.
- Next steps:
  - Analyse the tidal effect on sediment transport and river plume dynamics.
  - Extend the approach in other coastal areas, where at least one automatic radiometric station representative of the entire basin optical variability is present (as in the Western Black Sea, Baltic Sea, Northern Sea).

# Thanks for your attention.

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