





EDAP Framework for the geometric validation of high resolution optical data

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20th November 2019

VH-RODA

Optical Sensors Sessions -Room 1

OUTLINE

- EDAP Presentation
- Geometric Assessment Methods
- Planet Results.
- Landsat / S2 Results



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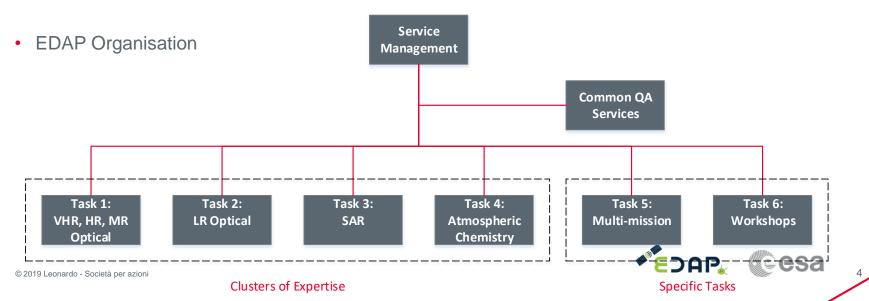
Earthnet Programme and Third Party Missions

- ESA's Earthnet Programme provides the framework for "integrating" non-ESA missions (Third Party Mission - TPM) into the overall ESA Earth Observation (EO) portfolio, allowing data access and supporting the development of new research and applications
- Earthnet support to TPMs can be divided in two types of activities:
 - Support to TPM cal/val and routine data quality monitoring,
 - TPM data supply for science and research purposes
- In the recent years, the EO capacity from space has grown with the multiplication of both institutional and commercial missions; in particular the domain of high-resolution optical sensors and SAR (Synthetic Aperture Radar) has dramatically increased.
- In this context, the ESA Earthnet Data Assessment Pilot (EDAP) project aims to perform an early data assessment for various missions, which may potentially become TPMs, covering specifically identified calibration and validation related tasks



What is EDAP?

- <u>ESA's Earthnet Data Assessment Pilot (EDAP</u>) is a project a 2-years project, started in November 2018.
- EDAP is designed to **perform early data quality assessments** on existing and future Earth Observation (EO) missions from national or commercial providers
- It is achieved through provision of <u>clusters of expertise in various domains</u>
- Specific focus will also be put on <u>capacity building</u> in the relevant data provider with the set up and evolution of documentations, tools and procedures to allow to efficiently perform data quality assessments in the domains of expertise defined within this activity.



Service Domain Clusters & Input Missions

• The missions covered in each of the Domain Clusters:

ТАЅК	Domain	Missions		
		Planet – PlanetScope		
		Planet – Skysat		
		USGS Landsat		
		KARI Kompsat 3		
Task 1	Very High, High and Moderate	SSTL DMC/Triplesat		
TASK 1	Resolution Optical	SSTL Superview		
		SSTL Vision-1		
		Earth-i Vivid-i		
		BlackSky		
		Proba-1 CHRIS		
Task 2	Low Resolution Optical	ISRO OceanSat 2		
1056 2	Low Resolution Optical	MOS		
		SAOCOM 1A/B		
Task 3	Synthetic Aperture Radar	ICEYE		
		PAZ		
		GCOM-C1		
		SPIRE		
Task 4	Atmospheric missions	Tansat		
		Gosat-2		
		GHGSat-D		
Task 5	Multimission	DEM study		
Task 6	Workshop organization			



Input products : Level 1C

"This level of imagery is orthorectified, which implies the removal of the perspective distortion and the influence of elevation differences. The orthorectified imagery can be used a planimetric map since the scale is uniform. Accurate reference digital terrain or surface models are needed to generate Level-1C imagery."

Geometric Validation Items for L1C products

The Planimetric accuracy,

The Band-to-band registration

The Multi temporal accuracy

The stereoscopic capability.

Reference Data (With known uncertainties)

Ground Control Points set collected from testfield GPS survey,

Raster reference

Digital Elevation Data

Lidar Data

(WP210 - Geometry Sites), http://calvalportal.ceos.org/calibration-test-sites

ToolImage MatchingMedicis (CNES) &OpenCVReprojection / ResamplingGDAL, SickitData Visualization / GCP handlingQGISAccuracy / Statistical analysisNumpy, Statsmodels



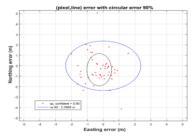


Geometric Site (dense): La Crau

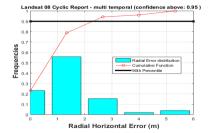
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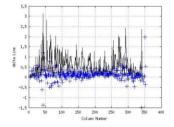


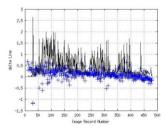
Reporting on the geometric quality











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You are here Home > EO Mission Performance > ESA 3rd Party Missions > Landsat 8 (2013 -) > OLI & TIRS > Quality Control Reports > Cyclic Quality Reports

Share I

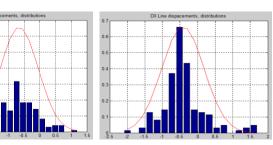
Landsat 8 Quality Reports

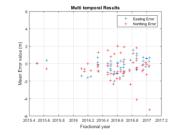
Validation activities of the Landsat 8 ESA Near Real Time (NRT) products are conducted on a monthly basis. The tests are performed on data from specific calibration / validation test sites including Libya-4 (the Pseudo Invariant Calibration Site (PICS)) and La Crau (France) (a Geometric Calibration Site). The following product specifications parameters are estimated, assessed and update:

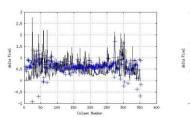
Radiometric Calibration Accuracy: By monitoring, at a given date, the OLI Top of Atmosphere (TOA)
reflectance measurements obtained from the Libya-4 test site and conducting inter-comparisons with
equivalent data acquired under the same sun illumination conditions.

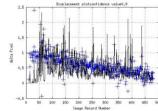
Geolocation Accuracy: By monitoring the absolute / relative geometric registration between the Landsat 8
input images and a reference image.

 Band to Band Registration Accuracy: By monitoring the overall accuracy of image registration; activities for which different combinations of image twins are considered.

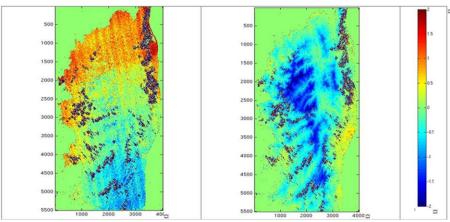




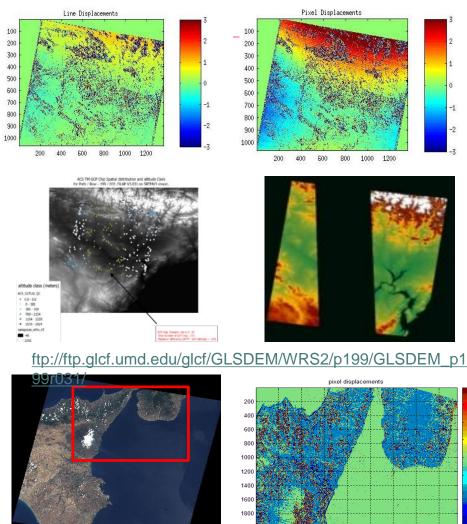




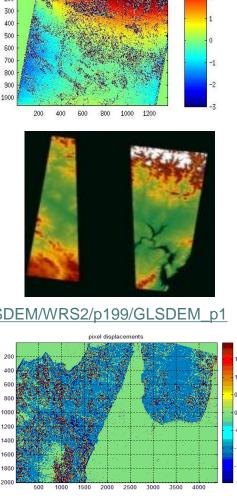
9



-3.5

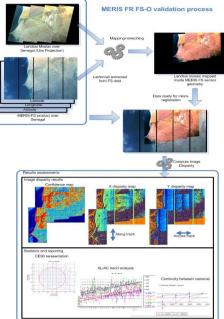


ON LIMIT = 13626823 / 51612352 (26.40) RMS = 1.171082 vs. 0.919324 (20) MINIMUM -2.000000 vs. -1.000000 MAXIMUM 000000 vs. MEAN 156528 vs. -0.812092 -0 STANDARD DEVIATION _ 1.161 vs Y DISPLACEMENT: ON LIMIT = 16142382 / 51612352 (31,2) RMS = 1.230662 vs. 0.886347 (* MINIMUM = -2.000000 vs. -1.000000 MINING... MAXIMUM = 2,000000 MAXIMUM = 2,000000 Società per azioni = -0.186541 vS. 2.000000 vs. -0.587803 STANDARD DEVIATION = 1.216 vs 0.663 (*)



Pixel Displacements

MERIS FR Full Swath; Camera pointing Validation.



Inter-channel registration errors on L1.5 image for MSG3 => Mirror Step Time Table update (Nain 2019)



- Activities :
 - Absolute geolocation accuracy by using GCP set for product observed over La Crau, Piemont & Wellington
 - Multi Temporal geolocation accuracy by using data from the constellation, whatever the patform
 - Interband registration accuracy by using data from all the sites, including (Libya 4 site).

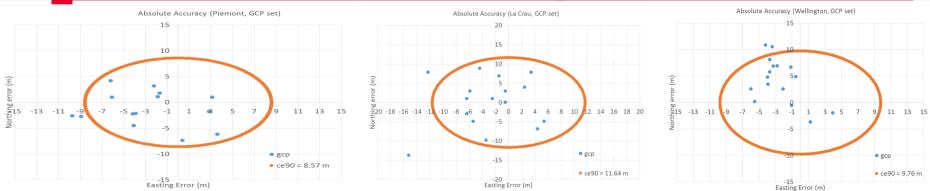
• Constraints :

- Early assessement (short time period)
- Select representative products, (different plaforms / version launch dates) ...
- Missions Specification =>
- <u>L1 Product Geometric Accuracy</u> <u>Specification (Public);</u> (10.0 m RMSE)

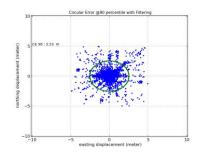
dission Characteristics	International Space Station Orbit	Sun-synchronous Orbit		
brbit Altitude (reference)	400 km (51.6° inclination)	475 km (~98° inclination)		
fax/Min Latitude Coverage	±52° (depending on season)	±81.5° (depending on season) 9:30 - 11:30 am (local solar time)		
quator Crossing Time	Variable			
ensor Type	Three-band frame Imager or four-band frame Imager with a split-frame NIR filter	Three-band frame Imager or four-band frame Imager with a split-frame NIR filter		
pectral Bands	Blue: 455 - 515 nm Green: 500 - 590 nm Red: 590 - 670 nm NIR: 780 - 860 nm	Blue: 455 - 515 nm Green: 500 - 590 nm Red: 590 - 670 nm NIR: 780 - 860 nm		
Ground Sample Distance (nadir)	3.0 m (approximate)	3.7 m		
Frame Size	20 km x 12 km (approximate)	24.6 km x 16.4 km (approximate)		
laximum Image Strip per orbit	8,100 km²	20,000 km²		
levisit Time	Variable	Daily at nadir (early 2017)		
mage Capture Capacity	Variable	200 million km²/day		

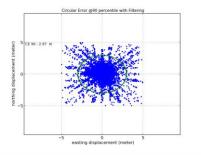
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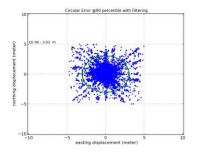
Planet DOVE Absolute geolocation

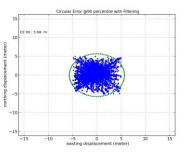


Planet DOVE Multi Temporal geolocation

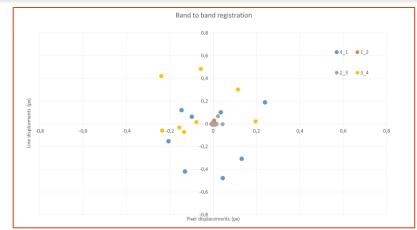








Planet DOVE Interband Registration





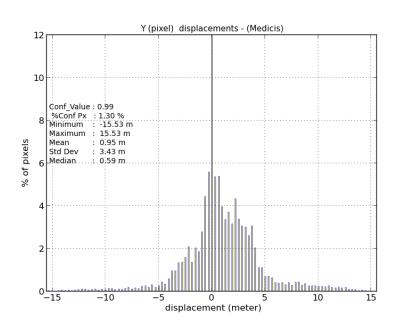
12

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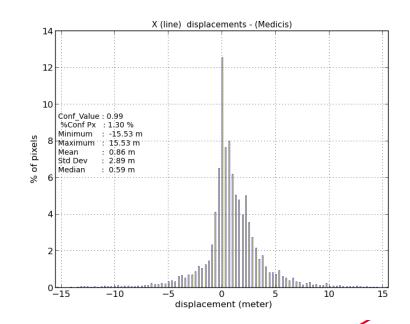
- Absolute geolocation accuracy Results fully in agreement with the product accuracy specifications (10.0 m RMSE).
- Multi Temporal geolocation accuracy

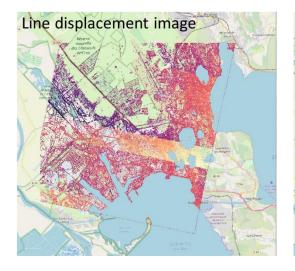
Results are correct, somehow band dependant, exceeding 5.5 m CE90 for the NIR band.

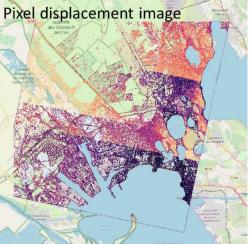
Interband registration accuracy The product RMSE accuracy is within 0.2 pixel for band twins (1,2) and (2,3) while it is above when band 4 is involved.

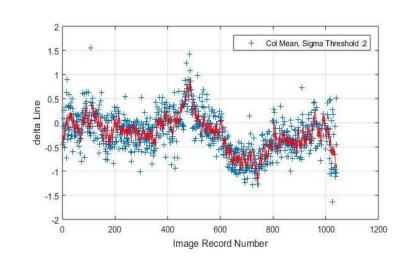


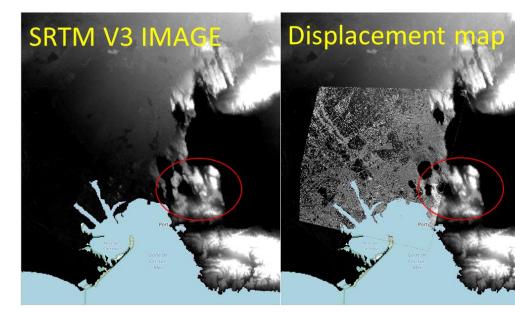
- Absolute geolocation accuracy We note that for Piemont and La Crau the CE@90 is high compared to RMSE
- Multi Temporal geolocation accuracy We note geometric distortions mosrly pronounced in the easting direction.
- Interband registration accuracy The interband registration is not stable, meaning variability in the internal image.

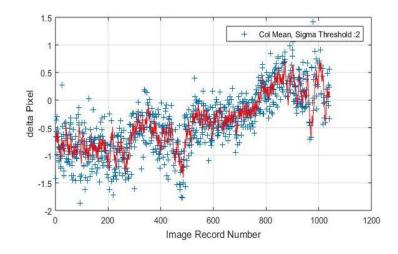














Planet DOVE Assessment 2/3

- Wellington Geometric Test Field (South Africa),
- Image comparison, at the GCP location for a same cartographic scale 1:8000).
- The image quality of input RS image influences the GCP Pointing accuracy



DOVE (RED)

@3.125 m

- Motivation 1 : Discern systematic / Non systematic effects in the Level 1C geometry, an analysis as close as possible to the sensor geometry.
- Motivation 2 : Evaluate interoperability between Missions
- Input Mission : All Landsat MSS / TM / EMT+ / OLI data, Sentinel 2 data, GLS
 - : First results presented @SPIE 2019 & Questions (for me)
- Current Method : Collect L1C data and performed Image matching in the Space Oblique Mercator between full orbits.
- Reference 1 : Evaluation of the geometric accuracy across the European Space Agency (ESA) Landsat historical archive. (Saunier & AI, 2019) , <u>https://doi.org/10.1117/12.2533198</u> (previous method)
- Reference 2 : JOHN P. SNYDER Space Oblique Mercator Projection, Mathematical development, Geological Survey Bulletin 1518.
 <u>https://pubs.usgs.gov/bul/1518/report.pdf</u>



History



The Space Oblique Mercator (SOM) map projection was developed to support LandSat which covers the same large geographic extent as MISR.

SOM was designed to minimize the shape distortion and scale errors throughout the length of the MISR swath near the satellite ground track.

SOM X is in the direction of the Spacecraft ground track and SOM Y is perpendicular X

n E. Rheingans, JPL, Cal. Tech, Workshop Sep. 19, 2005

•	[S2 data]	: No Georeferencing Model refinement with a GCP set (GRI)
		PlanetDem 90.0 m (2015)
•	[Landsat TPM data]	: Refinement with GCP set from the GLS product (ESA Process

- [Landsat TPM data] : Refinement with GCP set from the GLS product (ESA Processing) SRTM V3.0
- [Landsat 8 data]

© 2019 Leonar

 Refinement with GCP set from GLS product, Collection-1 products. (INFO : LS8 L1C data processing with GCP adjusted to the GRI foreseen for Collection-2 (1st Quarter 2020))

S2A	S2B	GLS	LT5	LS8	LT7	LM5
(R094)	(R094)	(WRS P 201)	(WRS P 201)	(WRS P 201)	(WRS P 201)	(WRS P 201)
	(R094) 2019/10/01 (125 Tiles), 2019/10/11 (141 Tiles)	(WRS P 201) p201r024_7dt20000619 p201r025_7dt20020913 p201r026_7dt2000721 p201r027_7dt20010521 p201r030_7dt20000619 p201r031_7dt20000619 p201r032_7dt20020422 p201r033_7dt20020422 p201r034_7dt20020422 p201r036_7dt20010606 p201r037_7dt20000502 p201r038_7dt20000502 p201r039_7dt20000502 p201r039_7dt20000331 p201r040_7dt20010214 p201r041_7dt20010129			(WRS P 201) 2000/04/16	(WRS P 201)
		p201r042_7dt20010129 p201r043_7dt20010129				
		p201r044_7dt20010129				
		p201r045_7dt20010521				
		p201r046_7dt20010214				
d		p201r047_7dt20010214				
~		p201r048_7dt20011231				

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Constellation Assessment / «Orbit» Analysis - statistical results

Image Matching Results, orbit configuration, (confidence: 0.95), unit: meter, AL: Along Track, AC: ACross Track							
Twin	total	median	mean	std	median	mean	std
	valid	AL	AL	AL	AC	AC	AC
	pixel						
GLS_LM5	927	-7,97	-7,04	31,32	4,22	4,22	77,72
GLS_LT5	7455	-0,70	-0,70	14,00	-1,17	-0,73	17,11
GLS_LS7	6080	-1,41	-1,41	10,41	-2,58	-2,14	12,51
GLS_LS8 (20141024)	22966	0,47	0,61	6,71	-1,88	-1,81	7,76
		_					
GLS_S2B (20191001)	5759	8,67	8,44	11,63	-13,83	-14,27	13,18
LS8-S2A (20191006)	24241	0,94	0,62	9,69	-9,14	-12,31	14,94
LS8-S2A (20180802)	6011	18,52	12,26	30,08	-4,69	-6,90	18,01
LS8-S2B (20191001)	15031	5,63	4,98	11,05	-9,14	- 10,30	11,32
LS8-S2B (20191011)	7562	7,03	8,47	11,86	-19,69	-22,50	17,45
S2A (20191006)	61232	4 22	4.00	2.24	2 11	1 61	2.06
S2B (20191001)	01232	4,22	4,00	2,34	-2,11	-1,61	3,06



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Constellation Assessment / «Orbit» Analysis - matching results S2A / S2B





Constellation Assessment / «Orbit» Analysis - matching results

GLS / LM5 (MSS) GLS / LT5 (TM)

WRS2 de S2A-S2E

> -0.57 -0.125

-0.2

0.5 GLS-LT

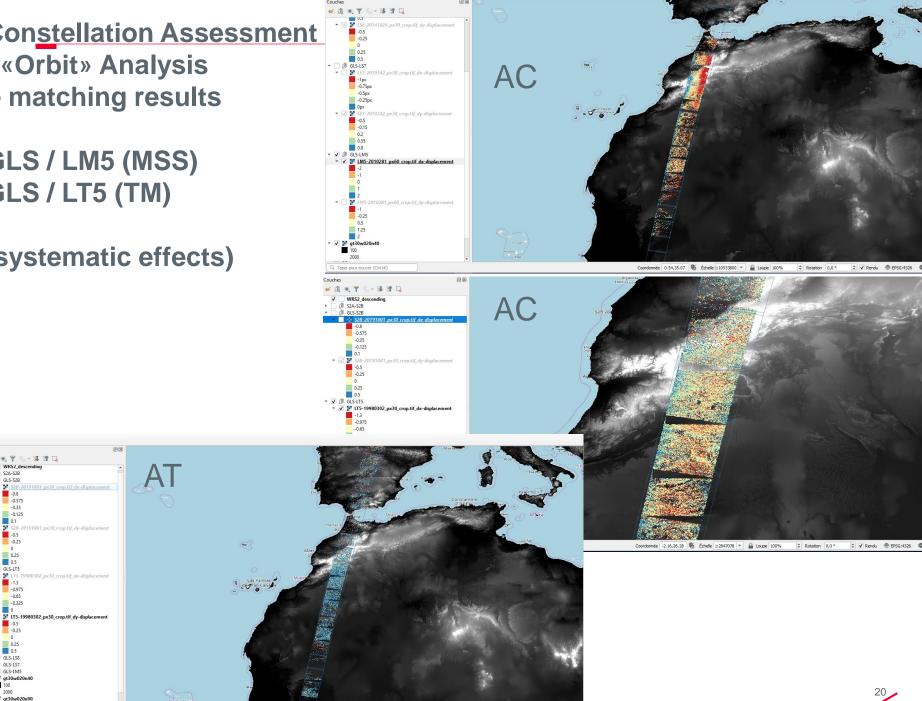
> -0.975 -0.65 -0.325

> > -0.5 -0.2

GLS-LS GLS-LS GLS-LM at30w02

dt30w020n9

(systematic effects)

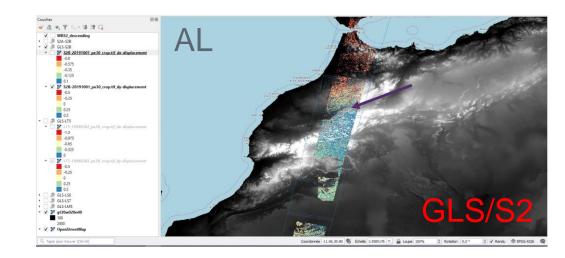


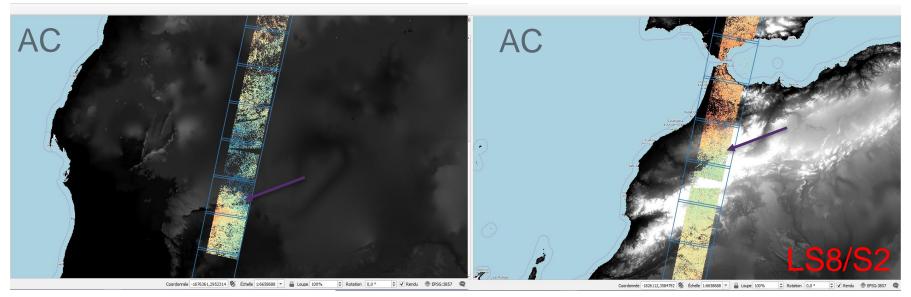
Coordonnée -3.61,28.57 🗞 Échele 1:11496884 🔻 🔒 Loupe 100% Rotation 0,0 ° @ EPSG:4326

Constellation Assessment / «Orbit» Analysis matching results

GLS/ S2, LS8 / S2

(non systematic)





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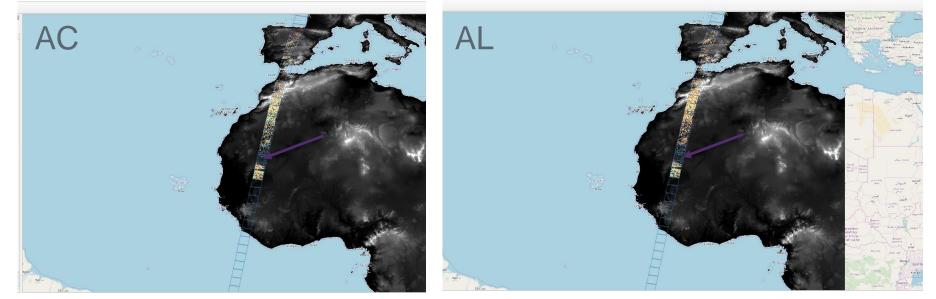
Constellation Assessment / «Orbit» Analysis matching results

GLS / LS8

For some regions, the image information to be matched is poor.

(The Level 1 processing might failed to find and accurate GCP set for georeferencing?)

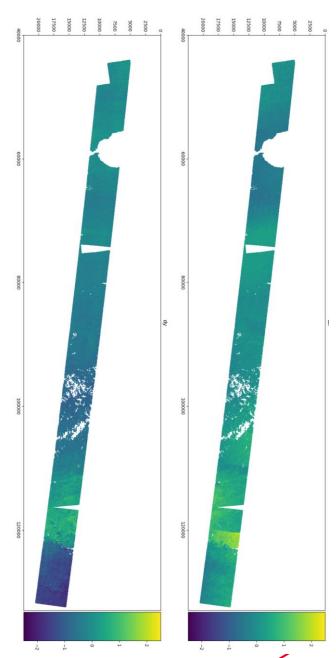






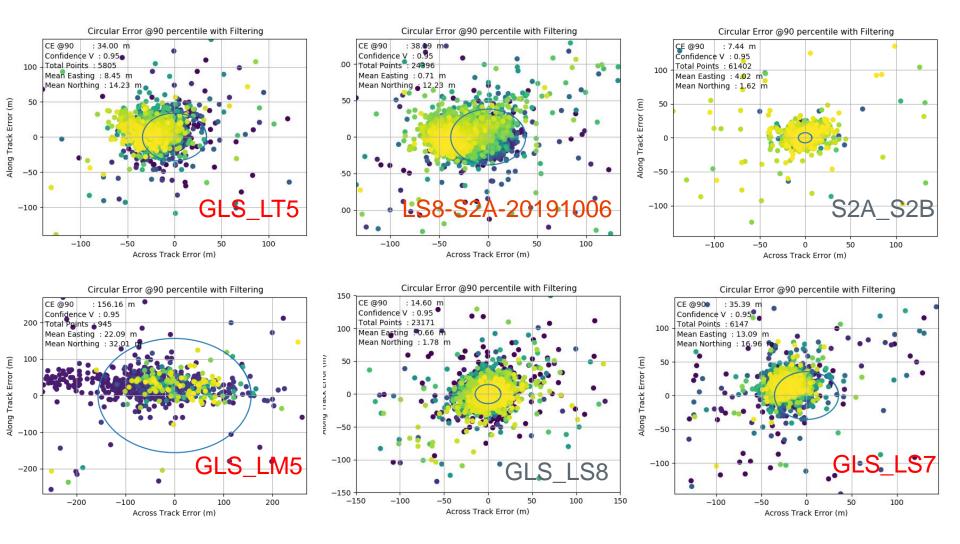
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- Assessing with an Alternative methods for matching (LS8/S2)
- Promising results !!!
- Deviation confirms



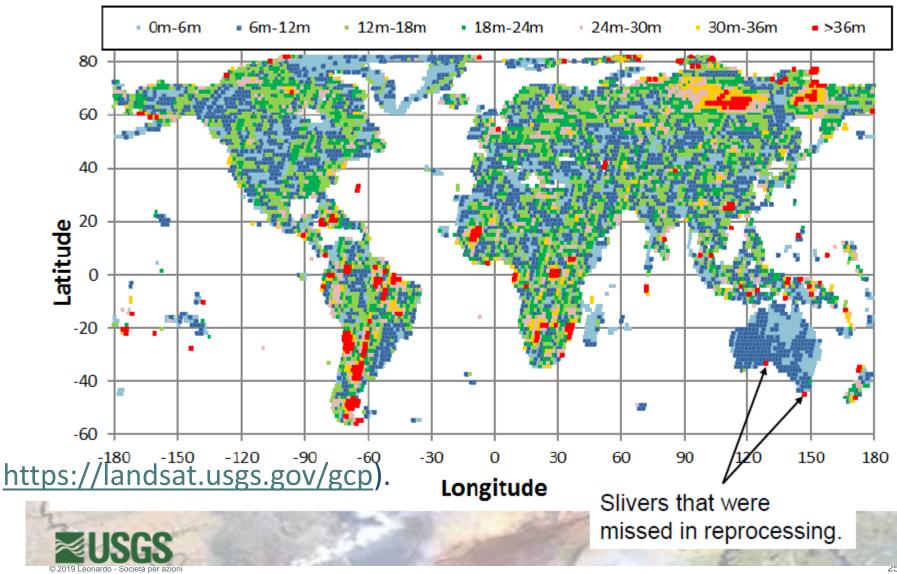
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Hello world



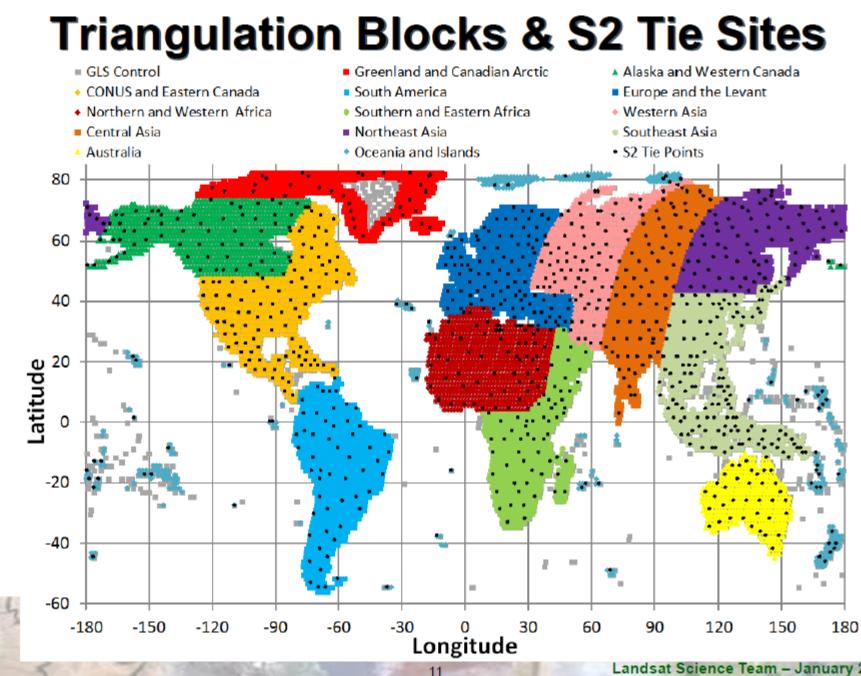
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L8 Estimate of GLS Horizontal Error



- Task 1 EDAP framework for geometric analysis is set up and used in an operational way to assess input missions.
- The reference data are essential
- The proposed QC / Validation methodologies provides consistent accuracy measured,
- It has been shown that the analysis of products for a long term orbit period is usefull.

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Landsat Science Team – January 20

sured Landsat 8 / Sentinel 2 egistration

registration accuracy was measured at 255 sites. I results before and after L8-only triangulation:

				# Scenes or				
	# Scenes			Blocks	L8 Trig	L8 Trig		
lock	or Blocks	Net RMSEr	2σ Difference	Completed	RMSEr	2σ		
tern Canada	13	13.272	18.769	13	10.953	15.490		
	10	9.900	14.000	10	9.900	14.000		
	19	19.653	27.794					
	16	13.787	19.498	16	6.618	9.359		
Levant	93	15.135	21.404	93	8.682	12.279		
anadian Arctic	8	18.692	26.435	8	13.670	19.333		
	29	16.945	23.964					
estern Africa	11	14.789	20.915	11	7.361	10.411		
	12	18.593	26.295	12	7.662	10.836		
	8	16.080	22.741					
istern Africa	15	16.369	23.150	15	9.634	13.624		
	21	12.936	18.294	21	9.102	12.872		
	255	15.622	22.093	199	9.017	12.751		
	12	15.744	22.265	9	9.502	13.438		

Outils de recherc

Commentai

🔔 Remplir et s

🔏 Autres outil



THANK YOU FOR YOUR ATTENTION

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