



Maximum Likelihood Analysis of the RVoG Model for Forestry Studies in PolInSAR

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→ **POLINSAR 2013**

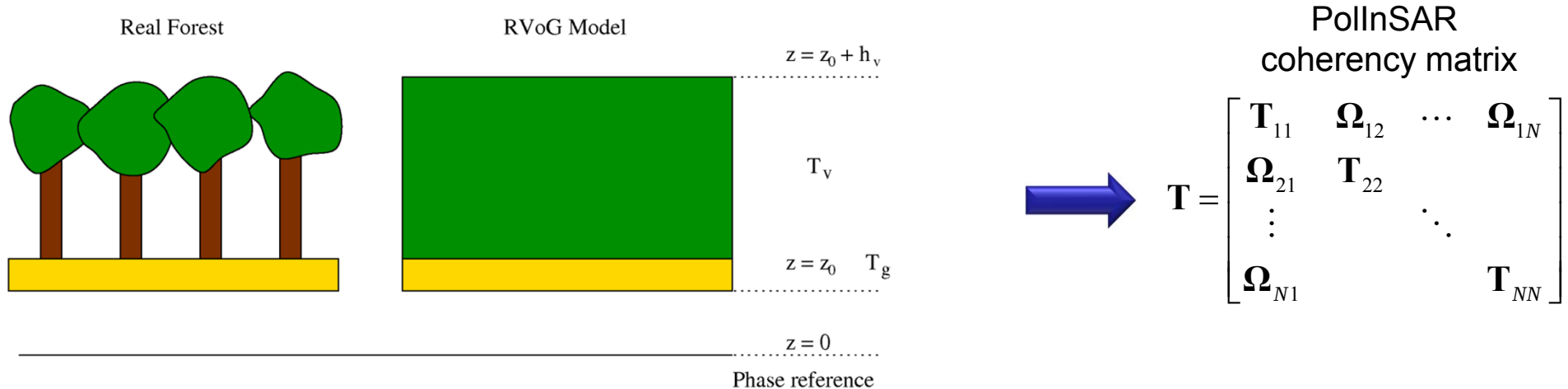
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- RVoG/Line model
- Coherence Linearity Hypothesis
- Validation and Estimation based on the RVoG/Line model
 - SB-PolInSAR
 - MB-PolInSAR
- Results & Comparison at P&L-band data
- Conclusions

Polarimetric SAR Interferometry

Random Volume over Ground **RVoG** scattering model or **Line** model

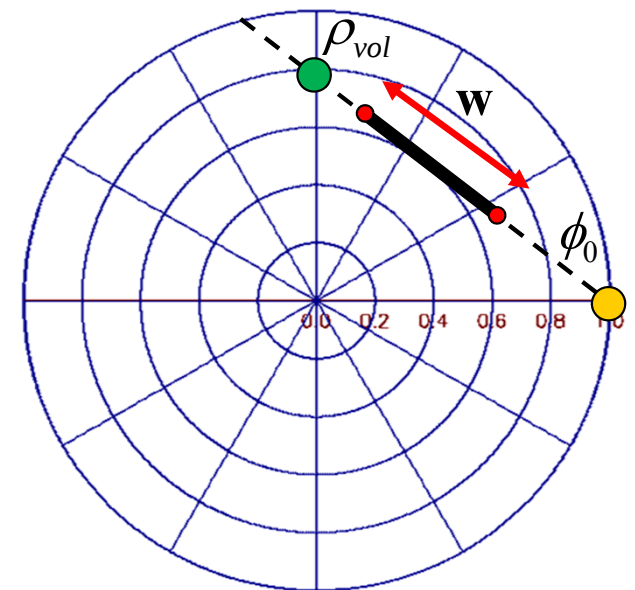


Interferometric coherence as a function of polarization $\mathbf{w}$

- Describes a line in the complex plane

$$\rho(\mathbf{w}) = e^{j\phi_0} \left(\rho_{vol} + \frac{\mu(\mathbf{w})}{1 + \mu(\mathbf{w})} (1 - \rho_{vol}) \right)$$

- **Slope**: Baseline, Veg. height, extinction, ground phase
- **Length**: Baseline, veg. height, extinction, Ground-to-Volume ratio $\mu(\mathbf{w})$



Polarimetric SAR Interferometry Statistics

Statistical description of SB-PolInSAR data. Extension to MB-PolInSAR is straightforward

$$\mathbf{k}_{p,1} = \frac{1}{\sqrt{2}} \begin{bmatrix} S_{hh,1} + S_{vv,1} \\ S_{hh,1} - S_{vv,1} \\ 2S_{hv,1} \end{bmatrix}$$

$$\mathbf{k}_{p,2} = \frac{1}{\sqrt{2}} \begin{bmatrix} S_{hh,2} + S_{vv,2} \\ S_{hh,2} - S_{vv,2} \\ 2S_{hv,2} \end{bmatrix}$$

$$\mathbf{k} = \begin{bmatrix} \mathbf{k}_{p,1} \\ \mathbf{k}_{p,2} \end{bmatrix}$$

$$\mathbf{T} = E \{ \mathbf{k} \mathbf{k}^H \} = \begin{bmatrix} \mathbf{T}_{11} & \mathbf{\Omega}_{12} \\ \mathbf{\Omega}_{12}^H & \mathbf{T}_{22} \end{bmatrix}$$

$$\mathbf{T} = \begin{bmatrix} \mathbf{T}_{11}^{1/2} & 0 \\ 0 & \mathbf{T}_{22}^{1/2} \end{bmatrix} \begin{bmatrix} \mathbf{I} & \tilde{\mathbf{\Omega}}_{12} \\ \tilde{\mathbf{\Omega}}_{12}^H & \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{T}_{11}^{1/2} & 0 \\ 0 & \mathbf{T}_{22}^{1/2} \end{bmatrix}$$

PolInSAR
coherency matrix

Multidimensional, zero-mean, complex Gaussian/Wishart PDF

$$\mathbf{k} = \begin{bmatrix} S_1 \\ S_2 \\ \vdots \\ S_m \end{bmatrix}$$

$$S_k = N_{C^2} \left(0, \sigma^2 / 2 \right)$$

$$\mathbf{Z} = \frac{1}{n} \sum_{i=1}^n \mathbf{k}_i \mathbf{k}_i^H$$

$$\mathbf{Z} \sim W(n, \mathbf{T})$$

Wishart PDF

$$p_{\mathbf{Z}}(\mathbf{Z}) = \frac{n^{mn} |\mathbf{Z}|^{n-m}}{|\mathbf{T}|^n \tilde{\Gamma}_m(n)} \text{etr}(-n\mathbf{T}^{-1}\mathbf{Z})$$

$$\text{Limitations} \begin{cases} \mathbf{Z} \quad \mathbf{T} \text{ Positive definite} \\ n \geq m \end{cases}$$

Conditions imposed by the RVoG model on the data, i.e., coherency matrix

- Polarimetric stationarity hypothesis (PS)

$$\rho_v = e^{j\phi_0} \frac{\int_0^{h_v} F(z) e^{jk_z z} dz}{\int_0^{h_v} F(z) dz} \quad \Rightarrow \quad \mathbf{T}_{11} = \mathbf{T}_{22} \quad \Rightarrow \quad \rho(\mathbf{w}) = \frac{\mathbf{w}^H \mathbf{\Omega}_{12} \mathbf{w}}{\mathbf{w}^H \mathbf{T}_{11} \mathbf{w}}$$

- Interferometrically polarimetric stationarity hypothesis (IPS)

$$\tilde{\mathbf{\Omega}}_{12} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^H \quad \Rightarrow \quad \tilde{\mathbf{\Omega}}_{12}^H \tilde{\mathbf{\Omega}}_{12} = \tilde{\mathbf{\Omega}}_{12} \tilde{\mathbf{\Omega}}_{12}^H \quad \tilde{\mathbf{\Omega}}_{12} \text{ is a normal matrix}$$

- Coherence linearity (CL)

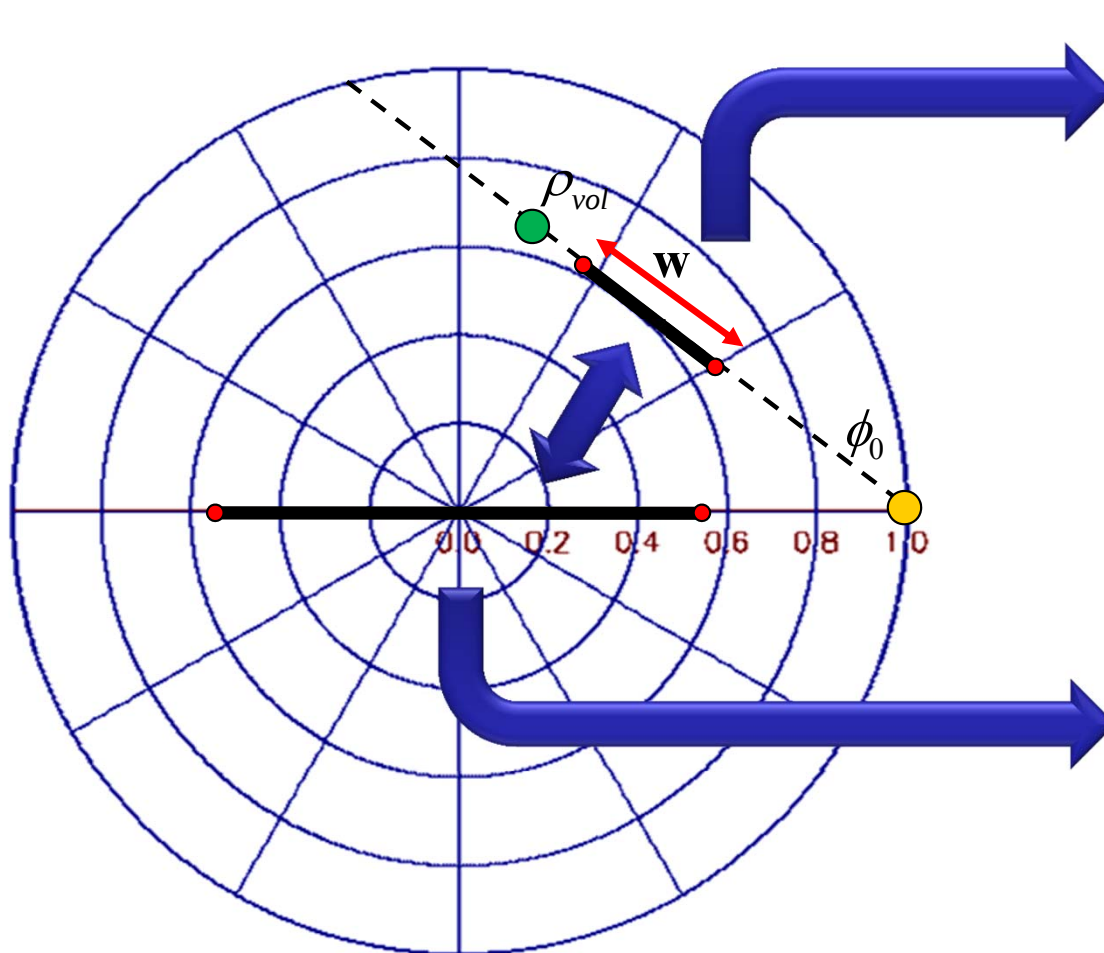
- $\rho(\mathbf{w})$ presents a linear behavior wrt $\mathbf{w}$ in the complex plane
- Does not result from PS and IPS hypotheses

Question: How to relate the CL hypothesis with a property of the coherency matrix?

Coherence Linearity Hypothesis

How to consider the CL hypothesis in terms of the coherency matrix ?

- **Mathematical conditions** imposed in the coherency matrix by CL



Depends on Ω_{12} or $\tilde{\Omega}_{12}$

Complex coherence $\rho(\mathbf{w})$ as a function of $\mathbf{w}$

Hermitian matrices present real eigenvalues that describe a line

CL is related with the **property of Hermiticity** of a matrix

- For real PolInSAR data, in presence of speckle, the transform needs to be **more general than translations and rotations**

Numerical Range

The interferometric coherence can be explored in terms of the **numerical range** of the matrix $\tilde{\Omega}_{12}$

$$W(\tilde{\Omega}_{12}) = \left\{ \mathbf{v}^H \tilde{\Omega}_{12} \mathbf{v}, \mathbf{v} \in \mathbb{C}^3, \mathbf{v}^H \mathbf{v} = 1 \right\}$$

For a given complex matrix $\mathbf{A}$ and a unitary vector $\mathbf{x}^H \mathbf{x} = 1$

$$\mathbf{H}_1 = \frac{\mathbf{A} + \mathbf{A}^H}{2}$$

Hermitian
part

$$\mathbf{H}_2 = \frac{\mathbf{A} - \mathbf{A}^H}{2j}$$

Non-Hermitian
part



$$\Re\{W(\mathbf{A})\} = \mathbf{x}^H \mathbf{H}_1 \mathbf{x}$$

$$\Im\{W(\mathbf{A})\} = \mathbf{x}^H \mathbf{H}_2 \mathbf{x}$$



If $\Im\{W(\mathbf{A})\} = 0$ $\mathbf{H}_2 = \mathbf{0}$, then
 $W(\mathbf{A})$ is a line in the real
axis

$$\mathbf{A} = \mathbf{H}_1 + j\mathbf{H}_2$$

If $\mathbf{A}$ is an Hermitian matrix, $W(\mathbf{A})$ is a line in the real axis, so the interferometric coherence describes a line and the **CL hypothesis applies**

In general, $\tilde{\Omega}_{12}$ is a **non-Hermitian matrix**

Affine Transformation in the Complex Plane

In geometry, an affine transformation is a transformation which **preserves straight lines** and **ratios of distances between points lying on a straight line**. It does not necessarily preserve angles or lengths

- **Translation**, geometric contraction, expansion, dilation, reflection, **rotation**, shear, similarity transformations, and spiral similarities

Affine transformations allow to transform straight lines in the complex plane

$$\begin{aligned} \tau_{abc}(\rho) &= a\Re\{\rho\} + jb\Im\{\rho\} + c, \quad \{a, b, c\} \in \mathbb{R} \\ \tau_{abc}(\rho) &= a\mathbf{x}^H \mathbf{H}_1 \mathbf{x} + jb\mathbf{x}^H \mathbf{H}_2 \mathbf{x} + c \\ \tau_{abc}(\mathbf{A}) &= a\mathbf{H}_1 + jb\mathbf{H}_2 + c\mathbf{I} = \mathbf{A}^\tau = \mathbf{H}_1^\tau + j\mathbf{H}_2^\tau \end{aligned} \quad \left\{ \begin{array}{l} \{a, b, c\} \text{ such that } \tau_{abc}(\rho) \in \mathbb{R} \\ \downarrow \\ \mathbf{A}^\tau \text{ is an Hermitian matrix} \end{array} \right.$$

Affine equivalent matrices

The numerical range of a matrix $\mathbf{A}$ is a line segment in the complex plane if it is **affine equivalent** to an Hermitian matrix. In terms of the interferometric coherence, it describes a line in the complex plane

Affine Transformation in the Complex Plane

Affine and Inverse Affine transformation maps

$$\begin{array}{ccc}
 \mathbf{A} = \mathbf{H}_1 + j\mathbf{H}_2 & \xrightarrow[\text{AT}]{\tau_{abc}} & \mathbf{A}^\tau = a\mathbf{H}_1 + jb\mathbf{H}_2 + c\mathbf{I} \\
 \uparrow & & \downarrow \\
 \mathbf{A} = a'\mathbf{H}_1^\tau + jb'\mathbf{H}_2^\tau + c'\mathbf{I} & \xleftarrow[\tau_{abc}^{-1} = \tau_{a'b'c'}]{\text{IAT}} & \mathbf{A}^\tau = \mathbf{H}_1^\tau + j\mathbf{H}_2^\tau
 \end{array}$$

The transform coefficients $\{a, b, c\} \in \mathbb{C}$ can be obtained by considering

$$\tilde{\mathbf{\Omega}}_{12} = a'\mathbf{H}_1^\tau + jb'\mathbf{H}_2^\tau + c'\mathbf{I} \quad \Rightarrow \quad \mathbf{H}_2^\tau = \mathbf{0}$$

$$\Rightarrow \mathbf{H}_2^\tau = \frac{\tilde{\mathbf{\Omega}}_{12}^\tau - \tilde{\mathbf{\Omega}}_{12}^{\tau H}}{2j} = \frac{(a\mathbf{H}_1 + jb\mathbf{H}_2 + c\mathbf{I}) - (a\mathbf{H}_1 + jb\mathbf{H}_2 + c\mathbf{I})^H}{2j} = \mathbf{0}$$

- In **absence of speckle noise**, $\{a, b, c\} \in \mathbb{C}$ can be obtained and define a **line transformation**
- In **presence of speckle noise**, there is no solution for $\{a, b, c\} \in \mathbb{C}$, but the following minimization can be adopted. It defines a **general affine transformation**

$$a, b, c = \arg \min_{a, b, c} |\mathbf{v}^H \mathbf{H}_2^\tau \mathbf{v}|$$

$$|\mathbf{v}^H \mathbf{H}_2^\tau \mathbf{v}|^2 \leq \|\mathbf{H}_2^\tau\|_2^2$$



$$a, b, c = \arg \min_{a, b, c} \|\mathbf{H}_2^\tau\|_2 = \arg \min_{a, b, c} \text{tr}(\mathbf{H}_2^{\tau H} \mathbf{H}_2^\tau)$$

Maximum Likelihood Analysis of the RVoG

The numerical range of a matrix $\mathbf{A}$ is a line segment in the complex plane if it is **affine equivalent** to an Hermitian matrix. In terms of the interferometric coherence, it describes a line in the complex plane

- **General structure** of the coherency matrix

$$\mathbf{T} = \begin{bmatrix} \mathbf{T}_{11} & \mathbf{\Omega}_{12} \\ \mathbf{\Omega}_{12}^H & \mathbf{T}_{22} \end{bmatrix}$$

- Based on the Affine Transformation it is possible to define the **structure of the coherency matrix under the RVoG hypothesis**

$$\mathbf{T}_{RVoG} = \begin{bmatrix} \mathbf{T}_{11} & \mathbf{T}_{11}^{1/2} \tilde{\mathbf{\Omega}}_{12} \mathbf{T}_{11}^{1/2} \\ \mathbf{T}_{11}^{1/2} \tilde{\mathbf{\Omega}}_{12} \mathbf{T}_{11}^{1/2} & \mathbf{T}_{11} \end{bmatrix} = \begin{bmatrix} \mathbf{T}_{11} & \mathbf{T}_{11}^{1/2} (a' \mathbf{H}_1^\tau + c' \mathbf{I}) \mathbf{T}_{11}^{1/2} \\ \mathbf{T}_{11}^{1/2} (a' \mathbf{H}_1^\tau + c' \mathbf{I}) \mathbf{T}_{11}^{1/2} & \mathbf{T}_{11} \end{bmatrix}$$

- **Generalized Likelihood Ratio Test (GLRT)** in the **original domain**

$$\begin{array}{l} H_0 : \mathbf{T} = \mathbf{T}_{RVoG} \\ H_1 : \mathbf{T} \end{array} \quad \Rightarrow \quad \Lambda_{RVoG} = \frac{p_Z(\mathbf{Z}; \hat{\mathbf{T}}_{RVoG}, H_0)}{p_Z(\mathbf{Z}; \hat{\mathbf{T}}, H_1)} \underset{H_1}{\overset{H_0}{>}} \gamma$$

Maximum Likelihood Analysis of the RVoG

In the **original domain**, the GLRT must **estimate**: $\{\mathbf{T}_{11}, \mathbf{H}_1^\tau, a', c'\}$

If the estimation is considered in the affined transformed domain

- **General structure** of the coherency matrix

$$\mathbf{T}^\tau = \begin{bmatrix} \mathbf{T}_{11} & \mathbf{T}_{11}^{1/2} (\mathbf{H}_1^\tau + j\mathbf{H}_2^\tau) \mathbf{T}_{22}^{1/2} \\ \mathbf{T}_{11}^{1/2} (\mathbf{H}_1^\tau + j\mathbf{H}_2^\tau) \mathbf{T}_{22}^{1/2} & \mathbf{T}_{22} \end{bmatrix}$$

- **Structure of the coherency matrix under the RVoG hypothesis**

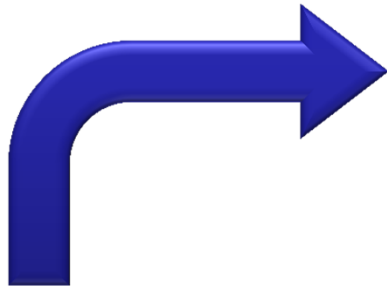
$$\mathbf{T}_{RVoG}^\tau = \begin{bmatrix} \mathbf{T}_{11} & \mathbf{T}_{11}^{1/2} \mathbf{H}_1^\tau \mathbf{T}_{11}^{1/2} \\ \mathbf{T}_{11}^{1/2} \mathbf{H}_1^\tau \mathbf{T}_{11}^{1/2} & \mathbf{T}_{11} \end{bmatrix} = \begin{bmatrix} \mathbf{T}_{11} & \mathbf{\Omega}_{12}^\tau \\ \mathbf{\Omega}_{12}^\tau & \mathbf{T}_{11} \end{bmatrix}$$

- **Generalized Likelihood Ratio Test (GLRT)** in the **transformed domain**

$$\begin{array}{l} H_0 : \mathbf{T} = \mathbf{T}_{RVoG} \\ H_1 : \mathbf{T} \end{array} \quad \Rightarrow \quad \Lambda_{RVoG}^\tau = \frac{p_{\mathbf{Z}}(\mathbf{Z}^\tau; \hat{\mathbf{T}}_{RVoG}^\tau, H_0)}{p_{\mathbf{Z}}(\mathbf{Z}^\tau; \hat{\mathbf{T}}^\tau, H_1)} \underset{H_1}{\overset{H_0}{>}} \gamma$$

Maximum Likelihood Analysis of the RVoG

Calculation of the Generalized Likelihood Ratio Test



$$\text{Maximized } \mathbf{Z}_{RVoG}^{\tau} = \begin{bmatrix} \frac{\mathbf{Z}_{11} + \mathbf{Z}_{22}}{2} & \frac{\mathbf{Z}_{12}^{\tau} + (\mathbf{Z}_{12}^{\tau})^H}{2} \\ \frac{\mathbf{Z}_{12}^{\tau} + (\mathbf{Z}_{12}^{\tau})^H}{2} & \frac{\mathbf{Z}_{11} + \mathbf{Z}_{22}}{2} \end{bmatrix}$$

$$\Lambda_{RVoG}^{\tau} = \frac{p_{\mathbf{Z}}(\mathbf{Z}^{\tau}; \hat{\mathbf{T}}_{RVoG}^{\tau}, H_0)}{p_{\mathbf{Z}}(\mathbf{Z}^{\tau}; \hat{\mathbf{T}}^{\tau}, H_1)} \underset{H_1}{\overset{H_0}{>}} \gamma$$

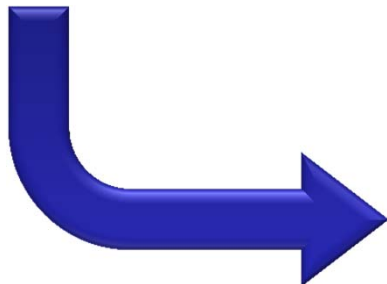
$$\Lambda_{RVoG}^{\tau} = \left(\frac{|\mathbf{Z}^{\tau}|}{|\mathbf{Z}_{RVoG}^{\tau}|} \right)^n = \left(\frac{|\mathbf{Z}_{11}| |\mathbf{Z}_{22}|}{\left| \frac{\mathbf{Z}_{11} + \mathbf{Z}_{22}}{2} \right|^2} \right)^n \left(\frac{|\mathbf{I} - \tilde{\mathbf{Z}}_{12}^{\tau} \tilde{\mathbf{Z}}_{21}^{\tau}|}{|\mathbf{I} - \tilde{\mathbf{Z}}_{12,RVoG}^{\tau} \tilde{\mathbf{Z}}_{21,RVoG}^{\tau}|} \right)^n$$

PS hypothesis

$$\Lambda_{PS}^{\tau}$$

CL hypothesis

$$\Lambda_{CL}^{\tau}$$



$$\text{Maximized } \mathbf{Z}^{\tau} = \begin{bmatrix} \mathbf{Z}_{11} & \mathbf{Z}_{12}^{\tau} \\ (\mathbf{Z}_{12}^{\tau})^H & \mathbf{Z}_{22} \end{bmatrix}$$

Maximum Likelihood Analysis of the RVoG

The **MLE estimation** of the covariance matrix under the RVoG model assumption is obtained in the **transformed domain** by the affine transformation

$$\mathbf{Z}_{RVoG}^{\tau} = \begin{bmatrix} \frac{\mathbf{Z}_{11} + \mathbf{Z}_{22}}{2} & \frac{\mathbf{Z}_{12}^{\tau} + (\mathbf{Z}_{12}^{\tau})^H}{2} \\ \frac{\mathbf{Z}_{12}^{\tau} + (\mathbf{Z}_{12}^{\tau})^H}{2} & \frac{\mathbf{Z}_{11} + \mathbf{Z}_{22}}{2} \end{bmatrix}$$

To obtain the estimated coherency matrix in the original domain, the **inverse affine transformation** must be applied

$$\mathbf{Z}_{RVoG} = \begin{bmatrix} \frac{\mathbf{Z}_{11} + \mathbf{Z}_{22}}{2} & \left(\frac{\mathbf{Z}_{11} + \mathbf{Z}_{22}}{2} \right)^{\frac{1}{2}} \left(a' \left(\frac{\tilde{\mathbf{Z}}_{12}^{\tau} + (\tilde{\mathbf{Z}}_{12}^{\tau})^H}{2} \right) + c' \mathbf{I}_3 \right) \left(\frac{\mathbf{Z}_{11} + \mathbf{Z}_{22}}{2} \right)^{\frac{1}{2}} \\ \left(\left(\frac{\mathbf{Z}_{11} + \mathbf{Z}_{22}}{2} \right)^{\frac{1}{2}} \left(a' \left(\frac{\tilde{\mathbf{Z}}_{12}^{\tau} + (\tilde{\mathbf{Z}}_{12}^{\tau})^H}{2} \right) + c' \mathbf{I}_3 \right) \left(\frac{\mathbf{Z}_{11} + \mathbf{Z}_{22}}{2} \right)^{\frac{1}{2}} \right)^H & \frac{\mathbf{Z}_{11} + \mathbf{Z}_{22}}{2} \end{bmatrix}$$

Extension to MB-PolInSAR

Straightforward extension to MB-PolInSAR

- The previous analysis can be considered for all the Ω_{ij} PolInSAR matrices, i.e, PolInSAR pairs

$$\mathbf{T} = \begin{bmatrix} \mathbf{T}_{11} & \Omega_{12} & \cdots & \Omega_{1N} \\ \Omega_{21} & \mathbf{T}_{22} & & \\ \vdots & & \ddots & \\ \Omega_{N1} & & & \mathbf{T}_{NN} \end{bmatrix}$$



$$\mathbf{Z} = \begin{bmatrix} \mathbf{Z}_{11} & \mathbf{Z}_{12} & \cdots & \mathbf{Z}_{1N} \\ \mathbf{Z}_{21} & \mathbf{Z}_{22} & & \\ \vdots & & \ddots & \\ \mathbf{Z}_{N1} & & & \mathbf{Z}_{NN} \end{bmatrix}$$

Unrestricted MLE

$$\mathbf{T}_{RVoG} = \begin{bmatrix} \mathbf{T}_{11} & \Omega_{12} & \cdots & \Omega_{1N} \\ \Omega_{21} & \mathbf{T}_{11} & & \\ \vdots & & \ddots & \\ \Omega_{N1} & & & \mathbf{T}_{11} \end{bmatrix}$$



$$\mathbf{Z}_{RVoG} = \begin{bmatrix} \mathbf{Z}_{Avg} & \mathbf{Z}_{12} & \cdots & \mathbf{Z}_{1N} \\ \mathbf{Z}_{21} & \mathbf{Z}_{Avg} & & \\ \vdots & & \ddots & \\ \mathbf{Z}_{N1} & & & \mathbf{Z}_{Avg} \end{bmatrix}$$

$$\Omega_{ij} = \mathbf{T}_{11}^{1/2} \left(a'_{ij} \mathbf{H}_{1,ij}^{\tau} + c'_{ij} \mathbf{I} \right) \mathbf{T}_{11}^{1/2}$$

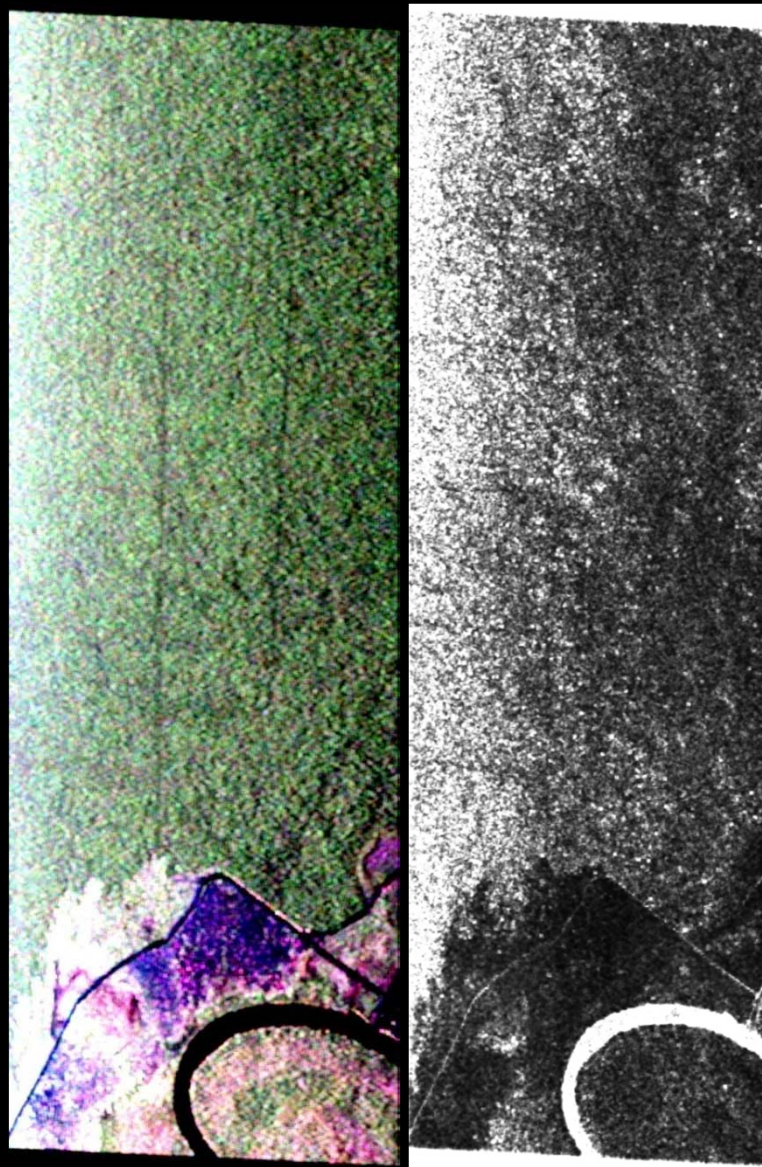
$$\mathbf{Z}_{ij} = \mathbf{Z}_{Avg}^{\frac{1}{2}} \left(a'_{ij} \left(\frac{\tilde{\mathbf{Z}}_{ij}^{\tau} + (\tilde{\mathbf{Z}}_{ij}^{\tau})^H}{2} \right) + c'_{ij} \mathbf{I}_3 \right) \mathbf{Z}_{Avg}^{\frac{1}{2}}$$

$$\mathbf{Z}_{Avg} = \frac{1}{N} \sum_{k=1}^N \mathbf{Z}_{kk}$$

Results: Real PolInSAR Data

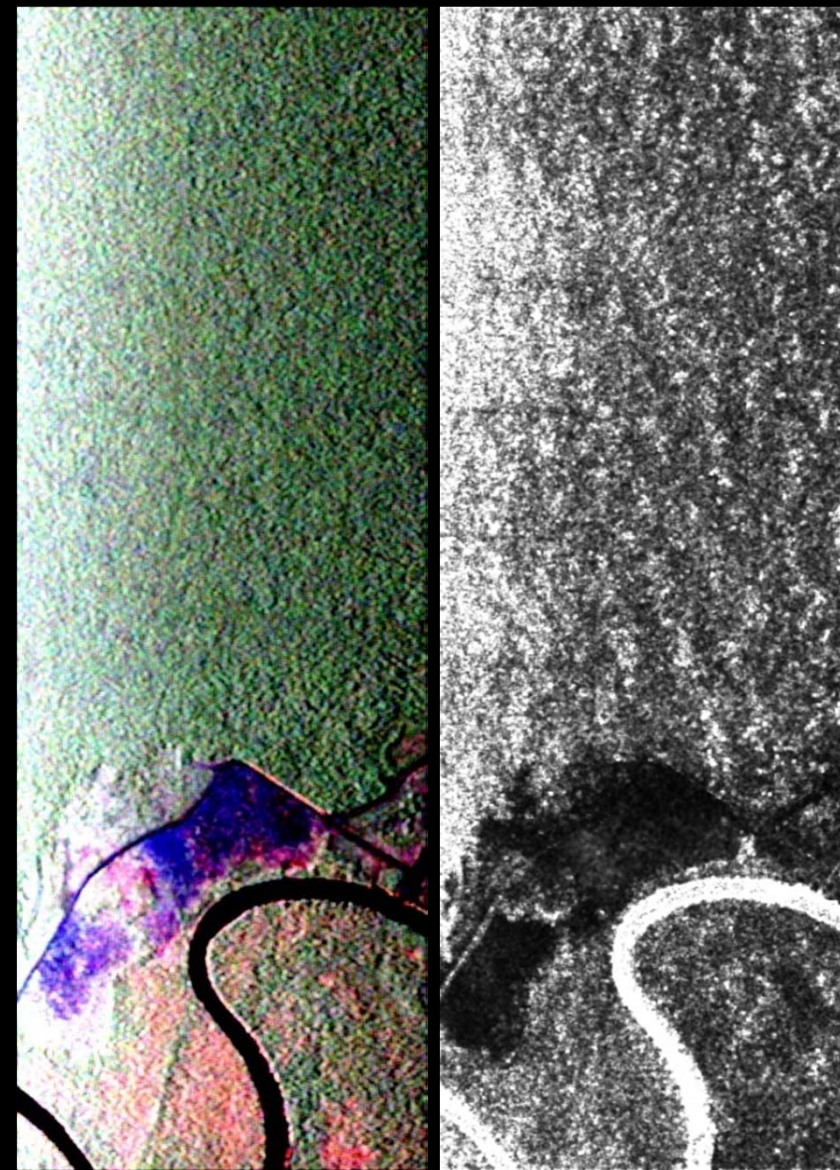
PolInSAR data: E-SAR INDREX-II Campaign **Tropical Forest**

P-band B=15m



$|HH+VV|$ $|HV|$ $|HH-VV|$ $-2 \ln(\Lambda_{RVoG}^\tau)$

L-band B=5m



$|HH+VV|$ $|HV|$ $|HH-VV|$ $-2 \ln(\Lambda_{RVoG}^\tau)$

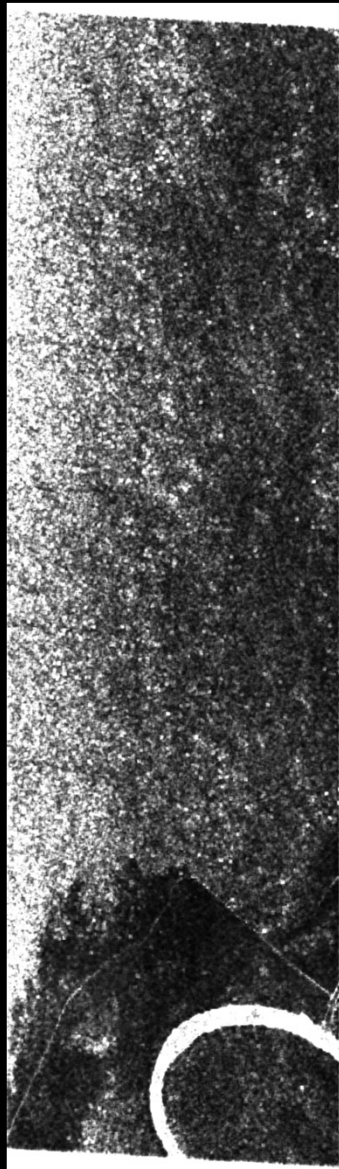
Data provided by ESA



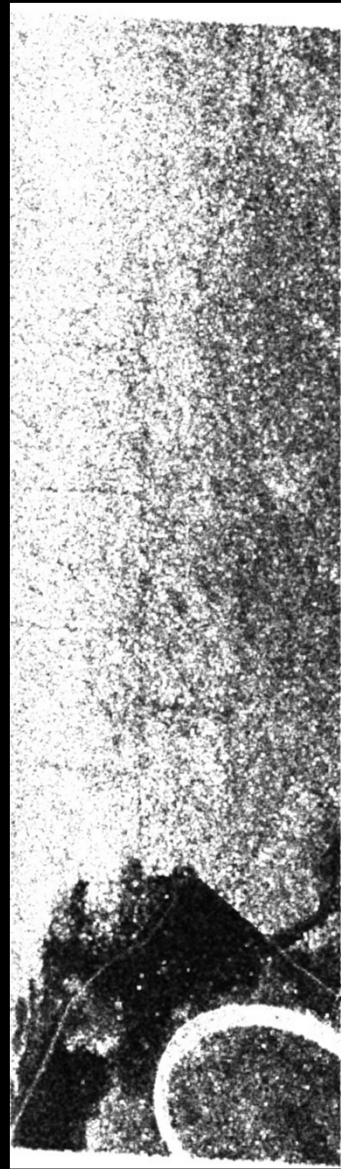
Results: Real PolInSAR Data

PolInSAR data: E-SAR INDREX-II Campaign **Tropical Forest**

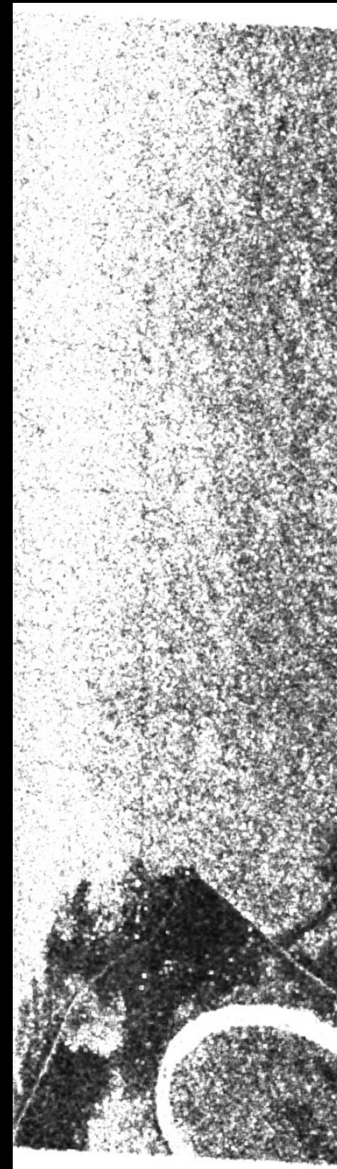
P-band



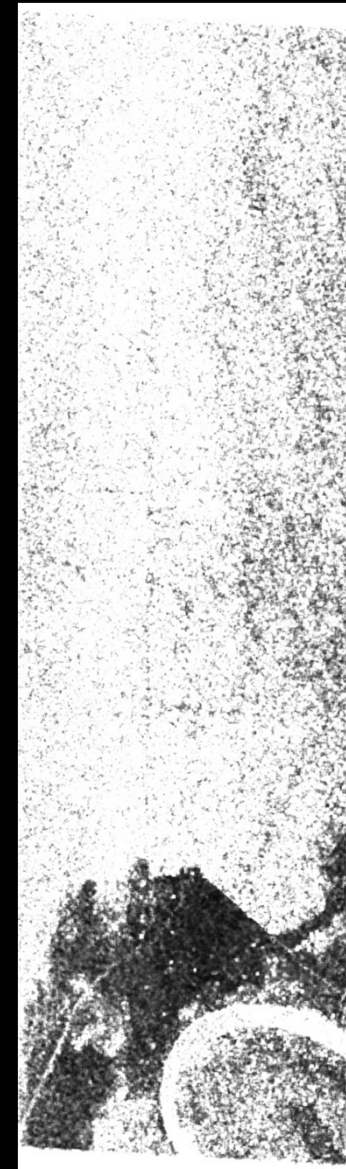
B=15m



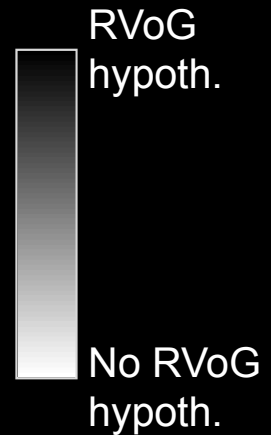
B=25m



B=30m



B=40m



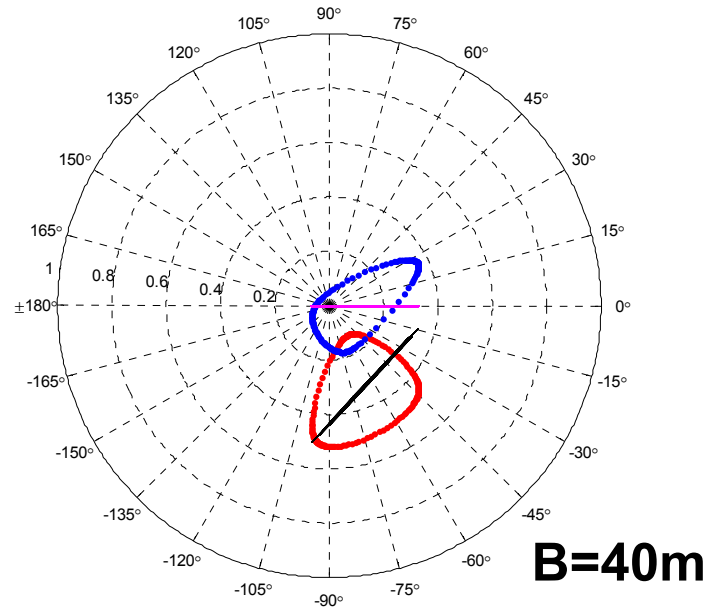
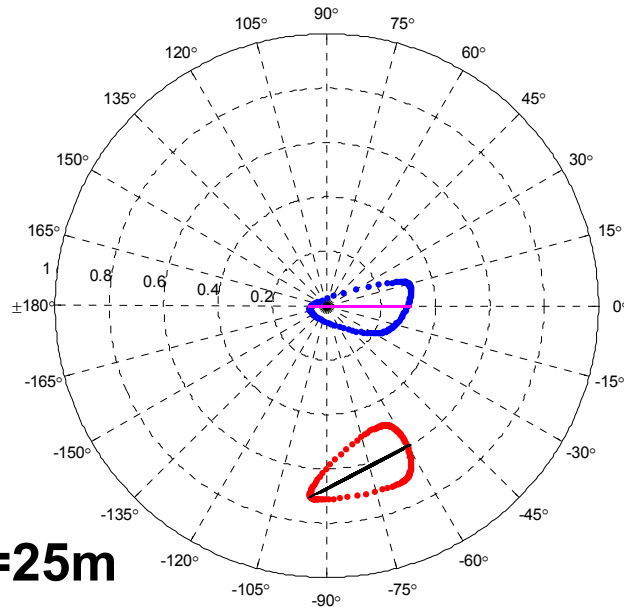
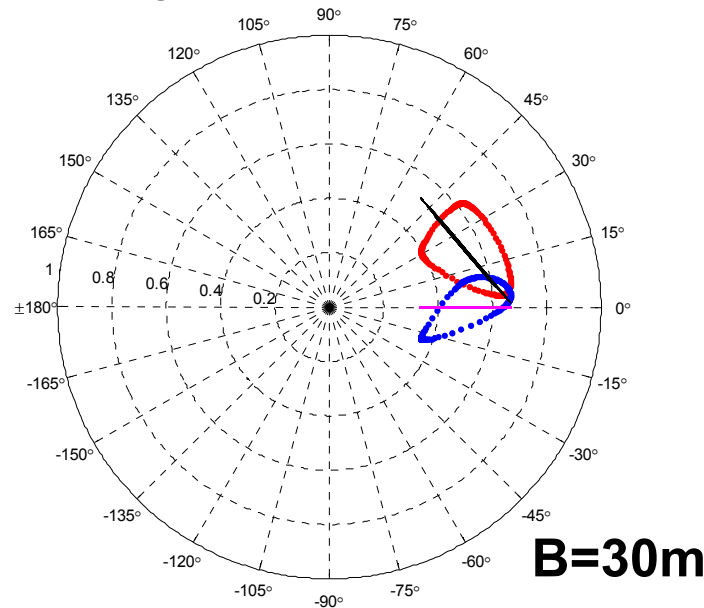
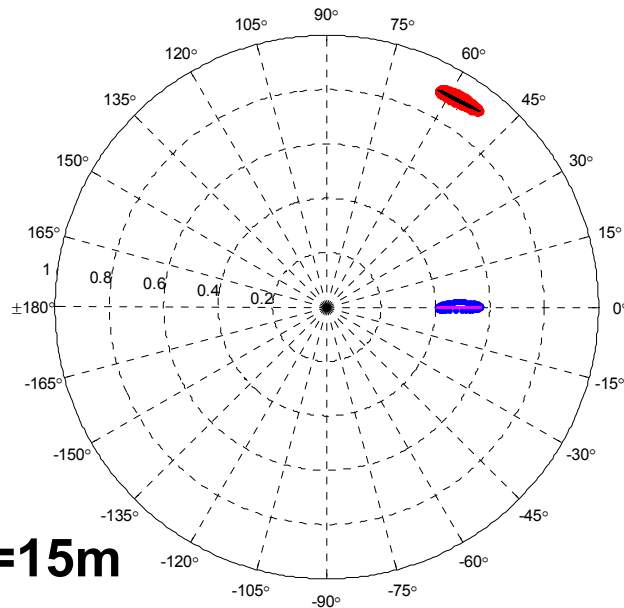
$$-2 \ln \left(\Lambda_{RVoG}^{\tau} \right)$$

Data provided
by ESA



Results: Real PolInSAR Data

PolInSAR data: E-SAR INDREX-II Campaign **Tropical Forest**



The four CRs refer to the same pixel

Estimated CR from multilook

Estimated CR from ML

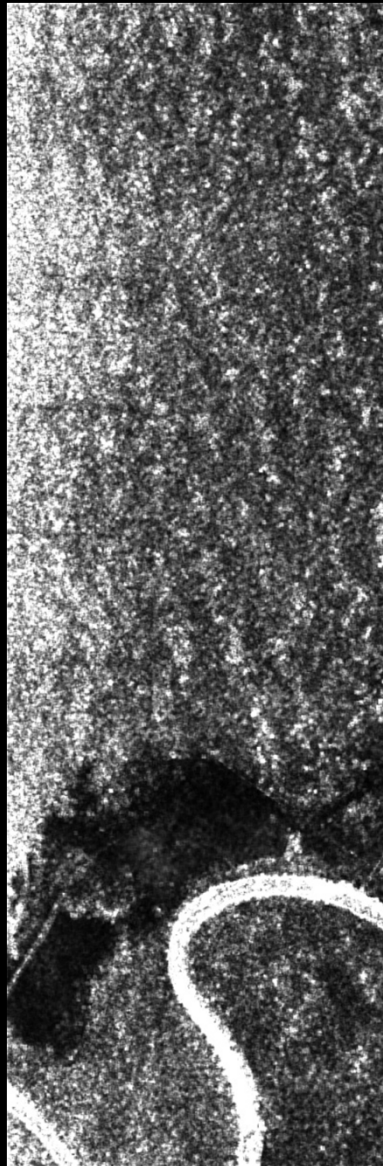
Estimated CR from multilook (transformed)

Estimated CR from ML (transformed)

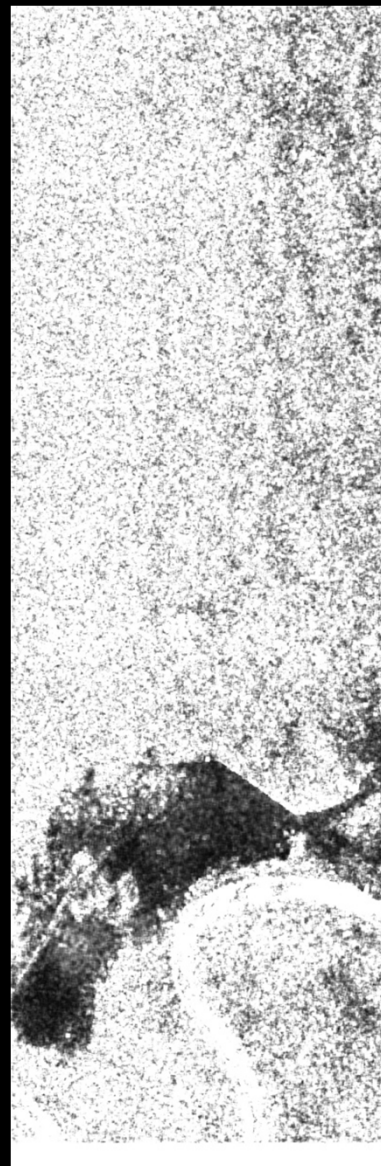
Results: Real PolInSAR Data

PolInSAR data: E-SAR INDREX-II Campaign **Tropical Forest**

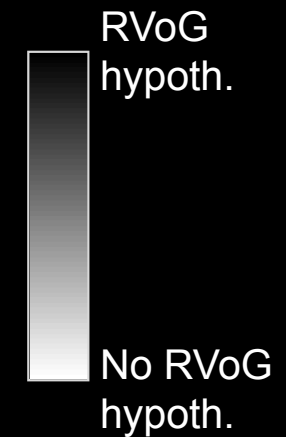
L-band



B=5m



B=15m



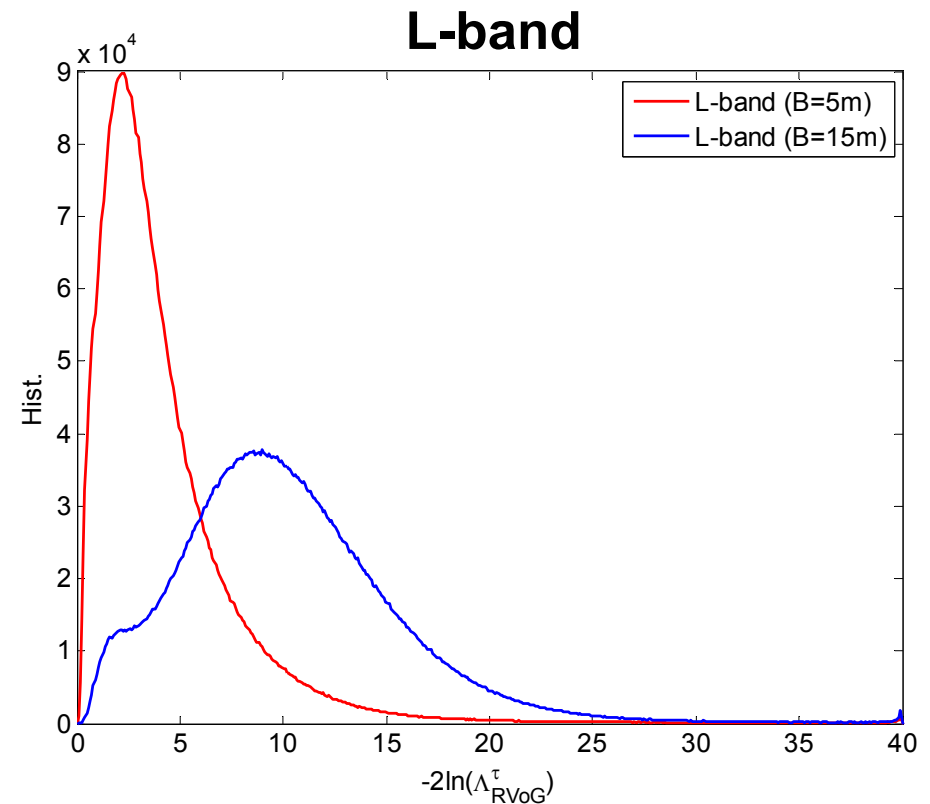
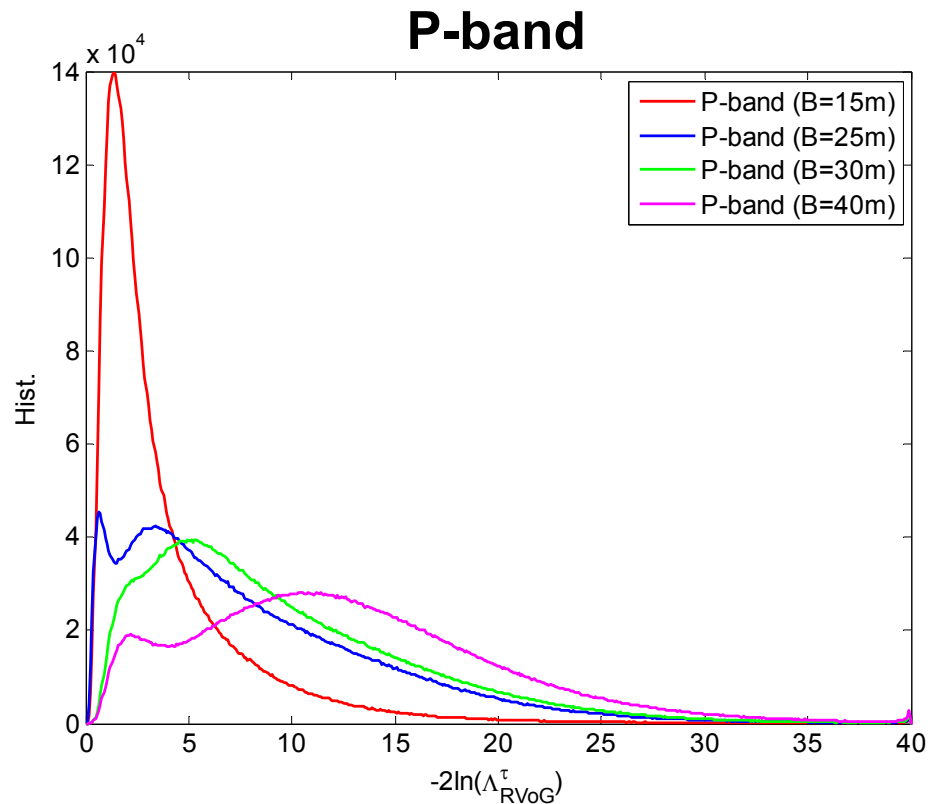
$$-2 \ln \left(\Lambda_{RVoG}^{\tau} \right)$$

Data provided
by ESA



Results: Real PolInSAR Data

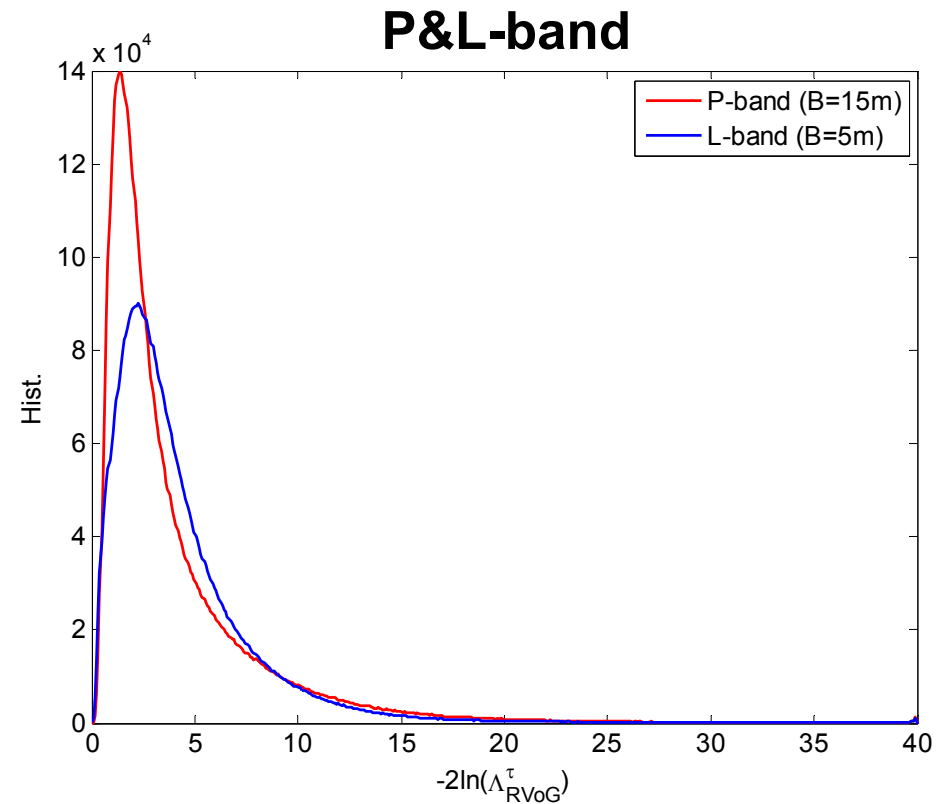
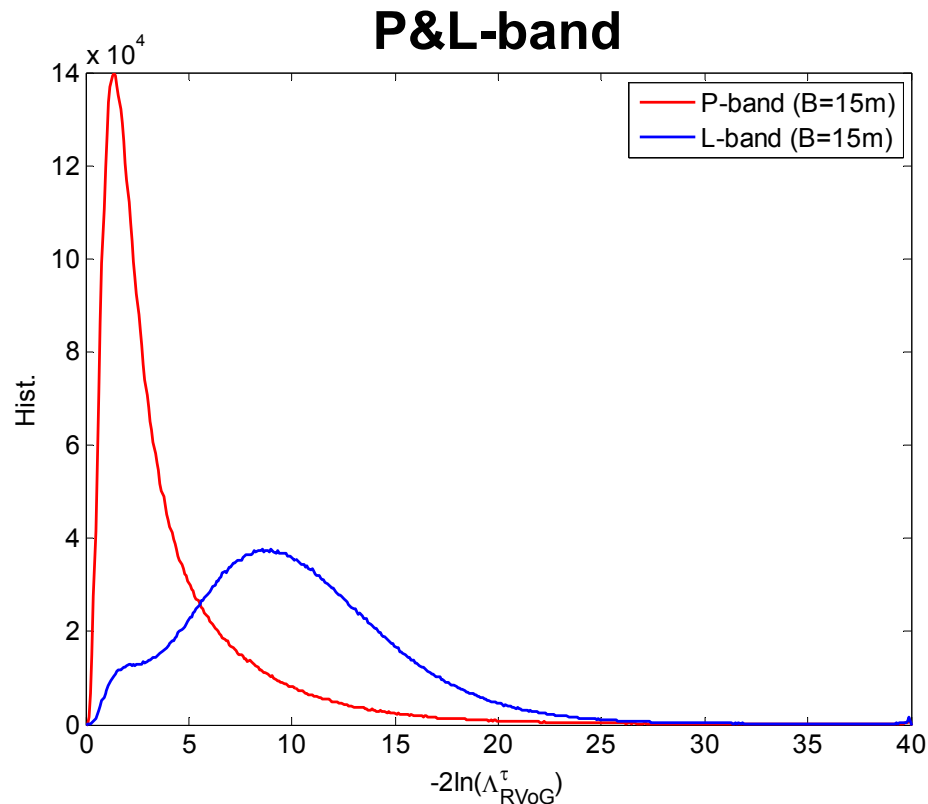
PolInSAR data: E-SAR INDREX-II Campaign **Tropical Forest**



- The **validity** of the RVoG **model hypothesis** depends on the spatial baseline

Results: Real PolInSAR Data

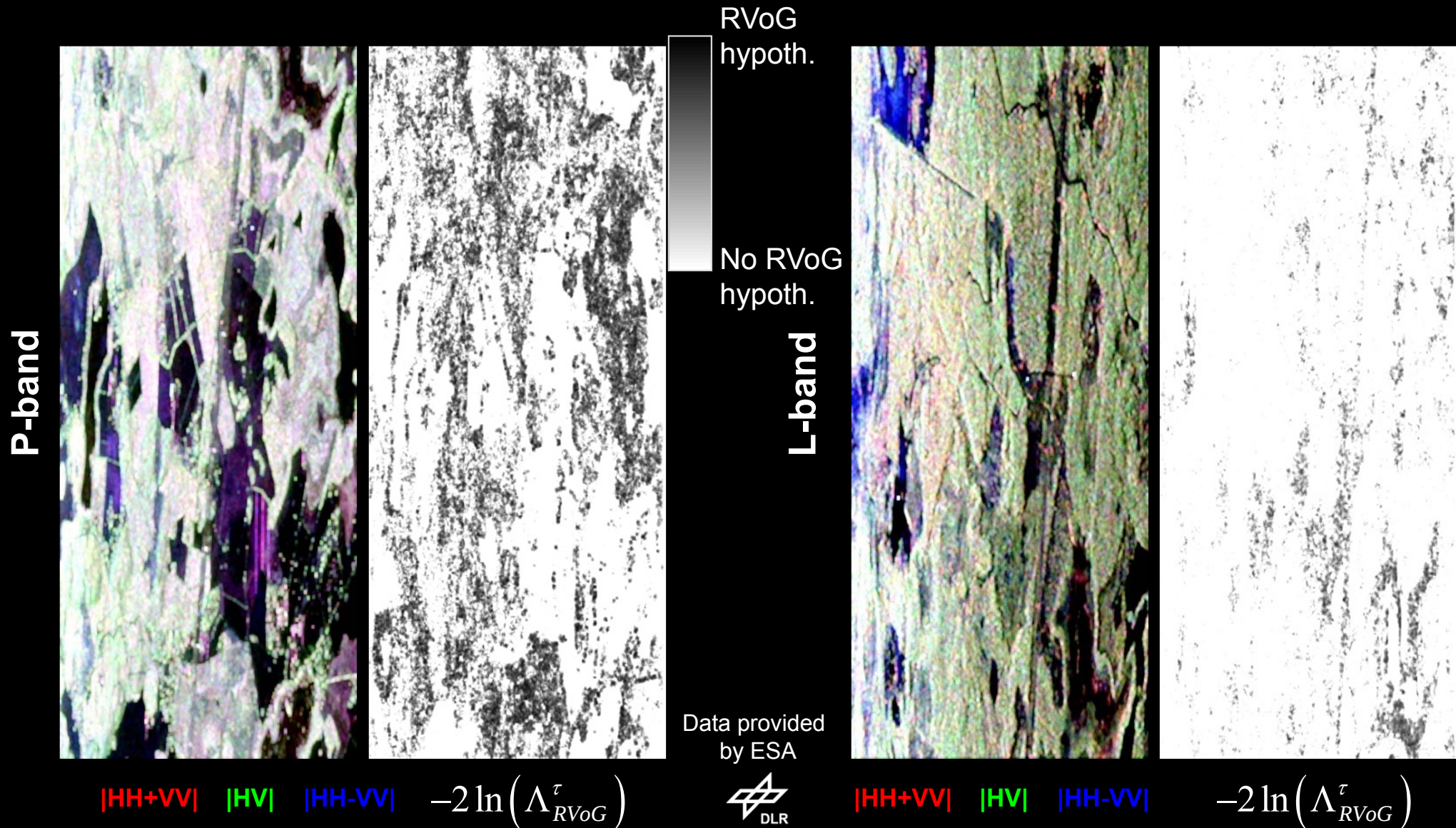
PolInSAR data: E-SAR INDREX-II Campaign **Tropical Forest**



- The **validity** of the RVoG **model hypothesis** is equal at P- and L-bands, but considering different baselines. In the same conditions, the validity is larger at P-band

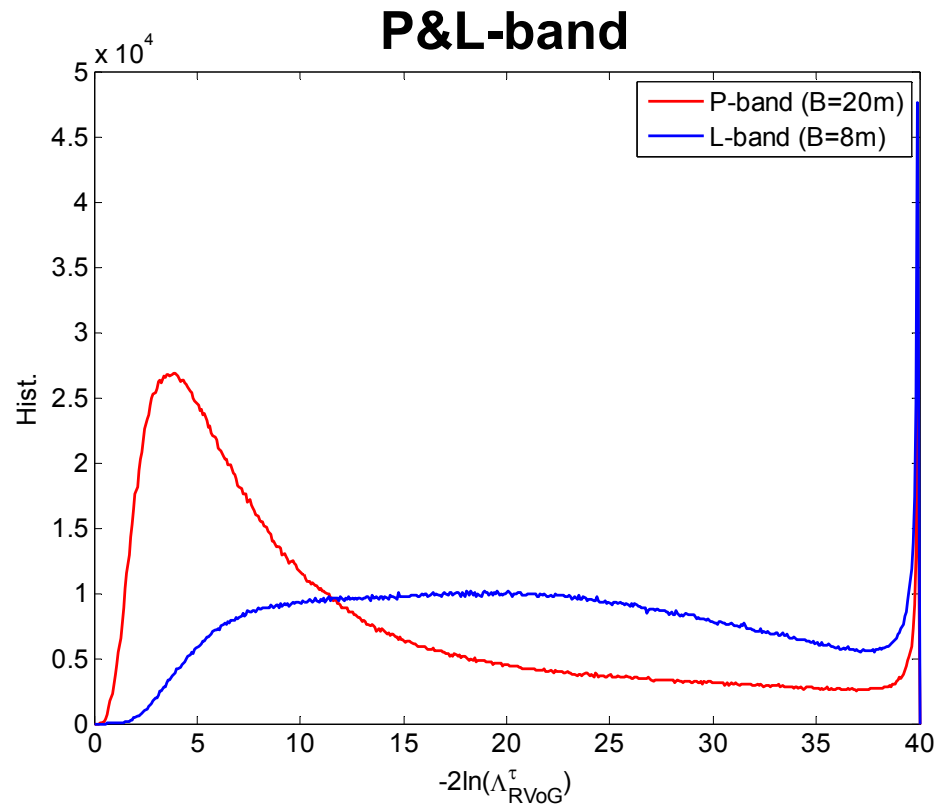
Results: Real PolInSAR Data

PollnSAR data: E-SAR BioSAR-1 Campaign **Boreal Forest**



Results: Real PolInSAR Data

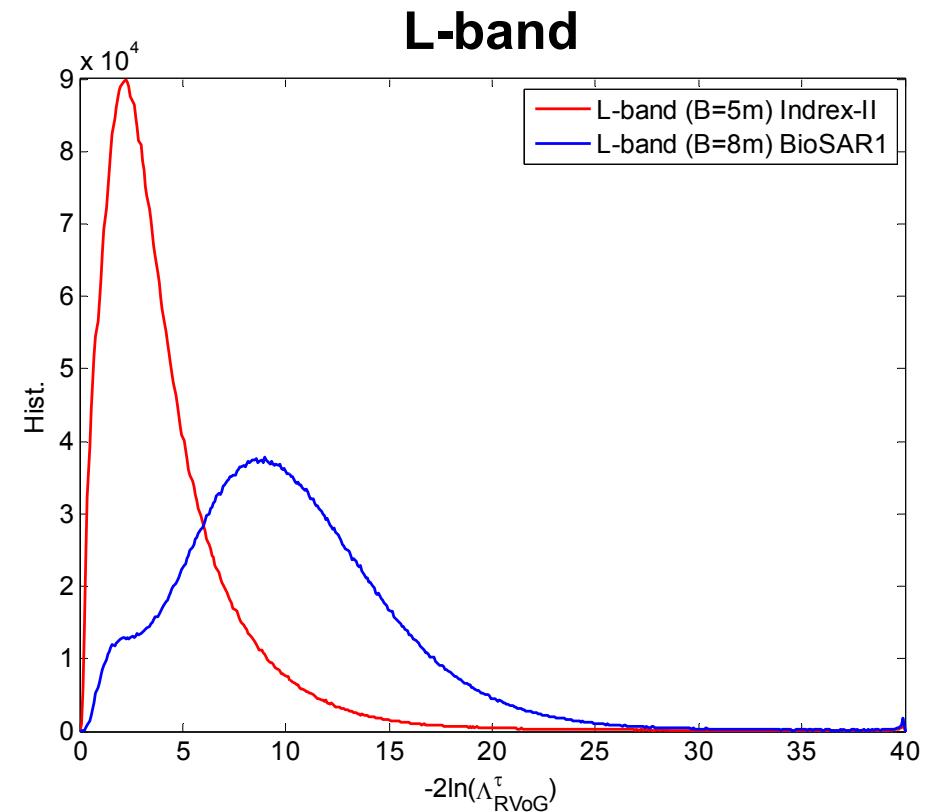
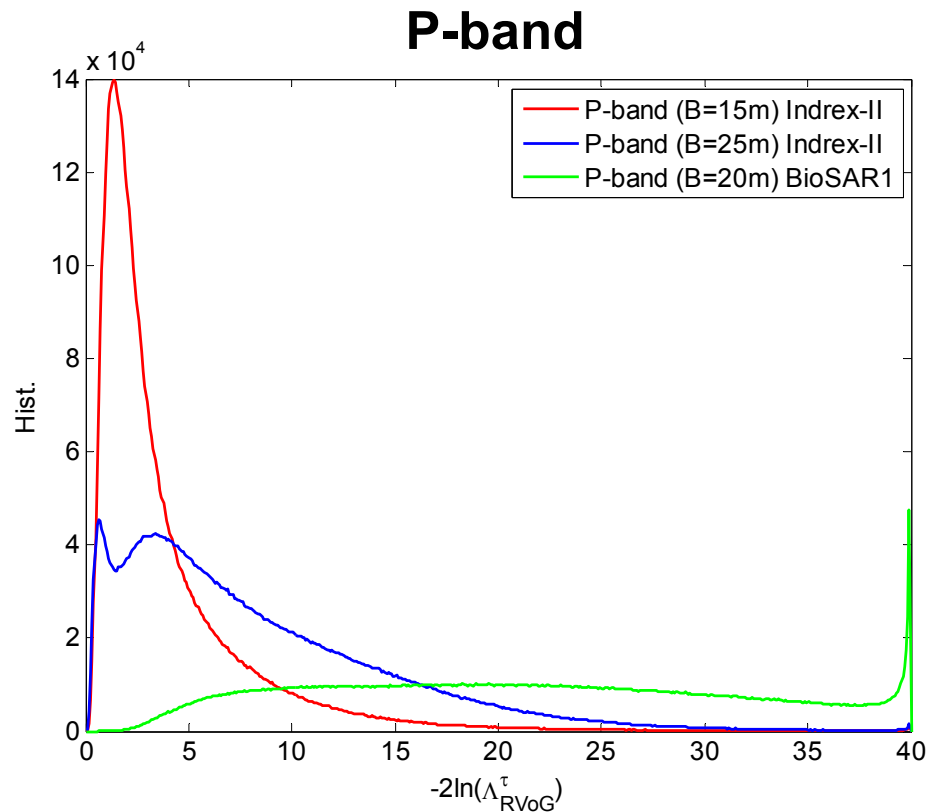
PolInSAR data: E-SAR BioSAR-1 Campaign **Boreal Forest**



- The **validity** of the RVoG **model hypothesis** depends on the spatial baseline

Results: Real PolInSAR Data

PolInSAR data: Tropical vs. Boreal Forest



- Analysis of the RVoG model in PolInSAR data for the **validation** and **estimation** of the model
 - MLR provides a **metric** to compare the effect of any parameter on the validity of the RVoG model hypothesis
- Validation
 - The RVoG hypothesis is true if the normalized PolInSAR matrix $\tilde{\Omega}_{12}$ is **affine equivalent to an Hermitian matrix**
 - Translations and rotations are insufficient in presence of speckle
 - Use of a **ML approach** to derive the **GLRT** for the RVoG hypothesis model analysis
- Estimation is SB-PolInSAR & MB-PolInSAR
 - Calculation of the **ML estimator** of the coherency matrix that makes data to fulfill the RVoG model
 - Estimation of the **line segment** of the RVoG and not only the line
- Results
 - RVoG validity depends on **frequency** and **baseline**
 - RVoG validity depends on **incidence angle** (ground-to-volume ratio?)
 - RVoG validity seems to be **higher in Tropical than in Boreal forests**

The Trace Matrix

The solution of the previous equations systems may be expressed in a **matrix form**

$$\underbrace{\begin{bmatrix} \text{tr}(\mathbf{H}_1) & \text{tr}(\mathbf{H}_2) & 3 \\ \text{tr}(\mathbf{H}_1\mathbf{H}_2) & \text{tr}(\mathbf{H}_2\mathbf{H}_2) & \text{tr}(\mathbf{H}_2) \\ \text{tr}(\mathbf{H}_1\mathbf{H}_1) & \text{tr}(\mathbf{H}_2\mathbf{H}_1) & \text{tr}(\mathbf{H}_1) \end{bmatrix}}_{\text{Trace matrix}} \begin{bmatrix} \Im\{a\} \\ \Re\{b\} \\ \Im\{c\} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad \Rightarrow \quad \Upsilon \mathbf{t} = \mathbf{0}$$

- If **CL applies**, $\text{rank}\{\Upsilon\}=2$, i.e., $\det\{\Upsilon\}=0$

- Line parameters derived in

L. Ferro-Famil, Y. Huang, M. Neumann, "Robust estimation of Multi-Baseline POL-inSAR parameters for the analysis of natural environments" EUSAR 2010

- If **CL does not apply**, $\text{rank}\{\Upsilon\}=3$, i.e., $\det\{\Upsilon\} \neq 0$

The rank of the Trace matrix indicates the **validity of the CL hypothesis**, i.e., the **validity of the RVoG model**

Continuous validity of the CL/RVoG model hypothesis based on the SVD decomposition of the trace matrix, based on the idea of the polarimetric Anisotropy

$$\sigma_1 \geq \sigma_2 \geq \sigma_3 \geq 0$$

Singular values of the Trace matrix



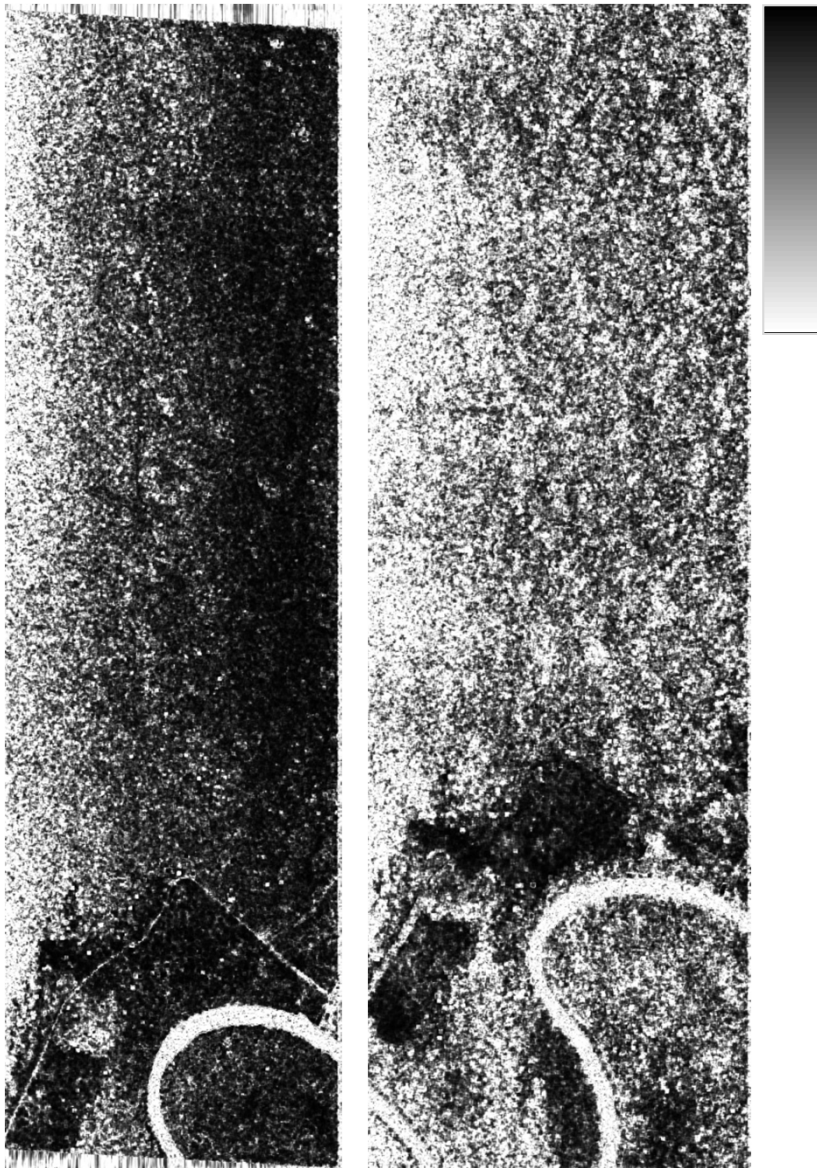
$$\Lambda_{RVoG}^A = \frac{\sigma_2 - \sigma_3}{\sigma_2 + \sigma_3}$$

$$0 \leq \Lambda_{RVoG}^A \leq 1$$

RVoG
hypothesis
is not valid

RVoG
hypothesis
is valid

Results: Real PolInSAR Data



Simulated PolInSAR data

- **Imaging systems:** DLR's E-SAR
 - Range spatial resolution 1.5 m
 - Azimuth spatial resolution 1.5 m
 - Wavelength $\lambda=0.23$ m (L-band)
 - Flight height $H=3000$ m
 - Mean incidence angle $\theta=45$ deg
- **Simulated scenarios:** Four different scenarios based on the RVoG model hypothesis

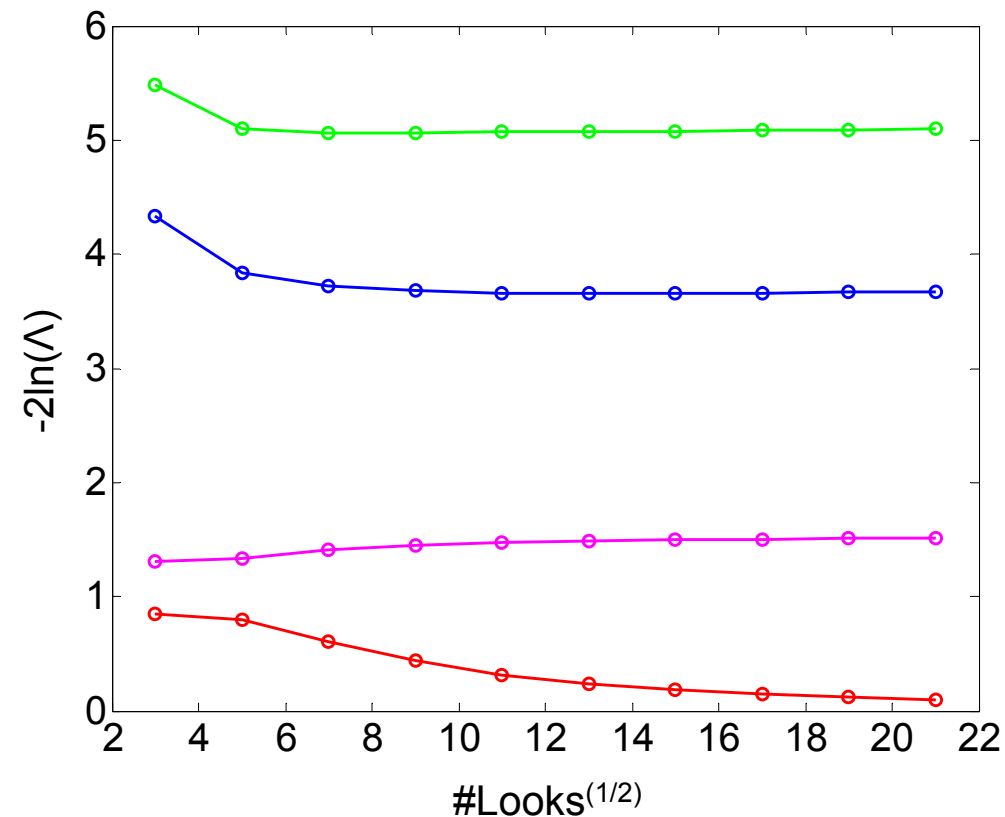
Scenario	Baseline [m]	h_v [m]	ϕ_1 [rad]	PS	CL
1	10	20	0	Yes	Yes
2	8	30	$\pi/2$	Yes	Yes
3	10	20	0	Yes	No
4	10	20	0	No	No

- **Statistical distribution:** Wishart pdf

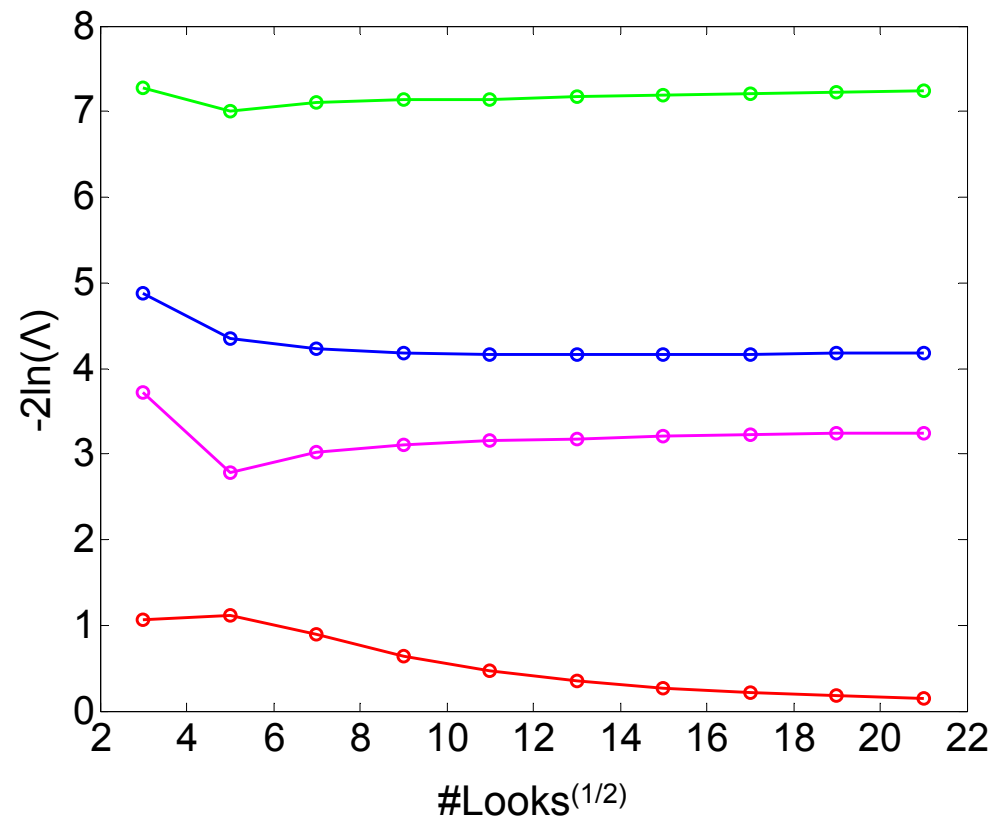
Results: Simulated PolInSAR Data

Ratio's values

Scenario 1: PS & CL



Scenario 2: PS & CL



Λ_{RVoG}^A —————

Λ_{RVoG}^{τ} —————

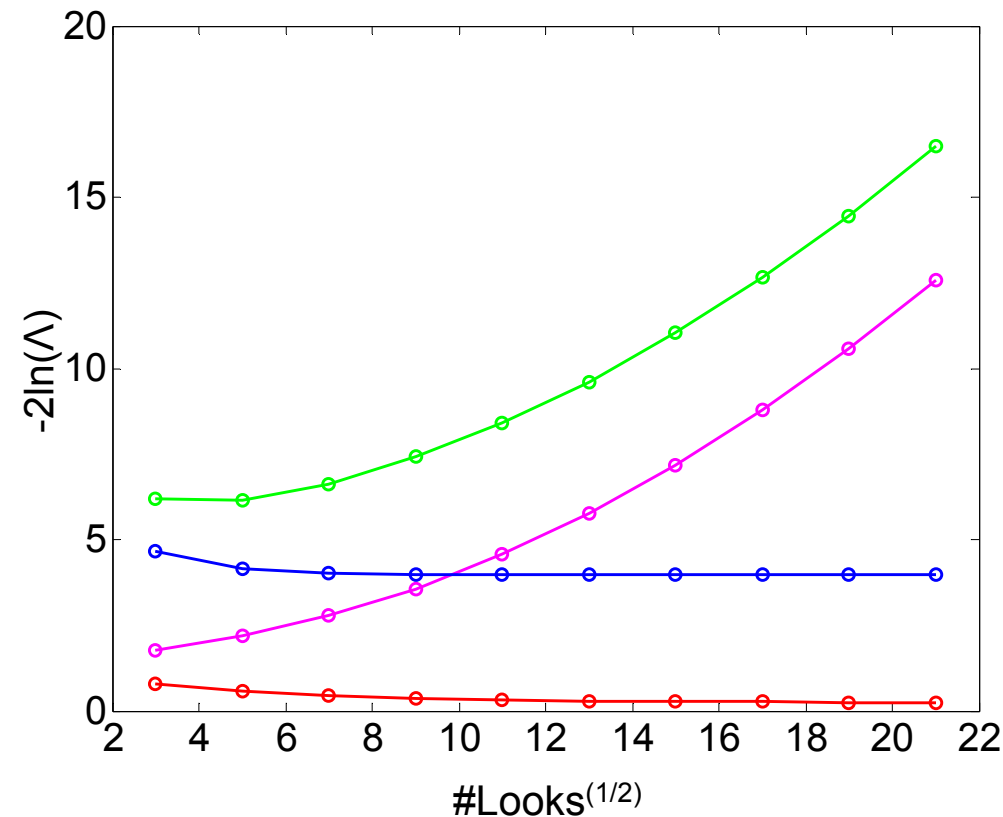
Λ_{PS}^{τ} ————— PS hypothesis

Λ_{CL}^{τ} ————— CL hypothesis

Results: Simulated PolInSAR Data

Ratio's values

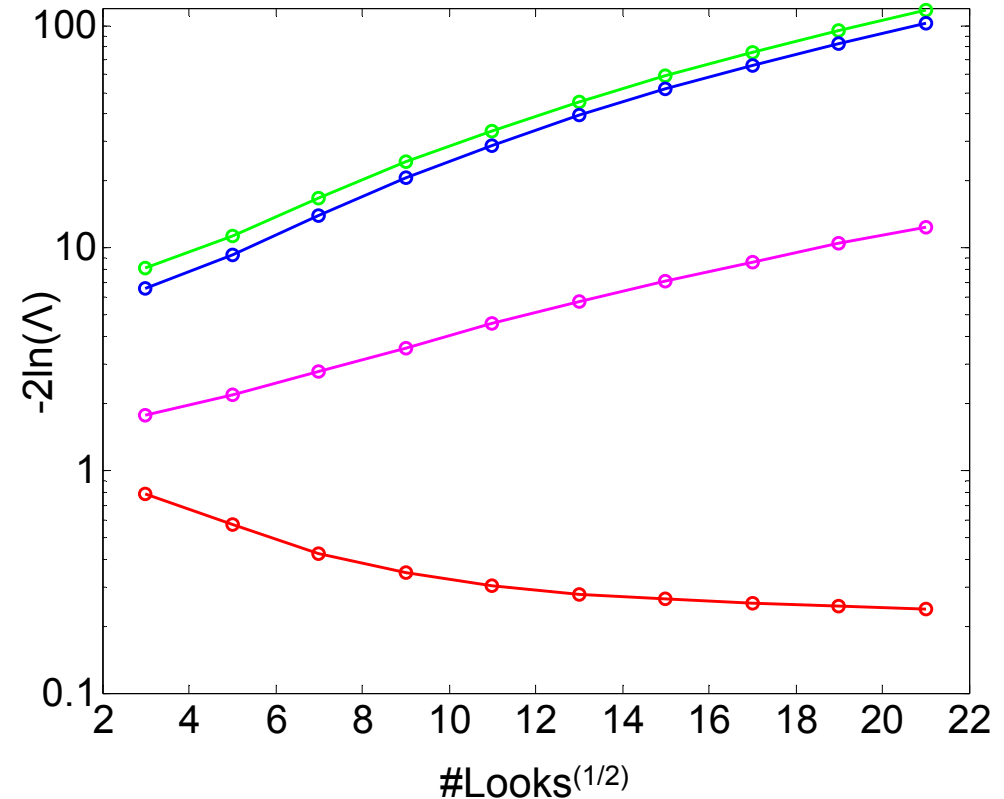
Scenario 3: PS



Λ_{RVoG}^A

Λ_{RVoG}^{τ}

Scenario 4



Λ_{PS}^{τ}

PS hypothesis

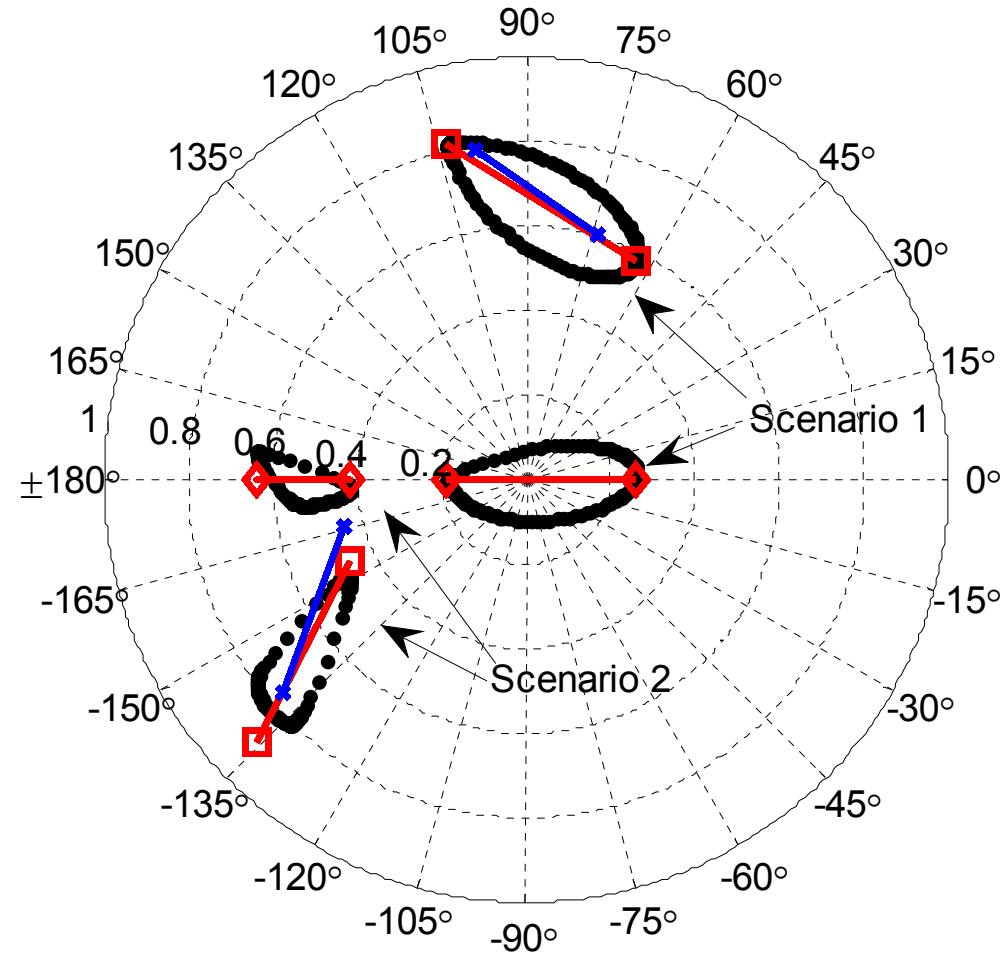
Λ_{CL}^{τ}

CL hypothesis

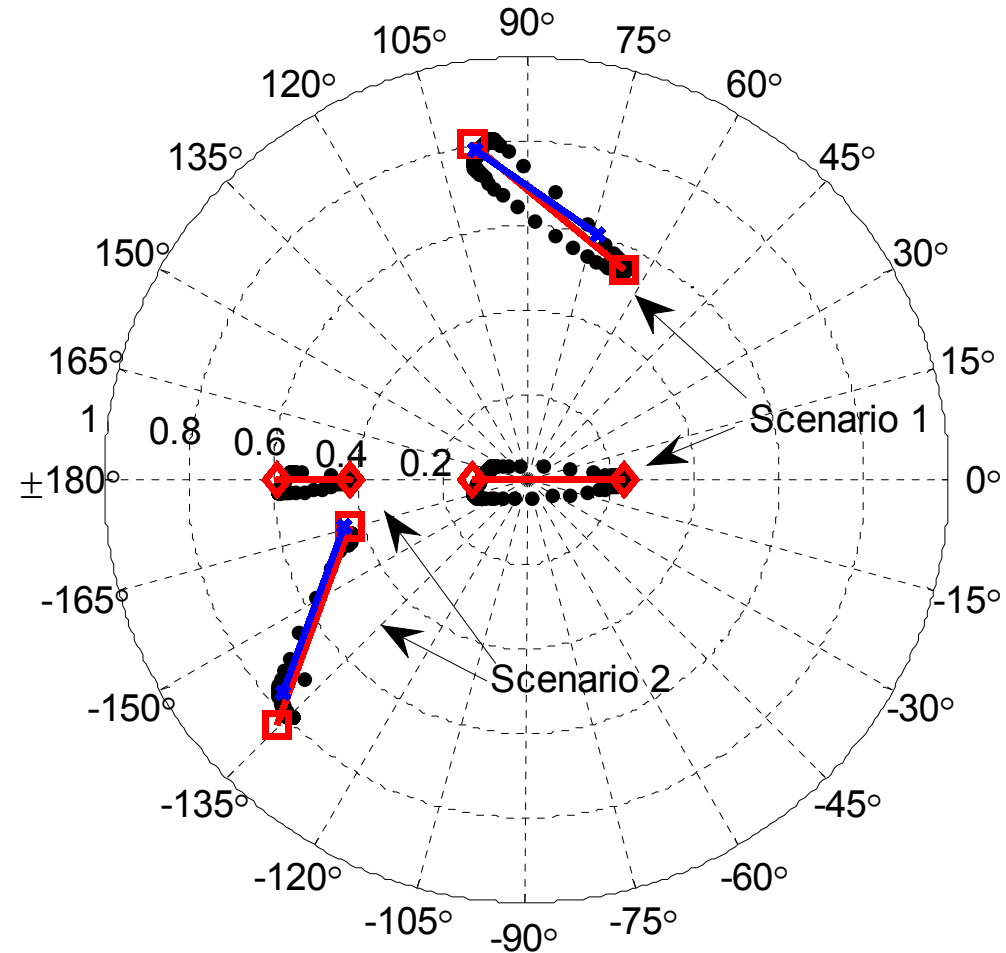
Results: Simulated PolInSAR Data

Coherence regions from individual pixels

9x9 Multilook



15x15 Multilook



— Theoretical CR

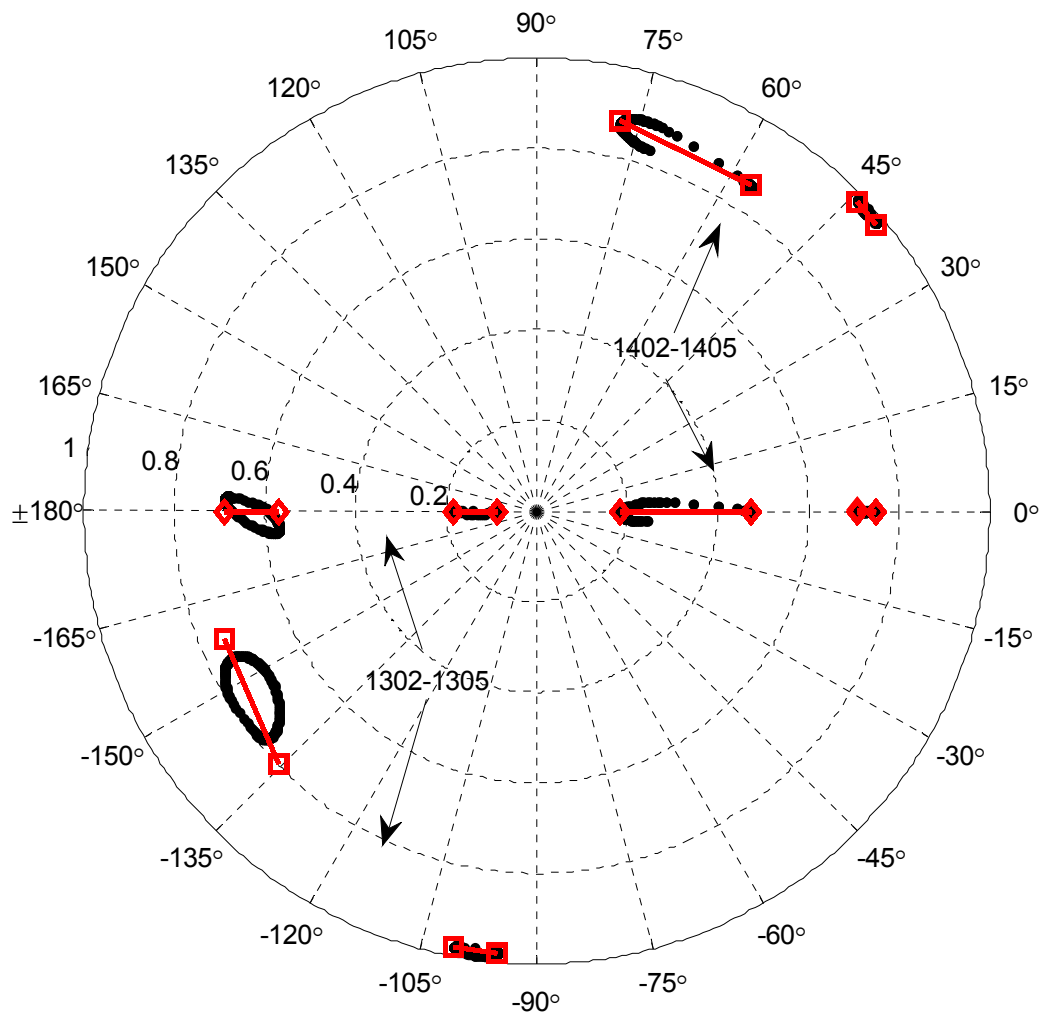
— Estimated CR
from multilook

— Estimated CR
from ML

Results: Real PolInSAR Data

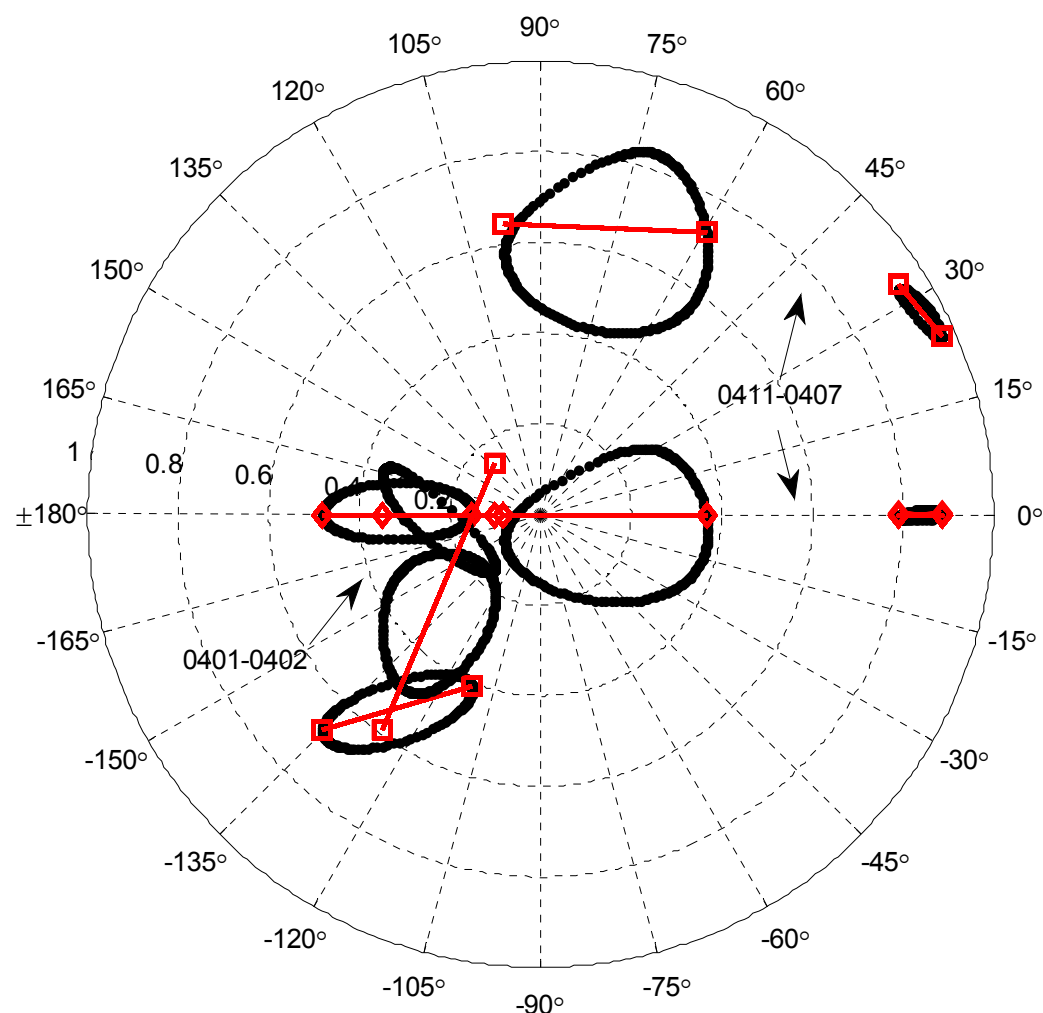
Coherence regions from individual pixels

INDREX-II



Estimated CR
from multilook

BioSAR



Estimated CR
from ML