
Polarimetric adaptive speckle filtering driven by temporal statistics for PSI applications

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Introduction

Persistent Scatterers Interferometry (PSI)

- Used to measure surface deformation evolution from SAR data
- Select for processing only good quality pixels:
 - Amplitude dispersion index → Persistent Scatterers (point-like, PS)
 - Average coherence → Coherent Pixels (distributed scatterers, DS)
- Urban environments: Mix of PS and DS
 - Estimation of DS parameters → speckle filtering
 - Speckle filtering → loss of PS information due to averaging
- **How to process together PS and DS?**

Introduction

Speckle filtering:

- Boxcar (multi-look) or sliding window:
 - Suitable for homogeneous areas with fully developed speckle
 - Resolution loss → **not suitable for PS analysis**
- Spatial adaptive speckle filters:
 - Adapt to filter only homogeneous areas
 - Driven by spatial statistics → spatial estimation window (**PS loss**)
- Spatial adaptive filters driven by temporal information:
 - Driven by temporal statistics → no initial spatial estimation window
 - **Homogeneous areas are filtered while PS are preserved**
 - Require a sufficient number of SAR images

Introduction

[Ferretti'11] → DespeckKS

- Two pixels are considered Statistically Homogeneous Pixels (SHP) based on a two-sample Kolmogorov-Smirnov test:
 - Compares p.d.f. of the pixel amplitudes.
 - P.d.f are estimated from multi-temporal data.
- Pixels with sufficient SHP neighbours are processed as DS.
- Pixels with few SHP neighbours are processed as PS.

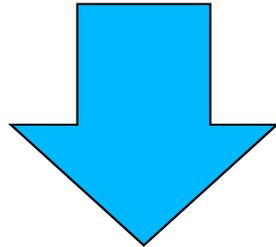
Limitations:

- Only takes into account amplitude information
- Conceived for single-pol data
- Multi-channel p.d.f. estimation is not straightforward

Introduction

Objectives:

- Polarimetric, PS preserving adaptive filter approach
- Polarimetric PSI with joint processing of PS and DS



INCREASED MAP DENSITY AND ACCURACY

Algorithm

Algorithm steps:

- Find homogeneous areas: Polarimetric Homogeneity Test
- Discriminate PS and DS
- Polarimetric Optimization. Find polarimetric channel that:
 - Minimizes amplitude dispersion for each PS
 - Maximizes average interferometric coherence for each DS
- Select pixels with good quality \rightarrow low σ_ϕ
- Process using any PSI technique

Polarimetric Homogeneity Test

Target vector (Pauli basis):

$$\mathbf{k} = \frac{1}{\sqrt{2}} \begin{bmatrix} HH + VV \\ HH - VV \\ 2HV \end{bmatrix}$$

Coherency matrix:

$$\mathbf{T} = E[\mathbf{k}\mathbf{k}^\dagger] \rightarrow \mathbf{T} = \frac{1}{L} \sum_{l=1}^L \mathbf{k}_l \cdot \mathbf{k}_l^\dagger$$

$$\mathbf{k} \sim \mathcal{N}_q^{\mathbb{C}}(0, \Sigma) \longrightarrow \mathbf{T} \sim \mathcal{W}_q^{\mathbb{C}}(L, \Sigma)$$

Temporal coherency matrix:

$$\mathbf{T} = \frac{1}{N} \sum_{n=1}^N \mathbf{k}_n \cdot \mathbf{k}_n^\dagger \quad N \text{ images} \rightarrow N \text{ independent samples}$$

Polarimetric Homogeneity Test

Equality test for Wishart distributed matrices

[Conradsen et al. 2003]:

- Hypothesis: $\Sigma_i = \Sigma_j$

- Test \rightarrow Likelihood ratio:
$$\Lambda = \frac{|\mathbf{T}_i|^{N_i} |\mathbf{T}_j|^{N_j}}{\left| \frac{N_i \mathbf{T}_i + N_j \mathbf{T}_j}{N_i + N_j} \right|^{N_i + N_j}}$$

- Equality condition:

$$\Lambda > c_\beta \quad P_{fa}(c_\beta) = P(\Lambda \leq c_\beta) = \beta$$

Hypothesis confirmed \rightarrow Polarimetrically Homogeneous Pixels (PHP)

- Pixels with more than R PHP are treated as DS (filtered)
- Pixels with less than R PHP are treated as PS (not filtered)

Polarimetric Homogeneity Test

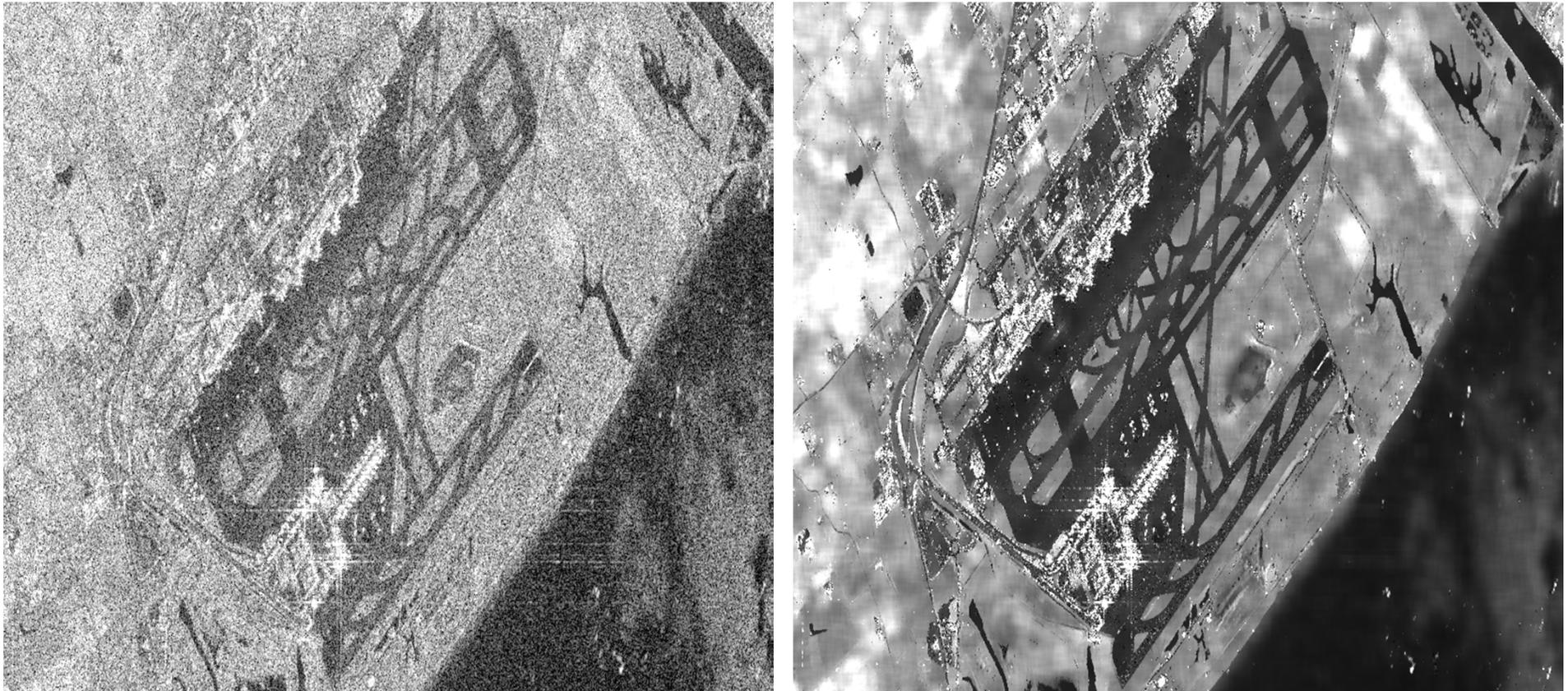
Search window = 15×15
 $\log \Lambda$ threshold = -20

Number of identified PHP
(Barcelona)



Polarimetric Homogeneity Test

Polarimetric adaptive speckle filter $\rightarrow R = 20$



Detail of Barcelona airport. HH+VV amplitude

PSI optimization review

General framework and formulation for vector interferometry

[Cloude and Papathanassiou, 1998]:

Projection:

$$\mu = \boldsymbol{\omega}^\dagger \mathbf{k}$$

Scattering coefficient (scalar complex) ← μ

$\boldsymbol{\omega}$ → Projection vector (unitary complex vector)

Projection vector parameterization:

$$\boldsymbol{\omega} = \begin{bmatrix} \cos(\alpha) \\ \sin(\alpha) \cos(\beta) e^{j\delta} \\ \sin(\alpha) \sin(\beta) e^{j\psi} \end{bmatrix},$$

$$\begin{cases} 0 \leq \alpha \leq \pi/2 \\ 0 \leq \beta \leq \pi/2 \\ -\pi \leq \delta < \pi \\ -\pi \leq \psi < \pi \end{cases}$$

**ESPO: Exhaustive Search
Polarimetric Optimization**

Search

PSI optimization review

- Average coherence optimization:

Maximize:

$$\overline{|\gamma|} = \frac{1}{K} \sum_{k=1}^K |\gamma_k|, \text{ with } \gamma_k(\omega) = \frac{\omega^\dagger \Omega_{ij} \omega}{\sqrt{\omega^\dagger \mathbf{T}_{ii} \omega} \sqrt{\omega^\dagger \mathbf{T}_{jj} \omega}} \quad \left\{ \begin{array}{l} \mathbf{T}_{ii} = E[\mathbf{k}_i \mathbf{k}_i^\dagger] \\ \mathbf{T}_{jj} = E[\mathbf{k}_j \mathbf{k}_j^\dagger] \\ \Omega_{ij} = E[\mathbf{k}_i \mathbf{k}_j^\dagger] \end{array} \right.$$

- Amplitude dispersion optimization:

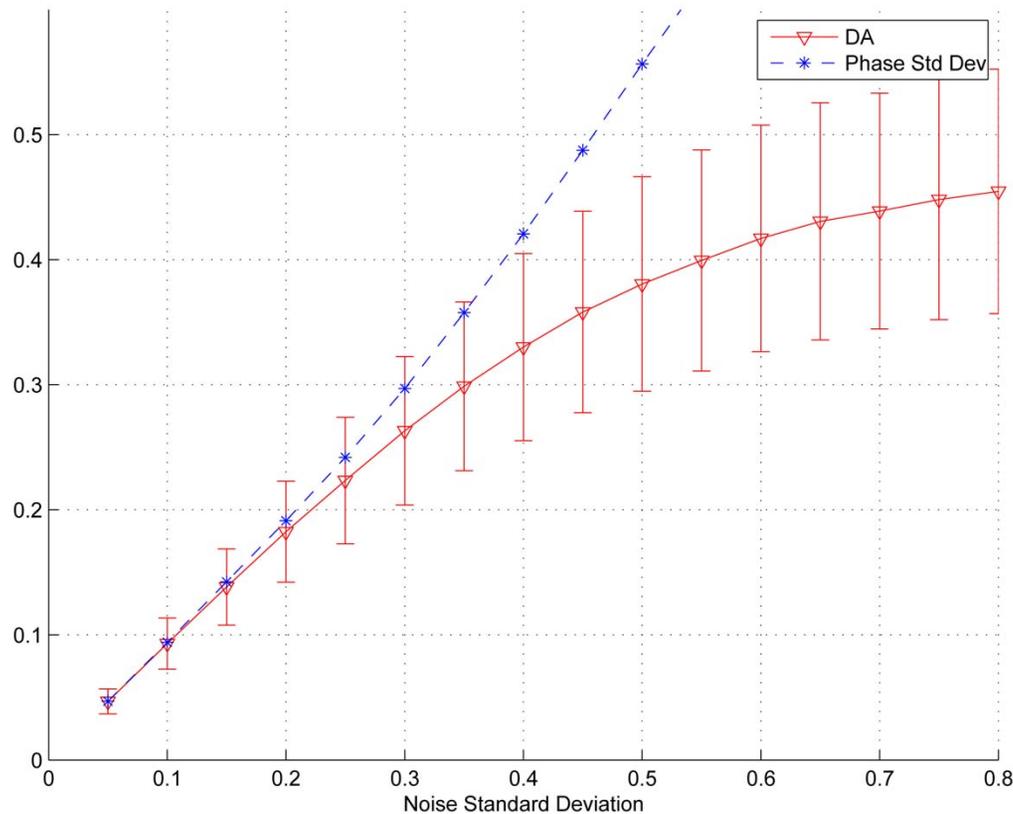
Minimize:

$$D_A = \frac{\sigma_a}{\bar{a}} = \frac{1}{|\omega^\dagger \mathbf{k}| \sqrt{N-1}} \sqrt{\sum_{i=1}^N \left(|\omega^\dagger \mathbf{k}_i| - |\omega^\dagger \mathbf{k}| \right)^2}$$

Constraint: $\omega_i = \omega_j = \omega \quad \forall i, j \rightarrow \text{ESM}$

Joint processing of DS and PS

- Common quality criterion \rightarrow phase standard deviation σ_ϕ
 - Amplitude dispersion: $D_A \approx \sigma_\phi$ for low values of DA (high SNR) [Ferretti et al., 2001]

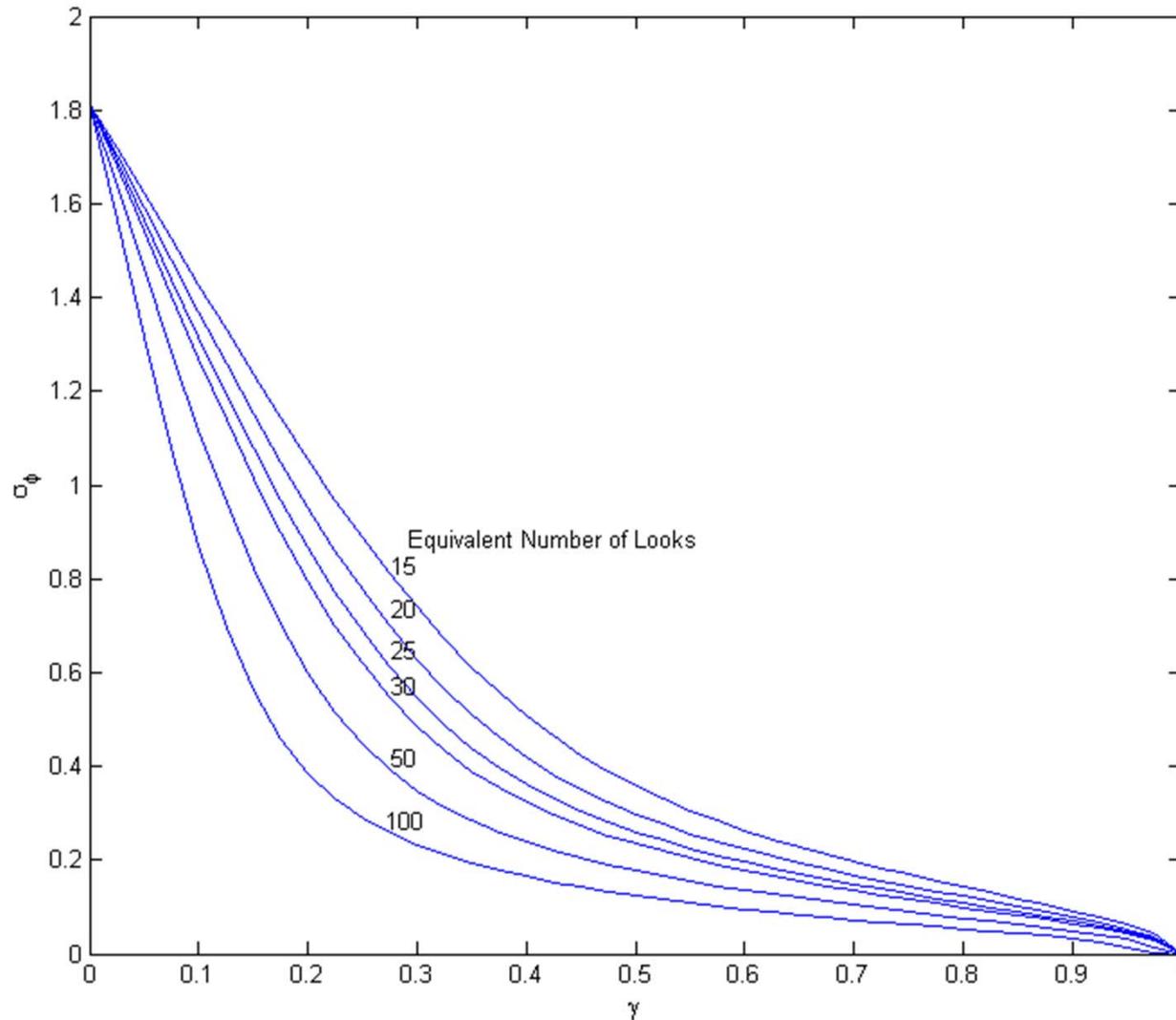


Joint processing of DS and PS

- Commc

- Ave
[Jon

$$\sigma_\phi = \sqrt{\int_{\phi} (\dots)}$$



$$\frac{(\phi - \phi_0)}{(\phi - \phi_0)^{L_e + 1/2}}$$

$$(\phi - \phi_0)$$

Results

Data set:

41 images of Murcia (Spain)
Feb-09 to May-10

- TerraSAR-X dual-pol: HH,VV
- Mean incidence angle: 37.8°
- Resolution: 6.6m Az, 1.17m Rg
- Spacing: 2.44m Az, 0.91m Rg
- Ovs. factors: 2.7 Az, 1.28 Rg



R = HH, G = VV, B = HH-VV

Images provided by DLR under the framework of project GEO0389

Results

Data set:

31 images of Barcelona (Spain)
Jan-10 to Feb-12

- RADARSAT-2 full-pol
- Mean incidence angle: 29°
- Resolution: 7.6m Az, 5.2m Rg
- Spacing: 5.1m Az, 4.7m Rg
- Ovs. factors: 1.49 Az, 1.11 Rg



R = HH-VV
G = 2HV
B = HH+VV

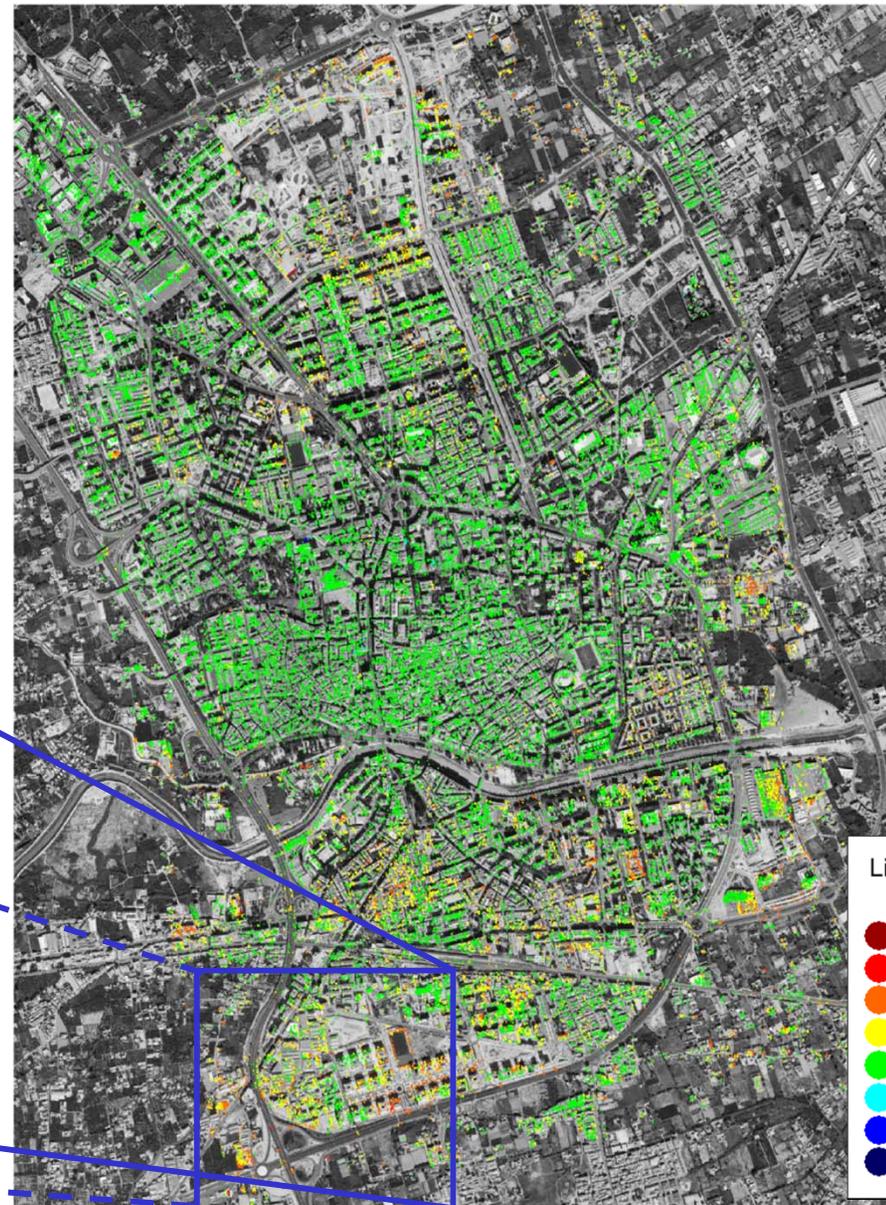
Images provided by MDA under the framework of project SOAR EU 6779

Results

Murcia (TERRASAR-X, DP)

σ_ϕ threshold = 0.25 ($\approx D_A$ 0.25)

HH	4.29 %
ESPO, DP	9.81 %
LR Filter + ESPO	15.02 %



Linear velocity
(mm/year)

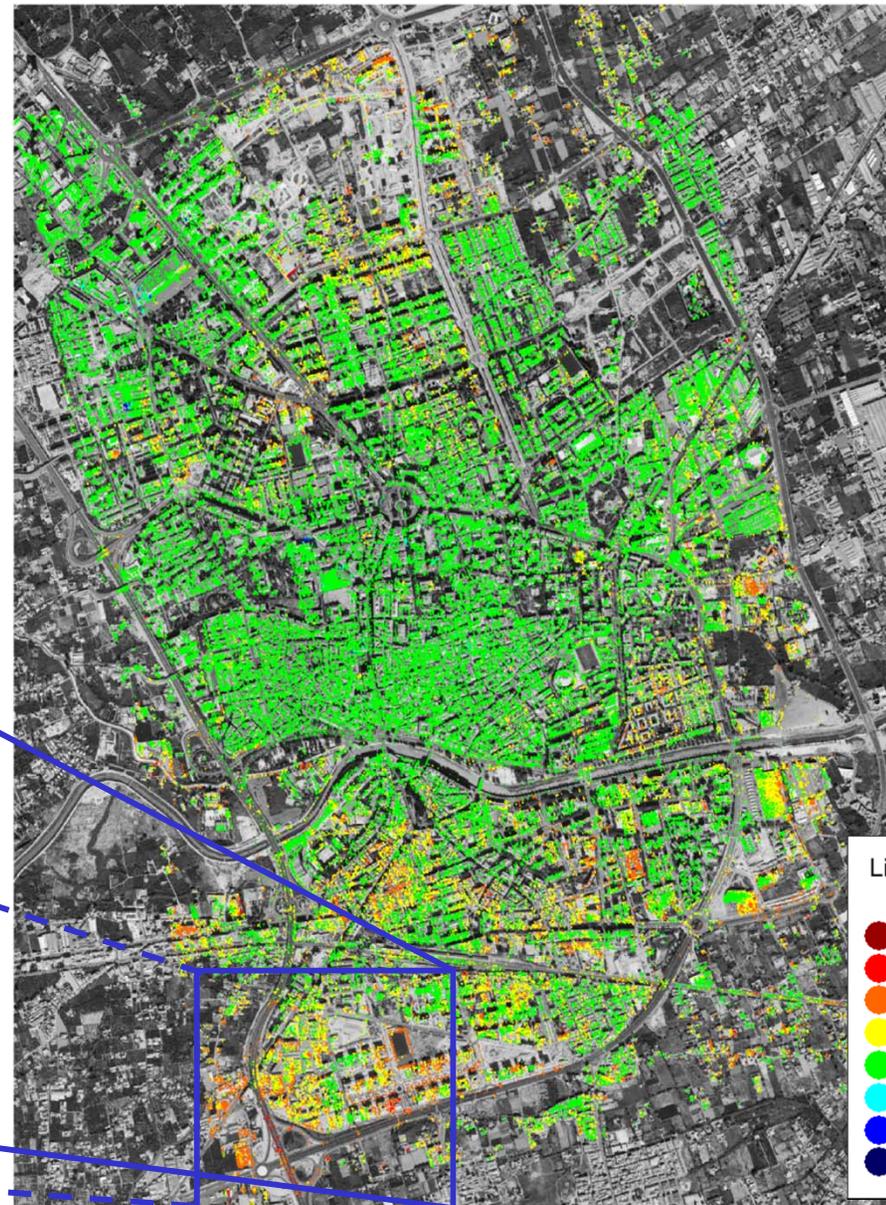


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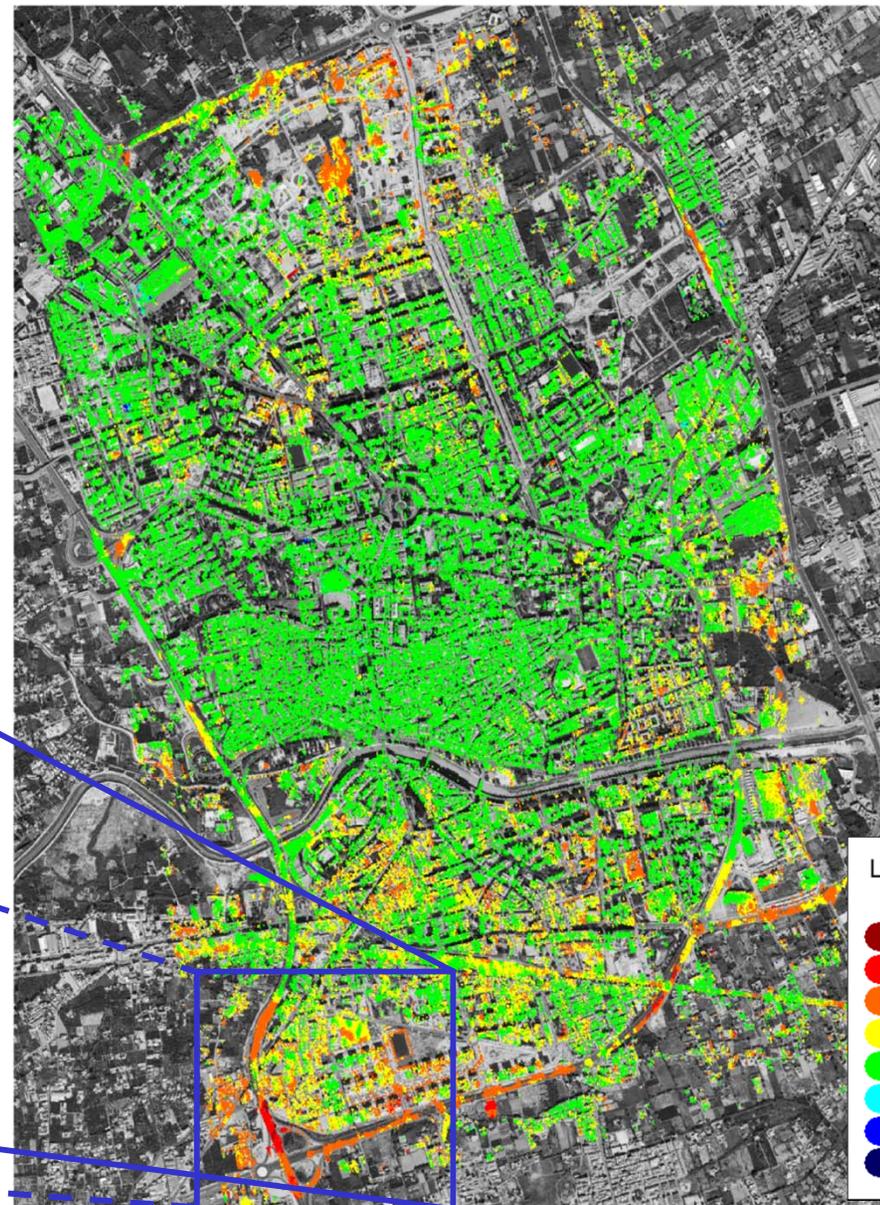


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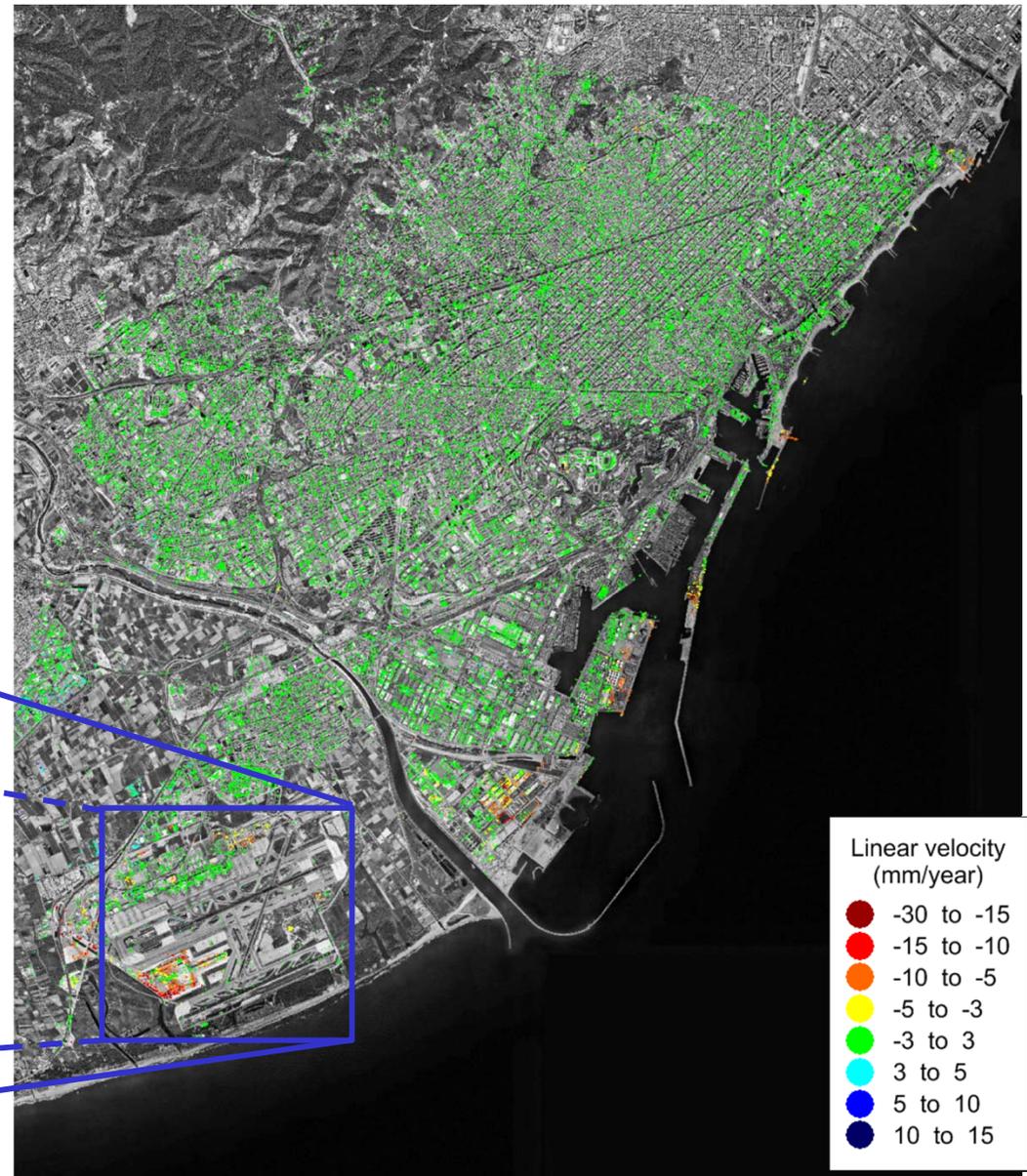


Results

Barcelona (RADARSAT-2, QP)

σ_ϕ threshold = 0.25 ($\approx D_A$ 0.25)

HH	2.01%
ESPO, QP	13.83 %
LR Filter + ESPO	18.62 %



Linear velocity
(mm/year)

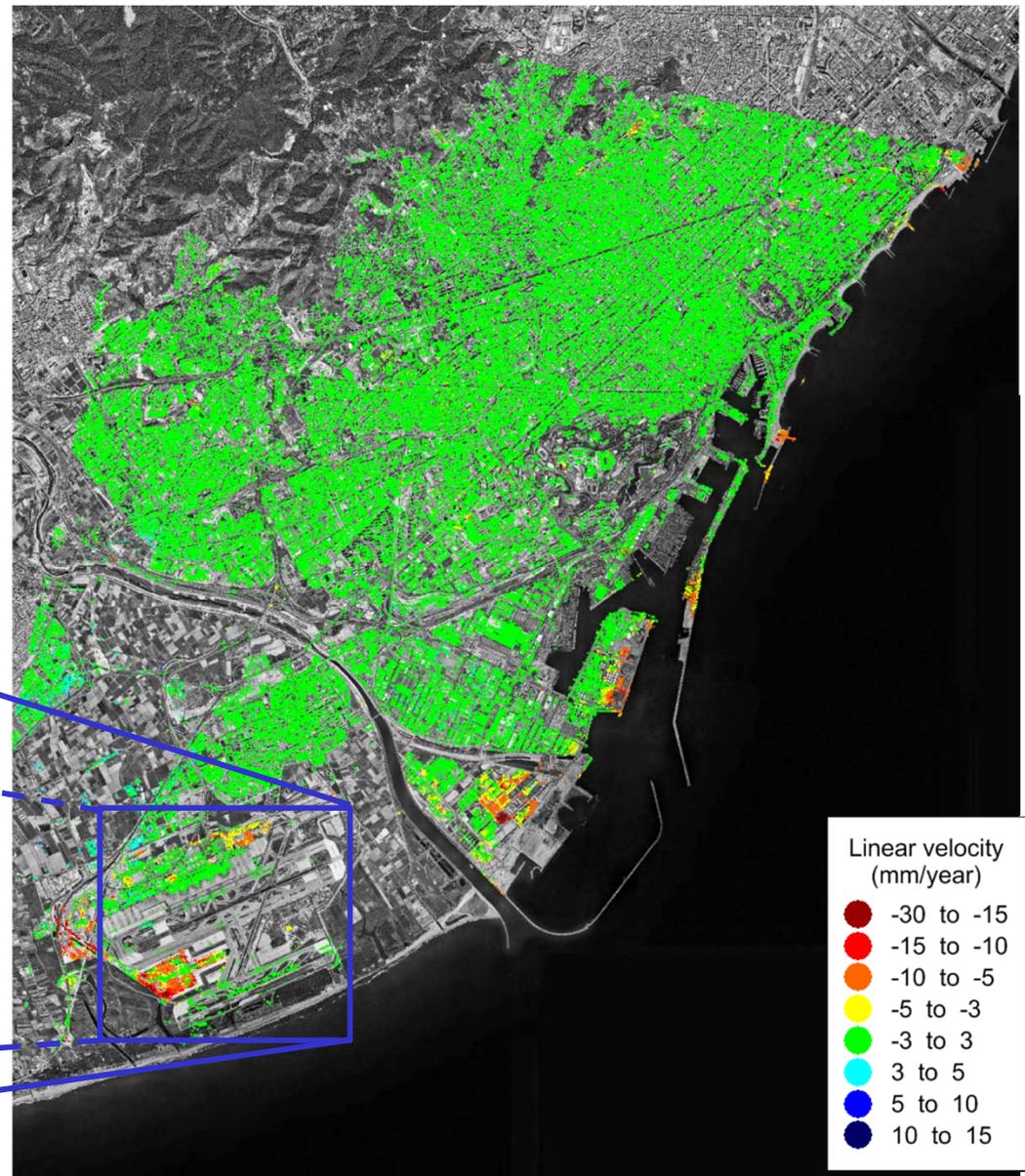
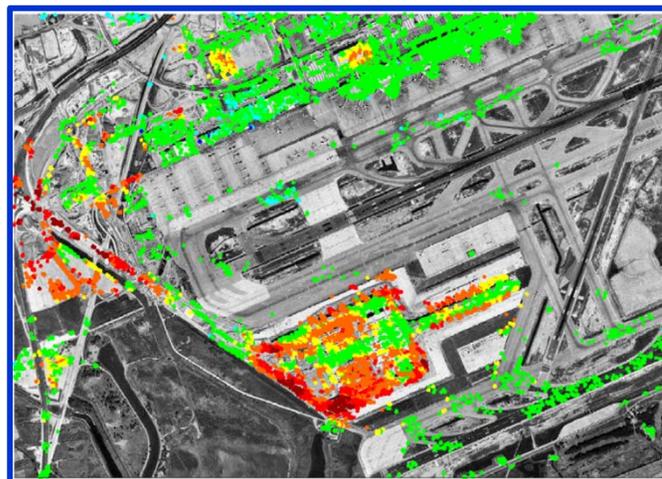


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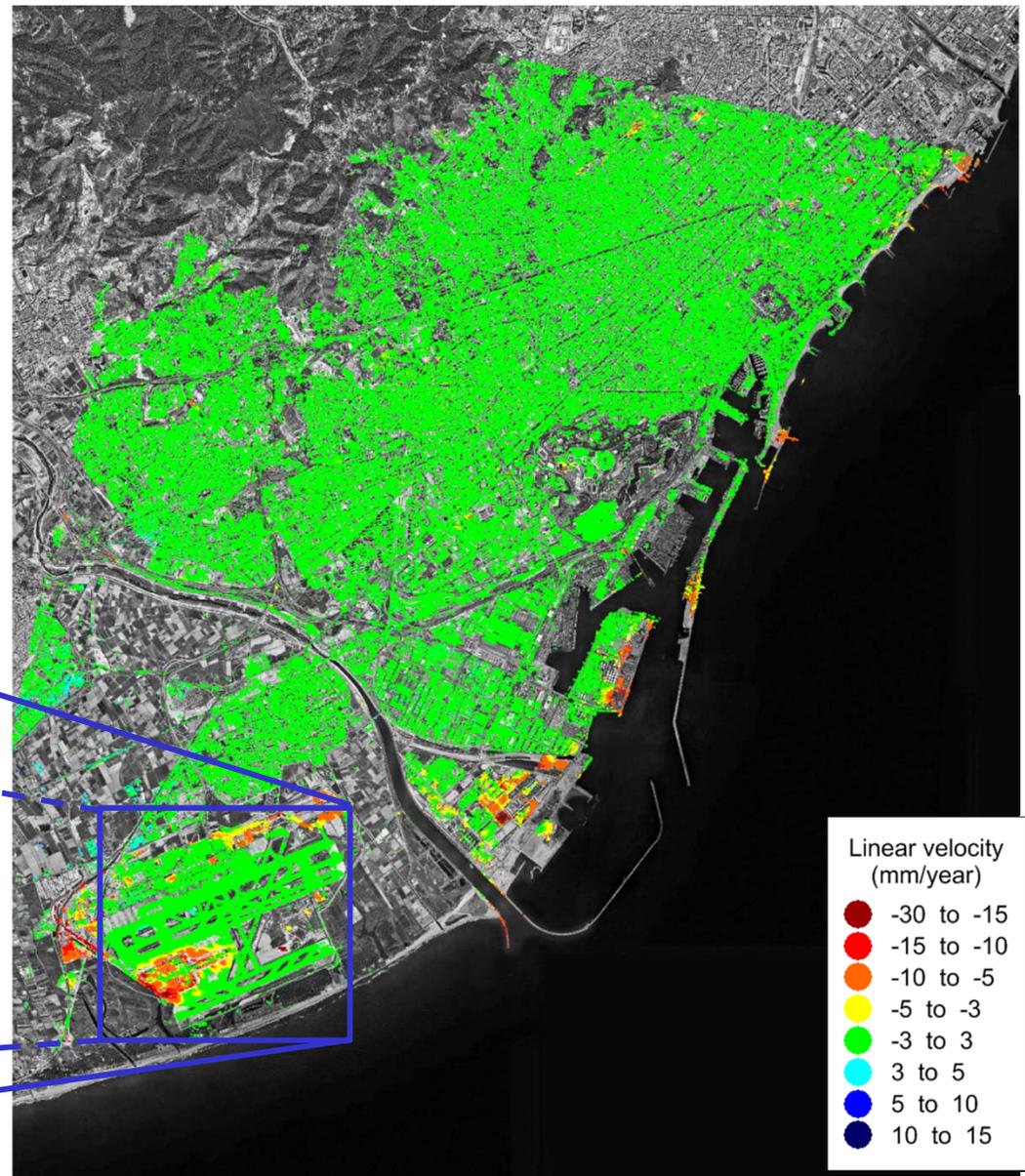
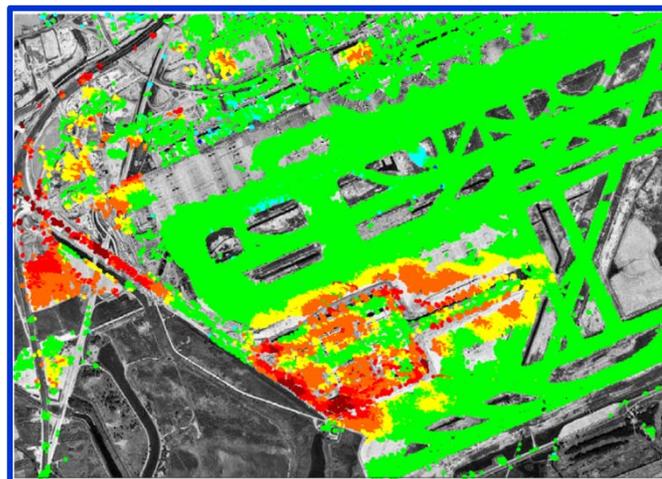


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Summary

- An adaptive speckle filtering approach has been presented:
 - Polarimetric
 - PS compatible
- Methodology for joint processing of PS and DS proposed
- Important increase of deformation maps density:
 - TerraSAR-X dual-pol
 - 1.53 times increase w.r.t. ESPO optimized data
 - 3.50 times increase w.r.t. single-pol (HH)
 - RADARSAT-2 full-pol
 - 1.35 times increase w.r.t. ESPO optimized data
 - 9.26 times increase w.r.t. single-pol (HH)

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