## Authors Table

<table>
<thead>
<tr>
<th>Name</th>
<th>Company</th>
<th>Responsibility</th>
<th>Date</th>
<th>Signature</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Written by</strong></td>
<td>S. Clerc &amp; MPC Team</td>
<td>ARGANS</td>
<td>Technical Manager</td>
<td>06/03/2018</td>
</tr>
<tr>
<td><strong>Verified by</strong></td>
<td>O. Devignot</td>
<td>CS</td>
<td>Quality Manager</td>
<td>06/03/2018</td>
</tr>
<tr>
<td><strong>Approved by</strong></td>
<td>L. Pessiot</td>
<td>CS</td>
<td>Service Manager</td>
<td>06/03/2018</td>
</tr>
</tbody>
</table>
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1. Introduction

1.1 Scope of the document

This document provides the status of Sentinel-2 mission products data quality. It documents measured product performance vs. specifications, observed anomalies and known issues, the list of defective pixels, processing chain improvements associated to each Processing Baseline, and an outlook on product evolution.

Note that a reference article provides an in-depth presentation of Sentinel-2 Calibration and Validation methods and results after one year in operation (F. Gascon et al., “Copernicus Sentinel-2 Calibration and Products Validation Status”, RS, 2017).

1.2 Main points for this month

- Sun calibration of S2B on 12/02/2018: temporary inconsistency in the calibration coefficients due to a minor anomaly in the Ground Segment (2.3.1.3)
- New minor anomaly: incorrect instrument temperature metadata (3.5.29)
- New minor anomaly: incorrect format for NODATA mask (3.5.30)
2. Measured Product Performances

2.1 Performances Overview

The following overview table provides a summary of the Level-1C products data quality performances measured on products in Processing Baselines 02.01 and higher, for a set of key mission requirements. Similar performances are observed for S2A and S2B, except for the geolocation performance which is not yet stabilized for S2B.

Table 2-1: Summary of Sentinel-2 L1C products measured performances for mission key requirements.

<table>
<thead>
<tr>
<th>Requirement</th>
<th>Description</th>
<th>Measured performance</th>
</tr>
</thead>
<tbody>
<tr>
<td>Absolute geolocation (without ground</td>
<td>The geo-location uncertainty shall be better than 20 m at 2σ confidence level (without Ground Control Points).</td>
<td>&lt; 11 m at 95.5% confidence (baseline 02.04)</td>
</tr>
<tr>
<td>control points)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Multi-spectral registration</td>
<td>The inter-channel spatial co-registration of any two spectral bands shall be better than 0.30 of the coarser achieved spatial sampling distance of these two bands at 3σ confidence level.</td>
<td>&lt; 0.3 pixel at 99.7% confidence</td>
</tr>
<tr>
<td>Absolute radiometric uncertainty</td>
<td>The absolute radiometric uncertainty shall be better than 5 % (goal 3%).</td>
<td>B1 to B12, excl. B10: &lt; 5%±2%</td>
</tr>
<tr>
<td>SNR</td>
<td>The Signal-to-Noise Ratio (SNR) shall be higher than specified values (see Table 2-5 in this document)</td>
<td>All bands compliant with &gt; 27% margin</td>
</tr>
</tbody>
</table>

Measured performances are detailed in the following sections.

2.2 Geometric Performance

2.2.1 Geometric Calibration Status

2.2.1.1 S2A

An improvement of the yaw angle bias correction has been performed on May, 30th 2016. Before this date, a relatively large along-track bias can be observed between different repeat orbits in the overlap region at the edges of the swath. The multi-temporal co-registration performance reported in this document is computed for products acquired after this date.

An update of the geometric calibration is planned in the coming months to avoid reoccurrence of anomaly #18 on S2A. The latter anomaly originated by an imperfect alignment of the back-up Star Tracker (STR3).
After degradation in December 2017, the geolocation performance of S2A has been improving in the beginning of 2018. Consequently, an update of geometric calibration does not seem to be necessary any more. Analysis of this variation is on-going.

2.2.1.2 S2B

The geometric calibration for S2B has been updated on December 21st to compensate an evolution of the line-of-sight biases. The performance is constantly monitored to determine if another update is required.

2.2.2 Geometric Refinement and Global Reference Image (GRI)

The L1C processing chain implements a geometric refinement step which aims at improving the repetitiveness of the image geolocation, in order to reach the multi-temporal geolocation requirement (< 0.3 pixel at 95%). The refinement step will be activated upon completion of the GRI and the final validation of the refining algorithm. At that point the processing baseline will be updated (major version change) and the archive will be reprocessed.

The GRI is a set of Level 1B images (in sensor frame) covering the whole globe with highly accurate geolocation information obtained through a spatio-triangulation algorithm using reference Ground Control Points (GCPs). The images use the reference band (B04) and are mostly (but not entirely) cloud-free. The GRI is an internal database used only for processing and not for dissemination. In particular, the GRI is not meant to be a cloud-free mosaic of the globe. Once the geometric refinement is activated, all images will have essentially the same geolocation accuracy.

The elaboration of the GRI is currently on-going. Continental sub-blocks are first built, processed and validated individually. In a second step, the sub-blocks (Europe, Africa and Asia on one hand, North and South America on the other hand) will be consolidated to improve the consistency at the boundary of the sub-blocks. The elaboration status is presented in the table below:

<table>
<thead>
<tr>
<th>GRI sub-block</th>
<th>Status</th>
</tr>
</thead>
<tbody>
<tr>
<td>Europe</td>
<td>Ready and Validated</td>
</tr>
<tr>
<td>North-Africa/Middle-East</td>
<td>Ready and Validated</td>
</tr>
<tr>
<td>Australia</td>
<td>Ready and Validated</td>
</tr>
<tr>
<td>South-Africa</td>
<td>Ready and Validated</td>
</tr>
<tr>
<td>North-America</td>
<td>Ready and Validated</td>
</tr>
<tr>
<td>South-America</td>
<td>Ready and Validated</td>
</tr>
<tr>
<td>Asia</td>
<td>Ready and Validated</td>
</tr>
<tr>
<td>Islands</td>
<td>Improvement in progress</td>
</tr>
</tbody>
</table>

Once the geometric refinement is activated, all images will have essentially the same geolocation accuracy.
2.2.3 Absolute Geolocation

Absolute geolocation is constantly monitored for S2A and S2B. For S2A, the latest performance estimation (based on 872 products since November 2016) is close to 12 m at 95%.

For S2B, the geolocation performance improved after the geometric calibration of December 21st but has since been deteriorating. An update of the geometric calibration is planned in the coming months.

Figure 1: Geolocation performance for S2A (top) and S2B (bottom). The performance is computed over a sliding window of 30 (respectively 10) days for S2A (resp. S2B). (ACT = across track, ALT = along track)
Note that the geolocation performance has a latitude-dependent component. This effect is particularly visible on the along-track component, and more pronounced for S2B than S2A. Images are shifted of 5 m Southward (approximately) in the Northern latitudes, to 5 m Northward in the Southern latitudes. This will be corrected with the introduction of the geometric refinement.

### 2.2.4 Multi-Spectral Registration

The co-registration requirement (< 0.3 pixel at 99.7% confidence) is met for all measured band couples. The performance for S2B has been improved with respect to S2A thanks to a better control of on-board vibrations.

<table>
<thead>
<tr>
<th>CE@99.73%</th>
<th>B01</th>
<th>B04</th>
<th>B05</th>
<th>B11</th>
</tr>
</thead>
<tbody>
<tr>
<td>B02</td>
<td></td>
<td>0.127</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B03</td>
<td>0.108</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>B06</td>
<td></td>
<td>0.074</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B07</td>
<td></td>
<td>0.090</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B08</td>
<td></td>
<td>0.124</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B09</td>
<td></td>
<td>0.180</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B11</td>
<td></td>
<td>0.165</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B12</td>
<td></td>
<td>0.152</td>
<td>0.173</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>CE@99.73%</th>
<th>B01</th>
<th>B04</th>
<th>B05</th>
<th>B11</th>
</tr>
</thead>
<tbody>
<tr>
<td>B02</td>
<td>0.172</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>B03</td>
<td>0.157</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>B06</td>
<td></td>
<td>0.074</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B07</td>
<td></td>
<td>0.090</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B08</td>
<td></td>
<td>0.124</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B09</td>
<td></td>
<td>0.172</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B11</td>
<td></td>
<td>0.165</td>
<td></td>
<td></td>
</tr>
<tr>
<td>B12</td>
<td></td>
<td>0.152</td>
<td>0.173</td>
<td></td>
</tr>
</tbody>
</table>

**Table 2-2: Multi-Spectral co-registration performance (per band couple and detector number) for S2A (top) and S2B (bottom).**
**Requirement is 0.3 pixel at 3σ.**
2.2.5 Multi-Temporal Registration

The multi-temporal registration error for one tile is estimated as the mean measured error for all control points of the tile. Then the global performance is taken as the 95.5% percentile of the value for all tiles measured on the reference band (B04). According to this methodology, the current performance is 12 m. Figure 2 shows the histogram of the distribution of multi-temporal registration errors, showing a peak at 3 m. Table 3 present the observed statistical distribution of the observed multi-temporal registration performance for S2A and S2B.

It is recalled that the objective is to meet the required 3 m performance (95.5% confidence level) with the activation of the geometric refinement using the GRI.

![Histogram of multi-temporal performance for S2A (top) and S2B (bottom, different scale). The 3 m requirement will be applicable only after activation of the geometrical refinement.](image-url)

The current performance is 11 m (S2A) and 13 m (S2B) at 95% confidence.

<table>
<thead>
<tr>
<th>Co-registration error</th>
<th>0&lt;X&lt;0.5 pixels</th>
<th>0.5&lt;X&lt;1 pixels</th>
<th>1&lt;X&lt;1.5 pixels</th>
<th>&gt;1.5 pixels</th>
</tr>
</thead>
<tbody>
<tr>
<td>S2A % of products</td>
<td>60%</td>
<td>32%</td>
<td>7%</td>
<td>1%</td>
</tr>
<tr>
<td>S2B % of products</td>
<td>46%</td>
<td>41%</td>
<td>12%</td>
<td>1%</td>
</tr>
</tbody>
</table>

Table 2-3: Multi-temporal performance statistics for Sentinel 2A and B

2.3 Radiometric Performance

2.3.1 Radiometric Calibration Status

2.3.1.1 Sun-diffuser model improvement

Product baseline 02.06 has been deployed on 23/10/2017. With this new baseline, the Sun-diffuser model used for calibration has been improved to reduce seasonal effects. The update did not result in a discrepancy in the time series of the radiometry (impact on calibration lower than 0.2% at this time of year, see DQR issue 22 for details).

2.3.1.2 S2A

Radiometric calibrations are performed routinely at the beginning of each month. Decontamination operations are scheduled every 6 months (January and July). A decontamination was successfully performed on the 4th of February 2018. The post-decontamination calibration is effective from February 8th 2018.

As mentioned in previous editions of the DQR, an anomaly was identified on the spectral response functions of S2A, affecting mostly bands B01, B02 and B08. This anomaly has been corrected on January 15th 2018 (cf. https://cophub.copernicus.eu/news/News00138) in the product metadata.

Note that this issue has negligible impact on the radiometry of the L1C reflectance products. On the other hand the conversion to radiance values and the computation of downstream products relying on the spectral response function can be impacted (such as L2A products).
A defect likely due to a dust particle covering one hundred pixels approximately has been detected on band B11 for S2A, starting from orbit 13545. This fact is currently under analysis and should be corrected with the calibration of January 5th 2018.

2.3.1.3 S2B

Radiometric calibration is currently performed once per month. After the last calibration, a minor anomaly in the Ground Segment led to a partial overlap of radiometric calibration baselines. A few products have been generated the outdated calibration coefficients. Although the products are still compliant with mission requirements, a reprocessing is planned to ensure a consistent radiometry within each orbit.

The S2B MSI underwent decontamination on November 26th, 2017. The calibration gains were subsequently adjusted on November 30th.

2.3.2 Radiometric Uncertainty

Radiometric validation has been performed using several methods:

✓ “Rayleigh” method: measurement of the Rayleigh atmospheric backscattering over deep ocean sites.
✓ Comparison with in-situ data.
✓ Measurement over well characterized, temporally stable desert areas (Pseudo-Invariant Calibration Sites (PICS)).
✓ Comparison with other sensors (Landsat-8 OLI and S2A for S2B case).

The results are presented in the figures below for S2A and for S2B. Results over S2A are provided for all bands, except B09 & B10 (water vapour absorption band) for which direct validation is not possible, while results over S2B are provided for all bands except B09 & B10. All results are compatible with the 5% (3%) radiometric accuracy requirement (Goal) respectively. PICS results for band B05 (705 nm in the figure below) are excluded as they are less reliable due to the significant impact of gaseous absorption (O₂ and water vapour).
A small systematic difference in radiometry is observed between S2A and S2B: S2A is brighter (measured reflectance higher) than S2B by about 1%. This difference is currently under study.

**Figure 4:** Comparison of radiometric accuracy for all spectral bands (except B09 and B10): ratio of S2A measurement on reference. Error bars indicate the method uncertainty.

**Figure 5:** Comparison of radiometric accuracy for all spectral bands (except B09 & B10): ratio of S2B measurement on reference. Error bars indicate the method uncertainty.
Tabulated results for bands B01 to B12 (B09 & B10 excluded) presented below indicate the effectiveness and reliability of the on-board calibration method for both sensors S2A/MSI and S2B/MSI.

**Table 2-4: Best estimate of S2A and S2B calibration gains from validation.**

<table>
<thead>
<tr>
<th>Sensor</th>
<th>Wavelength (nm)</th>
<th>S2A</th>
<th>S2B</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Gain Coefficient</td>
<td>Standard Deviation</td>
<td>Gain Coefficient</td>
</tr>
<tr>
<td>B01</td>
<td>443</td>
<td>1.01</td>
<td>0.03</td>
</tr>
<tr>
<td>B02</td>
<td>490</td>
<td>1.00</td>
<td>0.02</td>
</tr>
<tr>
<td>B03</td>
<td>560</td>
<td>1.00</td>
<td>0.01</td>
</tr>
<tr>
<td>B04</td>
<td>665</td>
<td>1.02</td>
<td>0.02</td>
</tr>
<tr>
<td>B05</td>
<td>705</td>
<td>1.01</td>
<td>NA</td>
</tr>
<tr>
<td>B06</td>
<td>740</td>
<td>1.01</td>
<td>0.01</td>
</tr>
<tr>
<td>B07</td>
<td>783</td>
<td>1.01</td>
<td>0.00</td>
</tr>
<tr>
<td>B08</td>
<td>842</td>
<td>0.99</td>
<td>0.00</td>
</tr>
<tr>
<td>B8A</td>
<td>865</td>
<td>1.01</td>
<td>0.01</td>
</tr>
<tr>
<td>B11</td>
<td>1610</td>
<td>1.02</td>
<td>0.01</td>
</tr>
<tr>
<td>B12</td>
<td>2190</td>
<td>1.00</td>
<td>0.02</td>
</tr>
</tbody>
</table>

Time series of measurements are also produced to monitor the evolution in time of the radiometric response, in particular to detect a possible degradation of the diffuser. The current assessment is compatible with the specified stability requirement for all visible and NIR bands (< 1% per year), and no-trend detectable yet for S2B.

### 2.3.3 Noise

The SNR for both S2A and S2B is exceeding requirements (worst-case >160 for band B8A). The table below provides the most recent estimates (August 2017 for S2A and September 2017 for S2B).

**Table 2-5: Estimated SNR performance for S2A and S2B at reference radiance.**

<table>
<thead>
<tr>
<th>Spectral Band</th>
<th>B1</th>
<th>B2</th>
<th>B3</th>
<th>B4</th>
<th>B5</th>
<th>B6</th>
<th>B7</th>
<th>B8</th>
<th>B8A</th>
<th>B9</th>
<th>B10</th>
<th>B11</th>
<th>B12</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ref. radiance [W/m²/sr/µm]</td>
<td>129</td>
<td>128</td>
<td>128</td>
<td>108</td>
<td>74.5</td>
<td>68</td>
<td>67</td>
<td>103</td>
<td>52.5</td>
<td>9</td>
<td>6</td>
<td>4</td>
<td>1.5</td>
</tr>
<tr>
<td>S2A</td>
<td>1400</td>
<td>210</td>
<td>239</td>
<td>222</td>
<td>247</td>
<td>216</td>
<td>224</td>
<td>217</td>
<td>157</td>
<td>222</td>
<td>391</td>
<td>160</td>
<td>167</td>
</tr>
<tr>
<td>S2B</td>
<td>1372</td>
<td>212</td>
<td>242</td>
<td>230</td>
<td>248</td>
<td>223</td>
<td>232</td>
<td>230</td>
<td>169</td>
<td>239</td>
<td>400</td>
<td>167</td>
<td>172</td>
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<tr>
<td>Requirement</td>
<td>129</td>
<td>154</td>
<td>168</td>
<td>142</td>
<td>117</td>
<td>89</td>
<td>105</td>
<td>174</td>
<td>72</td>
<td>114</td>
<td>50</td>
<td>100</td>
<td>100</td>
</tr>
</tbody>
</table>
As seen in the figure below, the noise characteristics are very stable over time.

Figure 6: Evolution of the SNR performance or S2A since 08/06/2016 (top) and S2B since 15/03/2017 (bottom)

Another aspect of the image noise is the so-called Fixed Pattern Noise: this is the residual pixel radiometric error after equalization. The performance is better than the specification for all bands (95.5% confidence level).
Figure 7: Fixed Pattern Noise (residual error after equalization) measured on diffuser images for S2A (top) and S2B (bottom). Blue curve: mean FPN, red: maximum specified value. Dashed: best- and worst-case pixels.

The noise occasionally exceeds the requirement level for a few pixels of SWIR bands.
2.3.4 Modulation Transfer Function

The Modulation Transfer Function (MTF) has been estimated by analysing images with sharp edges for all bands (except B10 for which in-orbit assessment is difficult).

Globally, the across track (ACT) values measured in flight are lower than those expected from ground measurements (see Table 2-6 below). The MTF is above the maximum value requirement for B5, B6, B7 and B8A for the across track direction. For the along track (ALT) direction, the requirement is generally met (marginally in some cases). Note that only the minimum value requirement has a direct impact on image quality. This requirement is satisfied for all bands.

The performance for S2B will be reported in future issues of the DQR. Preliminary results indicate similar or better performance than S2A.

Recently, an East-West asymmetry has been observed in the measured MTF. This effect is currently under study. Outcomes of the investigation will be reported in the DQR as they become available.

Table 2-6: S2A MTF performance assessment.

<table>
<thead>
<tr>
<th>Spectral Band</th>
<th>Measured ACT</th>
<th>Measured ALT</th>
<th>Requirement</th>
</tr>
</thead>
<tbody>
<tr>
<td>B01</td>
<td>0.34±0.03</td>
<td>0.28±0.03</td>
<td>0.15 &lt; MTF</td>
</tr>
<tr>
<td>B02</td>
<td>0.25±0.06</td>
<td>0.27±0.06</td>
<td>0.15 &lt; MTF</td>
</tr>
<tr>
<td>B03</td>
<td>0.27±0.03</td>
<td>0.28±0.04</td>
<td>0.15 &lt; MTF</td>
</tr>
<tr>
<td>B04</td>
<td>0.25±0.04</td>
<td>0.23±0.03</td>
<td>0.15 &lt; MTF</td>
</tr>
<tr>
<td>B05</td>
<td>0.42±0.03</td>
<td>0.34±0.05</td>
<td>0.15 &lt; MTF</td>
</tr>
<tr>
<td>B06</td>
<td>0.35±0.12</td>
<td>0.33±0.05</td>
<td>0.15 &lt; MTF</td>
</tr>
<tr>
<td>B07</td>
<td>0.35±0.07</td>
<td>0.34±0.03</td>
<td>0.15 &lt; MTF</td>
</tr>
<tr>
<td>B08</td>
<td>0.26±0.11</td>
<td>0.25±0.06</td>
<td>0.15 &lt; MTF</td>
</tr>
<tr>
<td>B8A</td>
<td>0.36±0.06</td>
<td>0.31±0.04</td>
<td>0.15 &lt; MTF</td>
</tr>
<tr>
<td>B09</td>
<td>0.25±0.10</td>
<td>0.27±0.03</td>
<td>0.15 &lt; MTF</td>
</tr>
<tr>
<td>B11</td>
<td>0.20±0.04</td>
<td>0.24±0.04</td>
<td>0.15 &lt; MTF</td>
</tr>
<tr>
<td>B12</td>
<td>0.24±0.07</td>
<td>0.22±0.06</td>
<td>0.15 &lt; MTF</td>
</tr>
</tbody>
</table>
3. Processing Chain Status

3.1 Product Format

On December 6th 2016, a new naming convention has been introduced (Product Specification Document version 14). The new convention leads to shorter product paths with less redundancy of information. The product name now includes the acquisition date and a “product discriminator” which is related to the acquisition date but can be different in some instances.

On 23/10/2017 a new processing baseline (02.06) and a new product format (PSD version 14.2, minor changes only) have been introduced.
3.2 Status of Processing Baselines and Known Processing Anomalies

The table below summarizes recent evolutions of the evolutions of the processing baseline and the known processing anomalies affecting the production. The dates mentioned in the table refer to the product creation date.

A minor anomaly has been also identified on a few S2B products (incorrect product names #40).

**Table 3-1: Summary of identified processing anomalies and associated processing baselines. Red: systematic anomaly. Orange: random anomaly affecting only a few products**

<table>
<thead>
<tr>
<th>Anomaly ID</th>
<th>Baseline number 02.01</th>
<th>02.02</th>
<th>02.03</th>
<th>02.04</th>
<th>02.05</th>
<th>02.06</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Deployment date</td>
<td>15/12/2015</td>
<td>31/03/2016</td>
<td>03/05/2016</td>
<td>09/06/2016</td>
<td>15/06/2016</td>
</tr>
<tr>
<td>4</td>
<td>Instrument Measurement Time metadata</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>Missing Physical Gains metadata</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>12</td>
<td>Anomalous Pixels</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>15</td>
<td>Strong Misregistration</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>16</td>
<td>Stretched 60 m bands</td>
<td>Orbit S2A 4427</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>19</td>
<td>Wrong footprint on antemeridiem</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>23</td>
<td>Degraded AUX files</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>24</td>
<td>Imprecise technical quality mask</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>25</td>
<td>Geolocation error on orbit 7174</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>26</td>
<td>Incomplete manifest</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>27</td>
<td>Incorrect footprint and missing metadata</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Anomaly ID</td>
<td>Baseline number</td>
<td>Deployment date</td>
<td>02.01</td>
<td>02.02</td>
<td>02.03</td>
<td>02.04</td>
</tr>
<tr>
<td>------------</td>
<td>----------------</td>
<td>----------------</td>
<td>-------</td>
<td>-------</td>
<td>-------</td>
<td>-------</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>15/12/2015</td>
<td>31/03/2016</td>
<td>03/05/2016</td>
<td>09/06/2016</td>
</tr>
<tr>
<td>Anomaly title</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>29</td>
<td>Incorrect cloud MTD</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>30</td>
<td>Corrupted metadata</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>32</td>
<td>Missing viewing angles at antemeridiem</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>33</td>
<td>Missing files</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>34</td>
<td>Missing ECMWF files</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>35</td>
<td>Wrong quantification value</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>36</td>
<td>Misregistration B09 and B10</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>37</td>
<td>Missing viewing angles</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>38</td>
<td>'Null' Folder</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>39</td>
<td>Incorrect S2A spectral response</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>40</td>
<td>Incorrect file name</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>41</td>
<td>Incorrect instrument temperature metadata</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>42</td>
<td>Incorrect NODAT mask format</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- Incorrect cloud MTD: A few products
- Corrupted metadata: Orbit S2A 9095 Tile 50SQA 20/03/2017
- Missing viewing angles at antemeridiem
- Missing files: A few products
- Missing ECMWF files: Sensing time near 9AM or 9PM
- Wrong quantification value: Orbit S2A 10724 to 10729
- Misregistration B09 and B10: Orbit S2A 11799
- Missing viewing angles: Some products
- 'Null' Folder: A few products
- Incorrect S2A spectral response: Until January 15th 2018
- Incorrect file name: A few products
- Incorrect instrument temperature metadata
- Incorrect NODAT mask format: A few products
3.3 Archive Reprocessing

A reprocessing campaign of images acquired during the commissioning period (from launch till 30/11/2015) has been completed. Another reprocessing has been started on products with baseline 02.00, originally affected with a wrong tile numbering. The new products will be created with baseline 02.04, multi-tile format.

The following products from the reprocessing campaign are defective:

- Products from orbits 1296 to 1304 processed on October 2016 (large geolocation error due to a GPS anomaly)
- Orbits 2148, 2154, 2159, 2171, 2195, 2204, 2216, 2220, 2225 (large geolocation error: these orbits have been reprocessed and the archive will be updated)
- Orbit 1147 (too dark): this orbit has been removed from the archive

Finally a minor anomaly affects some products from September 2015 (see anomaly #9 in the next chapter). SWIR bands are strongly degraded. However VISNIR bands are meeting quality standards, so these products will remain available in the future.

3.4 Level 2A production

Since 02/05/2017, Sentinel 2 Level 2A products (atmospherically corrected) are available from the Sentinel data hub. This production is provided in the frame of pre-operational pilot project and is based on Sen2Cor 2.3.1. PlanetDEM Digital Elevation Model (DEM) is used, while cirrus and Bidirectional Reflectance Distribution Function (BRDF) corrections are deactivated.

Products are available for Europe with sensing date after 28/03/2017.

3.5 Product Anomalies

This section describes all known product anomalies. Each anomaly is tagged with a code “#N” allowing linking it to a given Processing Baseline through Table 3-1.

The table below provides the status of anomalies which are not related to processing and can therefore not be corrected through reprocessing. It complements Table 3-1 above.

Anomalies affecting obsolete products (baseline 02.00) are no longer described in this report.
Table 3-2: Anomalies not related to processing.

<table>
<thead>
<tr>
<th>Anomaly ID</th>
<th>Anomaly title</th>
<th>Criticality</th>
<th>Unit</th>
<th>Affected products</th>
<th>Product status</th>
</tr>
</thead>
<tbody>
<tr>
<td>9</td>
<td>Stripping of SWIR bands</td>
<td>Minor</td>
<td>S2A</td>
<td>A few orbits, not systematic</td>
<td>Available</td>
</tr>
<tr>
<td>10</td>
<td>Stripping of Visible bands</td>
<td>Major</td>
<td>S2A</td>
<td>A few orbits, not systematic</td>
<td>Removed from archive</td>
</tr>
<tr>
<td>13</td>
<td>B10 saturation</td>
<td>Minor</td>
<td>S2A</td>
<td>Products with high reflectances</td>
<td>Available</td>
</tr>
<tr>
<td>14</td>
<td>Geolocation error</td>
<td>Major</td>
<td>S2A</td>
<td>Orbits 3218, 4080 and 4081</td>
<td>Removed from archive</td>
</tr>
<tr>
<td>17</td>
<td>Misaligned detectors on band 1</td>
<td>Minor</td>
<td>S2A</td>
<td>A few orbits impacted (beginning of the datastrip)</td>
<td>Available</td>
</tr>
<tr>
<td>18</td>
<td>Geolocation Error</td>
<td>Minor</td>
<td>S2A</td>
<td>Orbits 6003 to 6011</td>
<td>Available</td>
</tr>
</tbody>
</table>

3.5.1 Instrument Measurement Time metadata (#4)

Within the satellite ancillary metadata, the value of Instrument Measurement Time (IMT) is not represented correctly due to a formatting error. This anomaly is corrected with product baseline 02.05.

3.5.2 Missing Physical Gains metadata (#7)

Band 12 is missing in the “physical gains” metadata of the user product. However the full list of physical gains is present in the metadata at granule level. This error was corrected early August 2016 and recent products are not anymore affected.

3.5.3 Striping of SWIR Bands (#9)

This anomaly is characterized by along-track stripes on some detectors of SWIR band images (see image below). Other detectors are also misaligned (along-track shift).

![Figure 8: Striping of SWIR bands (anomaly #9). Top: B11, Bottom, B12.](image_url)
This anomaly occurred during commissioning as a result of an incorrect instrument configuration. Users are advised to use only VISNIR bands for the corresponding orbits.

<p>| | | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1118</td>
<td>1205</td>
<td>1302</td>
<td>1404</td>
</tr>
<tr>
<td>1143</td>
<td>1218</td>
<td>1308</td>
<td></td>
</tr>
<tr>
<td>1146</td>
<td>1227</td>
<td>1314</td>
<td></td>
</tr>
<tr>
<td>1151</td>
<td>1234</td>
<td>1319</td>
<td></td>
</tr>
<tr>
<td>1156</td>
<td>1244</td>
<td>1326</td>
<td></td>
</tr>
<tr>
<td>1159</td>
<td>1246</td>
<td>1329</td>
<td></td>
</tr>
<tr>
<td>1171</td>
<td>1251</td>
<td>1337</td>
<td></td>
</tr>
<tr>
<td>1175</td>
<td>1256</td>
<td>1342</td>
<td></td>
</tr>
<tr>
<td>1186</td>
<td>1261</td>
<td>1343</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1272</td>
<td>1348</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1274</td>
<td>1391</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1298</td>
<td>1394</td>
<td></td>
</tr>
</tbody>
</table>

**Table 3-3: List of orbits affected by anomaly #9.**

### 3.5.4 Striping due to lost source packets (#10)

Data downlink issue sometimes lead to missing instrument source packets. This results in missing or corrupted pixels in L1C image, typically affecting only odd or even detectors and some spectral bands. The figure below presents an example of product affected by missing packets.

![Figure 9: L1C product affected by a large number of missing packets. This type of feature is not considered as an anomaly and will not lead to removal of affected products.](image)

Under the current quality control policy, this effect is not considered as an anomaly. Products affected by missing packets will remain in the archive. This type of behaviour is expected and traced in the product:
3.5.5 Anomalous Pixels (#12)

This anomaly is characterized by anomalous pixel values at the boundary of a datastrip. This anomaly has been corrected with baseline 02.02.

3.5.6 Saturation noise on Band 10 Images (#13)

This feature is characterized by noise patterns on bright images. It has now been identified as generated by saturation of the detector. This effect is not an anomaly in itself, however the saturation is currently not correctly reported in the image quality masks. A modification of the processor is in progress to solve this issue.
3.5.7 Geolocation and Co-registration Error (#14)

A major anomaly has led to a strong and temporary geolocation and spectral registration errors. The anomaly occurred on February 3rd (orbit 3218) and 3rd of April 2016 (orbits 4080, 4081 and 4082). This anomaly has been correctly identified by the automatic on-line quality control and the degraded geometric performance is reported in the product metadata (geometric quality check status is “FAILED”). After identification of the anomaly, the defective products have been removed from the public archive.

The root cause of this anomaly has been identified. Missing data from attitude control telemetry is at the origin of the anomaly. An optimization of the management of the on-board telemetry has been implemented since and should avoid any re-occurrence.

Figure 11: Along-track noise pattern on B10 images over bright clouds (#13).

Figure 12: Spectral co-registration error (anomaly #14).
3.5.8 Strong Misregistration (#15)

Processing Baseline 02.03 deployed on 09/06/2016 was affected by an anomaly due to an incorrect configuration of the processing centres. This anomaly results in a strong spectral misregistration. This issue was rapidly identified, defective products have removed from the archive and subsequently reprocessed with baseline 02.02. After correction of the configuration error, baseline 02.04 was deployed on 15/06/2016.

3.5.9 Stretching of 60 m Bands (#16)

This anomaly is characterized by an incorrect appearance of the 60 m bands: images are stretched across-track and discontinuities are visible between detector boundaries. A few occurrences have been observed, and none since 27/04/2016.

![Figure 13: Stretching of 60 m bands (anomaly #16).](image)

3.5.10 Misaligned detectors on band 1 (#17)

An anomaly on the receiving ground station occurred on 12\textsuperscript{th} of July 2016 and led to corrupted products for a few orbits (5509 to 5525). The anomaly affects only band 1 and is limited the first products for the datastrips (Northern part). It is characterized by a misalignment of the odd and even detectors, as illustrated in the figure below.
Figure 14: Detector misalignment on band B1 (anomaly #17).

A possible correction of this anomaly by an ad-hoc reprocessing is under study.

### 3.5.11 Geolocation Error (#18)

This anomaly occurred while the satellite was performing a collision avoidance manoeuvre on 16th August 2016. One Star Tracker was temporarily blinded by the Sun, which led to a degradation of the attitude estimation. As a result, the geolocation of the products acquired during this period (orbits 6003 to 6011) is affected by a variable geolocation error of up to 100 meters.

The anomaly is related to the handling of the redundant Star Tracker in the attitude estimation system. A correction of the alignment of the redundant Star Tracker is planned to avoid a re-occurrence of this anomaly.

Figure 15: S2 image superimposed with reference map, showing a geolocation error of 35 m (anomaly #18).

### 3.5.12 Product footprint on the ante-meridiem (#19)

With the introduction of single tile products in October 2016, an issue has been identified in the product footprint for tiles crossing the ante-meridiem (180° longitude). The footprint should be composed of two polygons (above -180° and below +180°). Instead, only the second polygon is present.
This anomaly has been fixed on 26/01/2017. All points are now present but in a single polygon.

### 3.5.13 Degraded AUX files (#23)

This anomaly affects the ECMWF auxiliary files, for some specific tiles. The files are truncated and contain aberrant values. This anomaly is fixed with production baseline 02.05.

### 3.5.14 Imprecise technical quality mask (#24)

Since October 2016, technical quality masks (TECQA) are reporting instance of lost data packets (see anomaly #10). However it has been found that the masks are not perfectly accurate (see figure below). This anomaly is corrected with production baseline 02.05.

![Figure 16: Technical Quality masks (green: lost packets, red: degraded packets) overlaid over an affected imaged. A small gap exists between the mask and the affected area (anomaly #21).](image)

### 3.5.15 Geolocation error on orbit 7174 (#25)

A geolocation error of more than 100 m has been observed on the first datastrip of orbit 7174 (acquired 05/11/2016). A reprocessing is planned for this datastrip to correct this anomaly.

### 3.5.16 Incomplete manifest (#26)

In products generated before 18/05/2017, the meteorology Auxiliary files are missing from the file listing in the manifest.safe.
3.5.17 Inaccurate footprint and incomplete metadata (#27)

This anomaly occurred on January 20th 2017 following a change in the user product generation chain, and was solved on January 26th 2017. The anomaly affected the diffusion of products on the SciHub, and as a result few products affected by this anomaly have been disseminated. The characteristics of this anomaly are:

- Coarse precision of product footprint (1/3°)
- Missing Datastrip Identifier and granule Identifier attributes.

3.5.18 Incorrect cloud coverage metadata (#29)

Two products have been found affected by this anomaly. The products have very small data coverage and are completely cloudy. The cloud mask is accurate but the cloud coverage metadata is reported as zero. The affected products are 30UXB on 11/02/2017 and 50KQL on 12/04/2017.

The issue has been analysed and the correction will be deployed in the near future.

3.5.19 Corrupted metadata (#30)

The product for tile 50SQA generated on 20/03/2017 has several metadata with an incorrect “0” value (quantification value, spectral irradiances). No other product has been found with this anomaly so far.

3.5.20 Missing viewing angles metadata (#32)

Viewing angles metadata (part of L1C granule metadata) are systematically missing for tiles of UTM zone 01 crossing the ante-meridiem. This anomaly is fixed with baseline 02.06.

3.5.21 Missing files (#33)

Some recent products have been found with one or several files missing (spectral bands or metadata files). This anomaly is now corrected for real time processing and the archive is progressively cleaned.

3.5.22 Missing ECMWF auxiliary files (#34)

In some cases, the meteorology auxiliary files (ECMWF data) are missing in the products. The root cause has been identified and the correction is in progress.

3.5.23 Wrong quantification value (#35)

An incorrect calibration file has been deployed by error for S2A on 12/06/2017 and affected orbits 10724 to 10729. The quantification value is 1,000 instead of 10,000. The affected products have been reprocessed and the archive will be updated.
3.5.24  **Misregistration on bands 9 and 10 (#36)**

On 25/09/2017, an anomaly at the reception station led to a severe loss of instrument source packets. As a side effect, a mis-registration of bands B09 and B10 has been observed downstream of the area affected by missing packets. In view of this strong degradation, the affected orbit (S2A orbit 11 799) will be removed from the archive.

3.5.25  **Missing viewing angles (#37)**

This anomaly affected a few products of baseline 02.01: the viewing angles (part of the granule Metadata) are missing for some spectral bands. It has been corrected on 31/03/2016.

3.5.26  **“Null” folder (#38)**

A few products of baseline 02.04 have been generated with an additional empty Granule folder with a name ending with “null”. As a side effect, this generates a failure with Sen2cor. This very minor anomaly can be corrected by deleting the empty folder.

3.5.27  **Incorrect S2A Spectral Response Function (#39)**

The spectral response functions provided in the metadata of the S2A products are affected by errors affecting mostly bands B01, B02 and B08. The corrected response functions are now available on the Sentinel on-line website and will be corrected in the product metadata on January 15th 2018.

3.5.28  **Incorrect Product Name (#40)**

A few S2B products have been found with an additional number (0 or 1) at the end of the product discriminator field. This minor anomaly has been understood and correction actions are in progress to prevent re-occurrence. In the meantime the products will be removed and replaced with new ones with the correct naming.

3.5.29  **Incorrect Instrument Temperature metadata (#41)**

This anomaly affects the Instrument temperature data reported in the “expertise” section of the Datastrip metadata. The temperature are not converted to degrees Celsius as they should be. In addition the GPS time is not correctly reported. This minor anomaly affects all products of baseline 02.06 and earlier. Remediation is in progress.

3.5.30  **Incorrect NODATA mask format (#42)**

On 10/01/2018 a few products have been generated with a comma ‘,’ instead of a decimal point ‘.’ in the description of the mask polygon (NODATA and DEFECT
masks). This minor error is due to an incorrect language setting which has been corrected. Remediation steps are in progress to prevent re-occurrence.
4. Pixels Status

4.1 Defective pixels

4.1.1 S2A

In the following tables are listed all the identified defective pixels which are currently replaced by an interpolation of neighbouring pixels. The health status has been verified after the last decontamination operation in January.

New potentially defective pixels (noisy) have been detected on Band 12 Detector 5. The issue is currently under investigation. In addition an anomalous behaviour of some pixels on Band 11 has been observed and is currently analysed.

Table 4-1: Defective pixels on S2A Band 10.

<table>
<thead>
<tr>
<th>Band</th>
<th>Detector</th>
<th>Pixel number (from 0)</th>
<th>Current status</th>
<th>Last updated</th>
</tr>
</thead>
<tbody>
<tr>
<td>B10</td>
<td>4</td>
<td>1104</td>
<td>Defective</td>
<td>16/11/2015</td>
</tr>
<tr>
<td>B10</td>
<td>10</td>
<td>879</td>
<td>Defective</td>
<td>23/06/2015</td>
</tr>
<tr>
<td>B10</td>
<td>10</td>
<td>1174</td>
<td>Defective</td>
<td>23/06/2015</td>
</tr>
</tbody>
</table>

Table 4-2: Defective pixels on S2A Band 11.

<table>
<thead>
<tr>
<th>Band</th>
<th>Detector</th>
<th>Pixel number (from 0)</th>
<th>Current status</th>
<th>Last updated</th>
</tr>
</thead>
<tbody>
<tr>
<td>B11</td>
<td>D11</td>
<td>24</td>
<td>Defective</td>
<td>26/08/2015</td>
</tr>
</tbody>
</table>

Table 4-3: Defective pixels on S2A band 12.

<table>
<thead>
<tr>
<th>Band</th>
<th>Detector</th>
<th>Pixel number (from 0)</th>
<th>Current status</th>
<th>Last updated</th>
</tr>
</thead>
<tbody>
<tr>
<td>B12</td>
<td>1</td>
<td>440</td>
<td>Defective</td>
<td>26/08/2015</td>
</tr>
<tr>
<td>B12</td>
<td>1</td>
<td>703</td>
<td>Defective</td>
<td>06/11/2015</td>
</tr>
</tbody>
</table>
4.1.2 S2B

Table 4-4: Defective pixels on S2A band 12.

<table>
<thead>
<tr>
<th>Band</th>
<th>Detector</th>
<th>Pixel number (from 0)</th>
<th>Current status &amp; R2DEPI defective pixels</th>
</tr>
</thead>
<tbody>
<tr>
<td>B12</td>
<td>D3</td>
<td>1132</td>
<td>Defective</td>
</tr>
</tbody>
</table>

4.2 Reset Spike pixels

During the MSI design phase, it has been identified that a few pixels of the 10 m bands are affected by an electronic cross-talk during detector read-out. This results in errors which can reach a few digital counts, depending on the observed scene.

We provide below the list of affected pixels.

Table 4-5: S2A Pixel affected by reset spike noise.

<table>
<thead>
<tr>
<th>Band</th>
<th>Odd detector number</th>
<th>Even detector number</th>
<th>Current status</th>
</tr>
</thead>
<tbody>
<tr>
<td>B02, B03, B04</td>
<td>35</td>
<td>2556</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td>489</td>
<td>2102</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td>781</td>
<td>1810</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td>961</td>
<td>1630</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td>1036</td>
<td>1555</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td>1177</td>
<td>1414</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td>1252</td>
<td>1339</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td>1724</td>
<td>867</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td>1822</td>
<td>769</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td>B08</td>
<td>35</td>
<td>2556</td>
<td>Pixel Reset Noise</td>
</tr>
</tbody>
</table>
### Table 4-6: S2B Pixel affected by reset spike noise.

<table>
<thead>
<tr>
<th>Band</th>
<th>Pixel number</th>
<th>Odd detector number</th>
<th>Even detector number</th>
<th>Current status</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>618</td>
<td>1973</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>619</td>
<td>1972</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td>B2</td>
<td></td>
<td>715</td>
<td>1876</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>895</td>
<td>1696</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1047</td>
<td>1544</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1539</td>
<td>1052</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1596</td>
<td>995</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1612</td>
<td>979</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1669</td>
<td>922</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>187</td>
<td>2404</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>619</td>
<td>1972</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td>B3,B4</td>
<td></td>
<td>715</td>
<td>1876</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>895</td>
<td>1696</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1047</td>
<td>1544</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1539</td>
<td>1052</td>
<td>Pixel Reset Noise</td>
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<tr>
<td></td>
<td></td>
<td>1596</td>
<td>995</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1612</td>
<td>979</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1669</td>
<td>922</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td>B5</td>
<td></td>
<td>1243</td>
<td>52</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td>B7</td>
<td></td>
<td>1273</td>
<td>22</td>
<td>Pixel Reset Noise</td>
</tr>
<tr>
<td>B8</td>
<td></td>
<td>87</td>
<td>2504</td>
<td>Pixel Reset Noise</td>
</tr>
</tbody>
</table>
5. Product Features

5.1 Spectral Response Non-uniformity

In this section we report on a known feature of Sentinel 2 products created by the spectral response non-uniformity. This feature has been anticipated since the design phase and is compliant with mission specification. This feature is characterized by along-track soft-edged darker or brighter stripes near the detector boundaries, as shown on the figure below. Indeed, the spectral response is slightly different at the edges of the detectors, especially for bands B03 and B05. When the spectrum of the scene has strong gradient over the spectral bandwidth of the detector, a difference in the measured radiometry can be observed (up to 2% in worst-cases).

![Along-track stripes resulting from spectral response non-uniformity (band B03).](image)

5.2 Parallax effects

In this section we report on parallax effects created by the staggered configuration of the focal plane. Indeed the instrument swath is covered by 12 individual detectors assembled in a staggered manner. Because of this configuration, odd and even detectors do not see the ground under the same viewing angles. This can create visible effects on some images, as detailed in the next subsections.
5.2.1 Surface reflectance effects

Because the viewing angles are not the same for even and odd detectors, differences in measured radiometry can be observed on non-Lambertian surfaces. This is especially visible on Sun glint over sea surfaces (see Figure below).

![Figure 18: Stripe pattern over sea surface, due to the observation parallax effect between odd and even detectors.](image)

5.2.2 Misregistration of High Altitude Objects

The processing algorithm ensures the coregistration of images acquired by all spectral bands and the detectors for features at ground level. Objects at a higher altitude like planes and clouds cannot be properly coregistered. As already reported in the first issue of the Data Quality Report, this effect leads to spectral misregistration (“rainbow” effect) and discontinuities between detectors. Both effects can be seen in Figure 19 below.
5.3 Across-Track noise

This feature can be observed in very dark images (typically on B10 or B12 over the sea). It is characterized by across-track lines covering a whole detector. The typical range of this noise pattern is a few digital counts, and therefore within the requirements of the mission.

This phenomenon is induced by the compression noise on “blind” pixels used for dark signal correction. A solution to filter out this noise has been identified and its operational implementation is currently under study.
5.4 Gradient cross-talk

Figure 21: Gradient cross-talk on band B12 (highly enhanced contrast).

This feature can be seen on contrasted images on band B12 (typically near the coast). It can be explained by a cross-talk signal coming from the along-track gradient of the B11 image. The typical amplitude of the effect is 10 digital counts.

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