

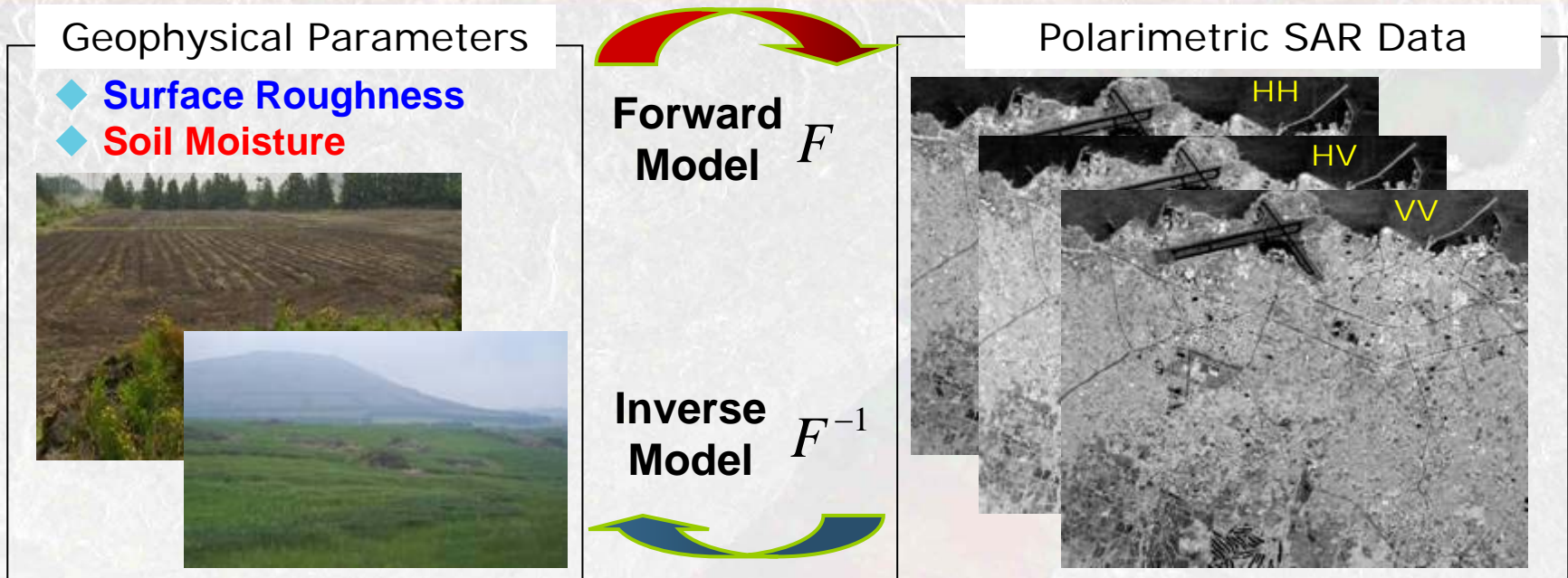
Dependence of Polarimetric Surface Scattering on Spatial Resolution

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- Nonlinear Forward Mapping

$$F(\Theta) \rightarrow \Omega$$

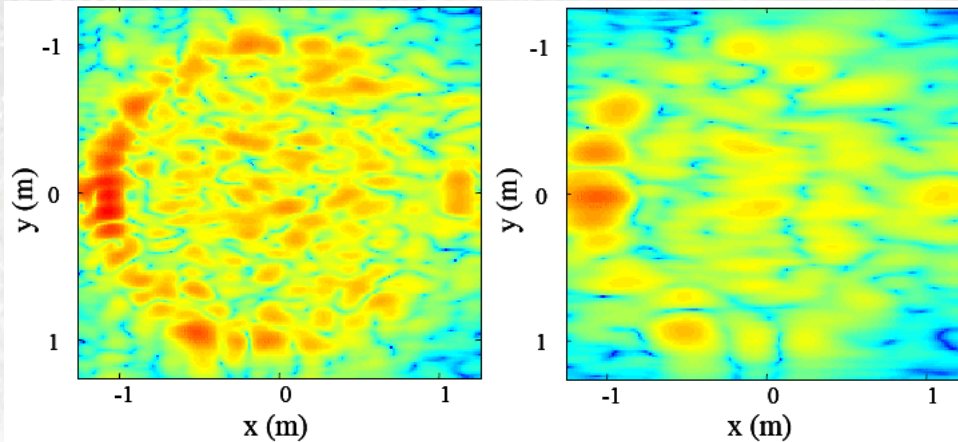
$$\Theta = \left\{ \begin{array}{l} \text{Dielectric constant,} \\ \text{Height distribution, Autocorrelation} \end{array} \right\}$$

$$\Omega = \left\{ \begin{array}{l} \text{Independent combination of} \\ \text{polarization measurements} \end{array} \right\}$$

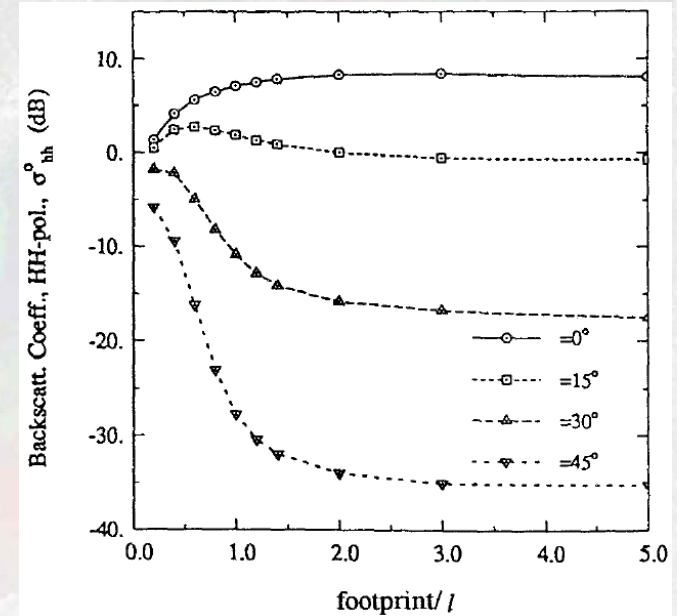
→ Finding the set of unknown surface parameters from polarization measurement

$$\bar{\Theta} = F^{-1}(\Omega)$$

[Nesti et al., 1996; Allain et al. 2003]



[Sarabandi and Oh, 1995]



■ Aims of the study

Understanding the effects of the spatial resolution of the radar sensor on

- 1) the statistical description of surface roughness properties
- 2) the surface backscattering characteristics

particularly for the high resolution polarimetric radar systems.

Height Probability Distribution	Autocovariance (Autocorrelation)
$\left(\begin{array}{l} \text{Zero mean Gaussian} \\ \text{characterized by its RMS height} \end{array} \right)$ $\sigma = \sqrt{\langle z(x)^2 \rangle - \langle z(x) \rangle^2}$	$R(l) = \langle z(x)z(x+l) \rangle - \langle z(x) \rangle^2$ $R_N(l) = R(l) / R(0) = R(l) / \sigma^2$ $R_N(l_C) = 1/e$

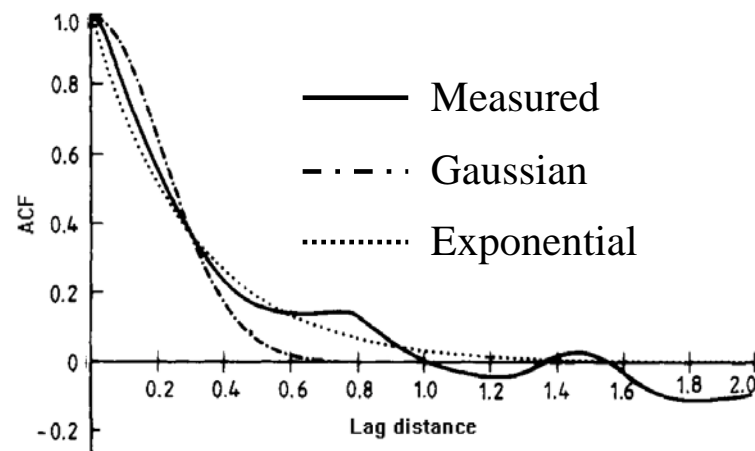
✓ Essential to define an appropriate mathematical function for the autocovariance

o The commonly used **Autocovariance Functions (ACVF)** are Gaussian and Exponential

$$\left\{ \begin{array}{l} R(l)_G = \sigma^2 \exp[-l^2 / l_C^2] \\ R(l)_E = \sigma^2 \exp[-|l| / l_C] \end{array} \right\} \text{Correlation length does not define the types of ACF}$$

o Roughness **Power Spectral Density (PSD)**

$$\left\{ \begin{array}{l} W(K)_G = FT\{R(\tau)_G\} = \sigma^2 \sqrt{\pi} l_C \exp[-l_C^2 K^2 / 4] \\ W(K)_E = FT\{R(\tau)_E\} = \sigma^2 2l_C [1 + l_C^2 K^2]^{-1} \end{array} \right\}$$



- ✓ Statistical properties of random rough surfaces are affected by the spatial resolution of the radar sensor.

□ Autocovariance of the **infinite surface**

$$R(l) = \langle [z(x) - \mu][z(x+l) - \mu] \rangle = \left\langle \lim_{L_x \rightarrow \infty} \frac{1}{L_x} \int [z(x) - \mu][z(x+l) - \mu] dx \right\rangle$$

□ Autocovariance defined in a range L_x

$$\rho(l) = \left\langle \frac{1}{L_x} \int [z(x) - \bar{z}][z(x+l) - \bar{z}] dx \right\rangle$$

$$= \underline{(1 - |l| / L_x) R(l) - (1 - |l| / L_x) \text{var}(\bar{z})}$$

$$\text{var}(\bar{z}) = \langle (\mu - \bar{z})^2 \rangle = \frac{2}{L_x} \int_0^{L_x} (1 - |t| / L_x) R(t) dt$$

Autocovariance Function of Truncated Surface (ACVFT)

$$\rho(l) = (1 - |l|/L_x) \{R(l) - \text{var}(\bar{z})\}$$

Gaussian ACVFT

$$\rho(l)_G = \left(1 - \frac{|l|}{L_x}\right) \left\{ \sigma^2 \exp\left[-\frac{l^2}{l_C^2}\right] - G \right\}$$

$$G = \sigma^2 \left\{ \alpha^2 (\exp[\alpha^{-2}] - 1) + \alpha \sqrt{\pi} \text{Erf}[\alpha^{-1}] \right\}$$

$$\alpha = l_C / L_x$$

Gaussian PSDT

$$S(K)_G = W(K)_G \otimes L_x \text{sinc}^2(L_x K)$$

$$- L_x G \text{sinc}^2(L_x K)$$

Exponential ACVFT

$$\rho(l)_E = \left(1 - \frac{|l|}{L_x}\right) \left\{ \sigma^2 \exp\left[-\frac{|l|}{l_C}\right] - H \right\}$$

$$H = 2\sigma^2 \left\{ \alpha^2 (\exp[\alpha^{-1}] - 1) + \alpha \right\}$$

$$\alpha = l_C / L_x$$

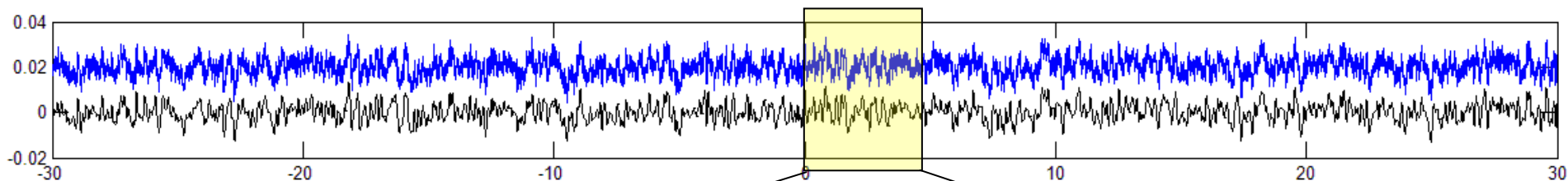
Exponential PSDT

$$S(K)_E = W(K)_E \otimes L_x \text{sinc}^2(L_x K)$$

$$- L_x H \text{sinc}^2(L_x K)$$

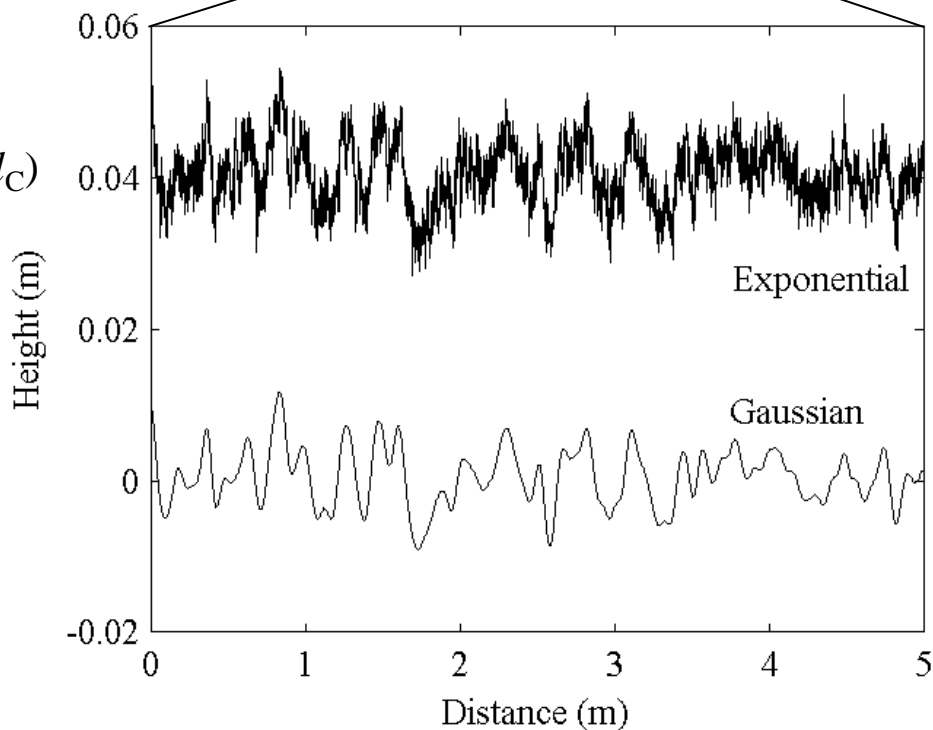
❖ Numerical Generation

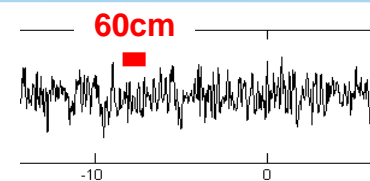
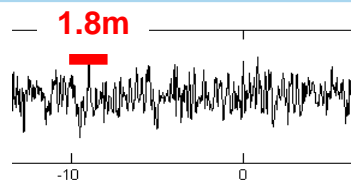
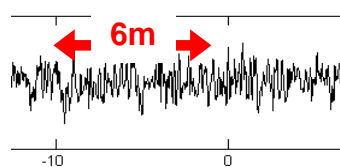
→ Gaussian and Exponentially Correlated Rough Surface



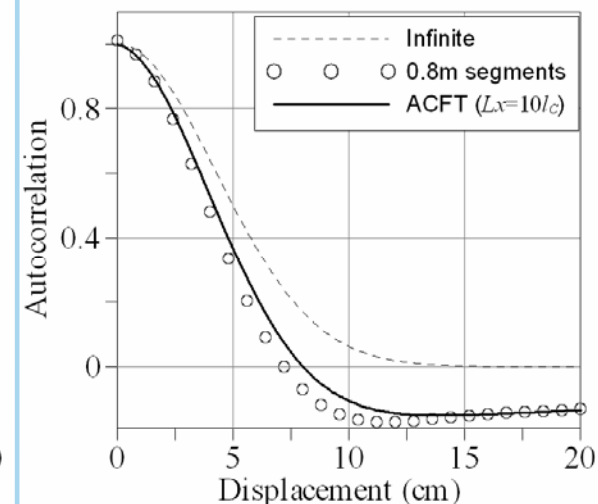
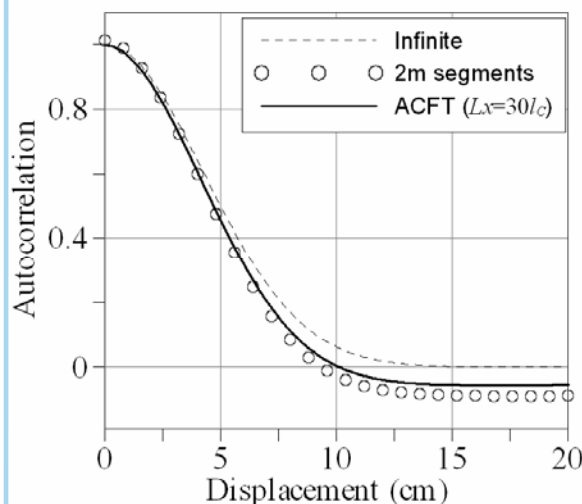
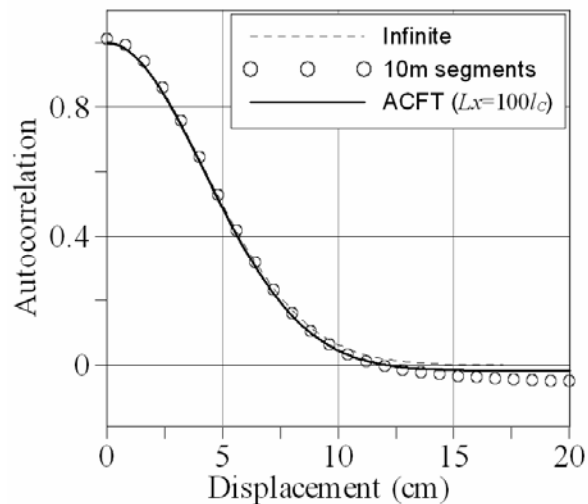
$$\sigma = 0.4\text{cm} \quad l_C = 6\text{cm}$$

Profile length: 60m (=1000 l_C)

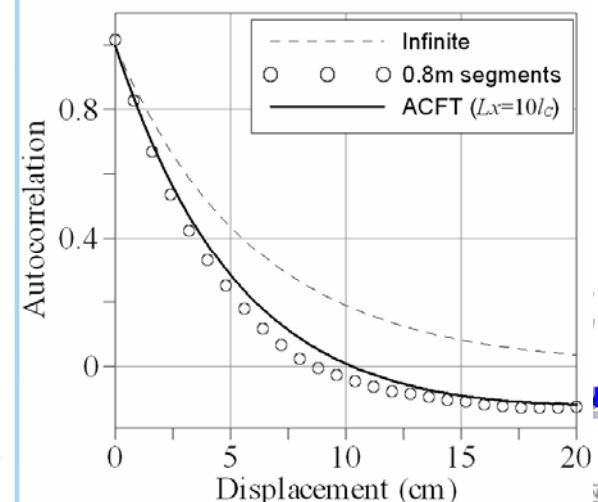
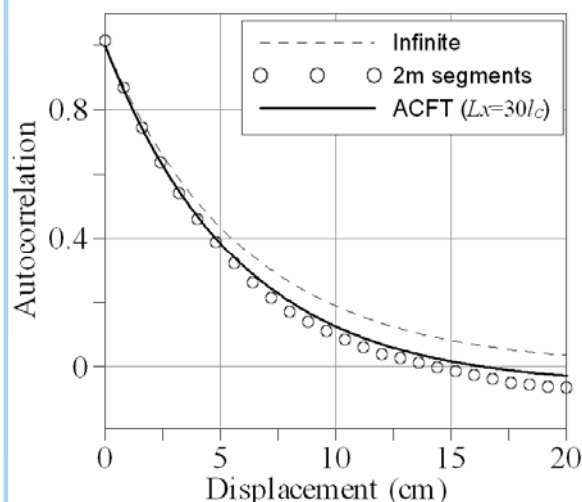
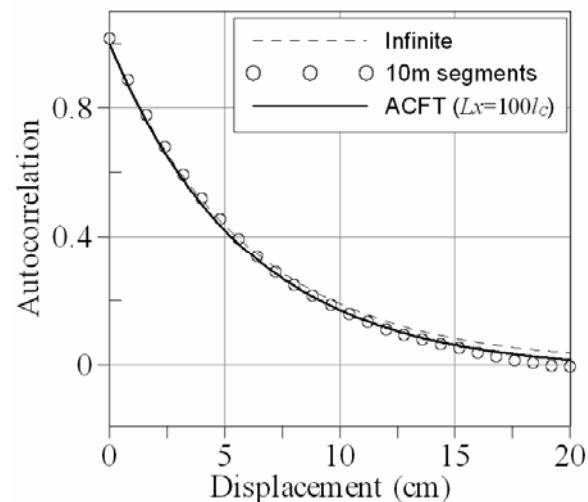




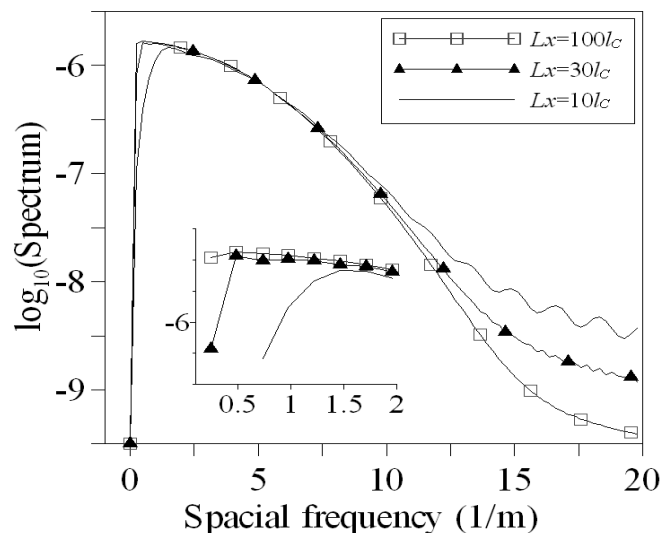
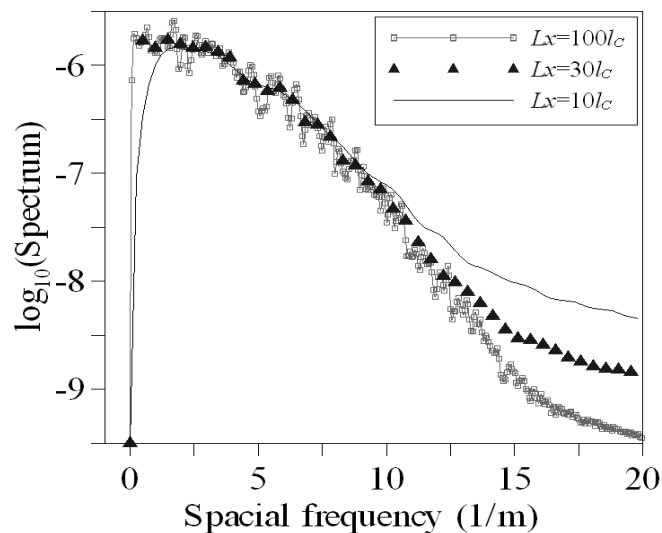
Gaussian



Exponential



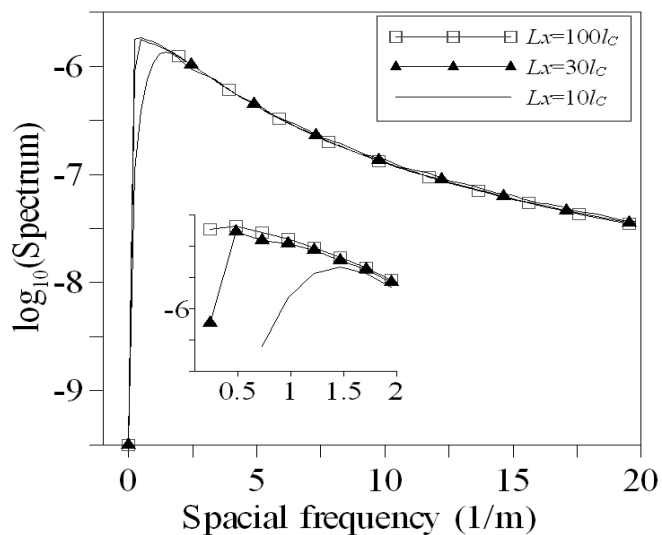
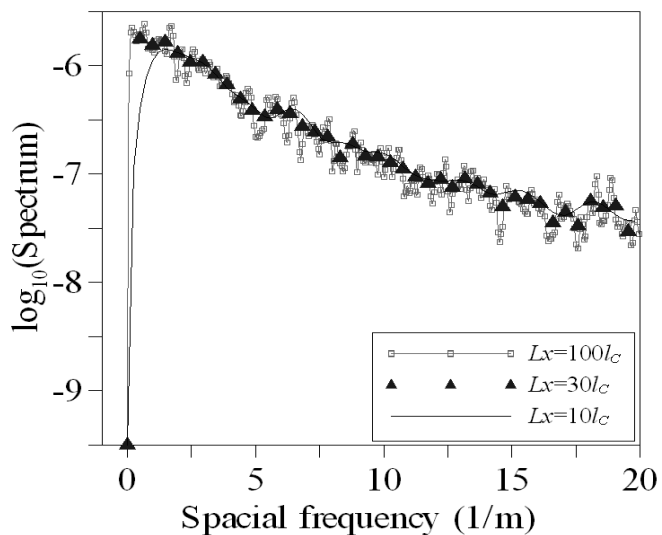
Gaussian



- The roughness power spectrum is band limited by a size of the resolution cell

$$f_c = \frac{1}{L_x}$$

Exponential



➤ Integral Equation Method

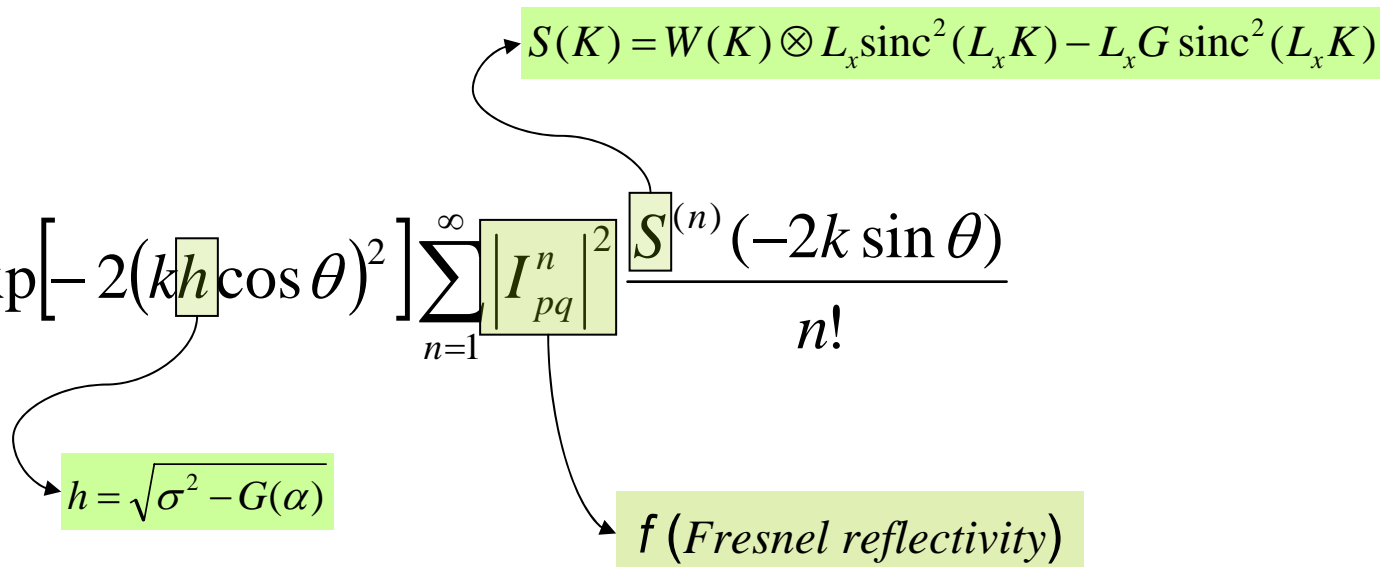
[Fung, 1992; 1994; Wu et al., 2001]

$$\sigma_{pq}^0 = \frac{k^2}{2} \exp\left[-2(kh \cos \theta)^2\right] \sum_{n=1}^{\infty} \left| I_{pq}^n \right|^2 \frac{S^{(n)}(-2k \sin \theta)}{n!}$$

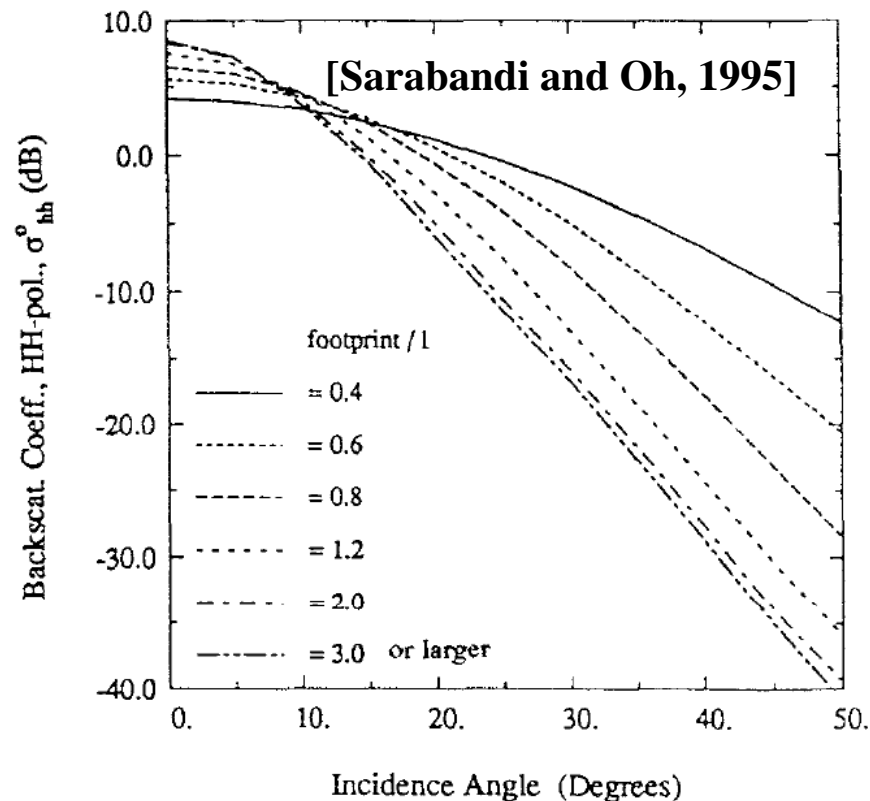
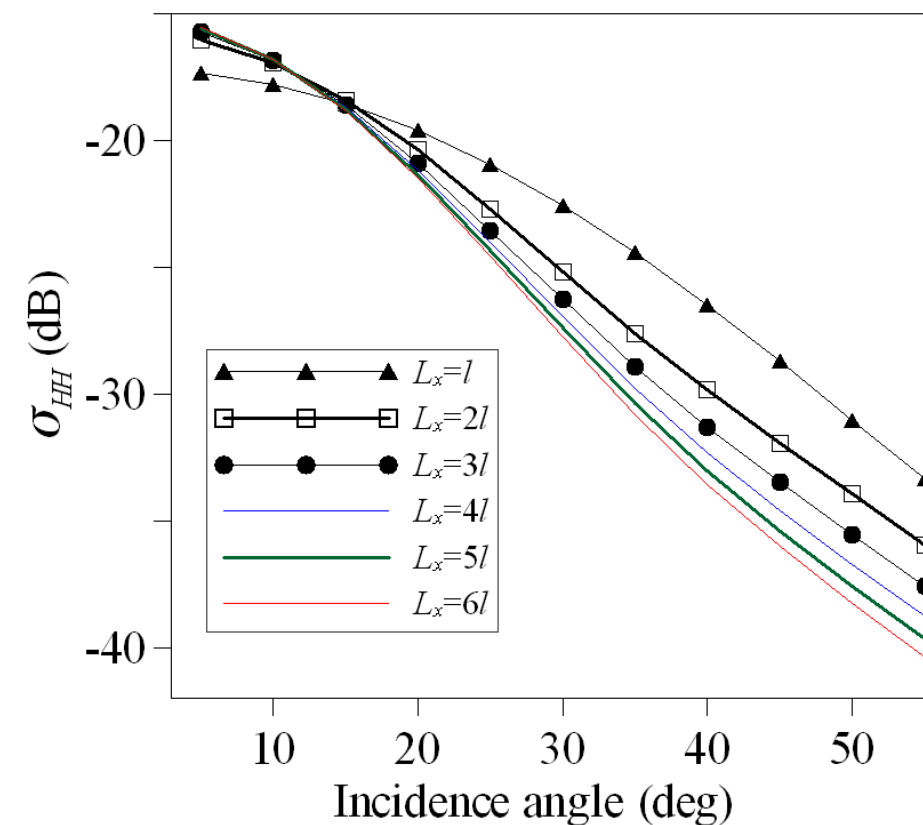
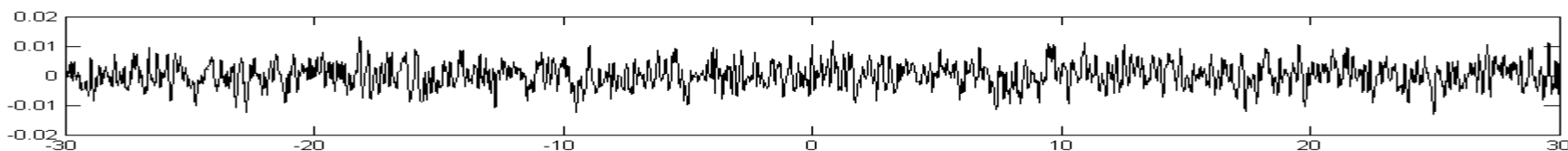
$h = \sqrt{\sigma^2 - G(\alpha)}$

f (Fresnel reflectivity)

$S(K) = W(K) \otimes L_x \text{sinc}^2(L_x K) - L_x G \text{sinc}^2(L_x K)$

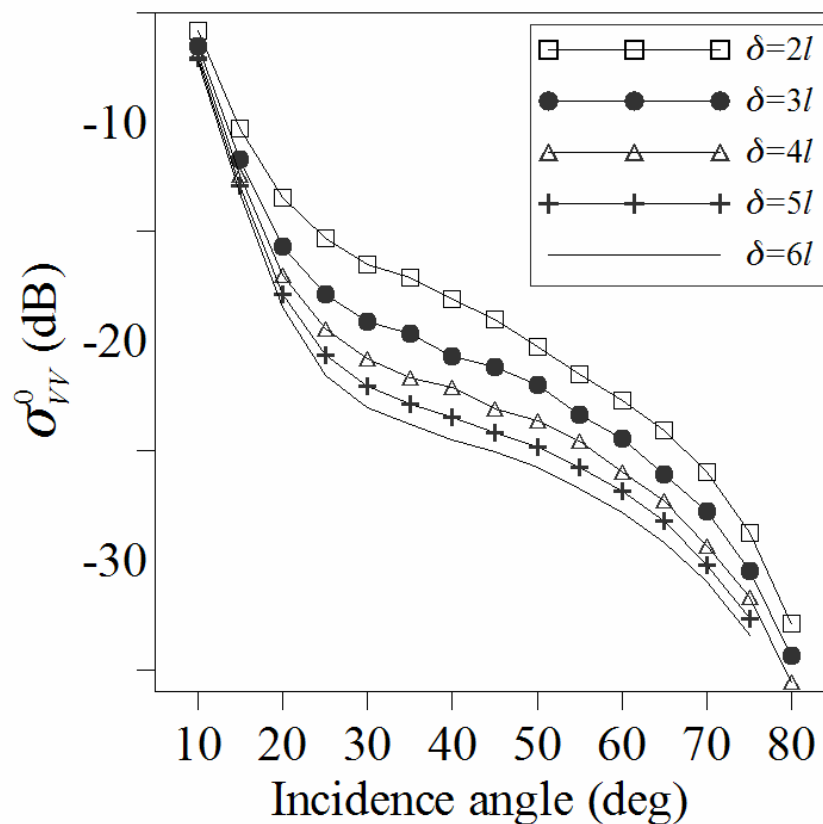
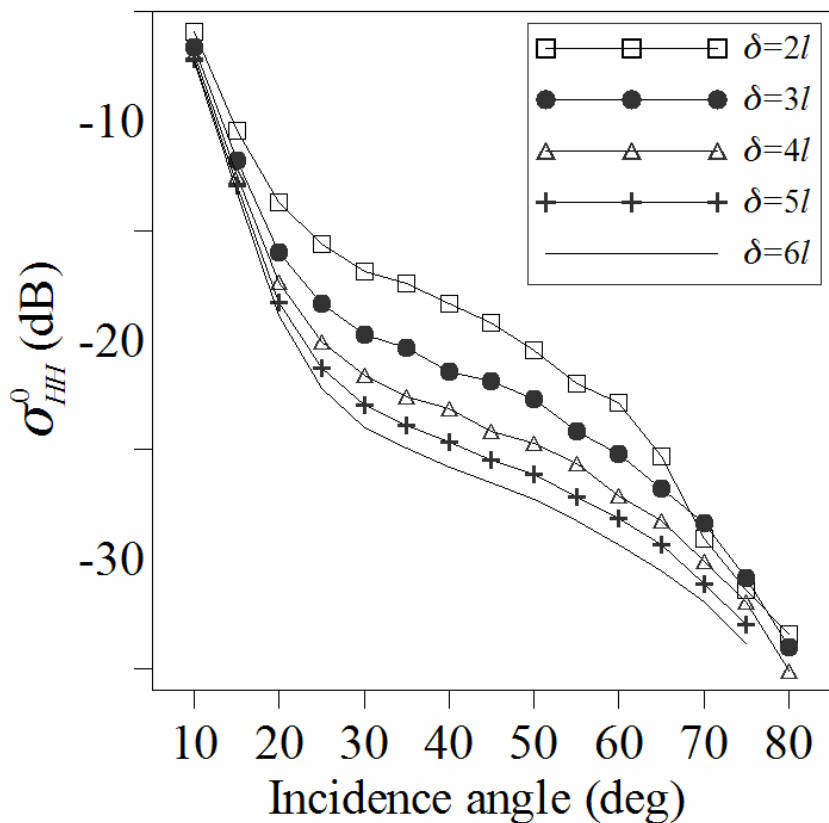
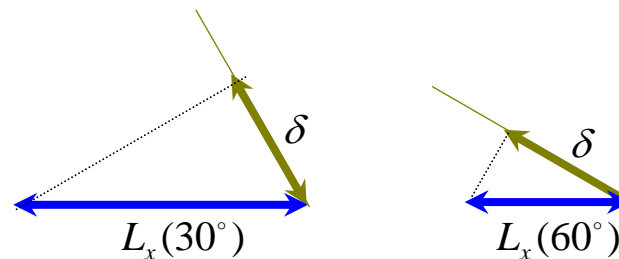


- Dependence of backscattering coefficients on the spatial resolution for the generated rough surface $\sigma = 0.4\text{cm}$, $l = 6\text{cm}$



✓ Spatial resolution on the Earth's surface

$$L_x = \frac{\delta}{\sin \theta} = \frac{c}{2B \sin \theta}$$

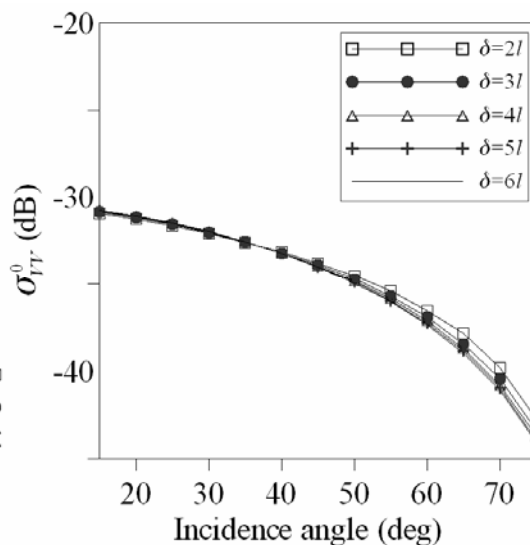
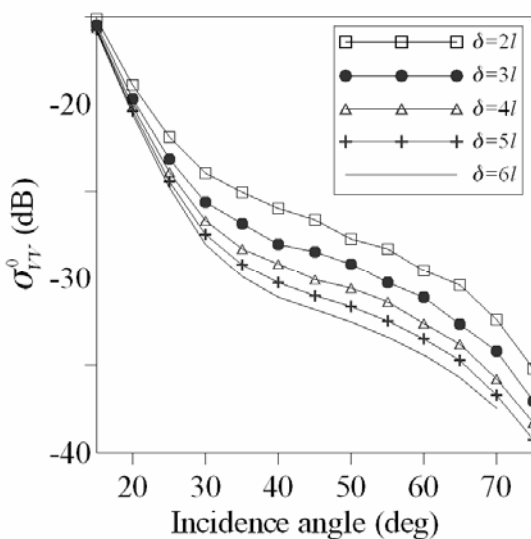
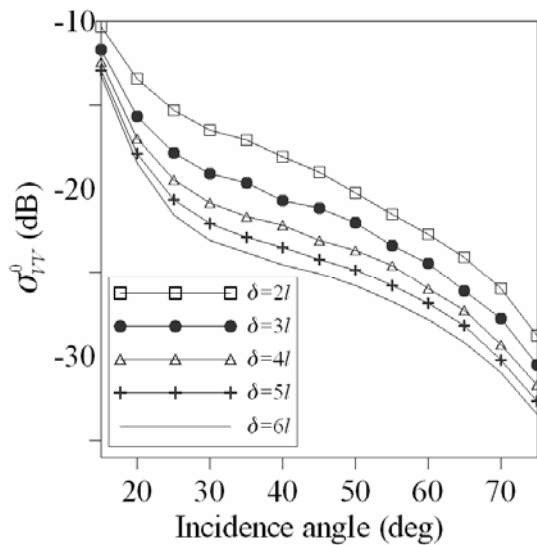


X-band

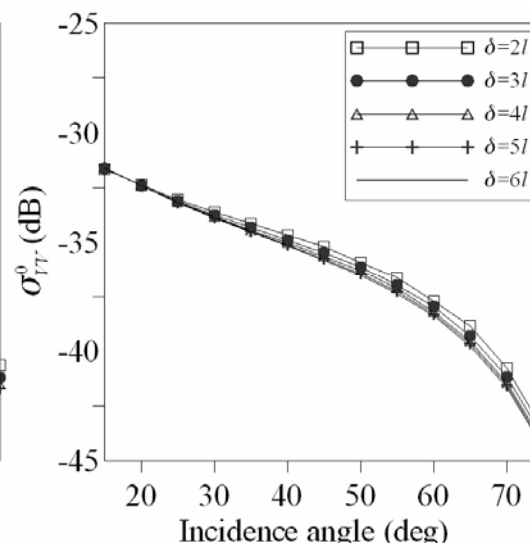
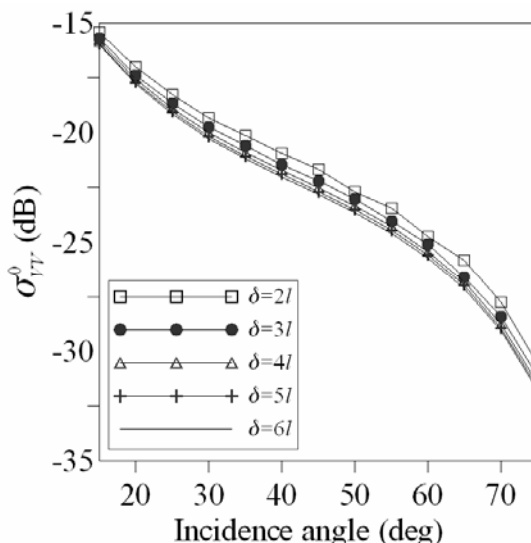
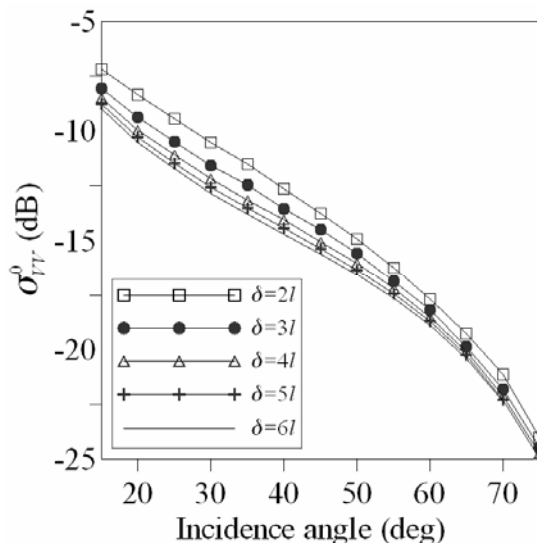
C-band

L-band

Gaussian



Exponential

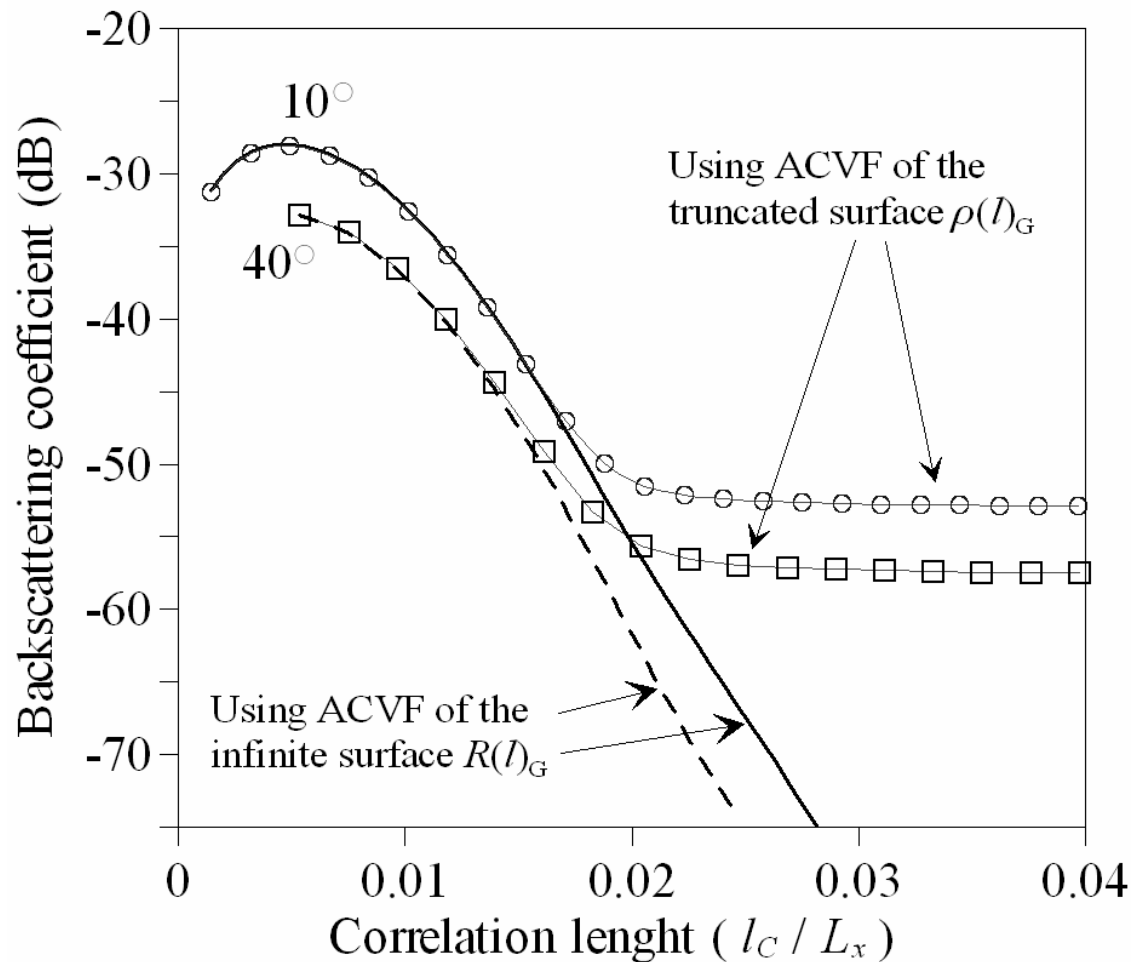


□ ACVFT or PSDT depends on

- spatial resolution, and
- correlation length



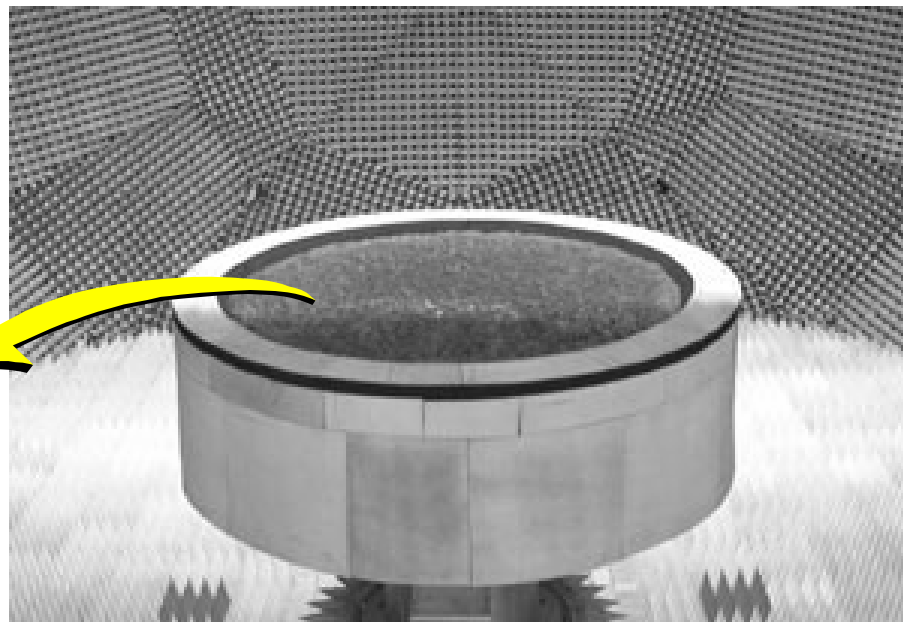
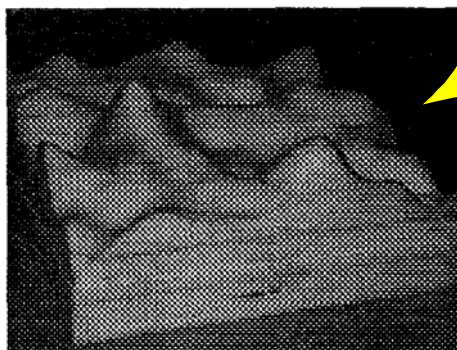
The correlation length may affect an analysis of radar backscattering coefficient



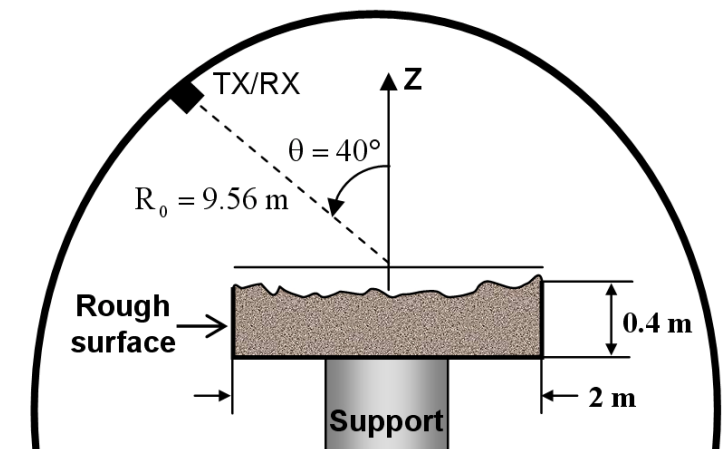
Gaussian isotropic surfaces

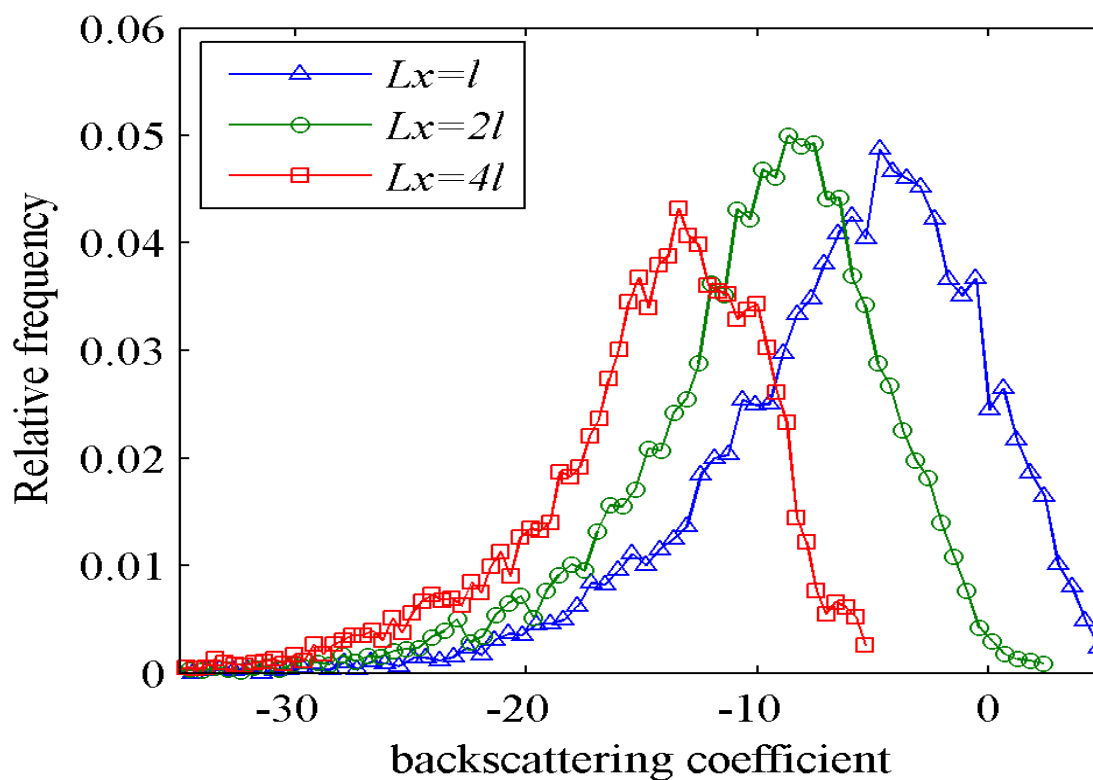
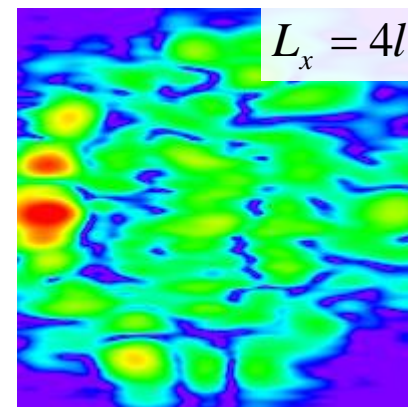
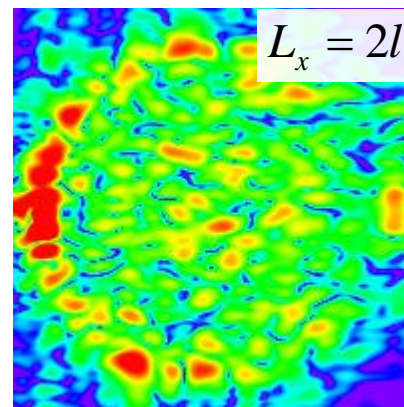
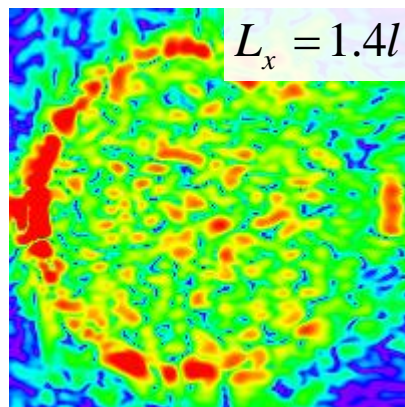
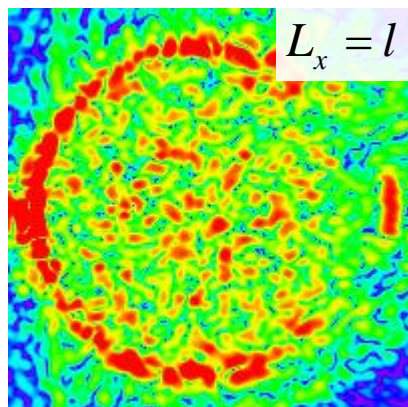
$$\sigma = 0.4\text{cm}$$

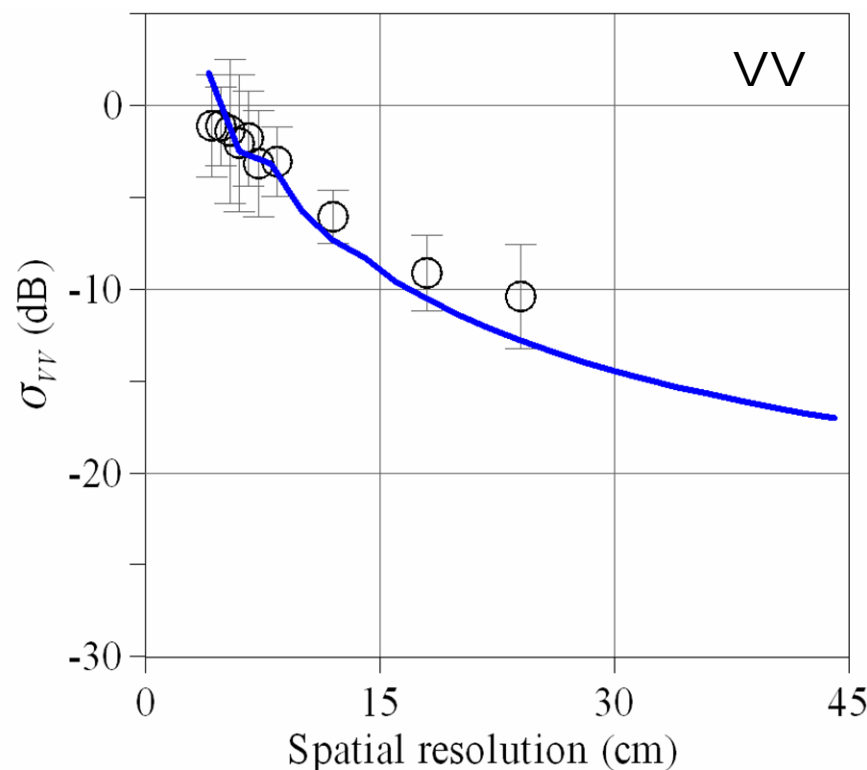
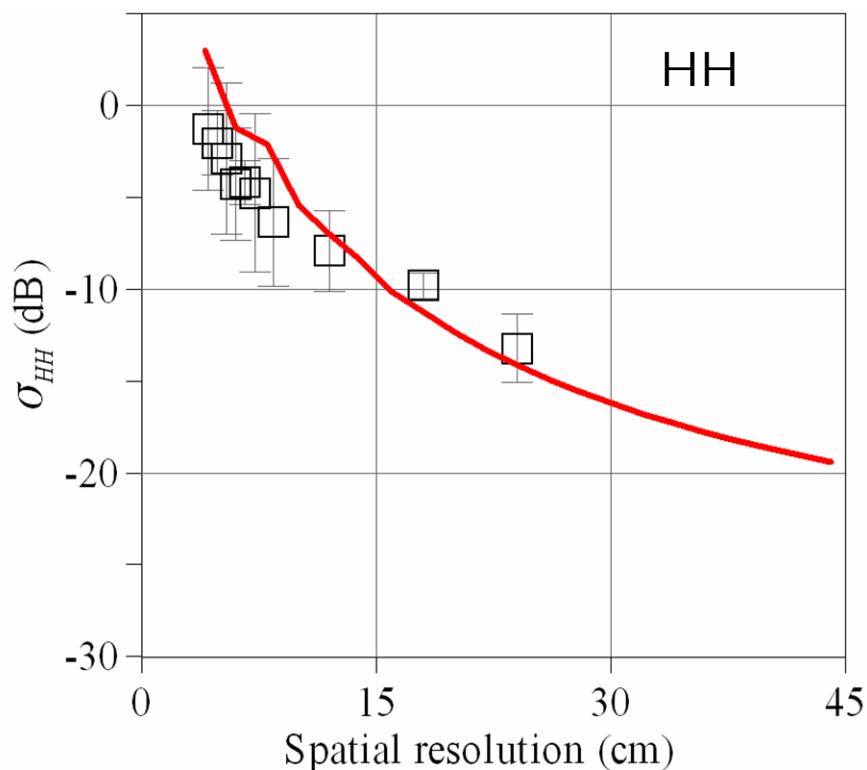
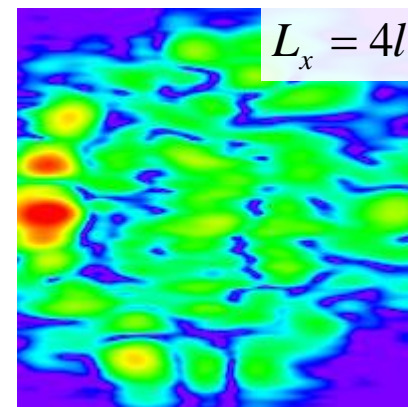
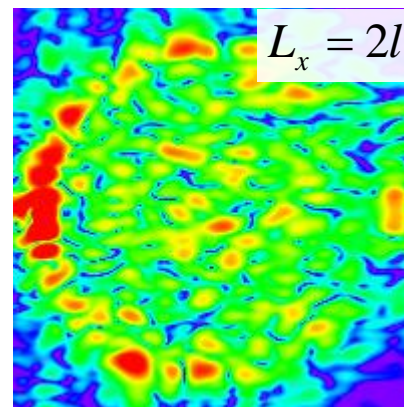
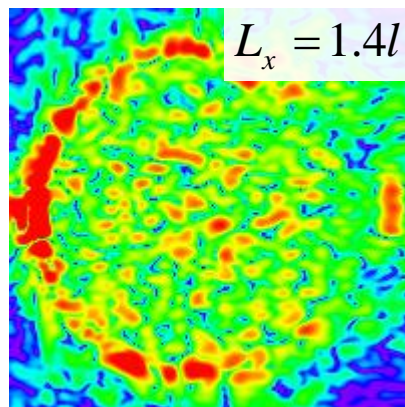
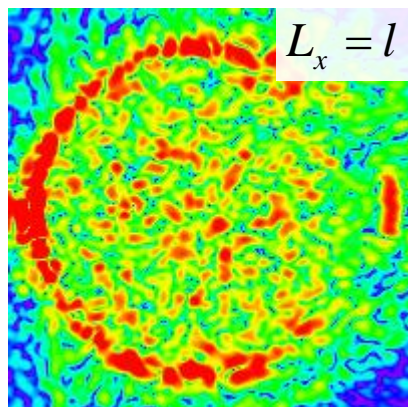
$$l = 6\text{cm}$$



- Incidence angle = 40°
- Frequency = 14 GHz
- Resolution = 4.2 cm - 24 cm







- ❖ An appropriate description of the effect of spatial resolution on statistical characteristics of rough surface has been presented by introducing the ACVF of truncated surface.
- ❖ Traditional computation of the surface backscattering based on the autocovariance function of infinite surface leads to an underestimation of the backscattering signature of high resolution radar.
- ❖ Forward and Inverse modeling of backscattering response based on the sample roughness statistics has not been completely resolved yet particularly due to the spatial variability of local Fresnel coefficients in high resolution radar.