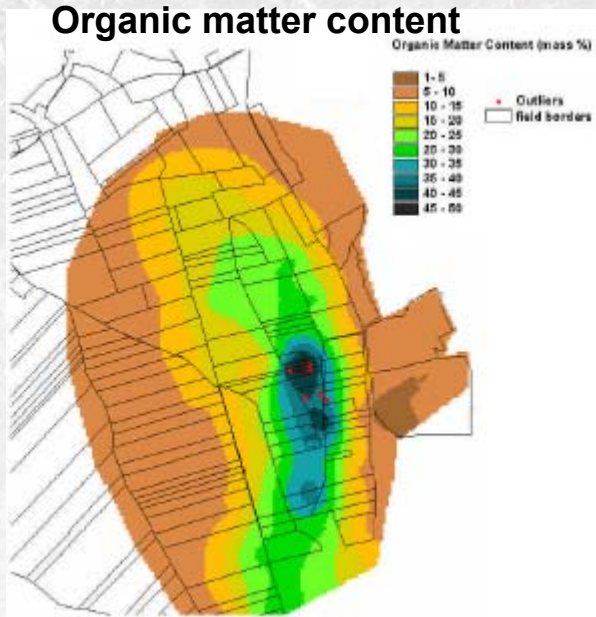


Soil moisture retrieval over periodic surfaces using PoISAR data

Sandrine DANIEL Sophie ALLAIN Laurent FERRO-FAMIL Eric POTTIER

IETR Laboratory, UMR CNRS 6164, University of Rennes1, France

- **Soil moisture retrieval over plowed fields: classical methods**
- **Time-Frequency analysis**
- **Polarimetric analysis**
- **Rough periodic surface scattering model**
- **Soil moisture retrieval**



RGB



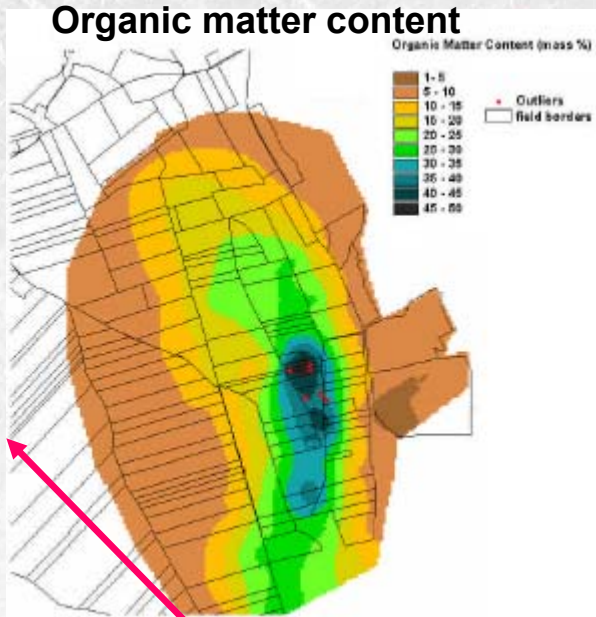
Ikonos image



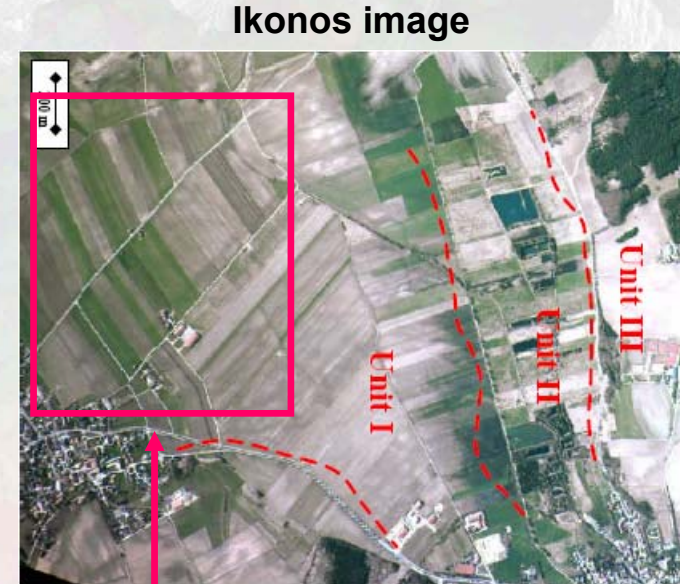
L band Quad pol data set
DLR E-SAR sensor
March 2000, Alling, Germany

Test site

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RGB



Slightly wet area

- Mainly rough and flat fields
- Some are plowed



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Herold M. et al., "Acquisition and evaluation of field measurements from the Alling-SAR 2000 campaigns", 2001.

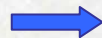
Objective

- Estimate soil moisture over all unvegetated agricultural fields

⇒ FLAT and PLOWED fields

Classical soil moisture retrieval schemes

- Oh's method



Co and Cross polar ratio analysis

$$p = \frac{\sigma_{HH}}{\sigma_{VV}}$$

$$q = \frac{\sigma_{HV}}{\sigma_{VV}}$$

- H/ α method



Entropy and α angle analysis

Polarimetric
degree of randomness

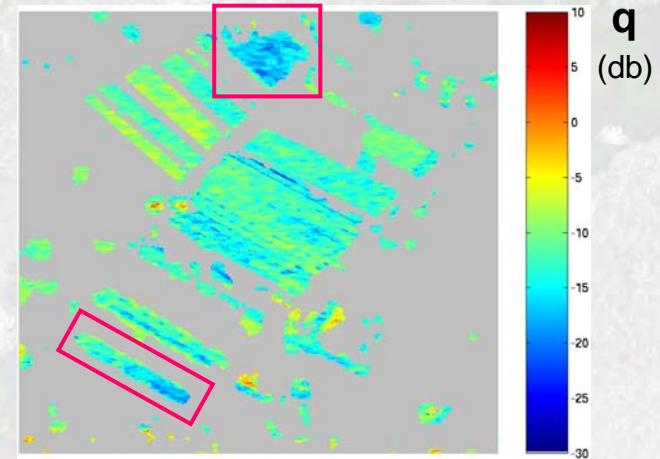
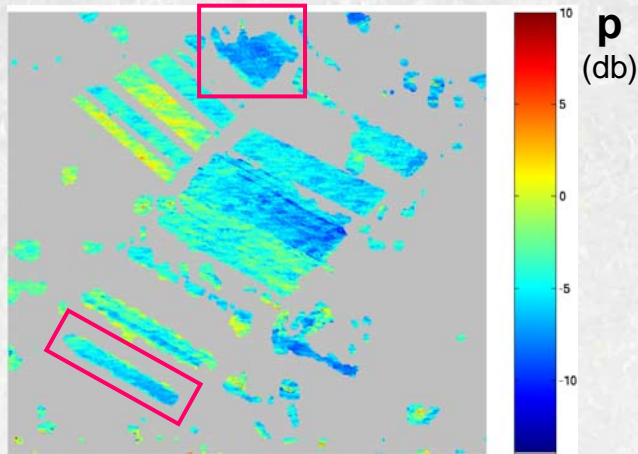
Nature of
scattering mechanisms

Oh's method

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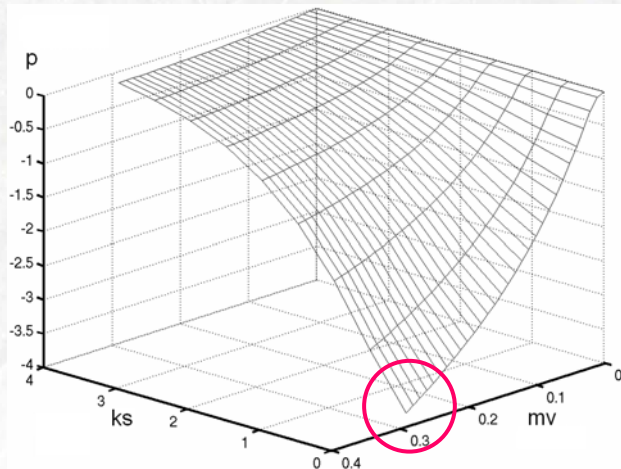


 Plowed fields

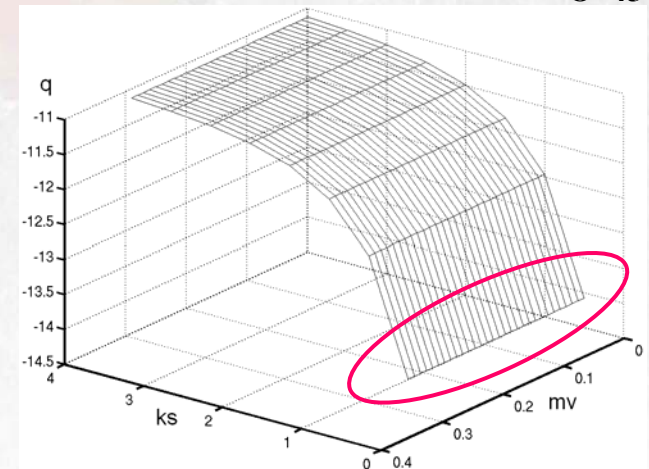


Oh's model co- and cross-polar ratios

$\Theta=45^\circ$



ks: roughness
mv: moisture content



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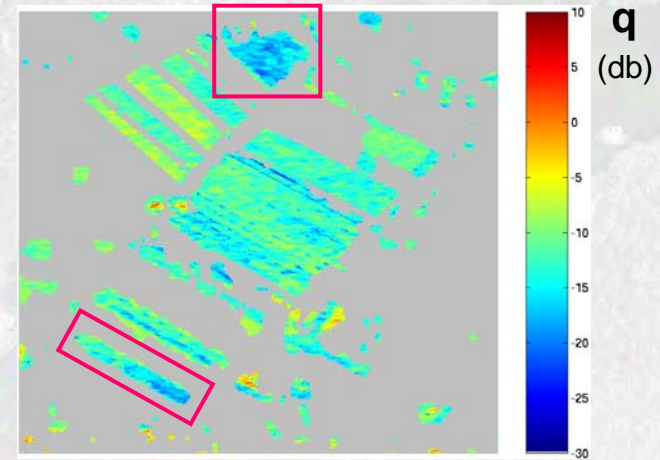
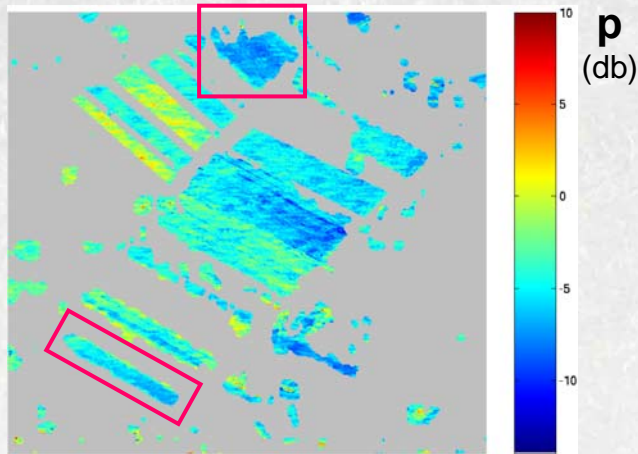
Oh Y., "Quantitative Retrieval of Soil moisture Content and Surface Roughness From Multipolarized Radar Observations of Bare Soil Surfaces", 2004.

Oh's method

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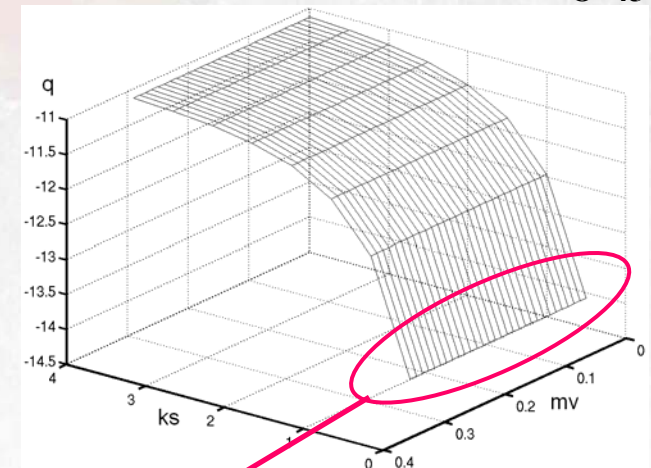
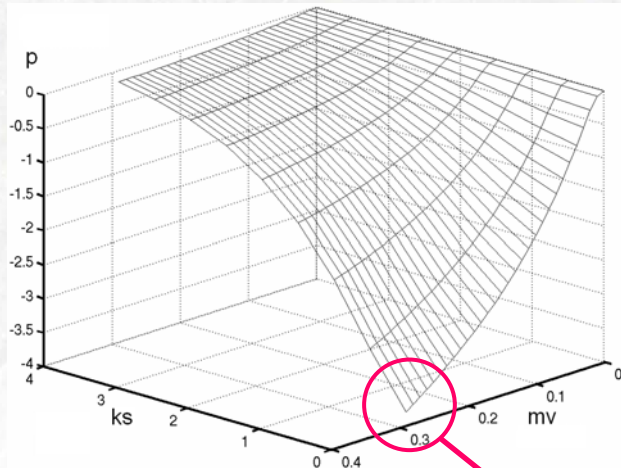


 Plowed fields



Oh's model co- and cross-polar ratios

$\Theta=45^\circ$



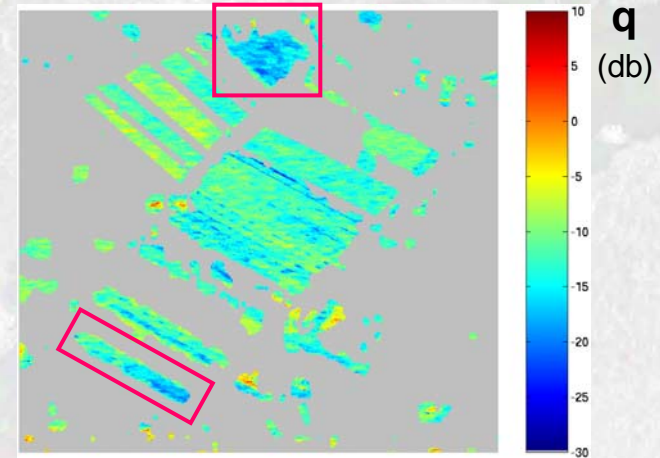
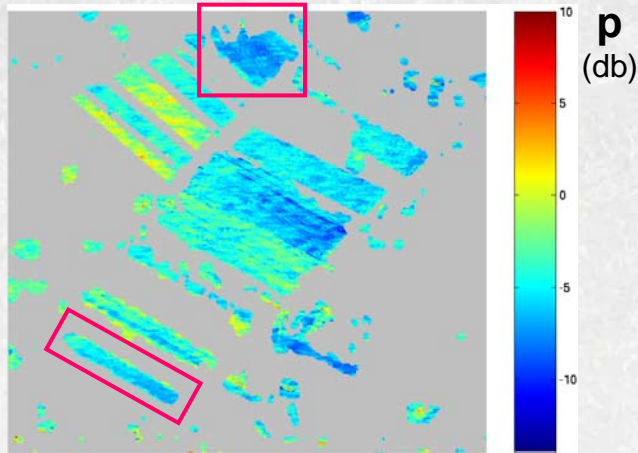
Soil estimation: very smooth and very wet

Oh's method

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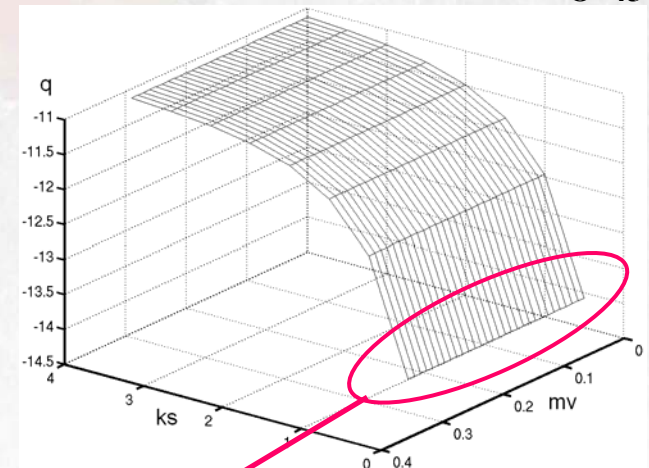
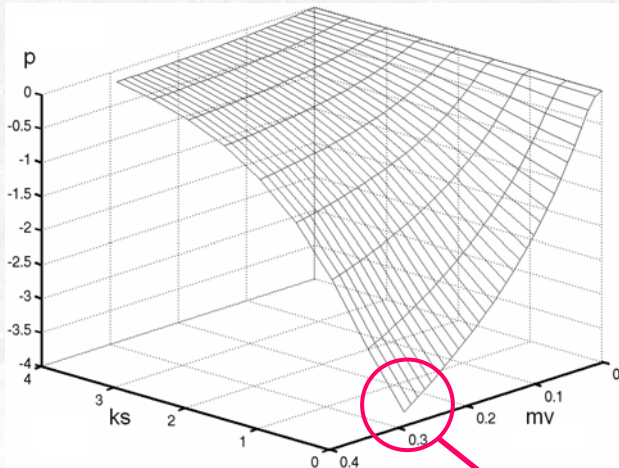


 Plowed fields



Oh's model co- and cross-polar ratios

$\Theta=45^\circ$



~~Soil estimation: very smooth and very wet~~

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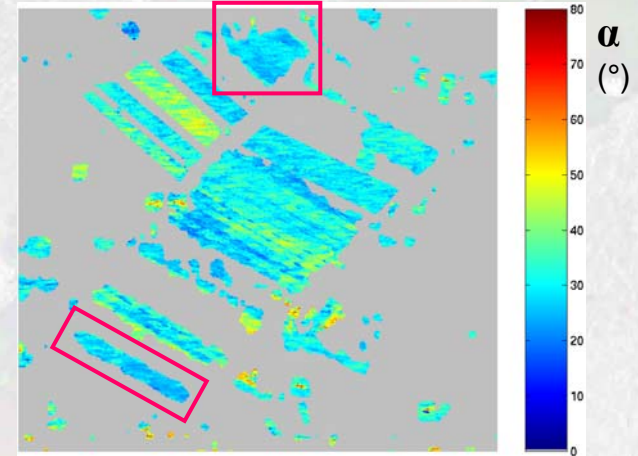
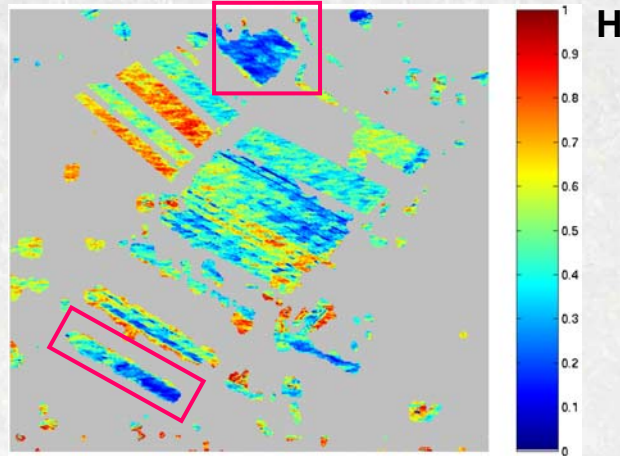
Ground truth: plowed fields and slightly wet

H/ α method

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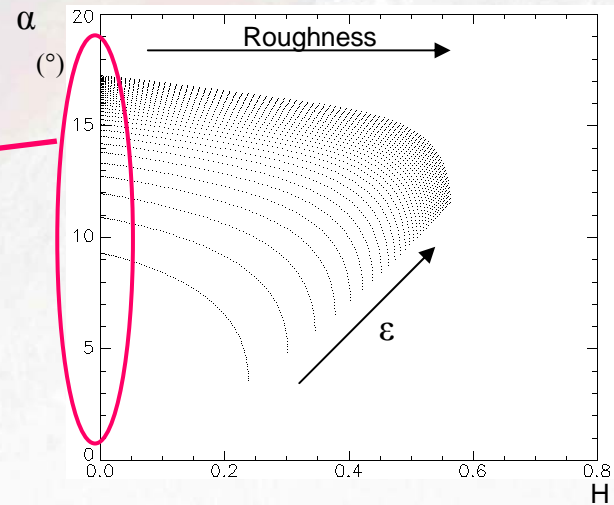


 Plowed fields



$\Theta=45^\circ$

Soil estimation: very smooth and very wet

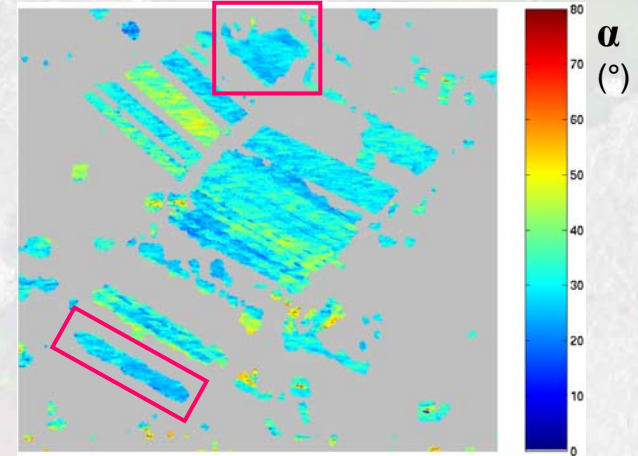
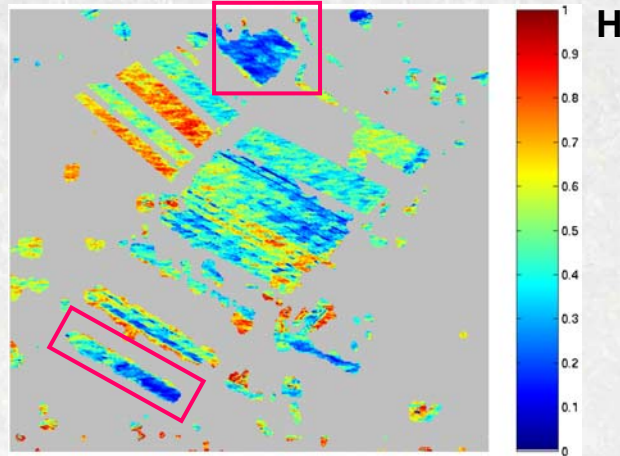


H/ α method

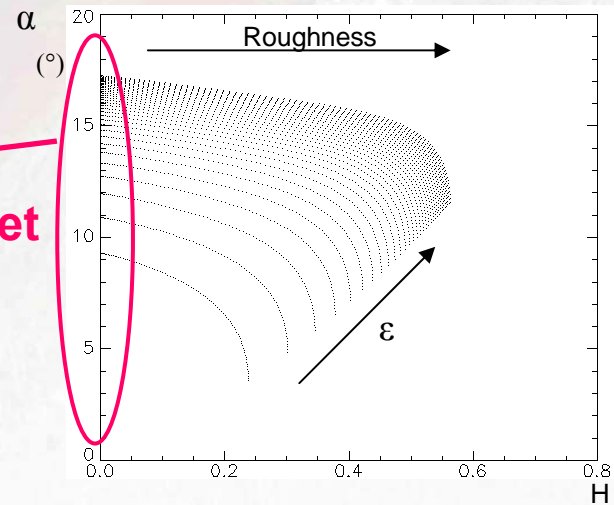
→ POLINSAR 2009 WORKSHOP



 Plowed fields



$\Theta=45^\circ$



Soil estimation: ~~very smooth and very wet~~

Ground truth: plowed fields and slightly wet

Erroneous estimates over some plowed fields



Classical methods are not adapted

Low values of entropy and α angle may be observed over anisotropic fields*



Non-stationary scattering pattern investigation



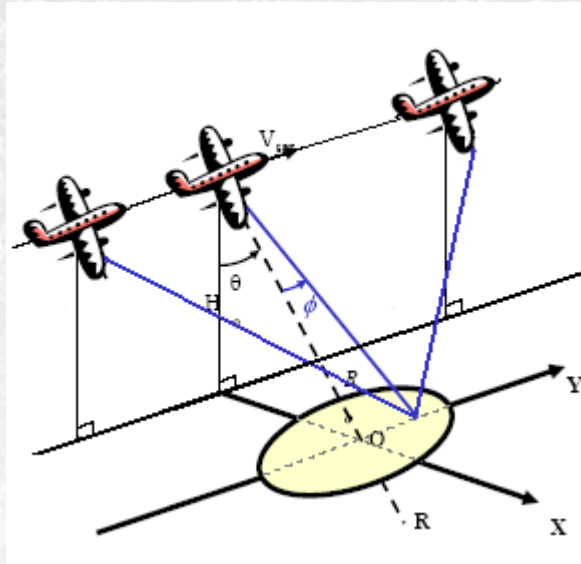
Time-frequency analysis

Time-Frequency analysis

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Principle of SAR

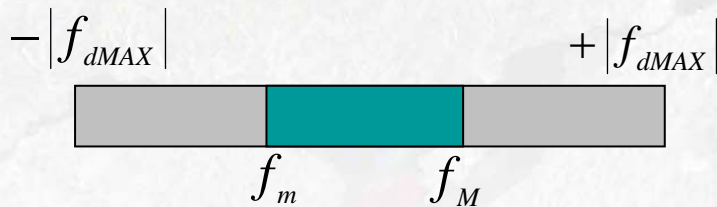


One scene is observed under different azimuth look angles



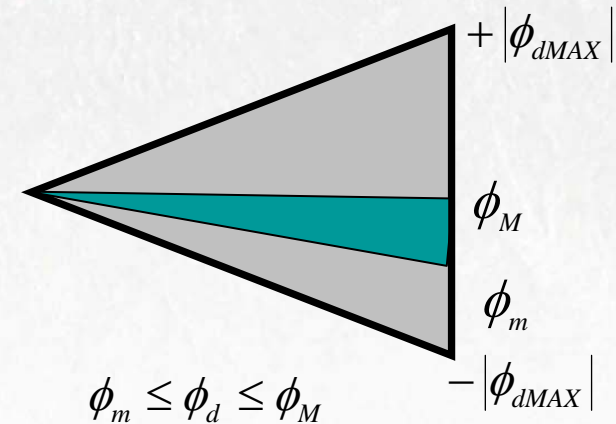
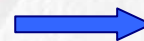
$$f_{az} = 2f_c \frac{V_{SAR}}{c} \sin \phi_0$$

Doppler spectrum



$$f_m \leq f_d \leq f_M$$

Antenna azimuth aperture



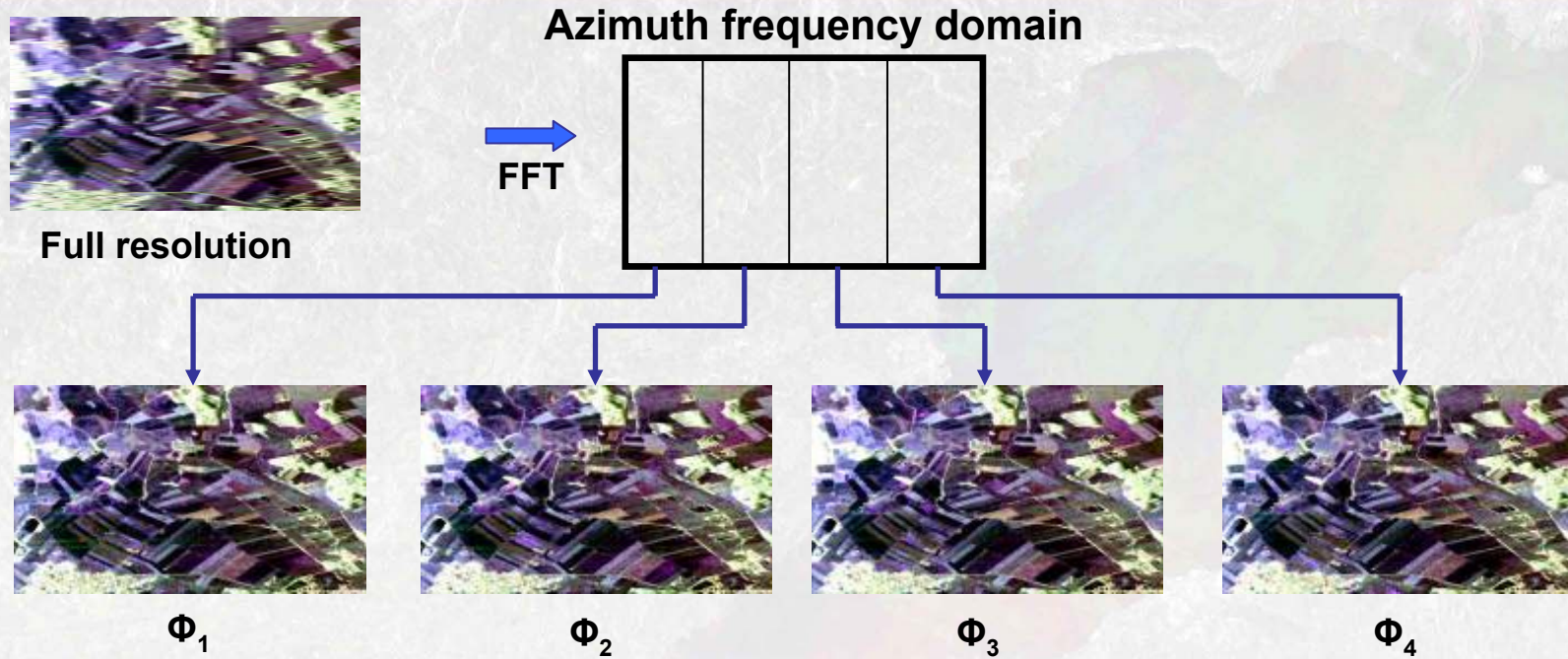
$$\phi_m \leq \phi_d \leq \phi_M$$

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Ferro-Famil L et al., "Scene Characterization Using Subaperture Polarimetric SAR data", 2003.

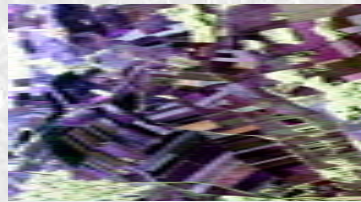
Time-Frequency analysis

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Time-Frequency analysis

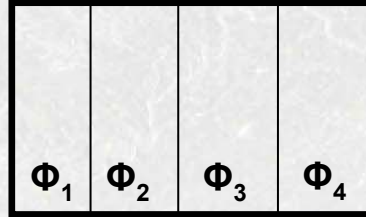
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Full resolution

→
FFT

Azimuth frequency domain

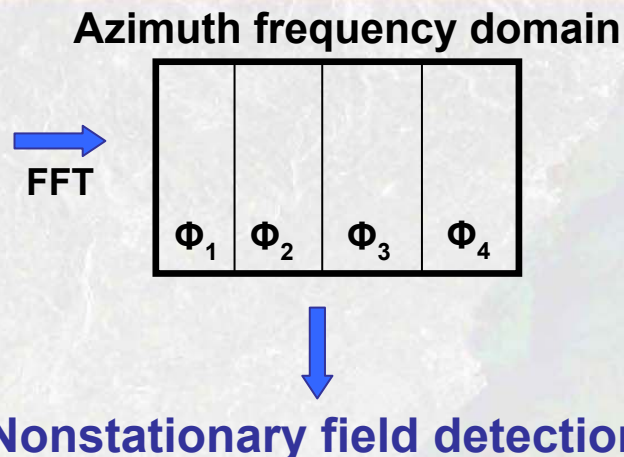


Bragg resonance





Full resolution



- Polarimetric representations statistics

Over homogeneous areas $S(\phi_i) \sim N_C(0, \Sigma_i)$

⇒ n-look sampled matrix $\mathbf{T}(\phi_i) \sim W_C(n, \Sigma_i)$

- Maximum-likelihood detection

Hypothesis: $\mathbf{T}(\phi_1), \dots, \mathbf{T}(\phi_R)$ follow the same distribution, i.e. $\Sigma_1 = \dots = \Sigma_R$

⇒ ML ratio test: $\Lambda = \frac{\prod_{i=1}^R |\mathbf{T}(\phi_i)|^{n_i}}{|\mathbf{T}_t|^{n_t}}$ with $n_t = \sum_{i=1}^R n_i$ and $\mathbf{T}_t = \frac{\sum_{i=1}^R n_i \mathbf{T}(\phi_i)}{n_t}$

Time-Frequency analysis

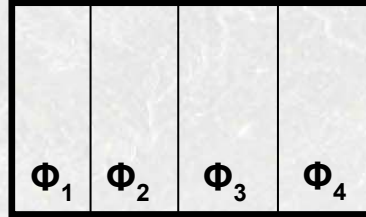
→ POLINSAR 2009 WORKSHOP



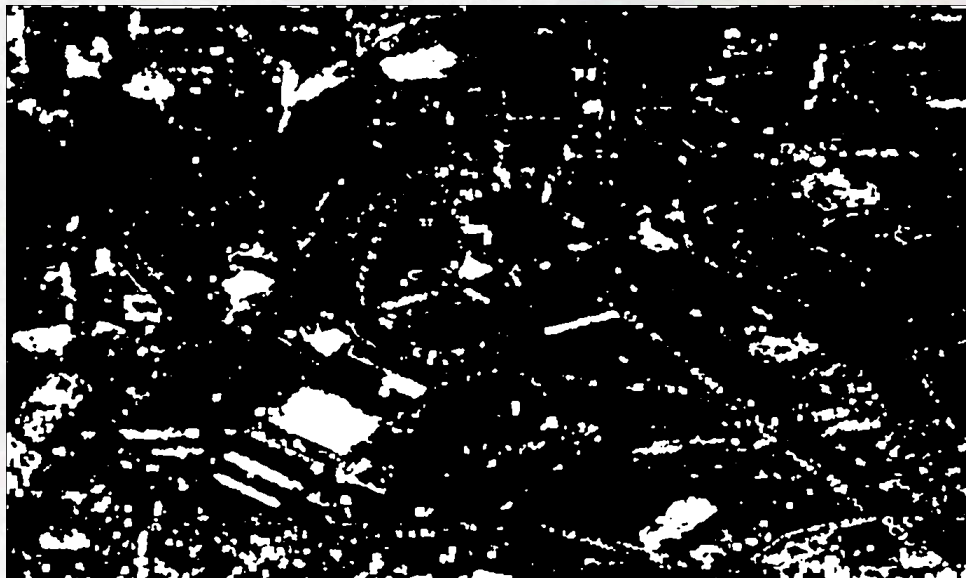
Full resolution

→
FFT

Azimuth frequency domain



Nonstationary field detection



Time-Frequency analysis

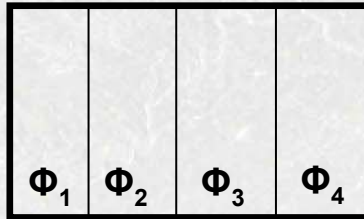
→ POLINSAR 2009 WORKSHOP



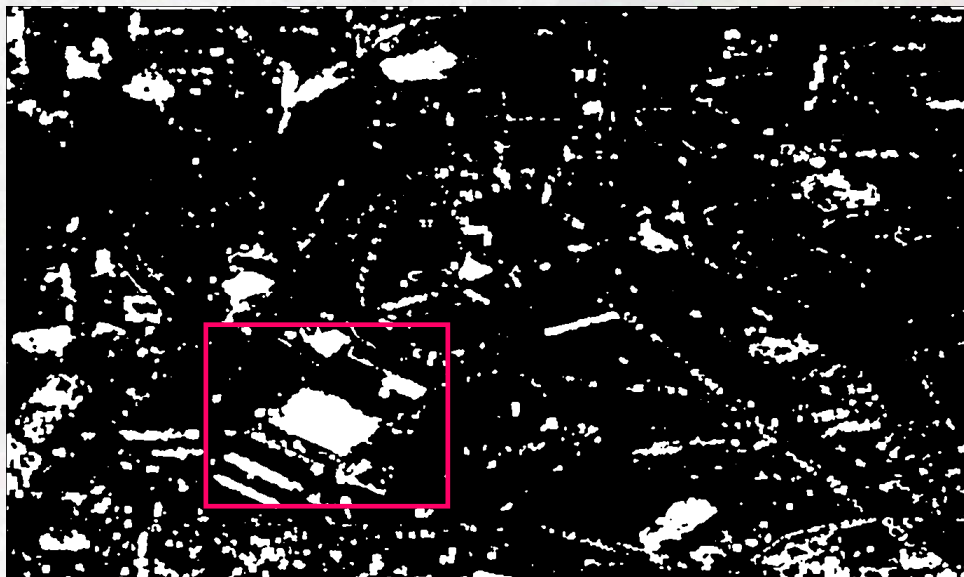
Full resolution

→
FFT

Azimuth frequency domain



Nonstationary field detection



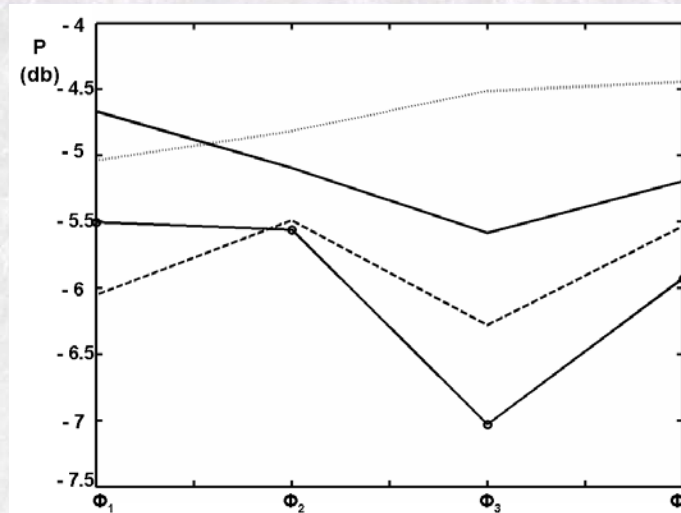
→
Polarimetric analysis

Nonstationary fields

Z_1 —●—●—
 Z_2 ————

Stationary fields

Z_3 - - - - -
 Z_4 ······



Co-polar ratio

- low variations between sub-images (± 1.5 db)
- may be used for soil moisture retrieval

Polarimetric Analysis

→ POLINSAR 2009 WORKSHOP

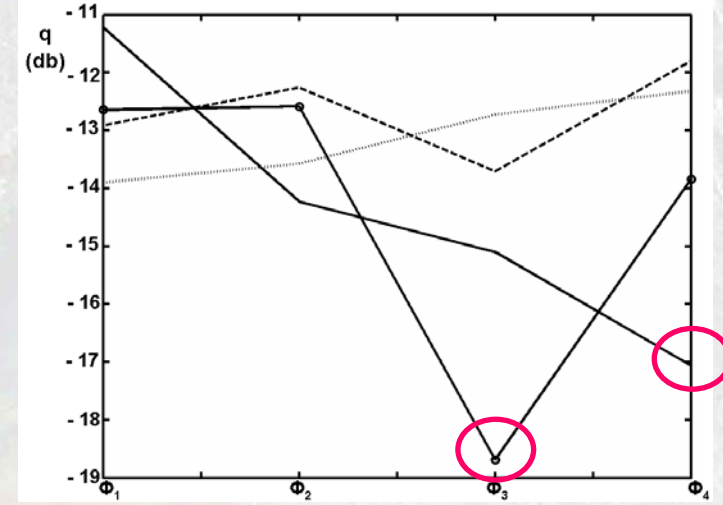
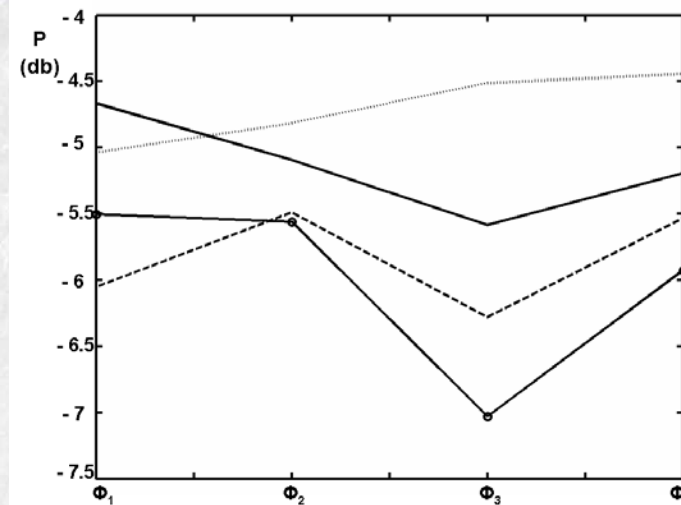


Nonstationary fields

Z_1 —●—●—
 Z_2 ————

Stationary fields

Z_3 - - - - -
 Z_4 ······



Cross-polar ratio

- strong variations between sub-images (± 6 db)
- lower depolarization in presence of Bragg resonance

Polarimetric Analysis

→ POLINSAR 2009 WORKSHOP

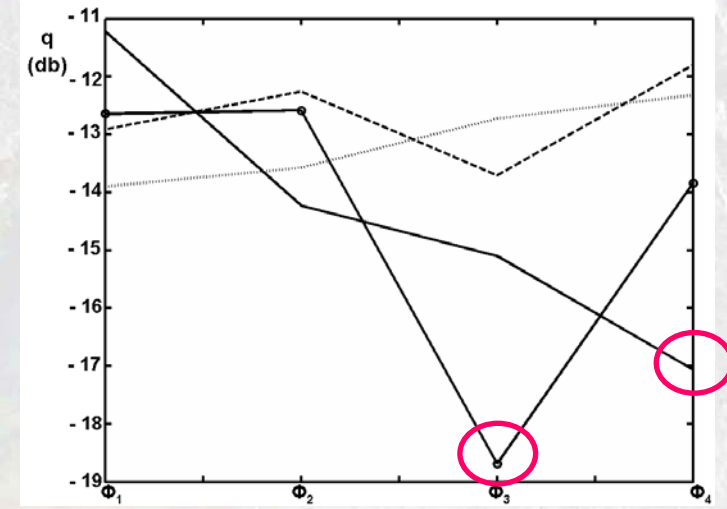
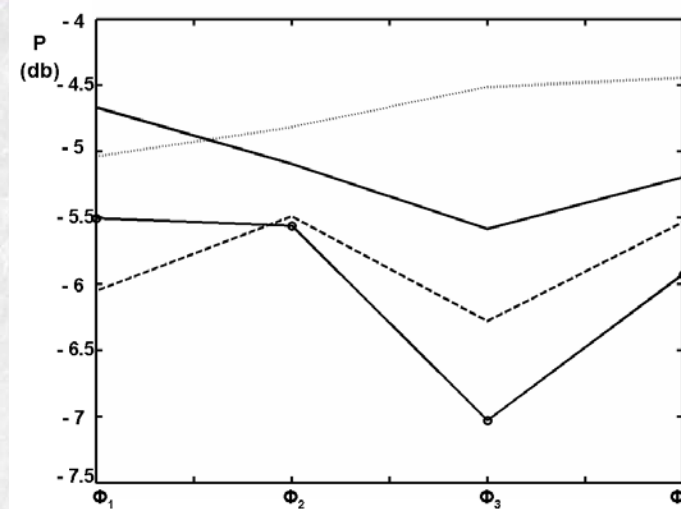


Nonstationary fields

Z_1 —●—●—
 Z_2 ————

Stationary fields

Z_3 - - - - -
 Z_4 ······



Co and Cross-polar ratios



**Not adapted for soil moisture retrieval
over nonstationary fields**

Polarimetric Analysis

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Nonstationary fields

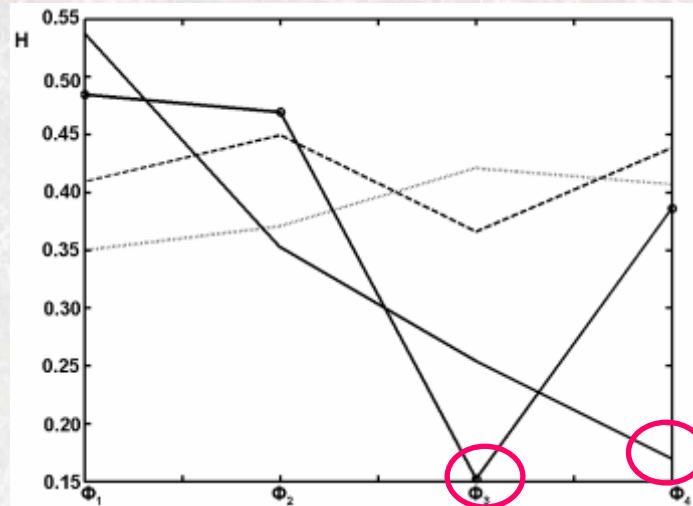
Z_1 —●—●—

Z_2 ———

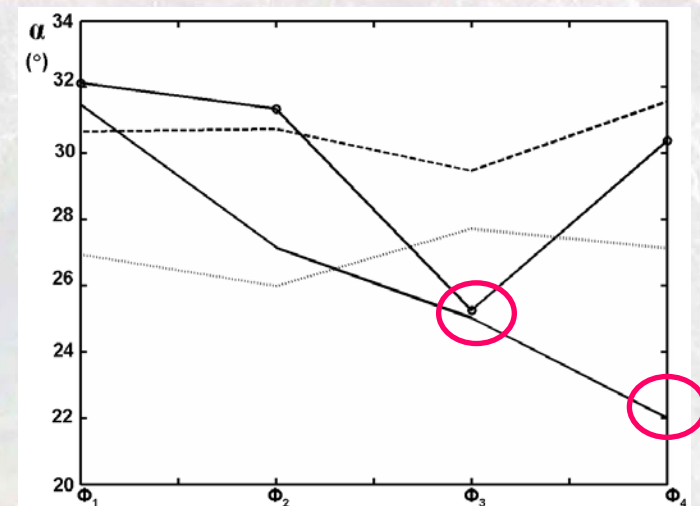
Stationary fields

Z_3 - - - - -

Z_4 ·····



Entropy / α



- strong variation between sub-images (± 0.4 for H and $\pm 10^\circ$ for α)
- one main scattering mechanism in presence of Bragg resonance



Not adapted for soil moisture retrieval over nonstationary fields



New inversion parameters are needed:

⇒ development of a new rough periodic surface scattering model

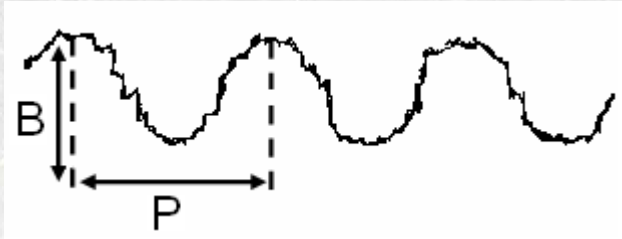
Rough periodic surface

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scattering Model

Surface characterization



$$f(x, y) = B \cos \frac{2\pi x}{P} + \xi(x, y)$$

periodic
component

random
component



Agricultural field

New rough periodic surface scattering model

- based on the Kirchhoff model with scalar approximation
- adapted to rough periodic surfaces

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Yueh H. A. et al., "Scattering from randomly perturbed periodic and quasi-periodic surfaces", 1988

Rough periodic surface

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scattering Model

Backscattering coefficients

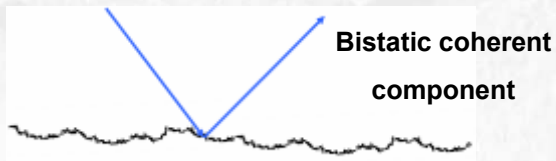
$$\sigma_{pq} = \sigma_{pq_c} + \sigma_{pq_n} + \sigma_{pq_s}$$

Coherent
component

Incoherent
component

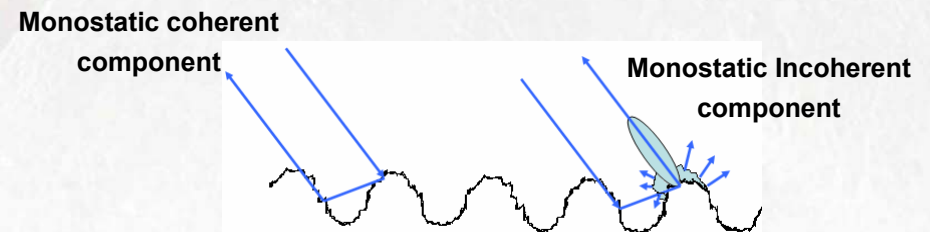
Slopes
components
negligible

Rough Surface



No coherent part in monostatic

Rough periodic Surface



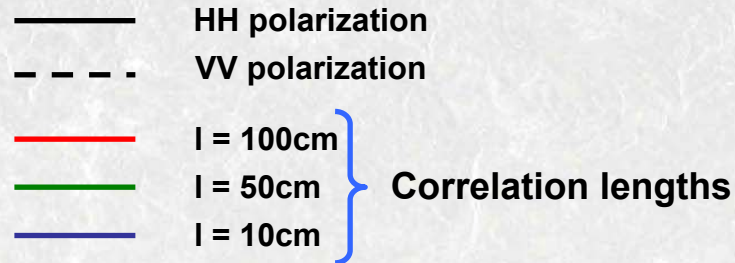
Rough periodic surface

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scattering Model

Incoherent backscattering coefficients



- Rough surface behavior

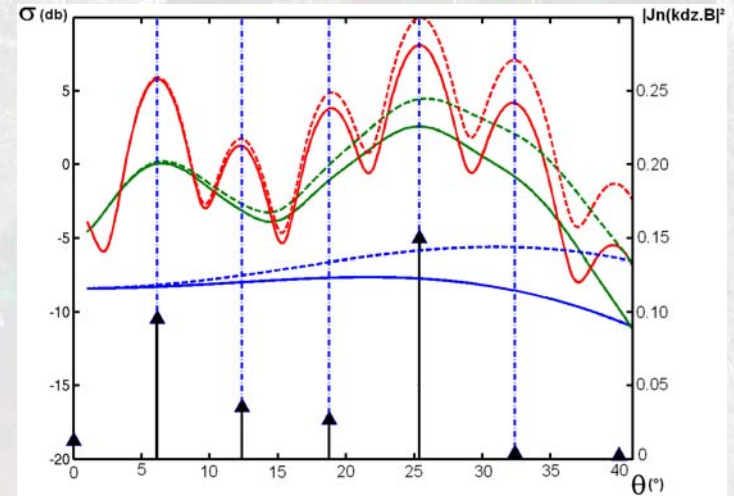
$$\sigma_{VV} > \sigma_{HH}$$

- l influences the coefficient shapes which depend on the Floquet modes

Floquet modes

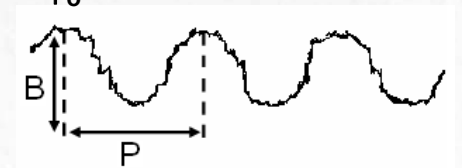
From Bragg resonance condition

$$\sin \theta \cos \phi_o = n \frac{\lambda}{2P}$$



Surface characteristics:

- $P = 100\text{cm}$
- $B = 10\text{cm}$
- rms height = 1cm
- $\epsilon = 6$
- $F = 1.3\text{GHz}$
- $\phi_o = 0^\circ$



Rough periodic surface

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scattering Model

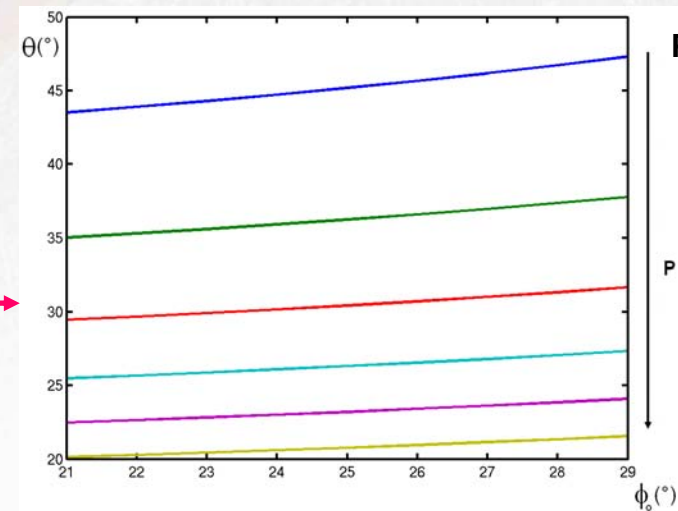
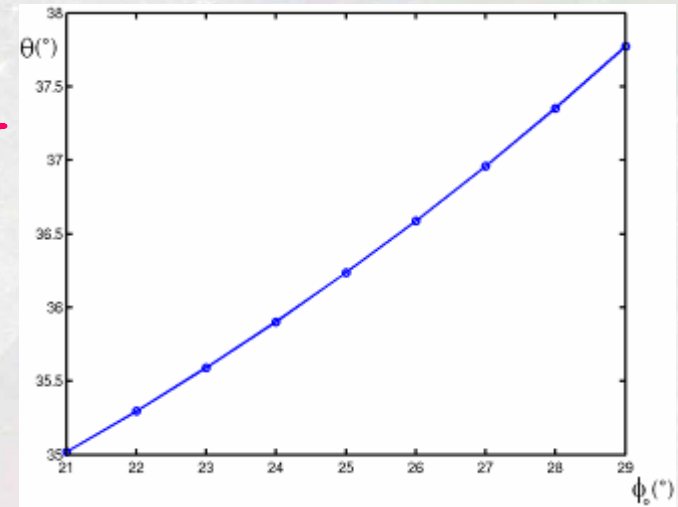
Bragg resonance conditions

depends on

- incidence angle: θ
- azimuth look angle: Φ_0

• Floquet mode: n

• period: P



$$\sin \theta \cos \phi_0 = n \frac{\lambda}{2P}$$

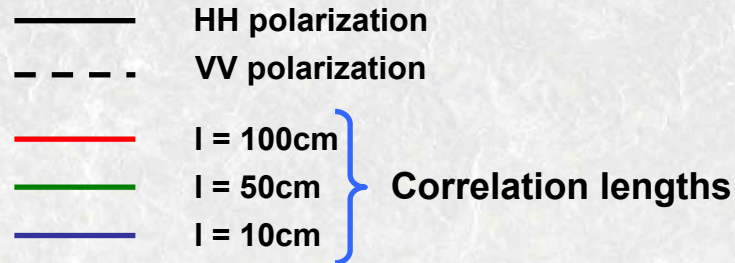
Rough periodic surface

→ POLINSAR 2009 WORKSHOP



scattering Model

Incoherent backscattering coefficients



Floquet modes

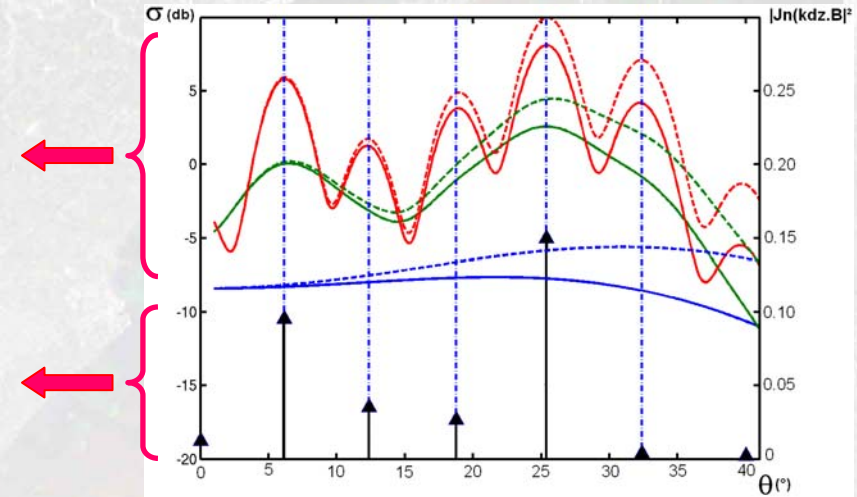
From Bragg resonance condition

$$\sin \theta \cos \phi_o = n \frac{\lambda}{2P}$$

$$\theta = \text{asin} \left(\frac{n\pi}{Pk \cos(\phi_o)} \right)$$

Locations and amplitudes of the Floquet modes:

$$|J_n(kdz.B)|^2 = f(\theta, \phi_o, P, B, k)$$



Surface characteristics:

- P = 100cm
- B = 10cm
- rms height = 1cm
- $\epsilon = 6$
- F = 1.3GHz
- $\phi_o = 0^\circ$



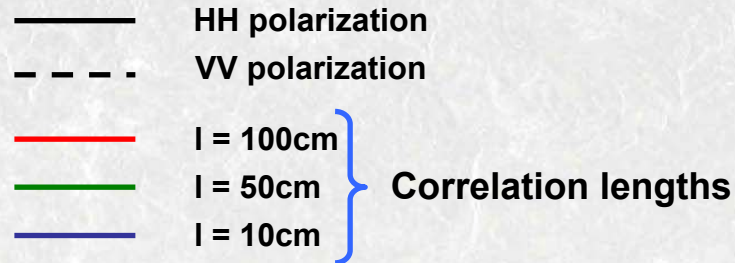
Rough periodic surface

→ POLINSAR 2009 WORKSHOP



scattering Model

Incoherent backscattering coefficients



Floquet modes

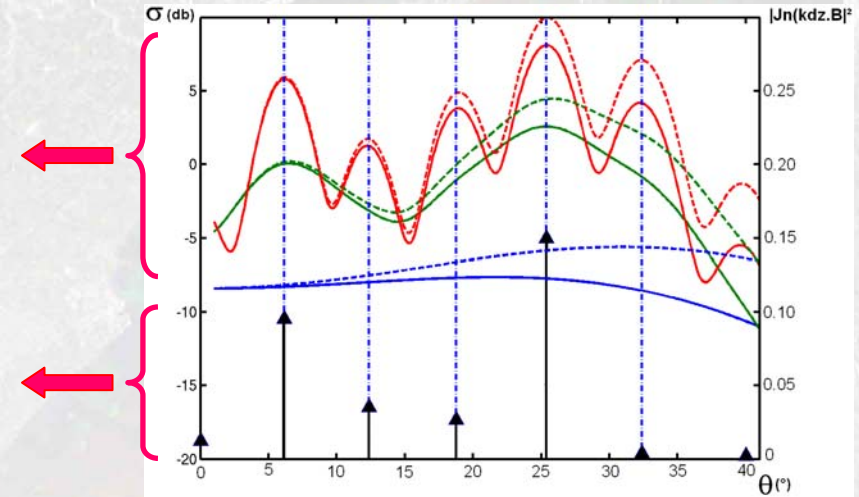
From Bragg resonance condition

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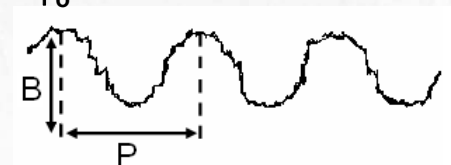


Polarimetric analysis



Surface characteristics:

- $P = 100\text{cm}$
- $B = 10\text{cm}$
- rms height = 1cm
- $\epsilon = 6$
- $F = 1.3\text{GHz}$
- $\phi_o = 0^\circ$



α_1 angle Analysis

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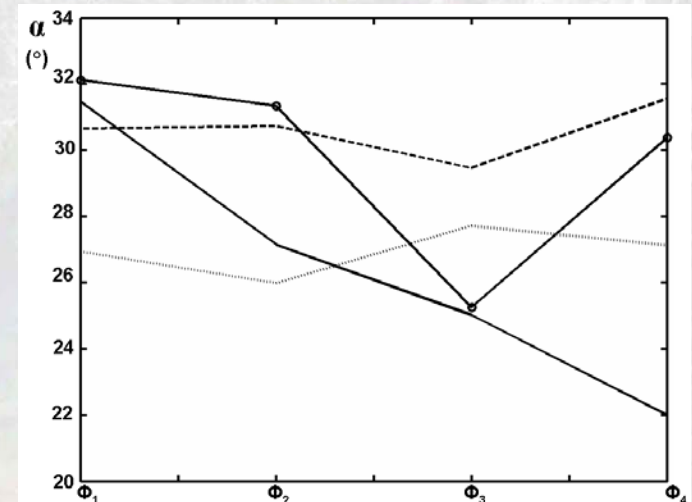
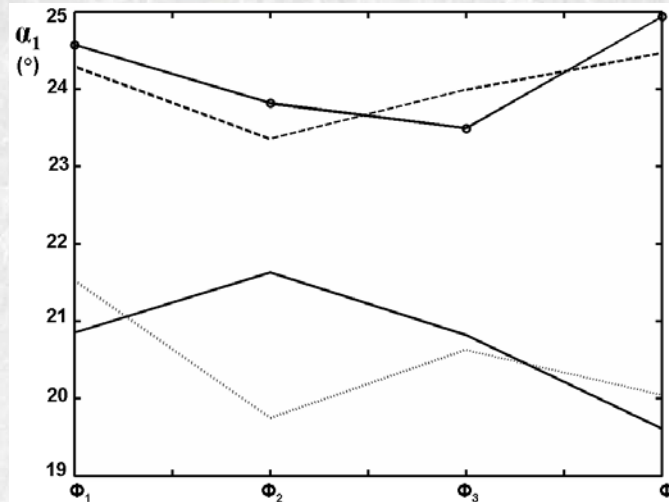


Nonstationary fields

Z_1 —●—●—
 Z_2 ————

Stationary fields

Z_3 - - - - -
 Z_4 ······

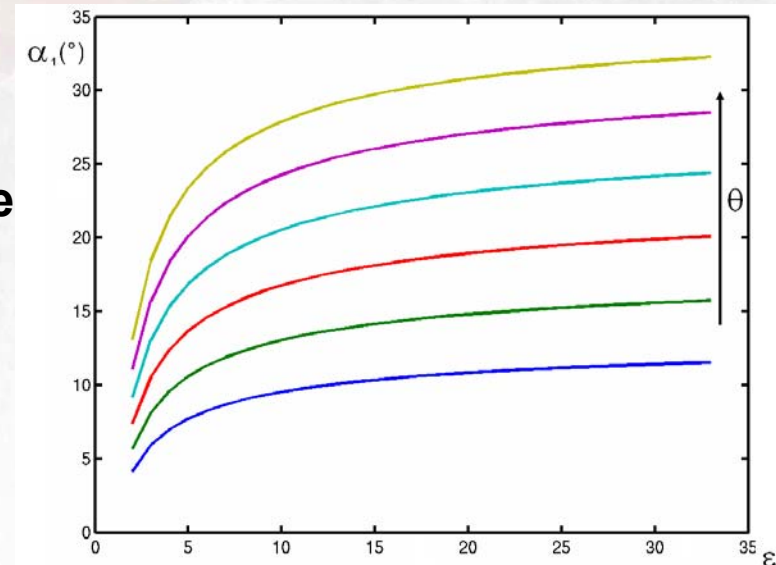


α_1 angle:

- low variation between sub-images ($\pm 2^\circ$)
- depends on soil moisture and incidence angle



May be used for soil moisture retrieval even
over nonstationary fields



Soil moisture retrieval

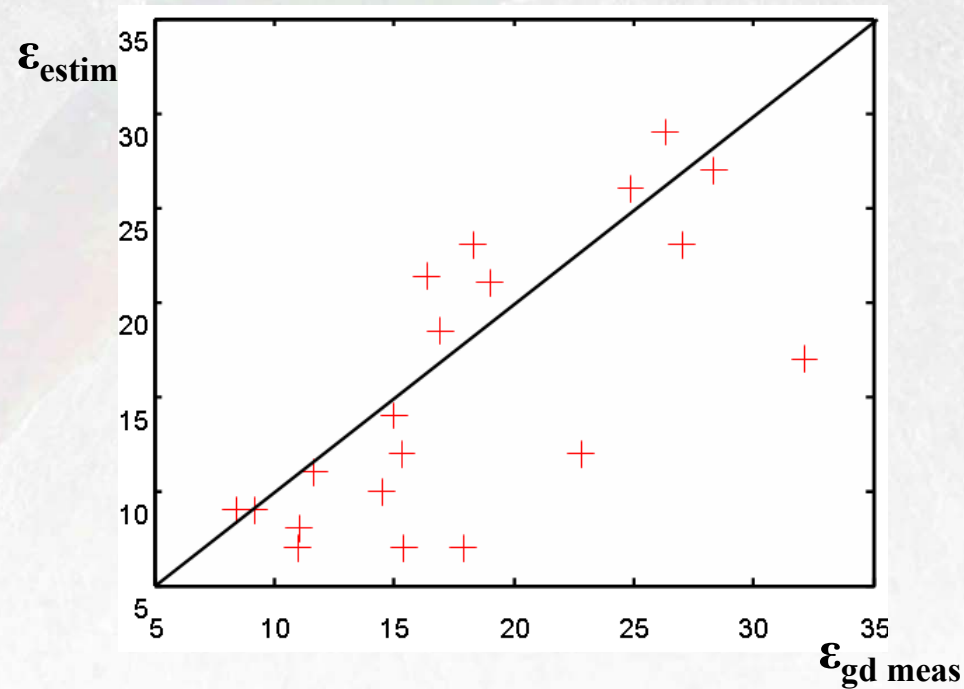
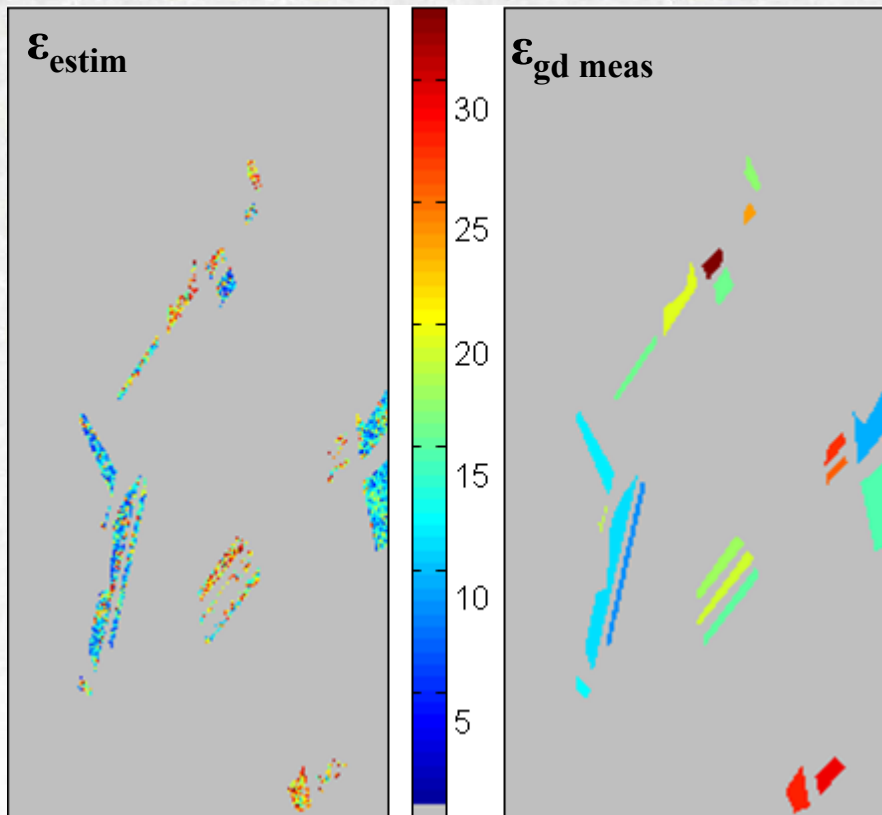
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α_1 inversion method

$$\alpha_{1_{corrected}} = \alpha_{1_{iem}} \frac{\text{mean}(\alpha_{1_{data/surface}})}{\text{mean}(\alpha_{1_{iem}})}$$

adapted for each θ



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Allain S. et al, "Two novel surface model based inversion algorithms using multi-frequency polSAR data", 2004.

Soil moisture retrieval

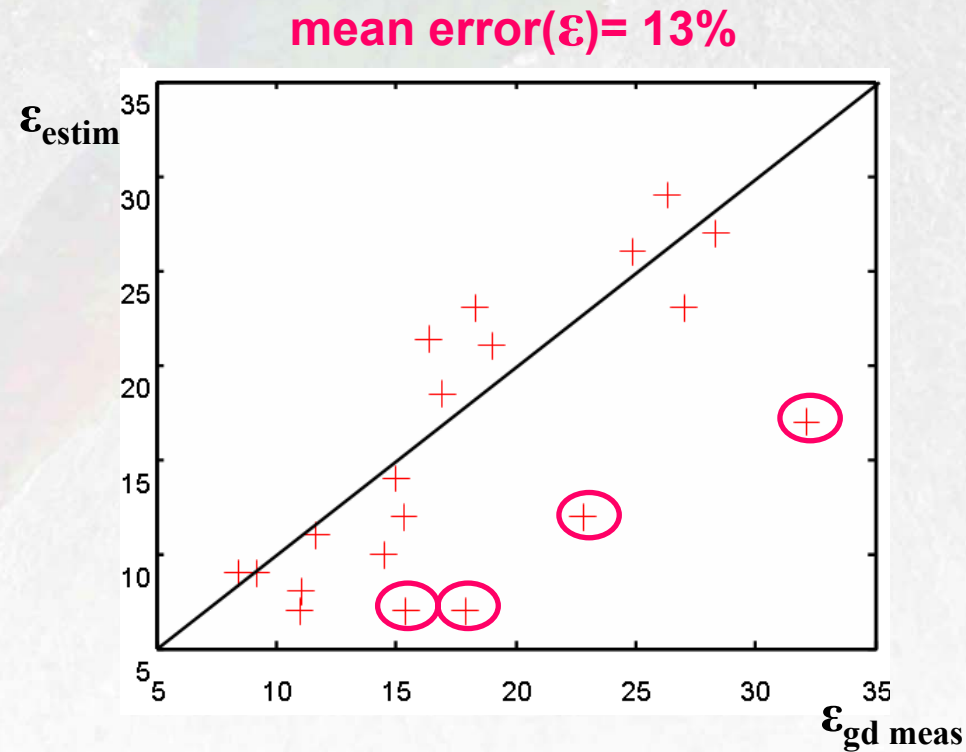
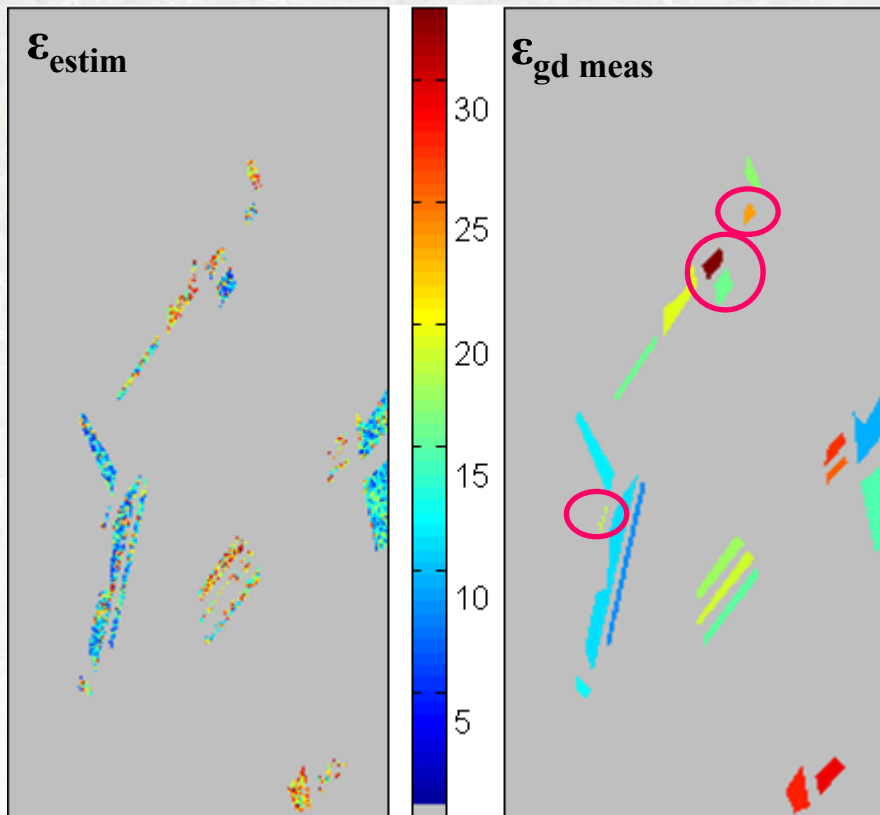
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α_1 inversion method

$$\alpha_{1_{corrected}} = \alpha_{1_{iem}} \frac{\text{mean}(\alpha_{1_{data/surface}})}{\text{mean}(\alpha_{1_{iem}})}$$

adapted for each θ



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Allain S. et al, "Two novel surface model based inversion algorithms using multi-frequency polSAR data", 2004.

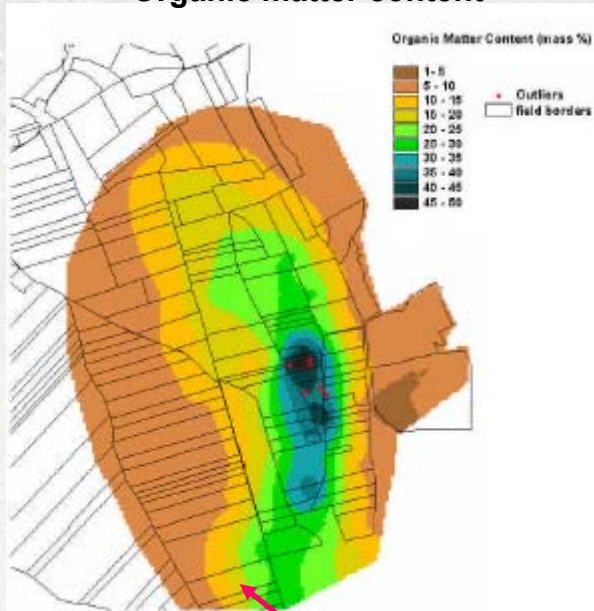
Soil moisture retrieval

→ POLINSAR 2009 WORKSHOP

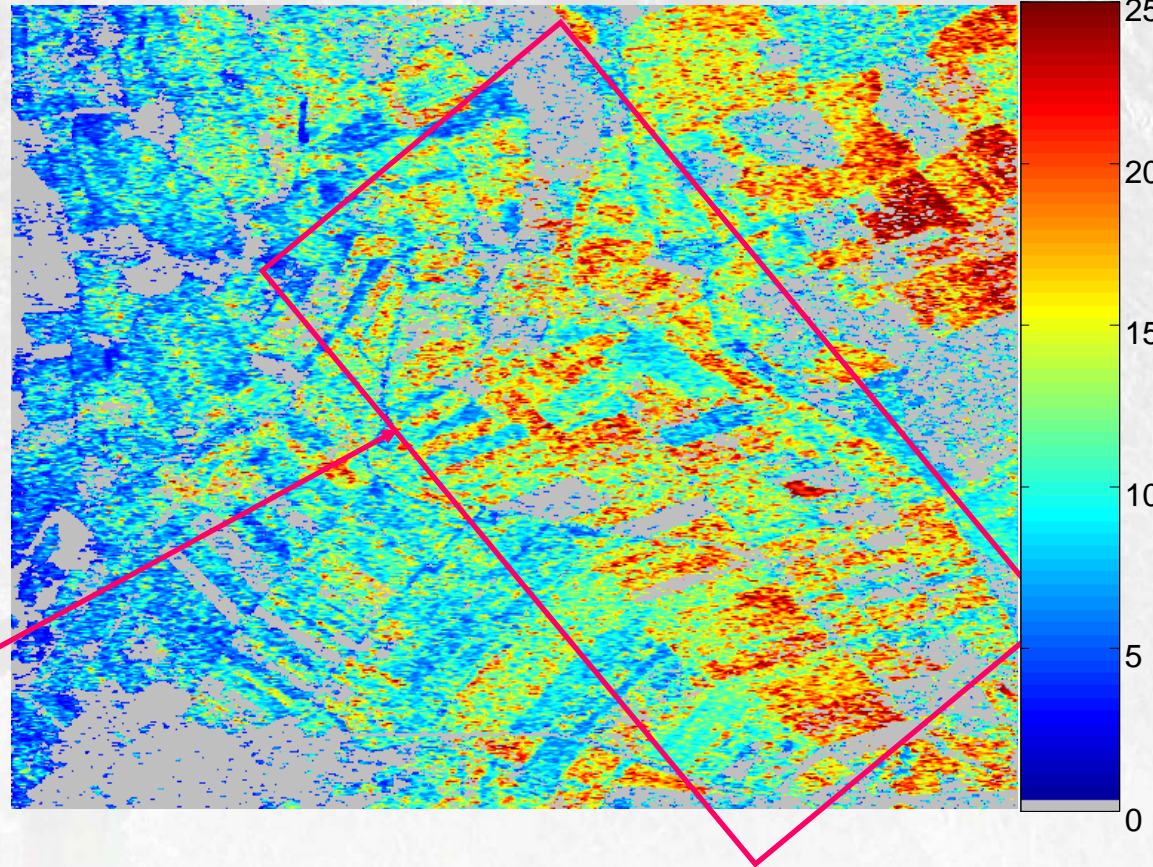


Dielectric constant retrieval

Organic matter content



Very wet area



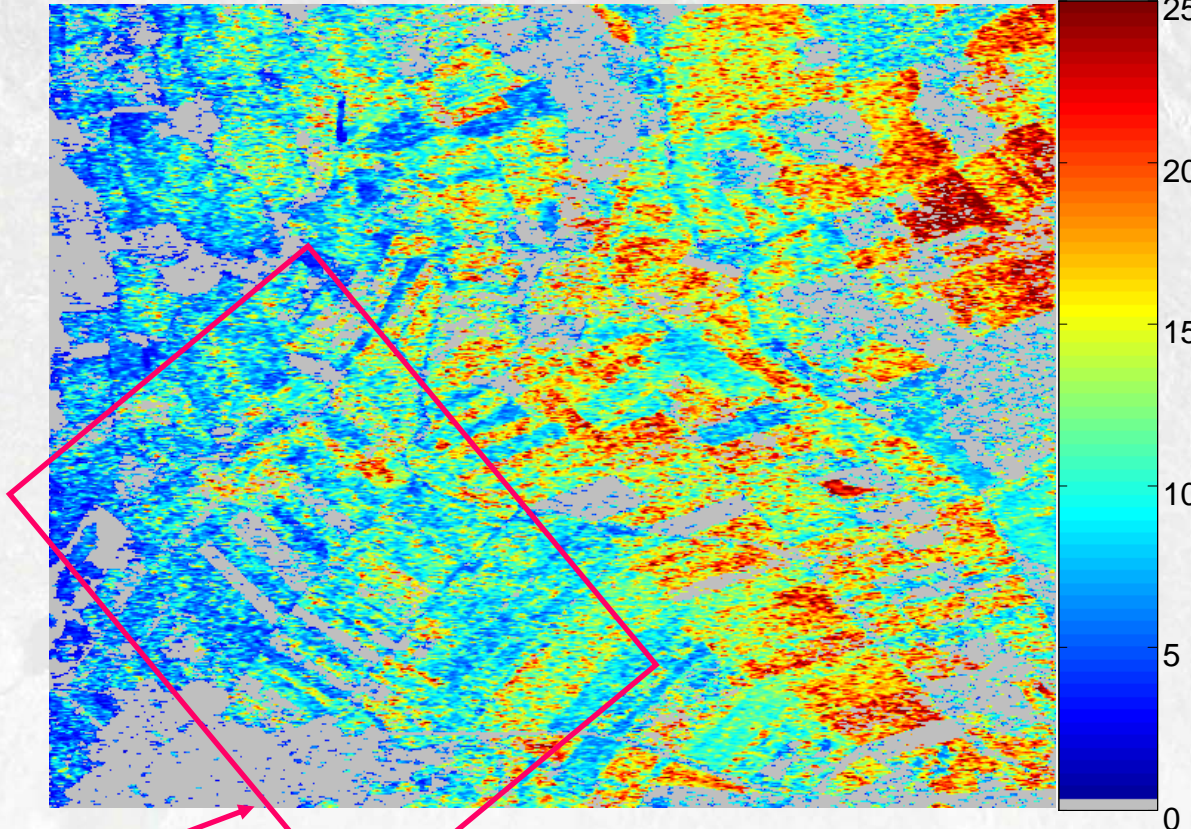
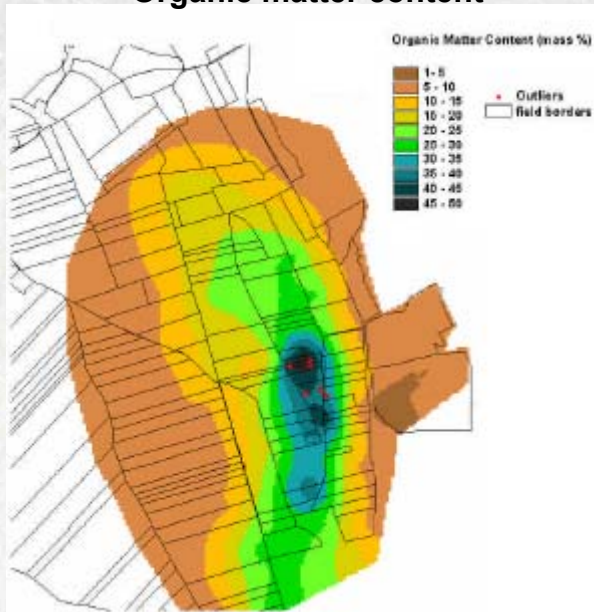
Soil moisture retrieval

→ POLINSAR 2009 WORKSHOP



Dielectric constant retrieval

Organic matter content



Slightly wet area

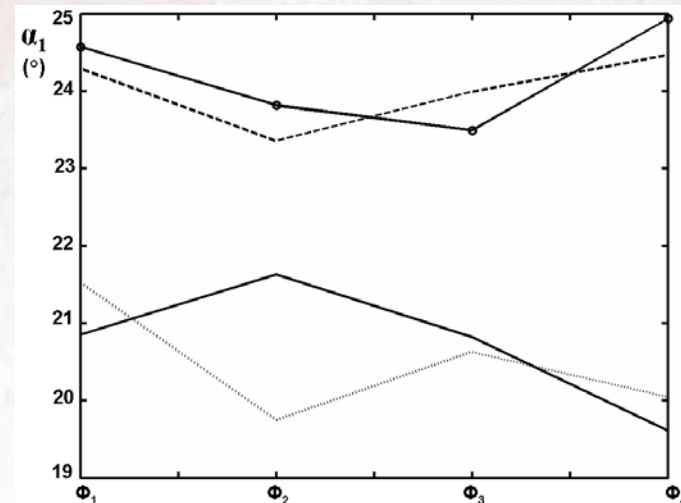
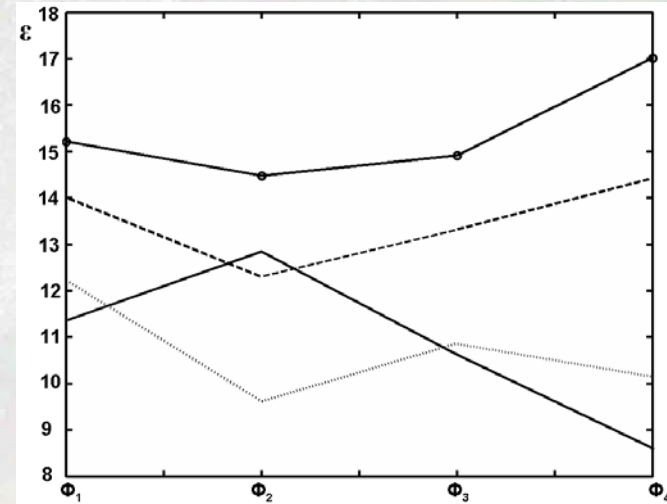
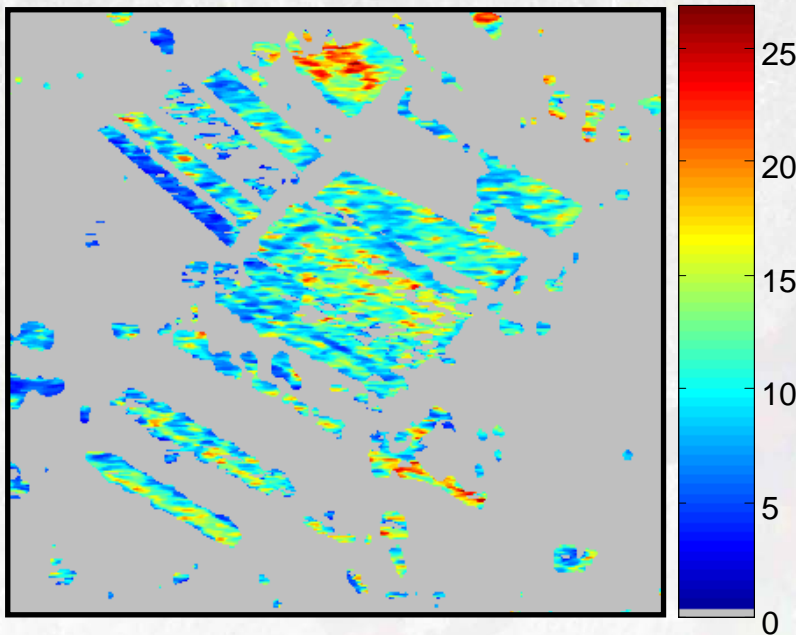
Soil moisture retrieval

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Azimuthal look angle variations

Dielectric constant retrieval



- **Classical retrieval methods**

- **anomalous behaviors may appear over periodic surfaces**

- **Time-Frequency analysis**

- **identify nonstationary fields**

- **confirms the dependence on the azimuth look angle**

- **New rough periodic surface scattering model**

α_1 parameter:

- **remains constant in presence of resonance phenomena**

- **highly sensitive to soil moisture**

- **Application over real SAR data acquired at L band**



AGRISAR 2006
L band Quad pol data set
DLR E-SAR sensor





Bragg phenomenon



Grazie