

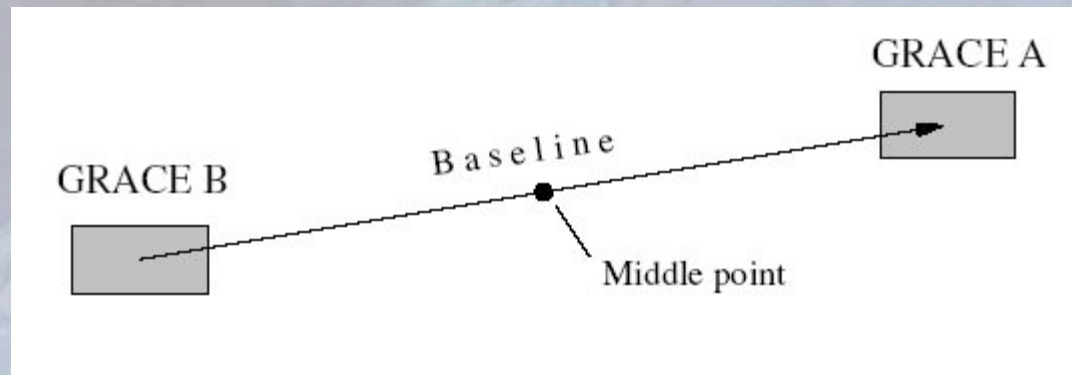
# Synergy of the GOCE and GRACE satellite missions



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# GRACE positioning



Positioning parameters not known with a high accuracy:

- Middle point position
- Cross-track and radial component of the baseline

# Influence of errors in the radial component of baselines

$$V_{12} \approx |\dot{r}_{\text{mp}}| \dot{\rho} - E_{12}$$

- where
- $V_{12}$  - difference of gravitational potentials at satellite locations
  - $|\dot{r}_{\text{mp}}|$  - velocity of the middle point
  - $\dot{\rho}$  - observed range-rates
  - $E_{12}$  - difference in the total mechanical energy of the satellites

# Influence of errors in the radial component of baselines (cont'd)

$$\epsilon(r_{12}^{(z)}) = \frac{|\dot{r}_{mp}|}{g} \epsilon(\dot{\rho})$$

$$g \approx 10 \text{ m/s}^2$$

$$|\dot{r}_{mp}| \approx 7,500 \text{ m/s}$$

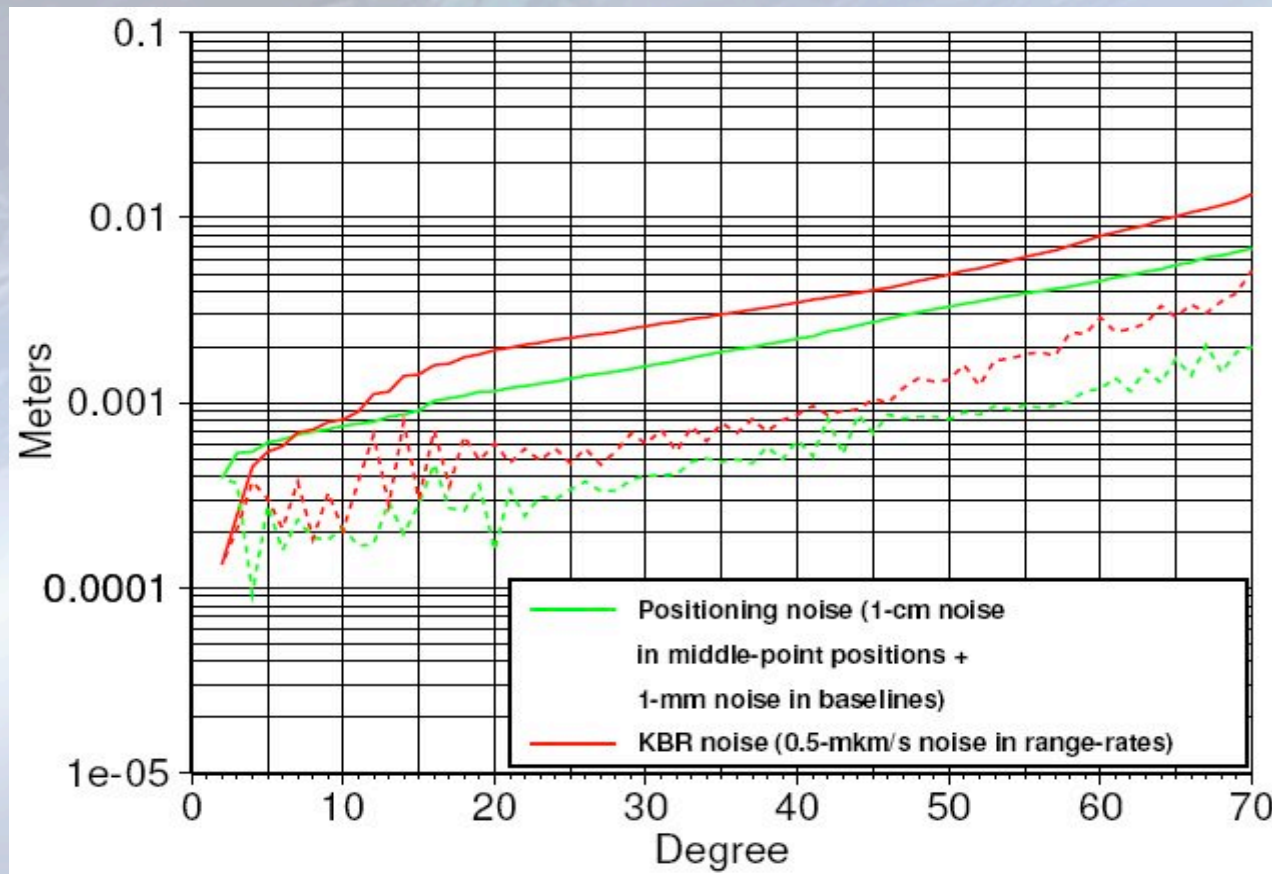
$$\epsilon(\dot{\rho}) \approx 0.5 \text{ mkm/s}$$

$$\Rightarrow \epsilon(r_{12}^{(z)}) = 0.4 \text{ mm}$$

# Sources of positioning information

- GPS data
- A priori model of gravitational and non-gravitational forces
- KBR data at neighbouring epochs

# Performance of a new functional model, in terms of geoid height errors (processing of 1-month synthetic data sets)



# Functional models are equivalent if ...

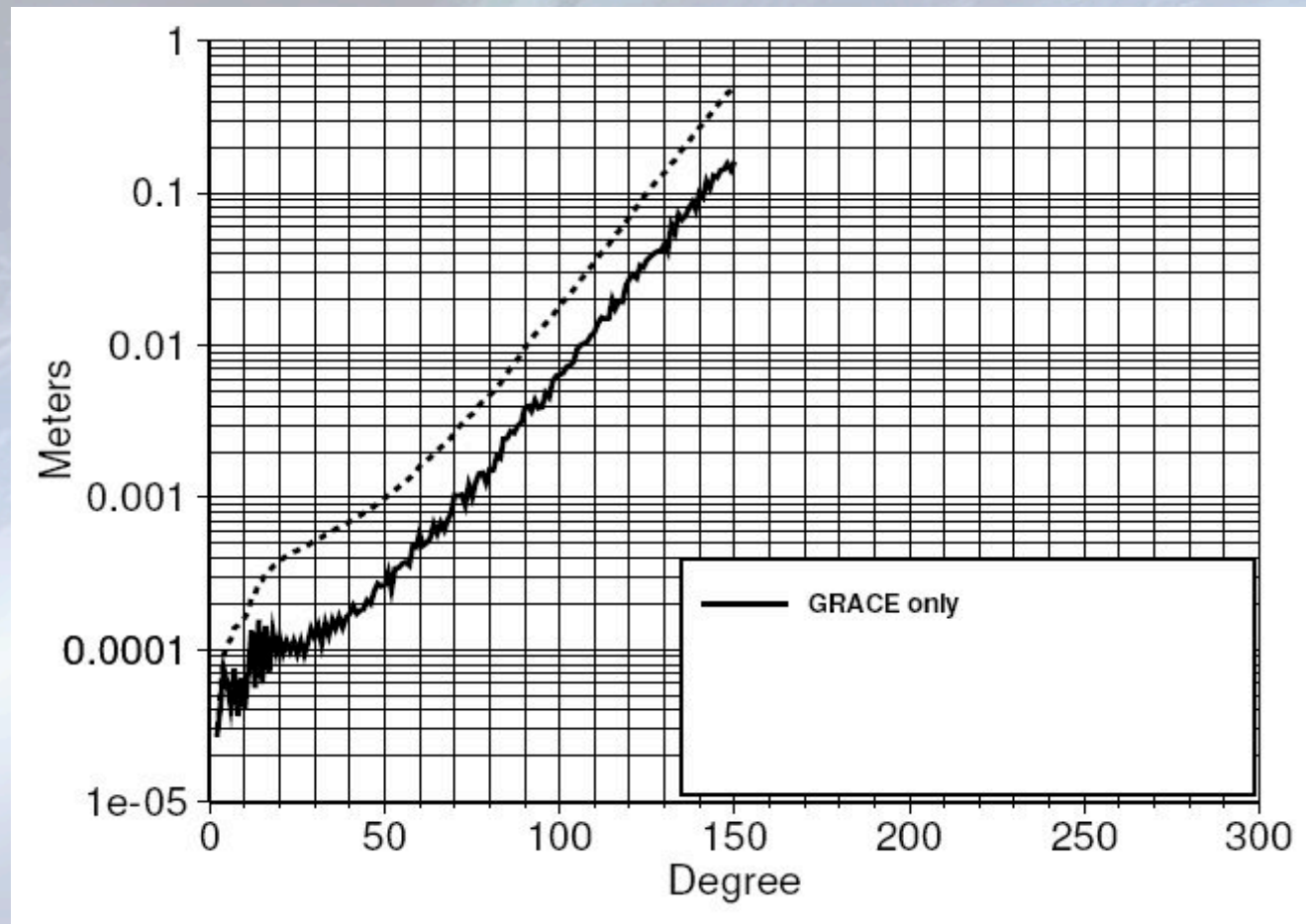
- Transformation of data is linear and reversible
- The data covariance matrix is transformed accordingly and used in data inversion



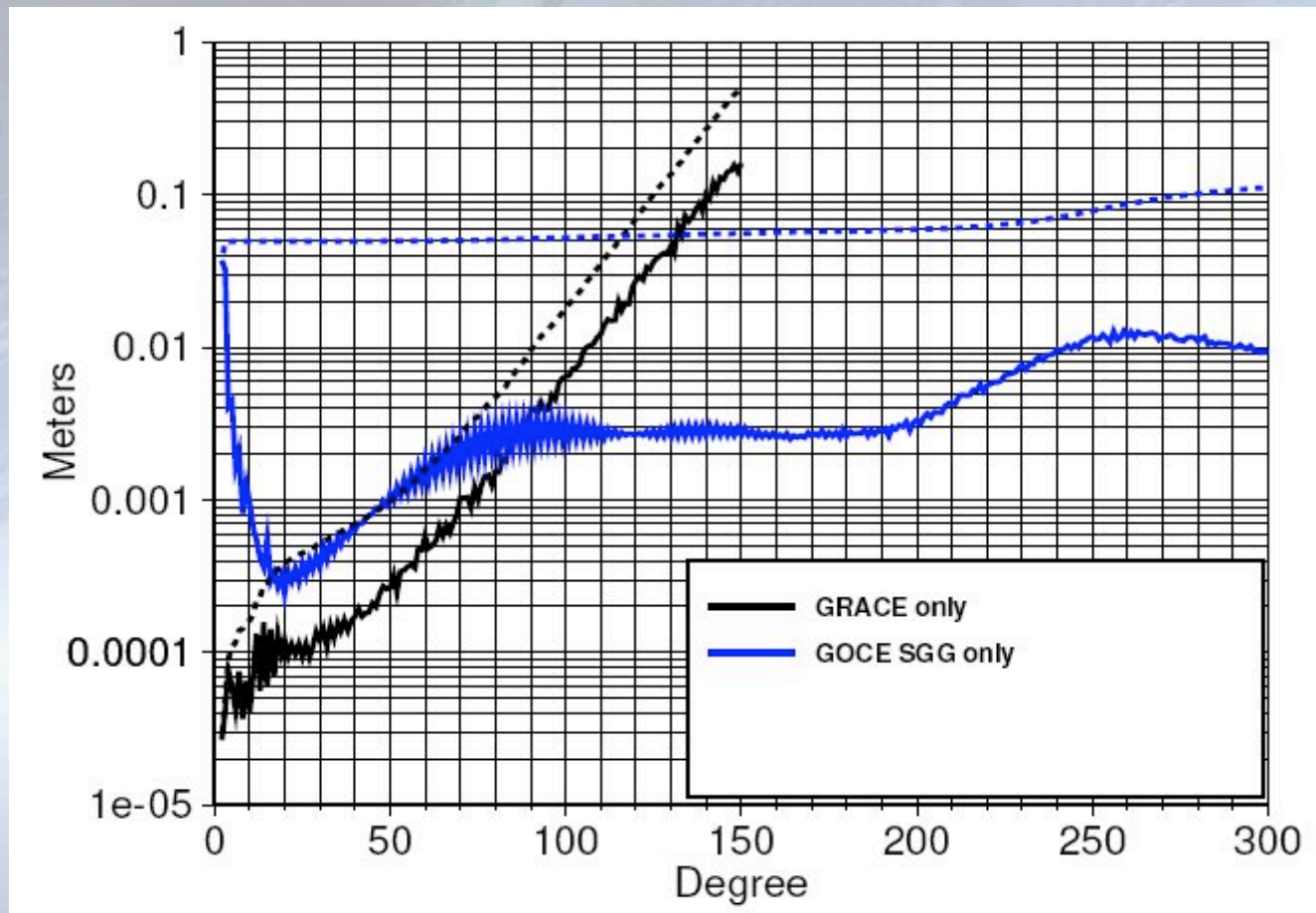
# Setup of the numerical experiment

- **“True” gravity field model: EIGEN-GL04C (truncated at degree 300)**
- **Reference gravity field model: EGM96 (truncated at degree 300)**
- **“GRACE” data: 1-month set of measurements with 5-s sampling, 0.1-mkm/s white noise in range-rates**
- **“GOCE SGG” data: 6-month set of diagonal tensor components with 1-s sampling, realistic colored noise**
- **“GOCE SST” data: 6-month set of satellite accelerations with 30-s sampling, realistic colored noise (taken over from the CHAMP mission)**

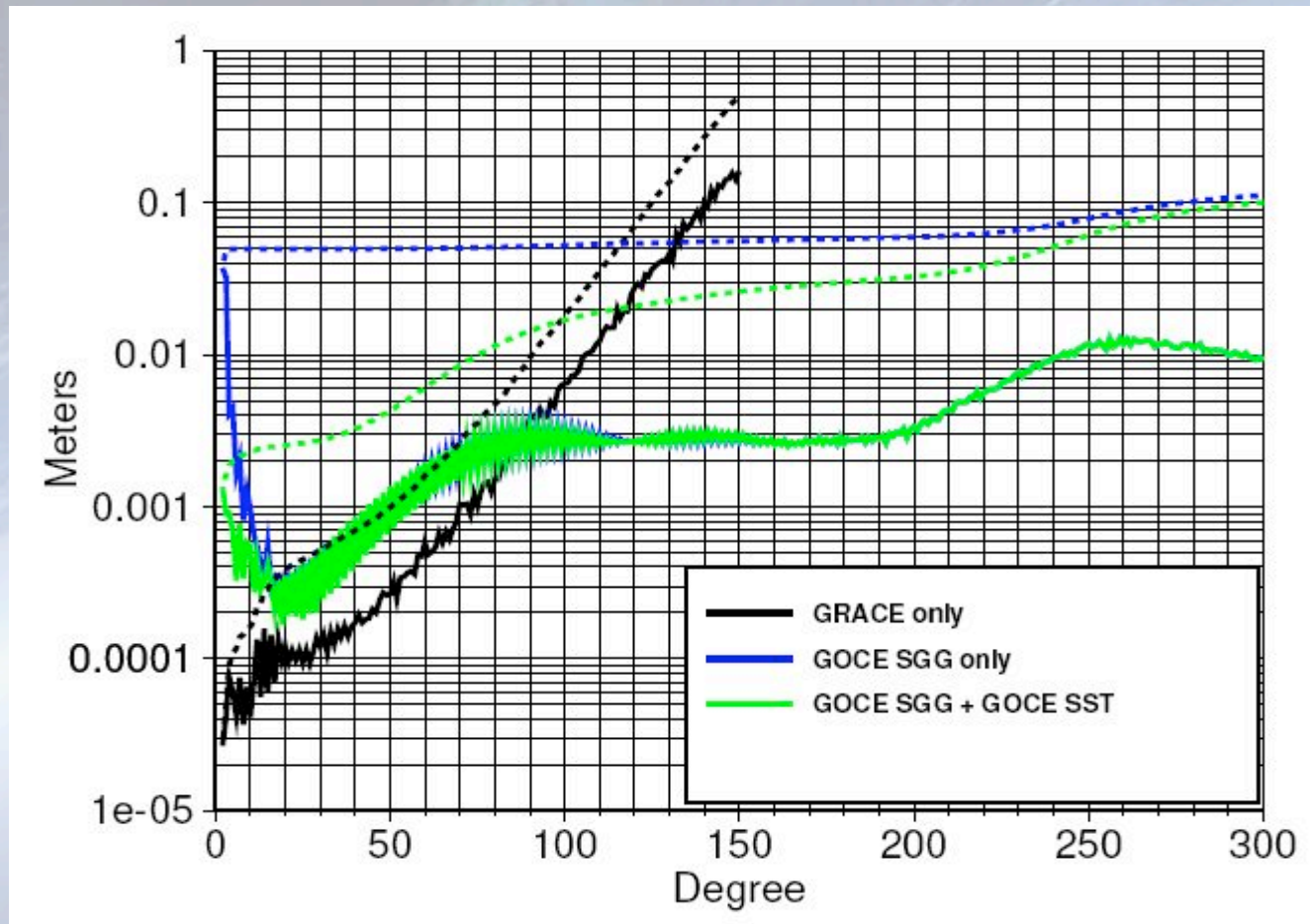
# Errors in the “GRACE”-based model



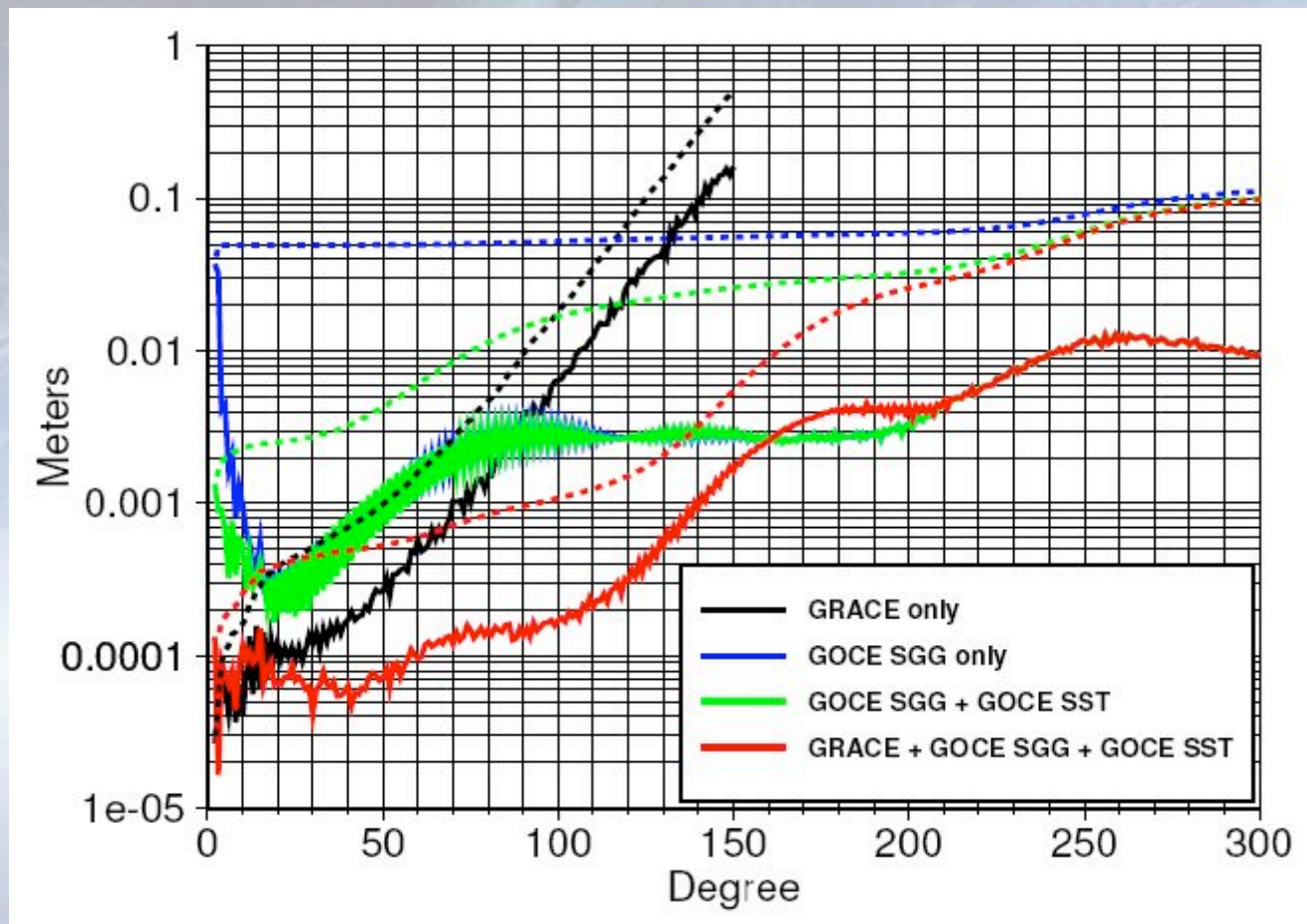
# Errors in the “GOCE SGG”-based model



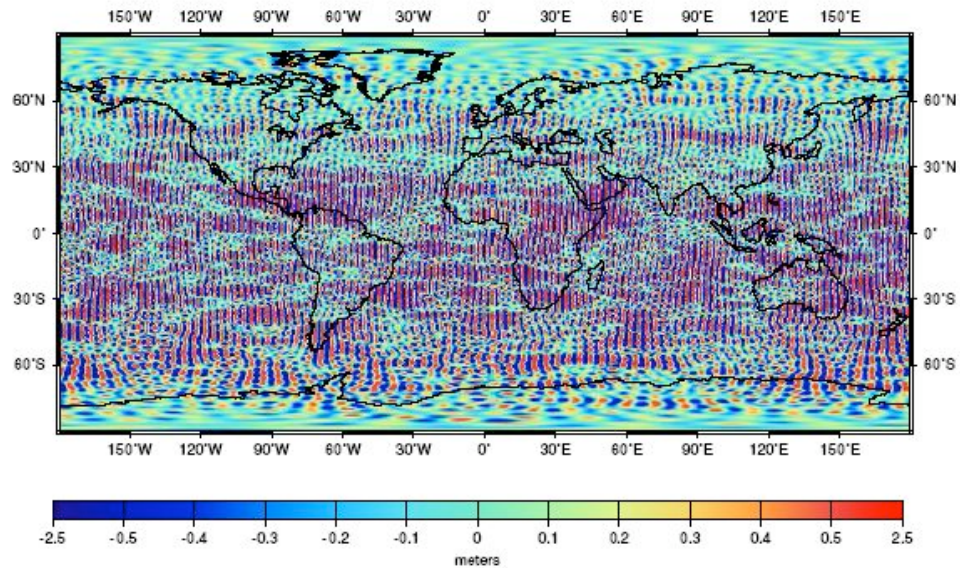
# Errors in the “GOCE”-based model



# Errors in the combined (“GRACE”+”GOCE”) model

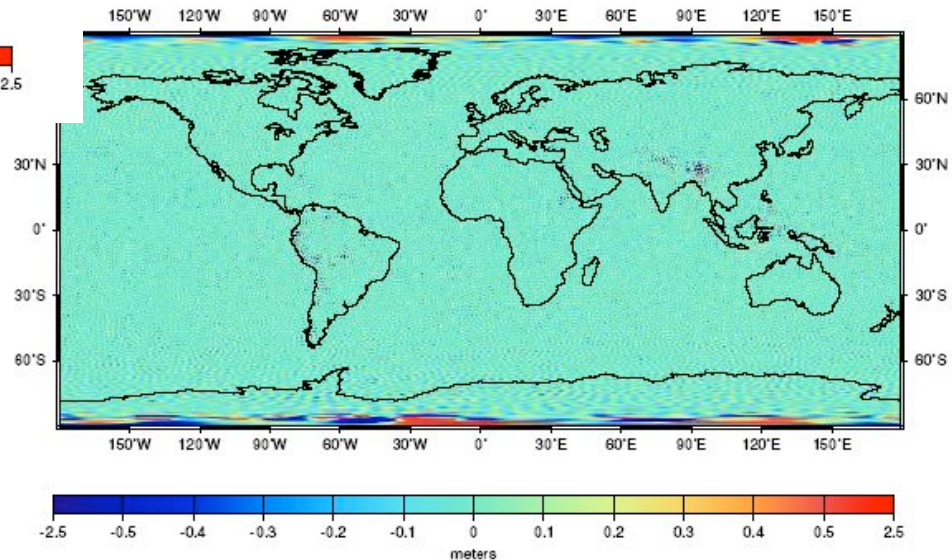


# Geoid height error maps

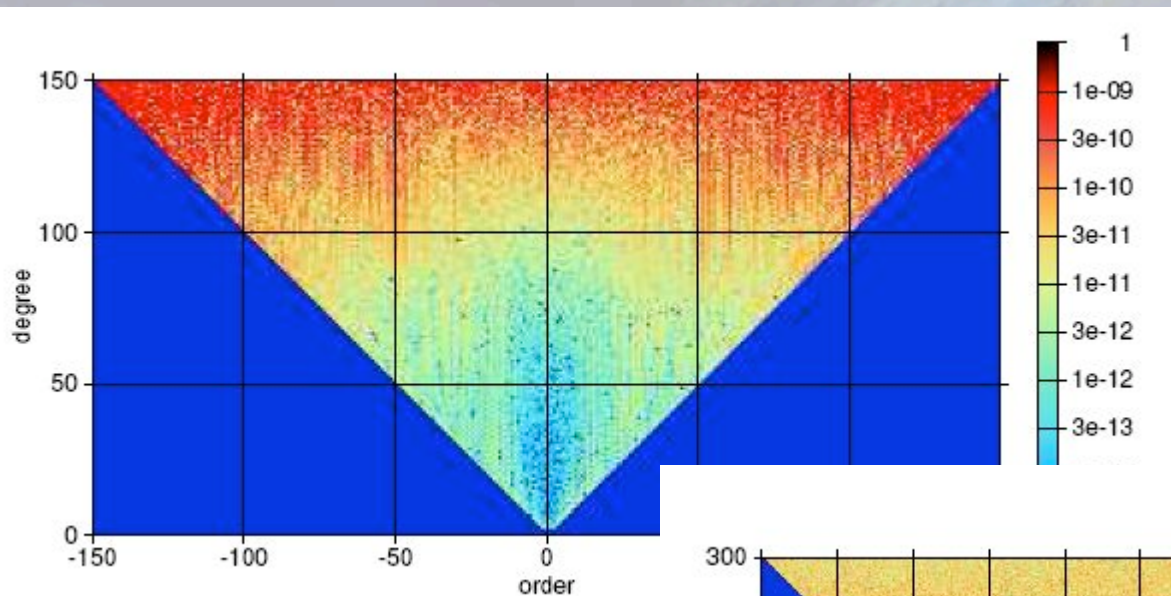


“GRACE”

“GOCE” (SGG + SST)



# Errors per coefficient

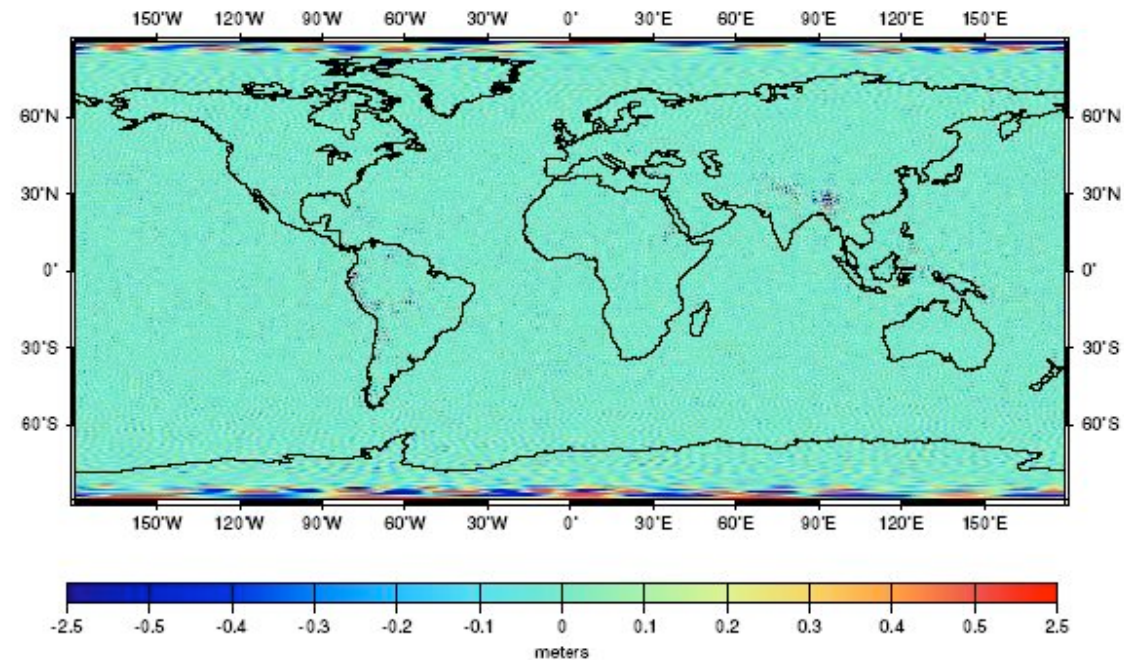
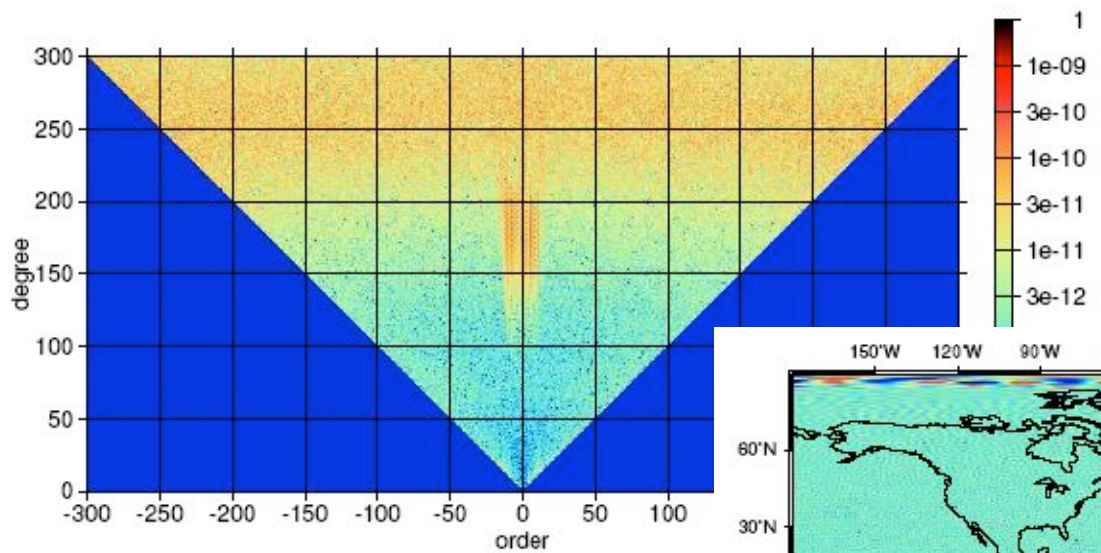


“GRACE”

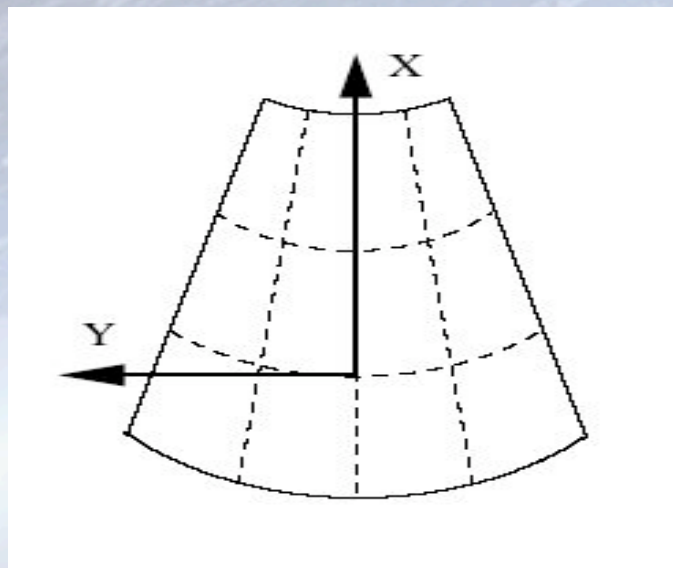


“GOCE” (SGG + SST)

# Errors in the combined “GRACE”+“GOCE” model



# Noisy nearly-sectorial coefficients: an intrinsic problem of GRACE KBR data



$$f_1 - f_2 \sim \frac{\partial f}{\partial x}$$

$$\text{Let } f =: f(y) \Rightarrow \frac{\partial f}{\partial x} = 0$$

# Conclusions

- **High-quality processing of GRACE KBR data requires an accurate satellite positioning (relative satellite altitudes are especially important)**
- **The relative satellite altitudes can be determined with a sufficient accuracy from GRACE KBR data themselves**
- **A joint GRACE + GOCE gravity field modeling may improve the quality of results dramatically (an order or magnitude at degree 100)**
- **Poor quality of GRACE solutions in the East-West direction is (most probably) an intrinsic feature of GRACE KBR data**

# Utilized model of SGG data noise

