



*Investigation of
Polarimetric L-band ALOS and C-band Radarsat2
for peatland subsurface water flow monitoring*

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Acknowledgment

CSA for support (GRIP)

Shimada and JAXA for ALOS
Data + Summer acquisitions



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¹R. Touzi, PolinSAR13, Frascatti, Jan. 31

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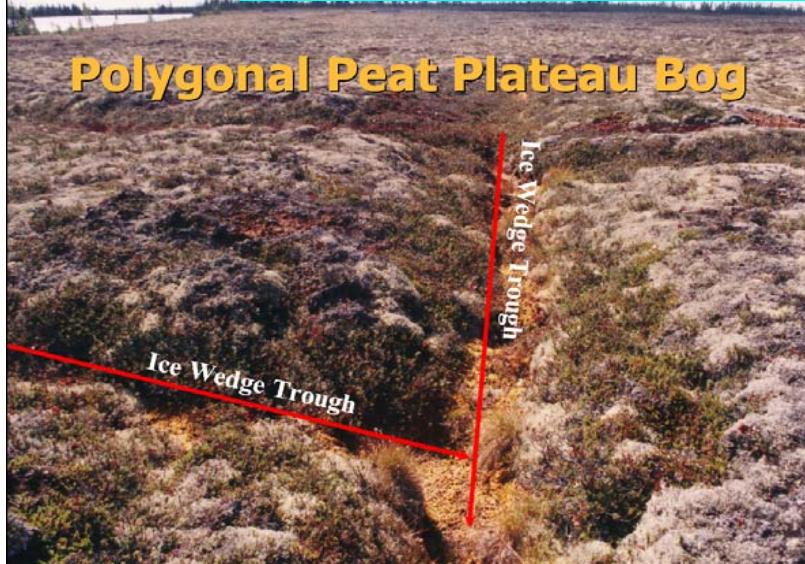
Background

- Wetland in Canada: 148 millions ha (25% of the World)
- Peatlands globally cover 3% of the land, they store 30% of the terrestrial carbon (11.3 Gtonnes)
- Maintain peatlands => reduce greenhouse gases
- Wetland are **under threat** ⇒ **Canadian Wetland Inventory (CWI)**
- EO CWI in collaboration with Env. Canada
- Park Canada: park integrity monitoring and CC effect
 - Wapusk National Park: Polar bear habitat
- Alberta ESDR: Boreal peatland change monitoring and identification of the source of stress (CC or oil sand exploration)



Subarctic Peatland Under Threat ⚡!!!

Wapusk National Park



Climate Change effect:

- ✿ **Bogs transformed to Fen**
 - ⇒ Affect **polar bear denning habitat** which is entirely within bogs with thick peat deposits
- 👉 ALOS => Peatland monitoring



Why Polarimetric SAR for Subarctic wetland monitoring?

- ▶ HH-Radarsat-1 of Limited Capability for vegetation-type discrimination
 - Radarsat-1 combined with **clear-sky-dependent Landsat** for wetland classification
 - Radarsat/Landsat approach not suitable for wetland monitoring

- ▶ Polarimetric SAR ⇔ Scattering mechanisms and target structure ⇔ Enhanced vegetation discrimination
- **Touzi decomposition** using polarimetric C-band Convair SAR:
 - Enhanced wetland classification
 - Scattering **phase sensitive** to peatland **subsurface** water flow ⇔ discrimination of poor fen and bogs

- ▶ Cost effective => ALOS, Radarsat2, TerraSAR



OUTLINE

- Touzi Decomposition for High-resolution and roll invariant incoherent target scattering decomposition
 - **Complex** entity (α_s , Φ_{as}) for unambiguous description of target scattering type
 - **High-resolution** scattering classification in contrast to conventional methods: Cloude-Pottier $\alpha|H$, Freeman , Yamagushi and Van Zyl ⇔ **coarse resolution** classif.
- Results obtained with polarimetric Convair580 SAR
 - Enhanced wetland classification
 - Scattering phase sensitive to peatland subsurface water flow discrimination of poor fen and bogs
- Polarimetric ALOS & Radarsat2 for peatland subsurface water flow monitoring

Target Scattering Decomposition in Terms of Roll-Invariant Target Parameters

Ridha Touzi, Member, IEEE

Abstract—The Kennaugh-Huynen scattering matrix con-diagonalization is projected into the Pauli basis to derive a new scattering vector model for the representation of coherent target scattering. This model permits a polarization basis invariant representation of coherent target scattering in terms of five independent target parameters, the magnitude and phase of the symmetric scattering type introduced in this paper, and the maximization parameters (orientation, helicity, and maximum). The new scattering vector model served for the assessment of the Cloude-Pottier incoherent target decomposition. While Cloude-Pottier scattering type α and entropy H are invariant, β and the so-called target-phase parameters do depend on the target orientation angle for asymmetric scattering. The vector model is then used as the basis for the development of new coherent and incoherent target decompositions in terms of unique and roll-invariant target parameters. It is shown that the phase and magnitude of the symmetric scattering type can be used for an unambiguous description of symmetric scattering. Target helicity is required for the assessment of the symmetry-asymmetry nature of target scattering. The scattering type phase is shown to be very promising for wetland classification in particular, using polarimetric Convair-580 synthetic aperture radar data collected over the Ramsar wetland site to the east of Ottawa, ON, Canada.

Index Terms—Characteristic decomposition, coherent, diagonalization, eigenvalues, eigenvectors, error, incoherent, polarimetry, speckle, synthetic aperture radar (SAR), wetlands.

NOMENCLATURE AND ABBREVIATIONS

$\alpha-\beta$ model	Model introduced by Cloude and Pottier for parameterization of the coherency eigenvector.
CTD	Coherent target decomposition.
ICTD	Incoherent target decomposition.
SSCM	Symmetric scattering characterization method introduced by Touzi and Charbonneau for optimum characterization of the maximized target symmetric scattering.
LOS	Radar line of sight.
$[S]$	Scattering matrix.
μ_1 and μ_2	Scattering matrix coneigenvalues.
k	Target scattering vector introduced by Cloude.
α	Scattering type parameter introduced by Cloude and Pottier.

β : Orientation angle introduced by Cloude and Pottier.
 α^c : Symmetric scattering type introduced in this paper as a complex entity.
 α_s : Symmetric scattering type magnitude.

Touzi Decomposition for High Resolution Characterization of Wetland Scattering

Can. J. Remote Sensing, Vol. 33, Suppl. 1, pp. S66-S67, 2007

Wetland characterization using polarimetric RADARSAT-2 capability

R. Touzi, A. Deschamps, and G. Rother

Abstract The use of single-polarization (HH) RADARSAT-1 synthetic aperture radar (SAR) data has been shown to be important for wetland water extent characterization. However, the limited capability of the RADARSAT-1 single-polarization C-band SAR in vegetation type discrimination makes the use of clear-sky-dependent visible near-infrared (VNIR) satellite data necessary for wetland mapping. In this paper, the potential of polarimetric RADARSAT-2 data for wetland characterization is investigated. The Touzi incoherent decomposition is applied for the roll-invariant decomposition of wetland scattering. In contrast with the Cloude-Pottier decomposition that characterizes target scattering type with a real entity, α , the Touzi decomposition uses a complex entity, the symmetric scattering type, for unambiguous characterization of wetland target scattering. It is shown that, like the Cloude α scattering type, the magnitude α_s of the symmetric scattering is not effective for vegetation type discrimination. The phase ϕ_{α} of the symmetric scattering type has to be used for better characterization of wetland vegetation species. The unique information provided by ϕ_{α} for improved wetland class discrimination is demonstrated using Convair-580 polarimetric C-band SAR data collected over the Mer Bleue wetland in the east of Ottawa, Canada. The use of ϕ_{α} makes possible the discrimination of shrub bog from sedge fen and even permits the discrimination between conifer-dominated treed bog and upland deciduous forest under leafy conditions.

Résumé L'utilisation des données radar à synthèse d'ouverture (RSO) de RADARSAT-1 en polarisation unique (HH) a déjà fait ses preuves pour la caractérisation de l'étendue d'eau en milieu humide. Cependant, la capacité limitée du RSO en bande C de RADARSAT-1 en polarisation unique pour la détermination des types de végétation rend nécessaire l'utilisation de données satellites visibles et proches de l'infrarouge (VNIR) pour la cartographie des milieux humides. Dans cet article, nous examinons la possibilité d'utiliser les données polarimétriques de RADARSAT-2 pour la caractérisation des milieux humides. La décomposition incohérente de Touzi est appliquée pour la décomposition enroulante des signaux de réfraction des milieux humides. En comparaison avec la décomposition de Cloude-Pottier qui caractérise le type de réfraction des cibles par une entité réelle, α , la décomposition de Touzi utilise une entité complexe, le type de réfraction symétrique, pour une caractérisation ambiguë des cibles de milieux humides. Il est montré que, comme le type de réfraction α de Cloude, la magnitude α_s du type de réfraction symétrique n'est pas efficace pour la discrimination des types de végétation. La phase ϕ_{α} du type de réfraction symétrique doit être utilisée pour une meilleure caractérisation des espèces végétales des milieux humides. L'information unique fournie par ϕ_{α} permet d'améliorer la discrimination des classes de milieux humides. La discrimination entre les milieux humides est démontrée à l'aide des données SAR polarimétriques Convair-580 à bande C collectées au-dessus du site Ramsar de Mer Bleue, dans l'est d'Ottawa, Canada. L'utilisation de ϕ_{α} permet de discriminer le marais arboreux des tourbières à scirpes et même de discriminer entre les forêts décidues dominées par les conifères et les forêts décidues sous feuilles.

Manuscript received July 13, 2006; revised August 18, 2006. This work was supported in part by the Canadian Space Agency.

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Digital Object Identifier 10.1109/TGRS.2006.886176

Phase of Target Scattering for Wetland Characterization Using Polarimetric C-Band SAR

Ridha Touzi, Member, IEEE, Alice Deschamps, and G. Rother

Abstract—Wetlands continue to be under threat, and there is a major need for mapping and monitoring wetlands for better management and protection of these sensitive areas. Only a few

I. INTRODUCTION

ADAR polarimetry, which has been an active area of research for more than 50 years [2]–[6], has started recent launch of polarimetric satellite instruments (SARs), namely, L-band ALOS-TerraSAR [8], and, most recently, C-band RADARSAT-2 is the first satellite that will use polarimetric information at multiple wavelengths (9-m (fine-mode) and 24-m (standard-mode)). This should permit a deeper exploration of wetlands and enhanced extraction of target parameters. The Canada Centre for Remote Sensing has been investigating C-band polarimetric data for more than 20 years using the Convair-580 polarimetric capability was added in 1988 [10], and, at the end of the RADARSAT-2 project in 1998, investigating key applications that promote RADARSAT-2 fully polarimetric capabilities. Ship classification [11], [12], agricultural crop characterization [13], and forest-type classification [14] were shown to be promising applications that can benefit greatly from polarimetric data. Recently, a preliminary study using polarimetric data collected over the Mer Bleue wetland site in Ontario, Canada, using the C-band polarimetric SAR could be promising for wetland mapping [15]. This investigation has continued, using polarimetric data collected in the fall season for demonstration of the promising potential of polarimetric data for wetland characterization and for detection of their seasonal changes. These results will be presented in this paper.

Weather characteristics and sensitivity to weather characteristics, RADARSAT-1 has been a primary data source for characterization of wetlands [6]–[18]. Unfortunately, the limited capability of RADARSAT-1's single-polarization C-band SAR in vegetation type discrimination makes the use of clear-sky-dependent visible near-infrared (VNIR) satellite data necessary for wetland mapping. In this paper, the potential of polarimetric RADARSAT-2 data for wetland characterization is investigated.

The Touzi incoherent decomposition is applied for the roll-invariant decomposition of wetland scattering.

In contrast with the Cloude-Pottier decomposition that characterizes target scattering type with a real entity, α , the Touzi decomposition uses a complex entity, the symmetric scattering type, for unambiguous characterization of wetland target scattering.

It is shown that, like the Cloude α scattering type, the magnitude α_s of the symmetric scattering is not effective for vegetation type discrimination.

The phase ϕ_{α} of the symmetric scattering type has to be used for better characterization of wetland vegetation species.

The unique information provided by ϕ_{α} for improved wetland class discrimination is demonstrated using Convair-580 polarimetric C-band SAR data collected over the Mer Bleue wetland in the east of Ottawa, Canada.

The use of ϕ_{α} makes possible the discrimination of shrub bog from sedge fen and even permits the discrimination between conifer-dominated treed bog and upland deciduous forest under leafy conditions.



The Touzi Decomposition for Roll invariant Incoherent Target Scattering Decomposition



- 50 years R&D (Kennaugh 51, Huynen 65, Cloude-Pottier 96)

$$[T] = \lambda_1 [T_1] + \lambda_2 [T_2] + \lambda_3 [T_3]$$

- New coherent Target Scattering Vector Model (TSVM):

$$\vec{e}^{SVM} = m |\vec{e}^{SVM}|_m \cdot e^{j\Phi_s} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos 2\psi & -\sin 2\psi \\ 0 & \sin 2\psi & \cos 2\psi \end{bmatrix} \begin{bmatrix} \cos \alpha_s \cos 2\tau_m \\ \sin \alpha_s e^{j\Phi_{\alpha_s}} \\ -j \cos \alpha_s \sin 2\tau_m \end{bmatrix}$$

* **Solves for Cloude-Pottier target scattering type (α) ambiguities**

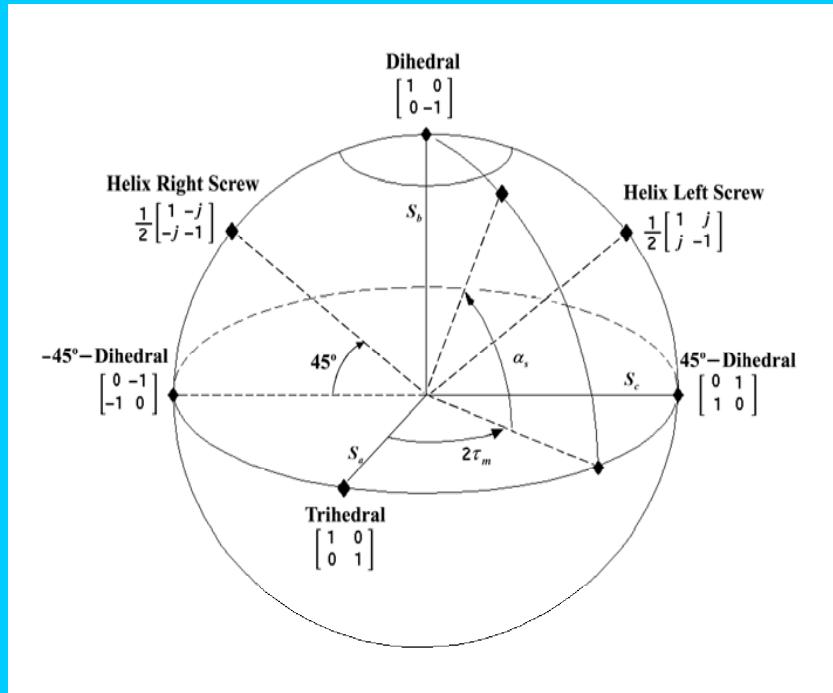
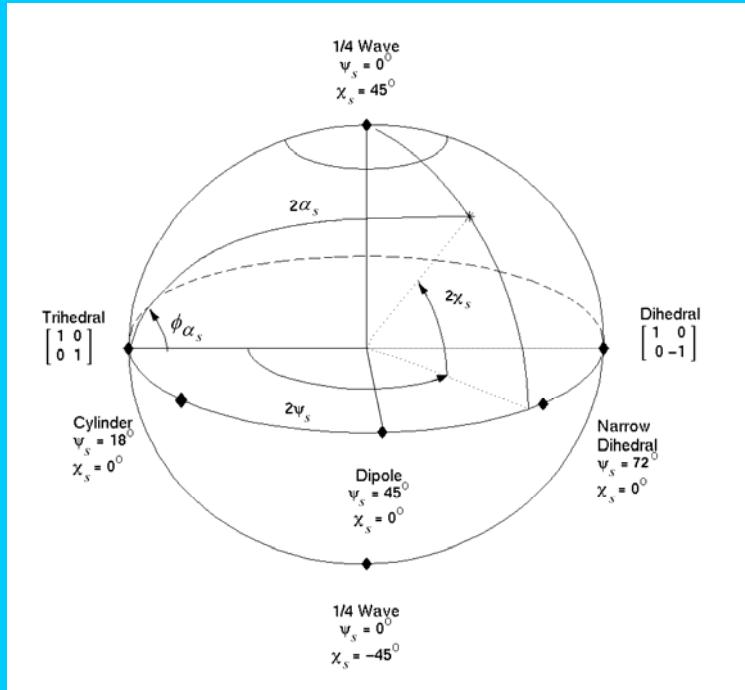
- A complex entity (α_s , $\Phi_{\alpha s}$)
- **Helicity** (τ) \Rightarrow Local **asymmetry** \rightarrow Forest structure



Two Poincaré spheres for representation of Single Scattering Parameters

- ▶ Scattering type (α_s , $\Phi_{\alpha s}$)
- ▶ HV=0 => $\Phi_{\alpha s}$ = Pauli phase

$$\tan(\alpha_s) e^{j\phi_{\alpha s}} = \frac{|\mu_1 - \mu_2|}{|\mu_1 + \mu_2|}$$



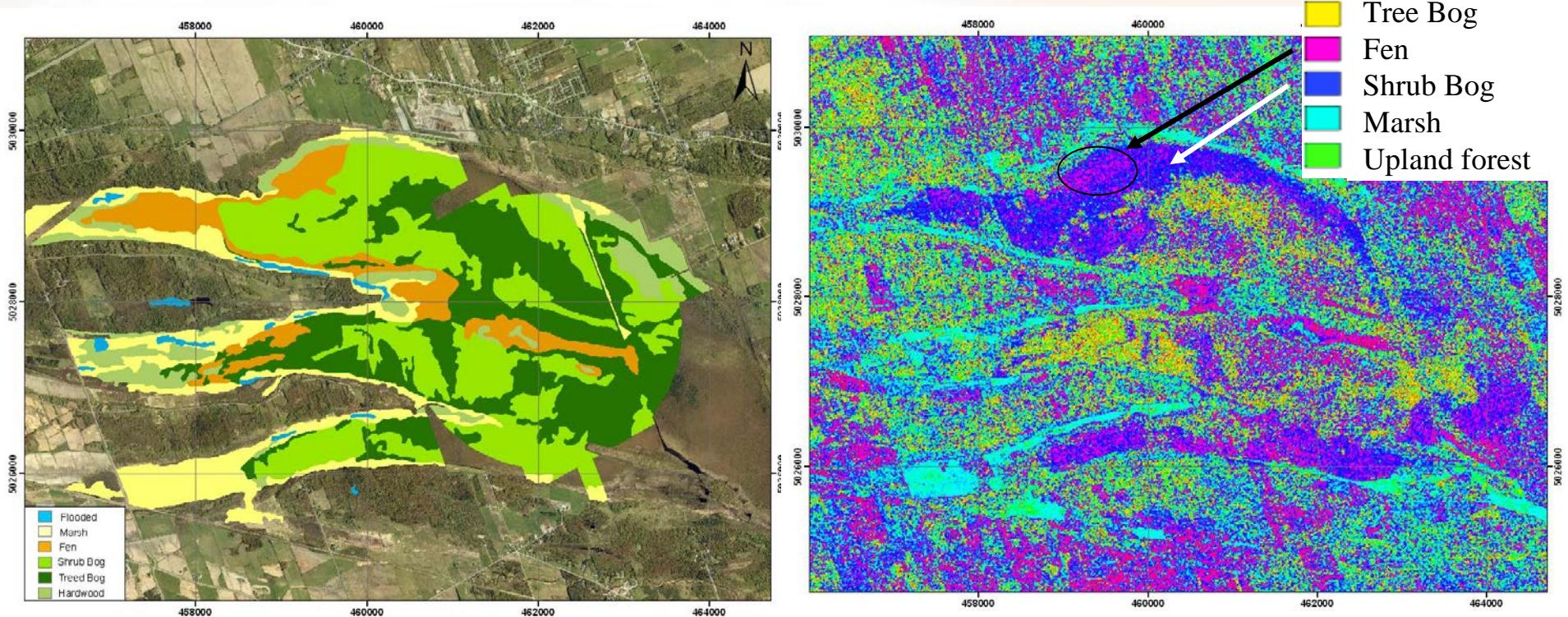
$$-\frac{\pi}{4} \leq \tau \leq \frac{\pi}{4}$$

$$0 \leq \alpha_s \leq \frac{\pi}{2}$$

- ▶ $(\alpha_s, \Phi_{\alpha s}, \tau) \rightarrow$ unambiguous description of target scattering



Dominant scattering Type Phase $\Phi_{\alpha s1}$ for Wetland Classification

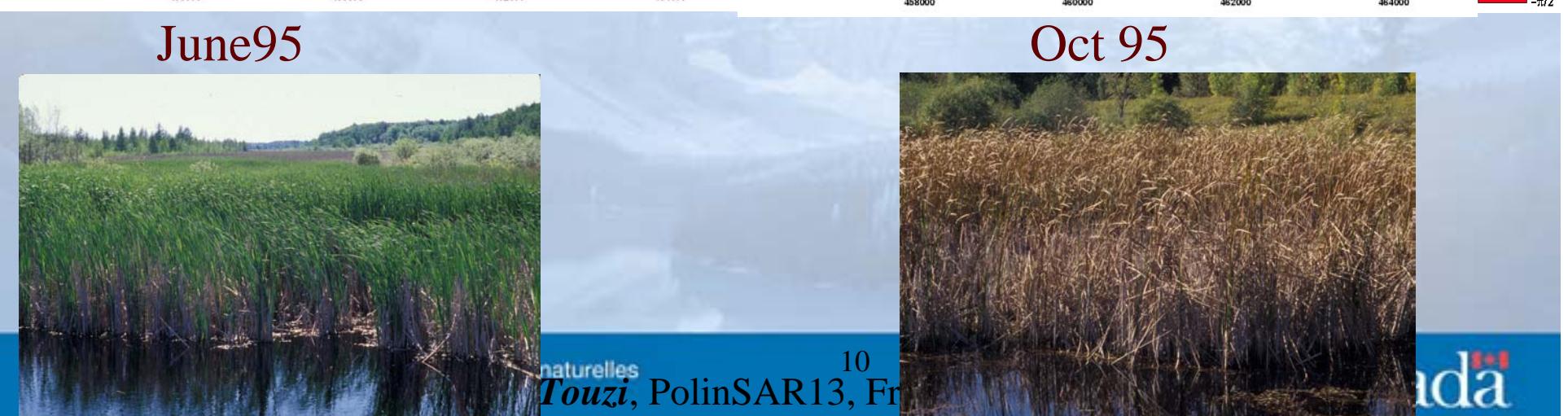
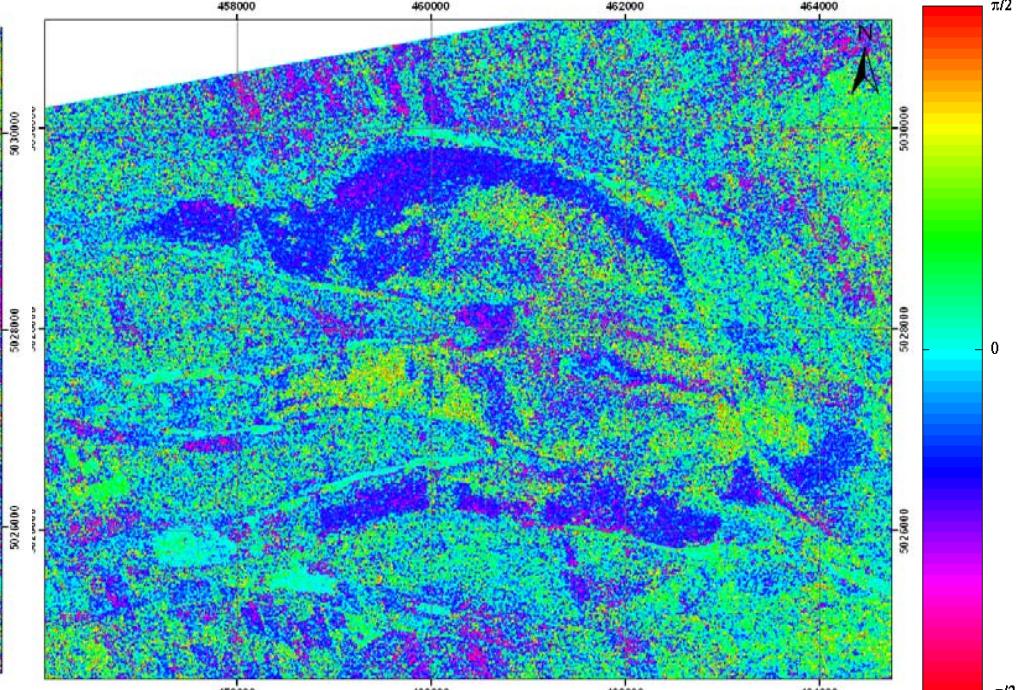
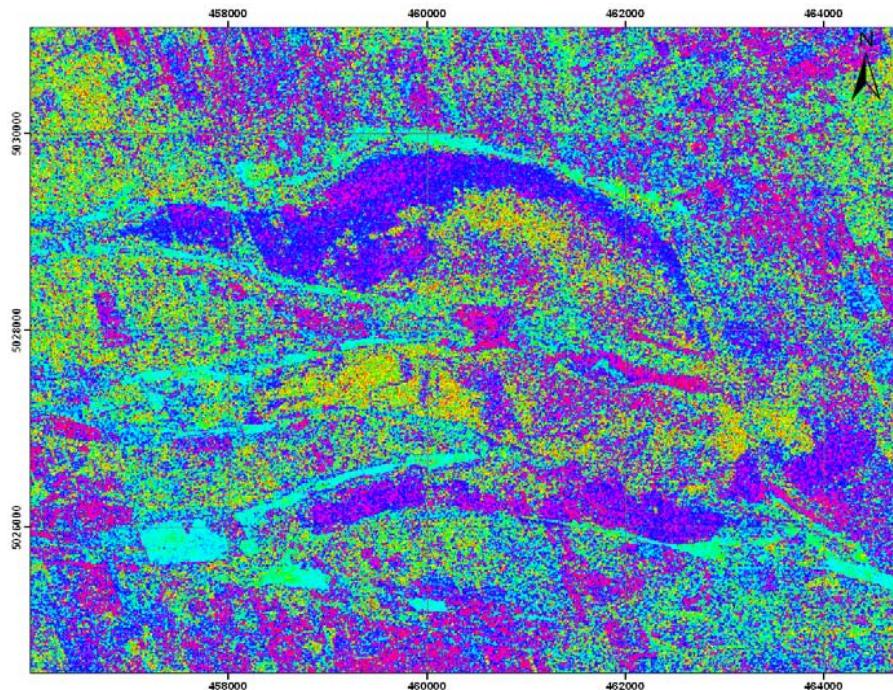


Color aerial photographs(2002) overlaid with a wetland classification based on the NCC the forest cover inventory.

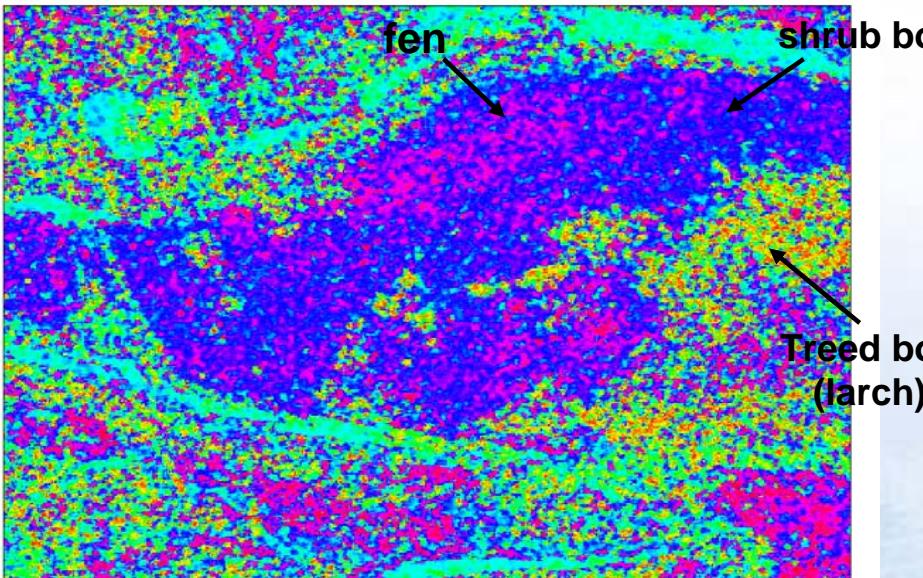
$\Phi_{\alpha s1}$ (June 95)

👉 Scattering Type Phase $\Phi_{\alpha s1}$ Discriminates **bog** from **fen**

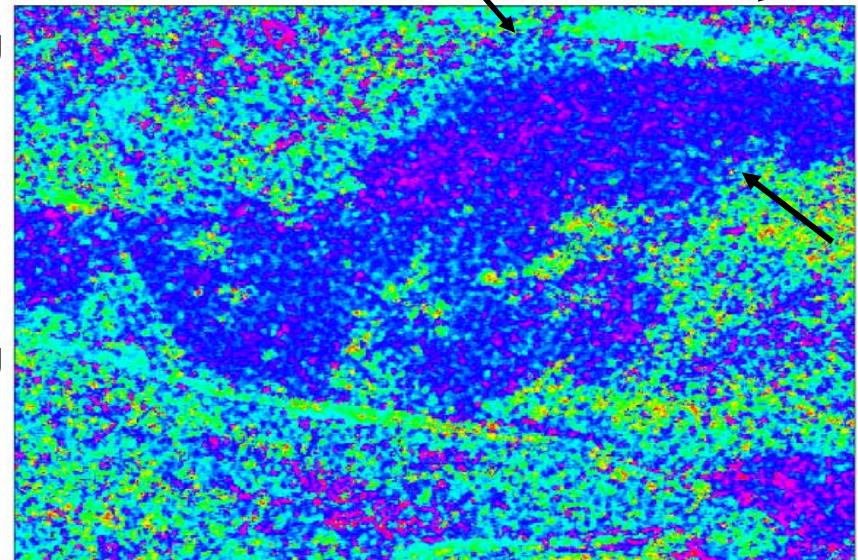
$\Phi_{\alpha s1}$ For Wetland Seasonal Changes



Touzi phase sensitive to peatland subsurface water Flow



June 1995



October 1995

- Sedge-dominated **fens** and **shrub-bog** well separated
- Treed bog: Larch seasonal needle loss detected



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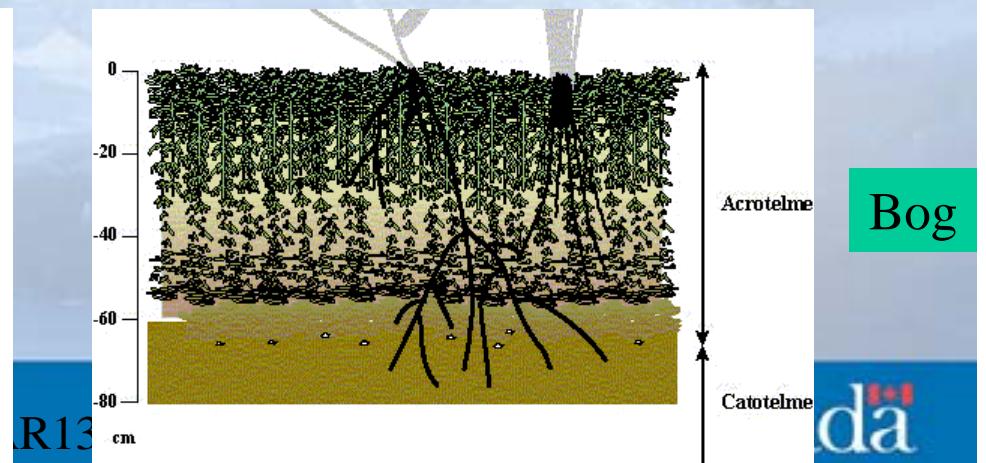
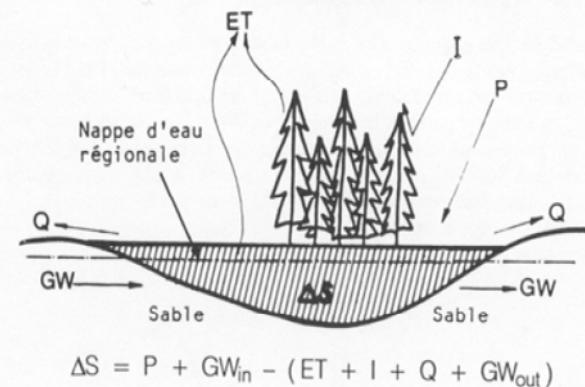


Scattering Phase Sensitivity to Subsurface Water Flow

Sciences Sector

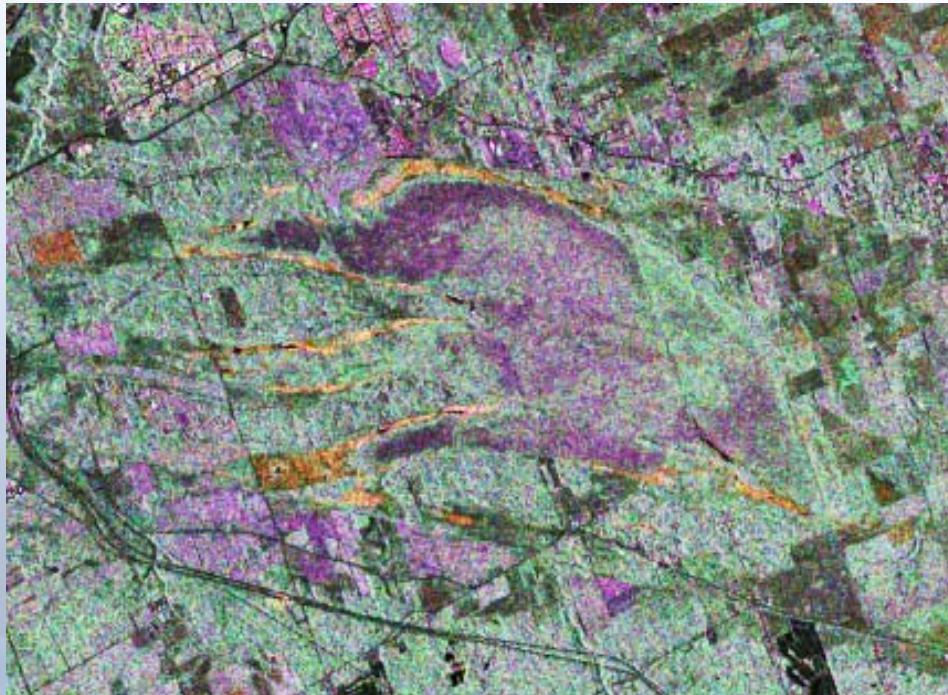


- Two sublayers: Acrotelm (high hydraulic conductivity) and Catotelm (low hydraulic conductivity)
 - Fen: water level 20 cm below the peat surface
 - Bog: water level 50 cm below the peat surface
- Radiometry (HH, VV, VH, Cloude α) not sensitive to subsurface water
- ϕ_{as} detects fen run-off water

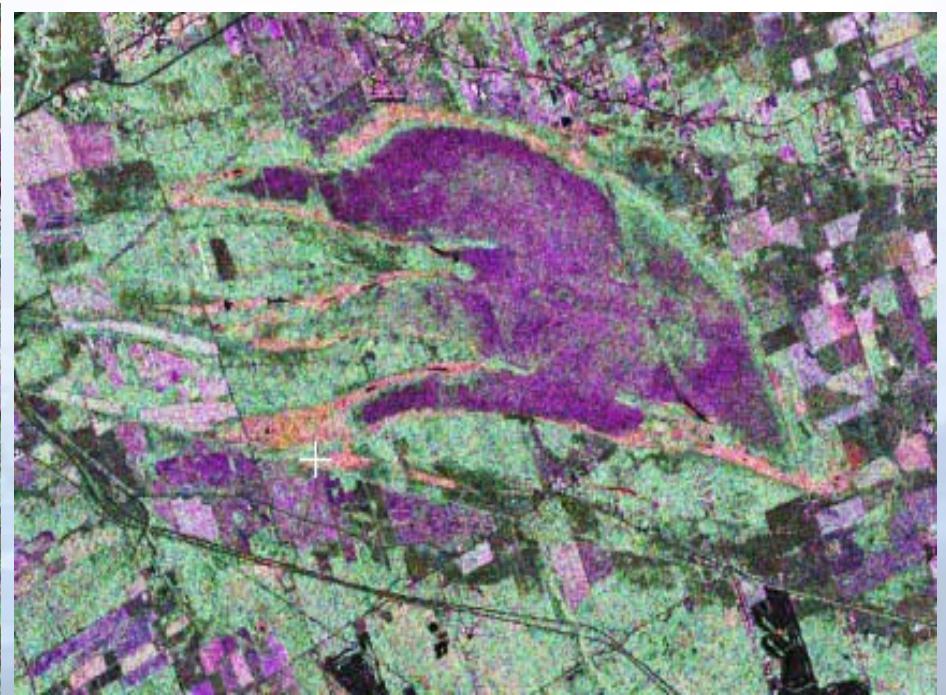




Mer Bleue Wetland seasonal change Detection Using Radarsat 2 (FQ12, HH-HV-VV in RGB)



July08 (dry conditions)



Oct 27, 08 (wet conditions)



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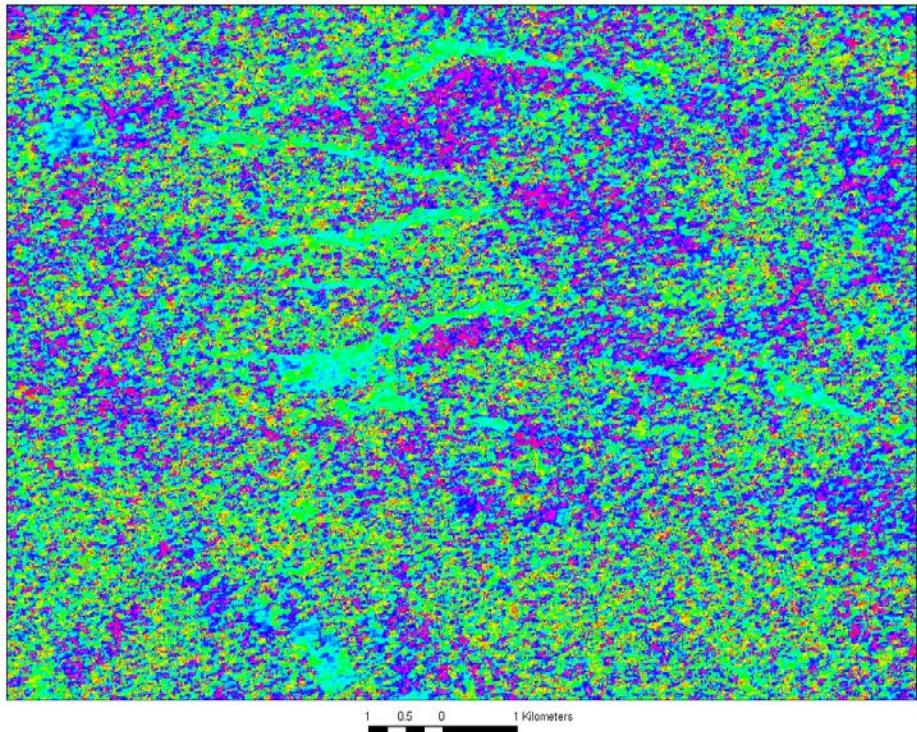
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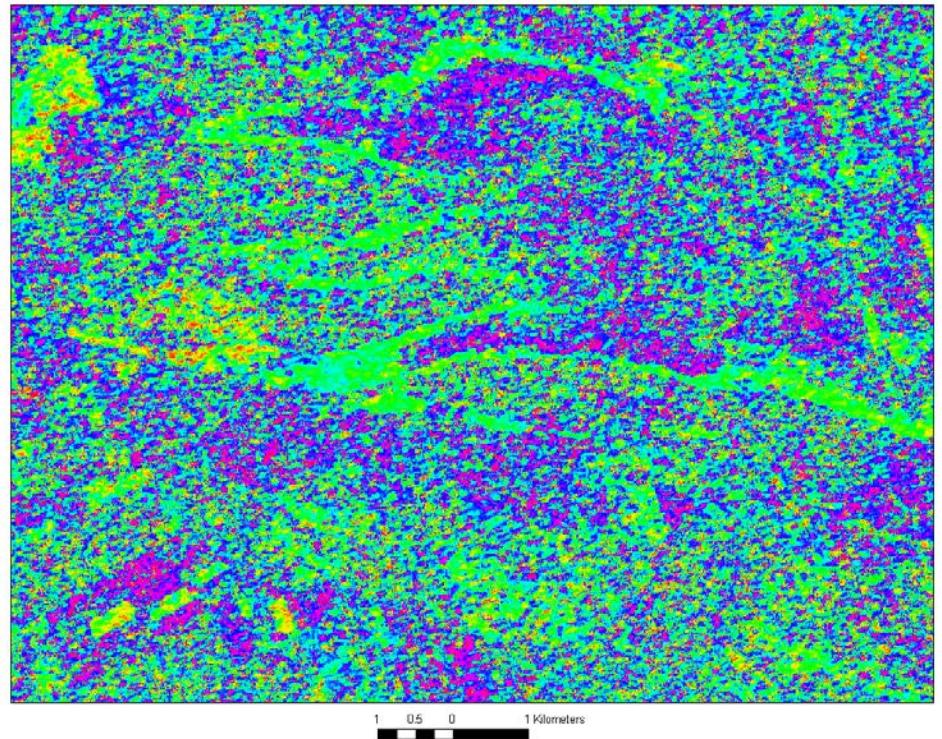


Radarsat 2 Scattering Phase $\phi_{\alpha s}$

July 2008



Oct 2008



- ➡ Scattering Phase Not Sensitive to peatland subsurface water flow
Seasonal changes



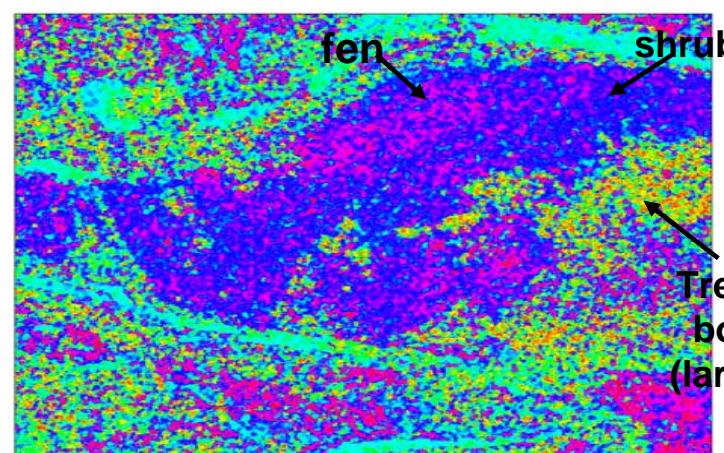
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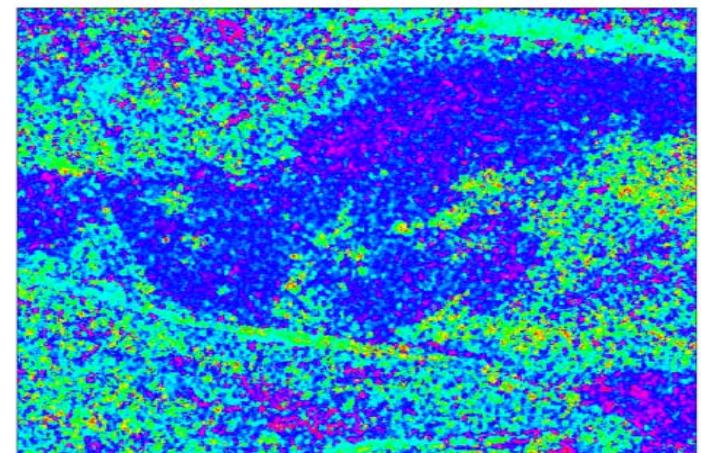
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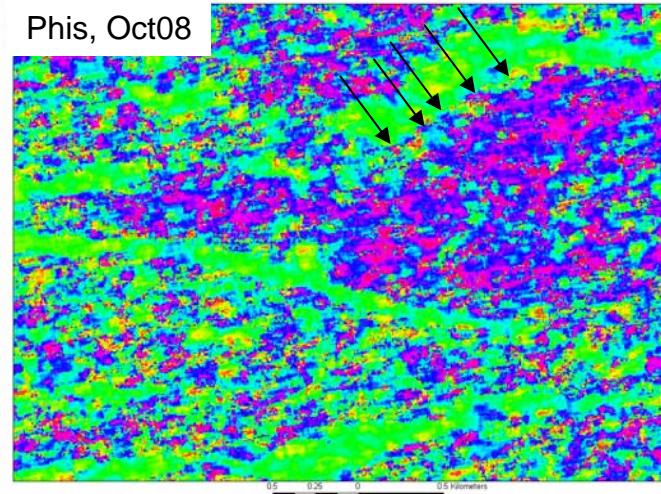
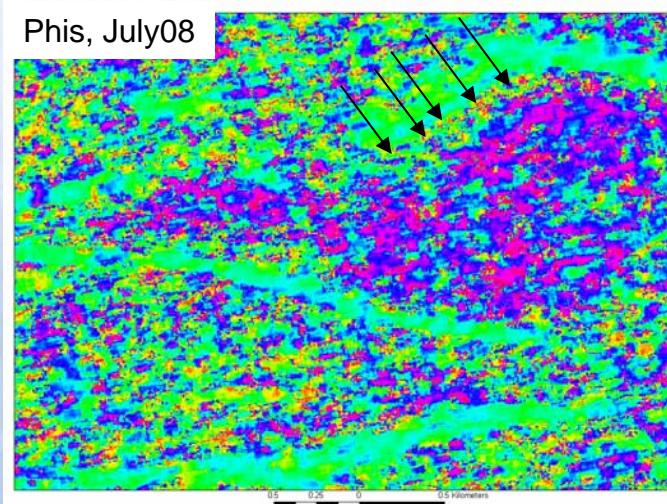


June 1995



CV-580

Oct. 1995



Radarsat-2

✳ RS2 Phase **not sensitive** to subsurface water

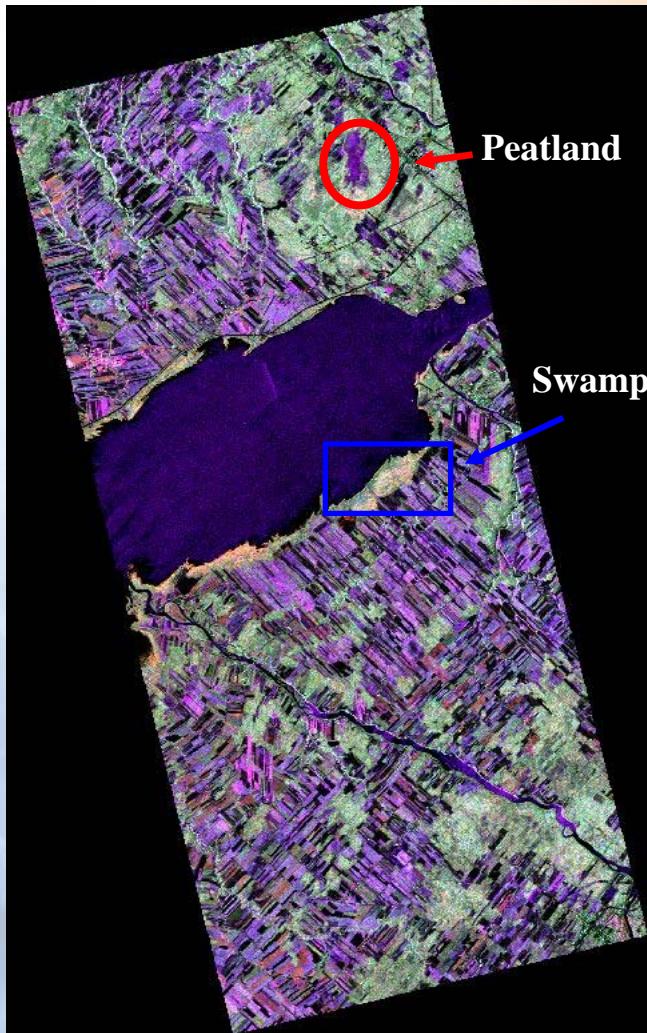
👉 Noise floor (-35 dB) **not** sufficiently low (CV580 : NESZ=-48 dB)



L-Band PALSAR for Wetland Characterization Lac Saint Pierre (Canada)



ALOS / PALSAR
JAXA / JAROS (J)



PALSAR, Nov. 10, 2007



PALSAR, May 13, 2007



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Lac St Pierre Peatland Characterization Using Polarimetric ALOS

• Earth Sciences Sector

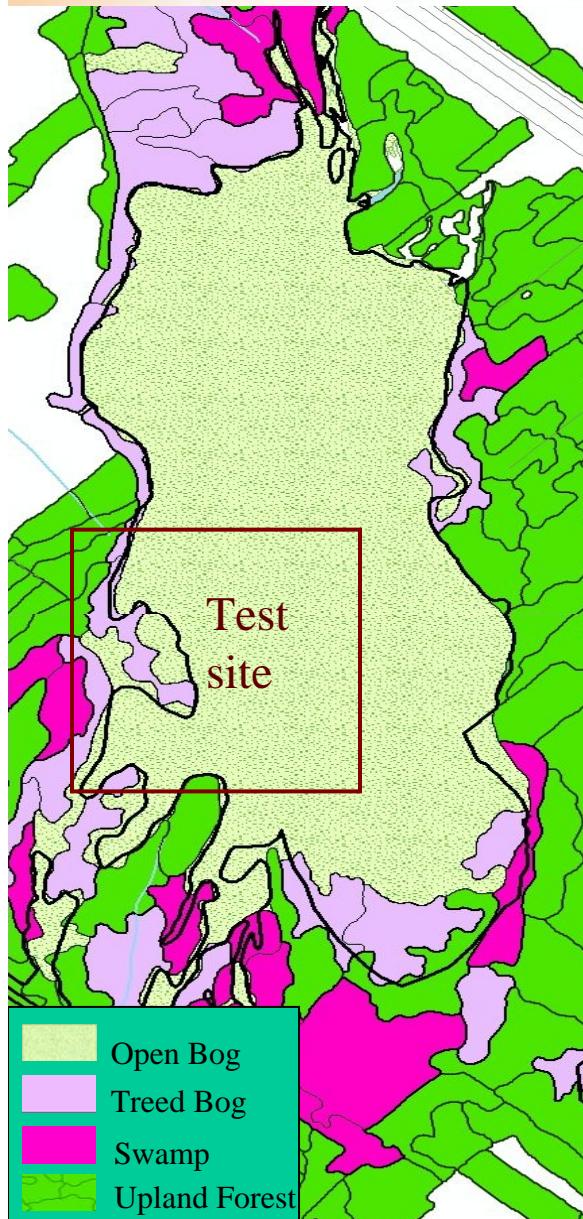


Frasccatti,

canada

Peatland: Poor fen + Bog

☞ Cannot be discriminated with Optic Sensors



- **Bog:**

- **Ombrotrophic:** . precipitations, fog and snow are the primary water sources

- **Poor Fen:**

- **Minerotrophic:** fens are connected to small streams and may also receive water from surrounding uplands.

- As such, poor fens of high water retention are **continuously irrigated** with subsurface water even under no rainy conditions.

Shrub Bog

Peat Thickness larger than 3m



Ledum groenlandicum
(Labrador Tea)

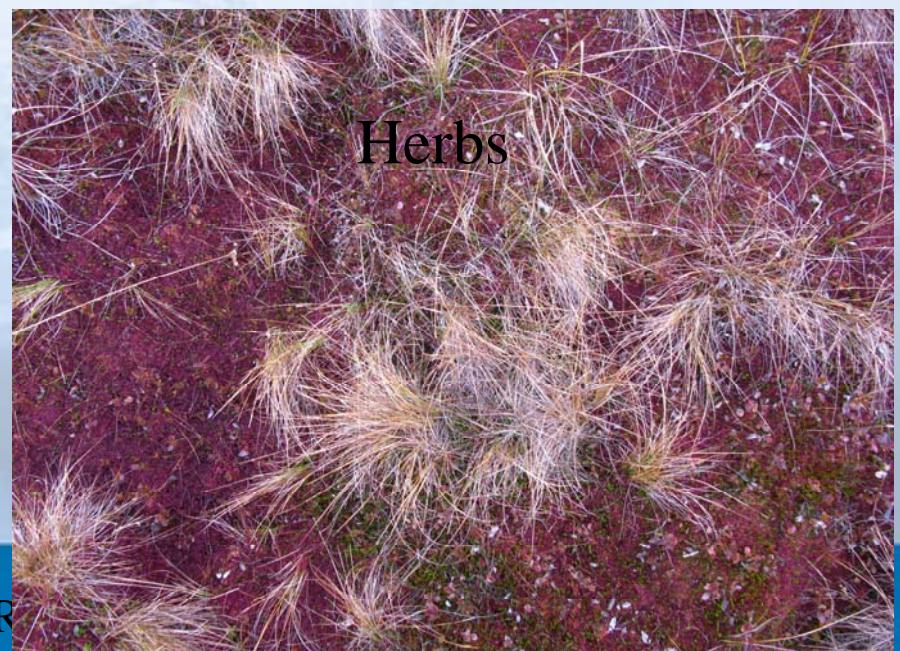


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Shrub Fen



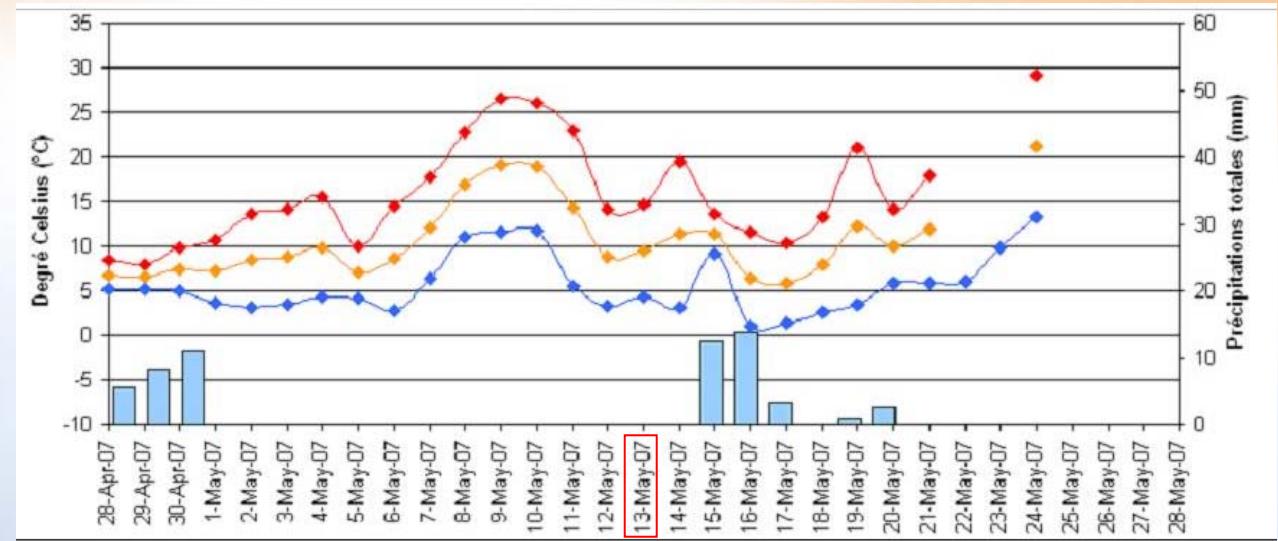
Herbs



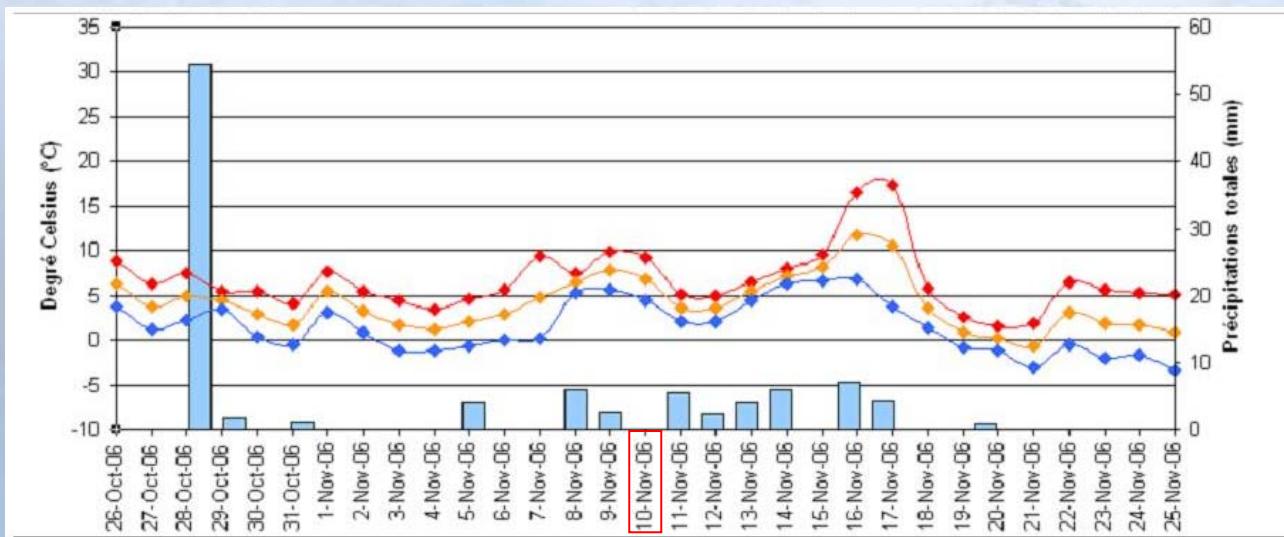
nSAR



Weather & Precipitations



- █ Precipitations (mm)
- ◆ T. max ($^{\circ}\text{C}$)
- ◆ T. mean ($^{\circ}\text{C}$)
- ◆ T. min ($^{\circ}\text{C}$)

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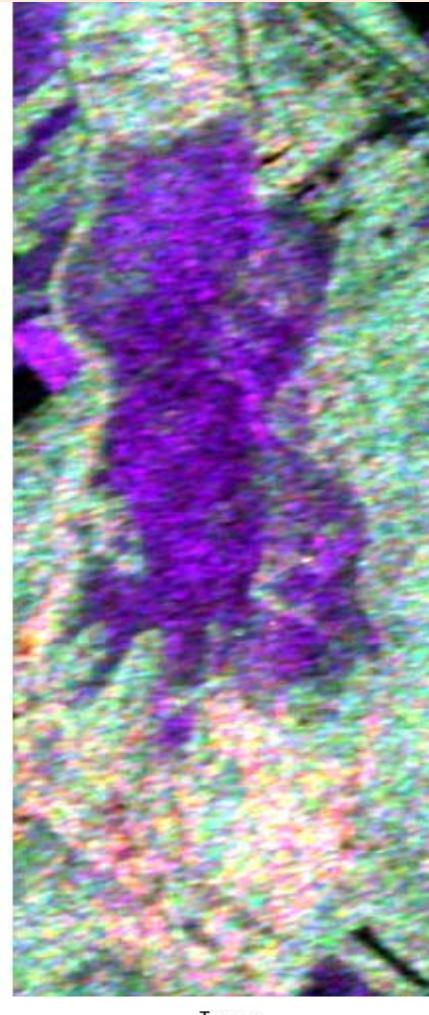
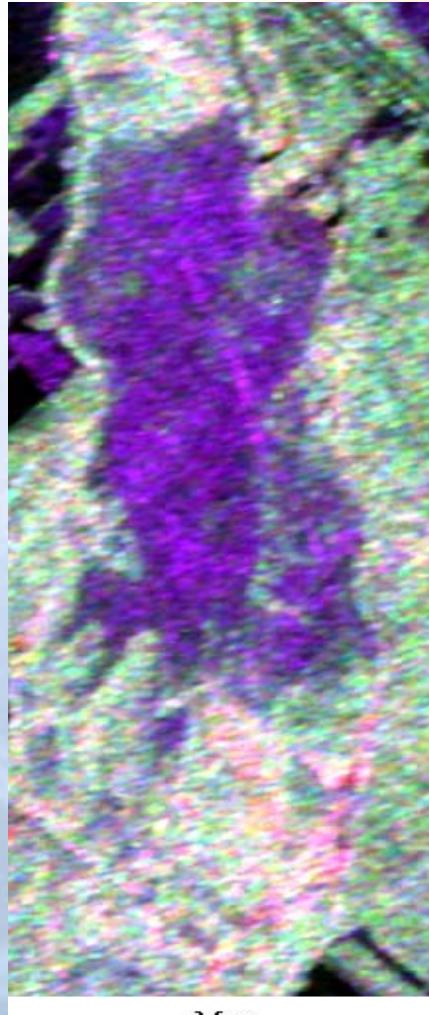
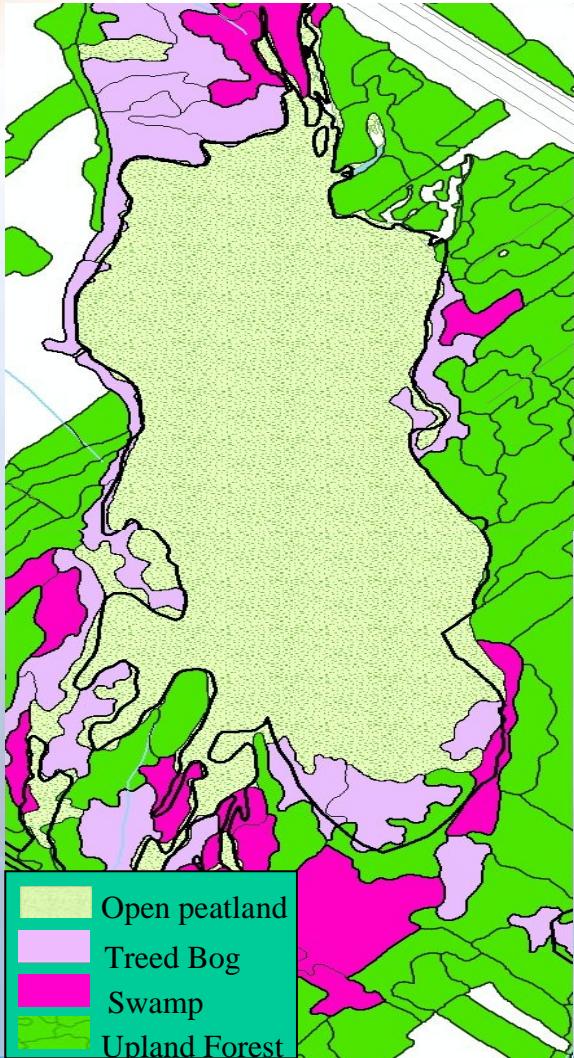
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☞ HH-HV-VV not sensitive to water flow variations **beneath** the peat surface



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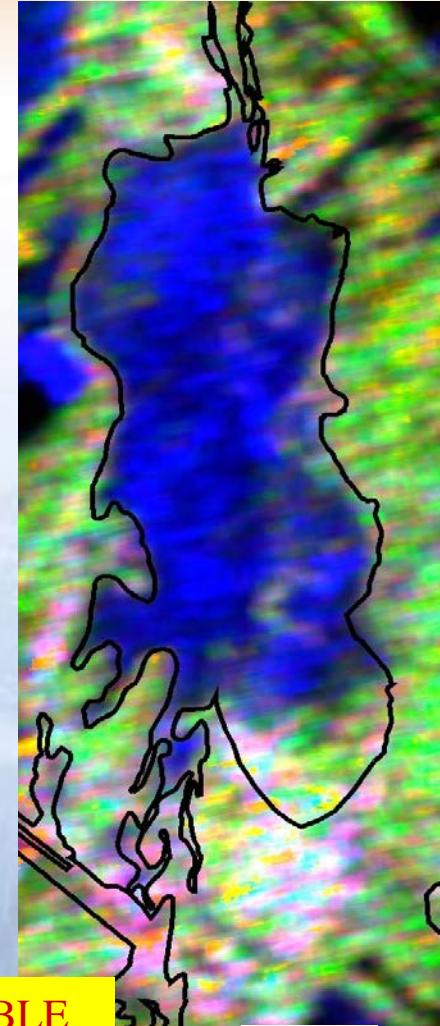
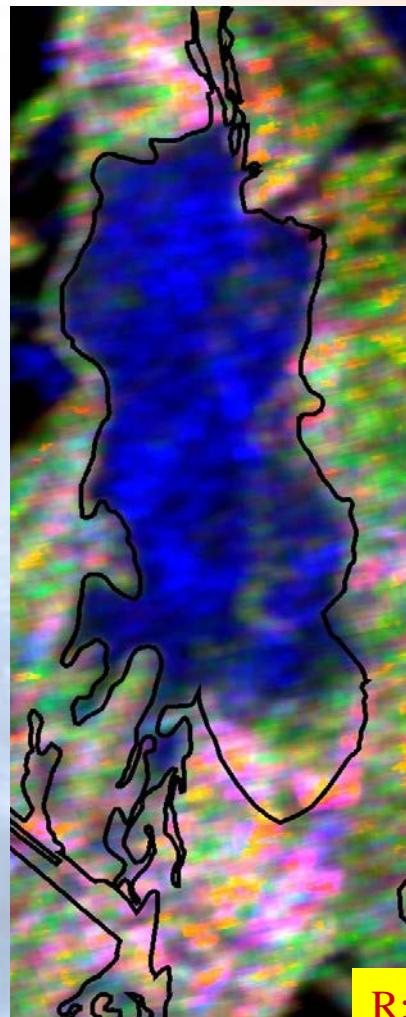
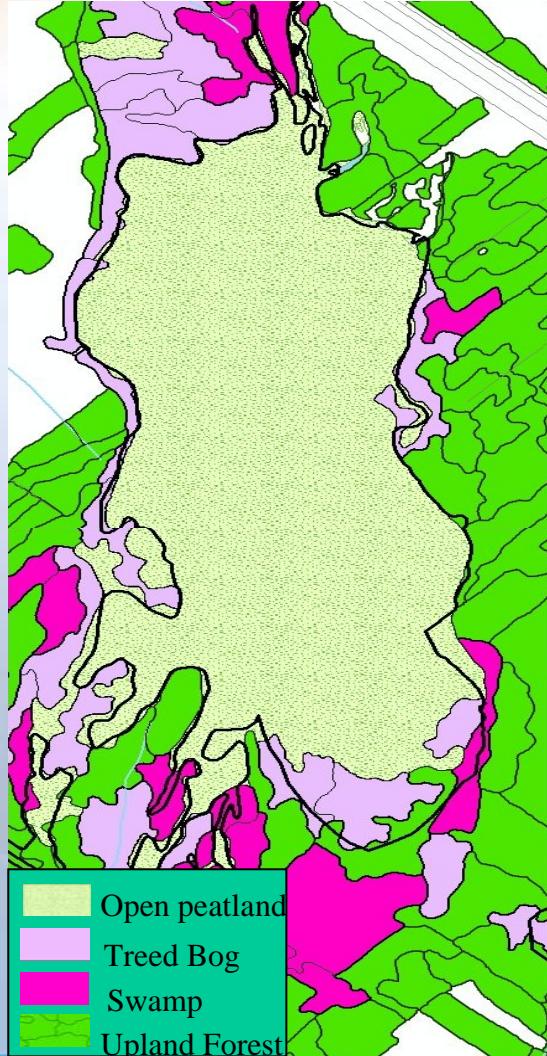
21

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Freeman Coarse Scattering Classification not sensitive to water flow variations **beneath** the peat surface



R:DOUBLE
G:VOLUME
B:ODD



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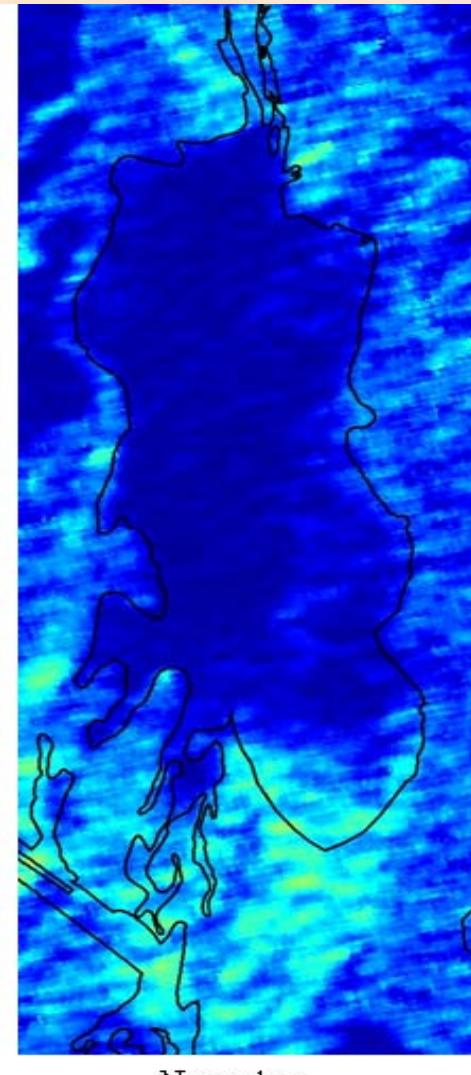
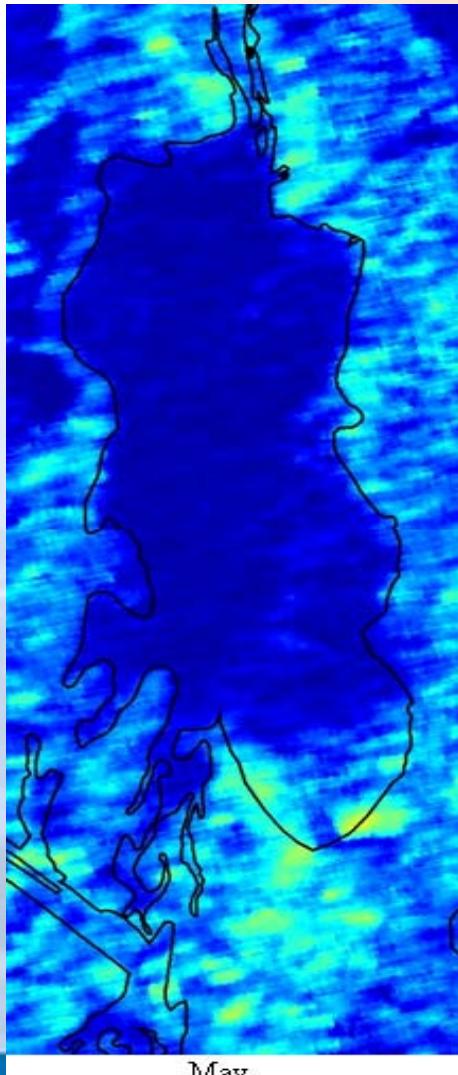
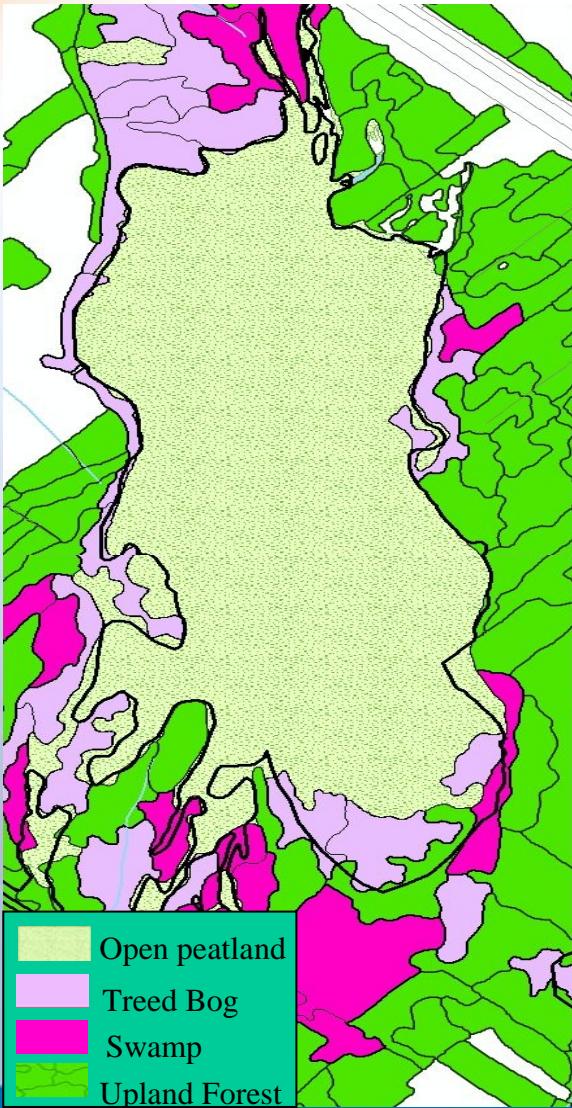
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Nov

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May
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➡ α_s (Cloudy α) not sensitive to water flow variations **beneath** the peat surface



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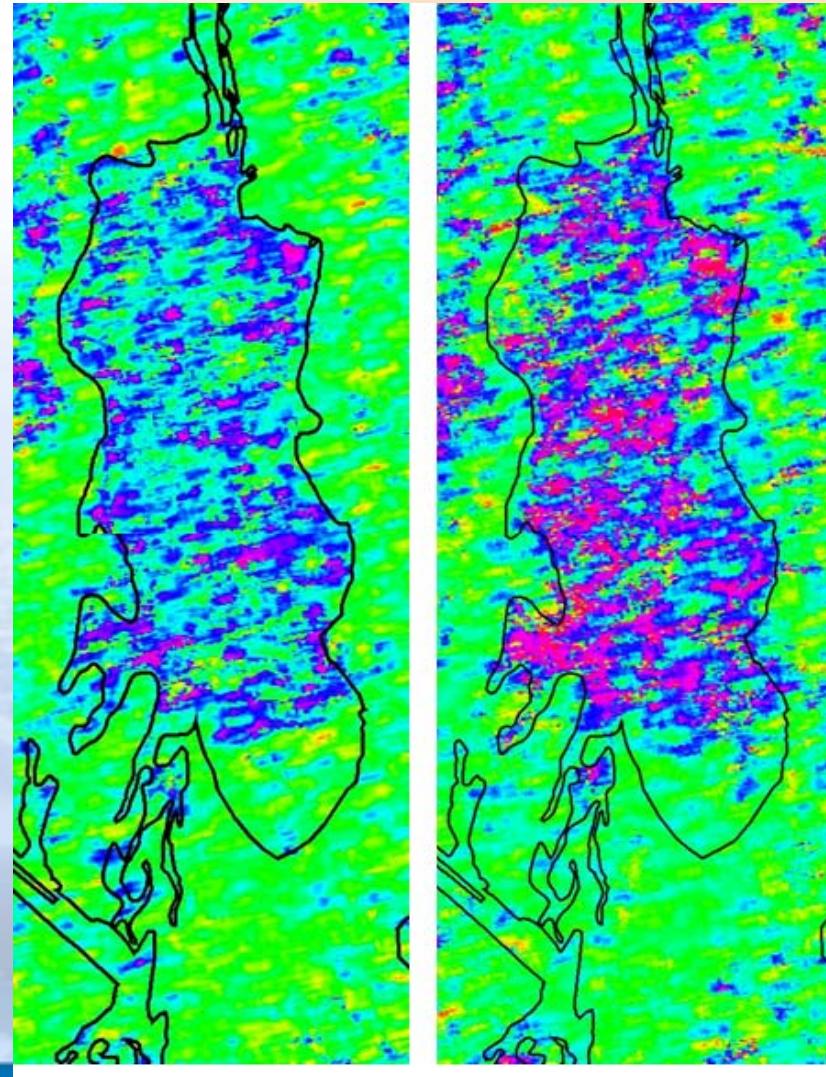
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► Touzi phase **detects** water flow variations **beneath** the peat surface

- **Pink** ⇨ subsurface water (less than 20 cm)
- ⇨ Fen: subsurface run off water
- **Bleue** ⇨ deep underground water
- Bog: water level at the catotelm (40-50 cm)

► **Essential** information for monitoring Bog-Fen Transformations in the North due to climate change stress



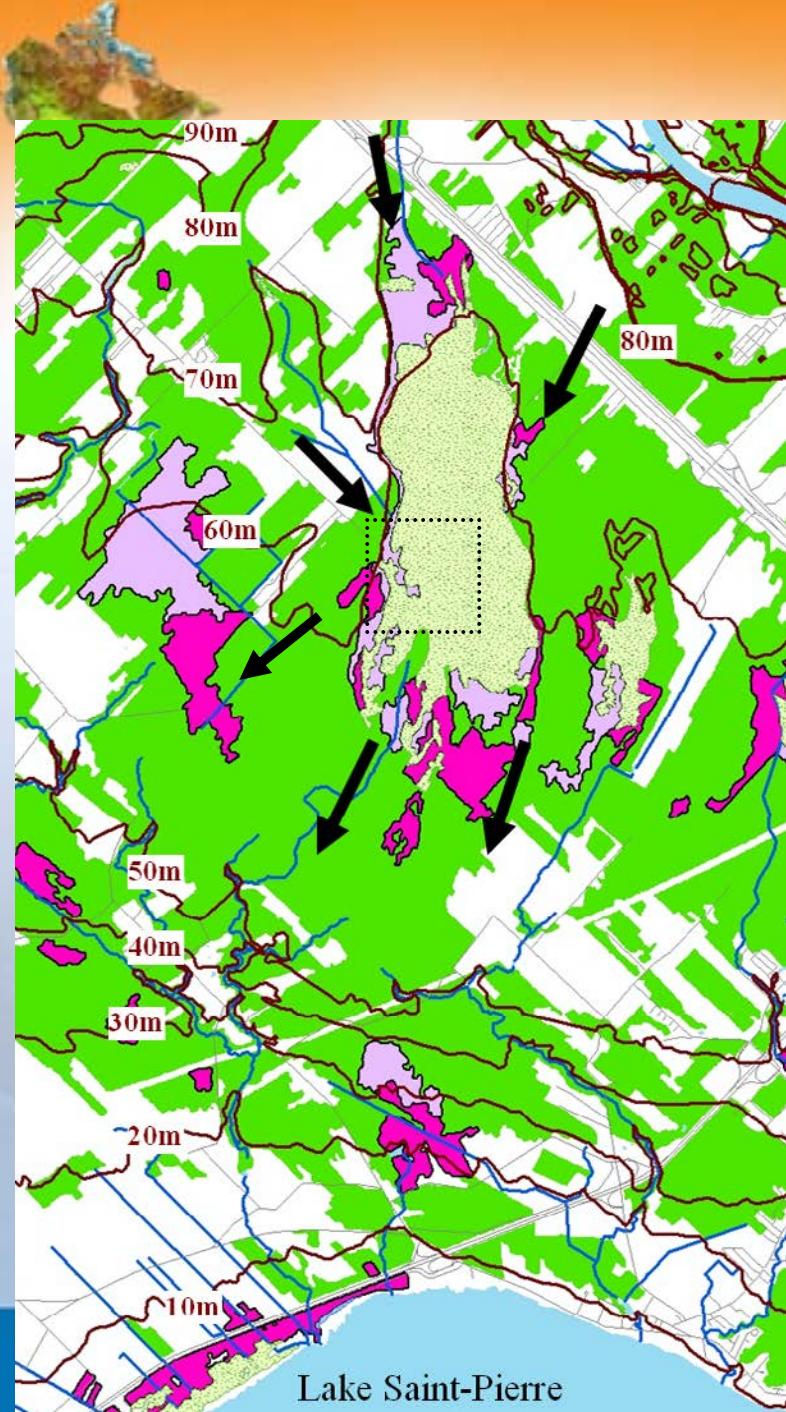
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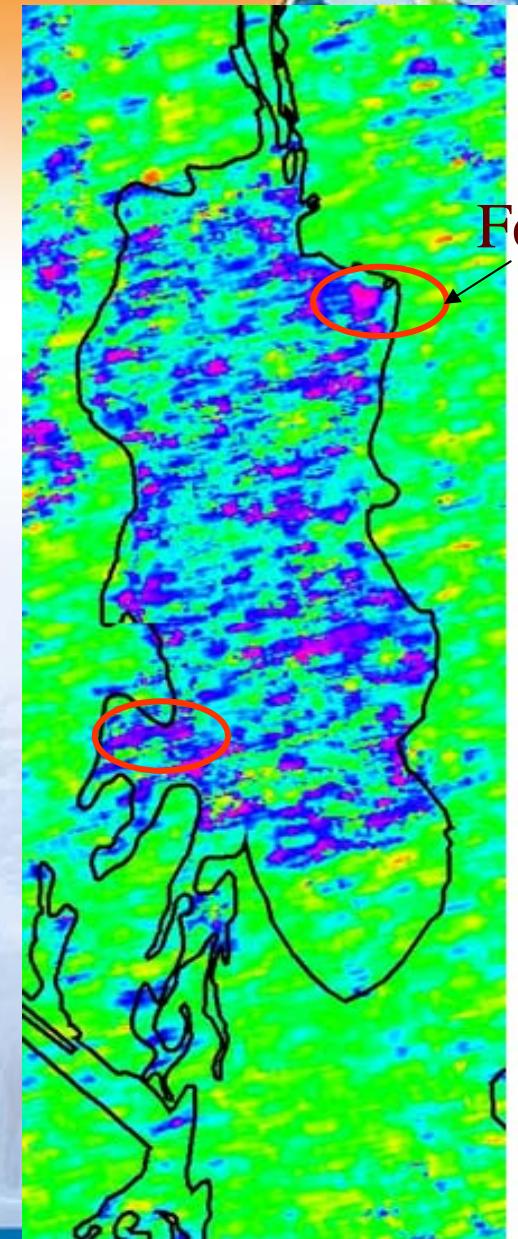
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Detection of Poor fens in Open Bog

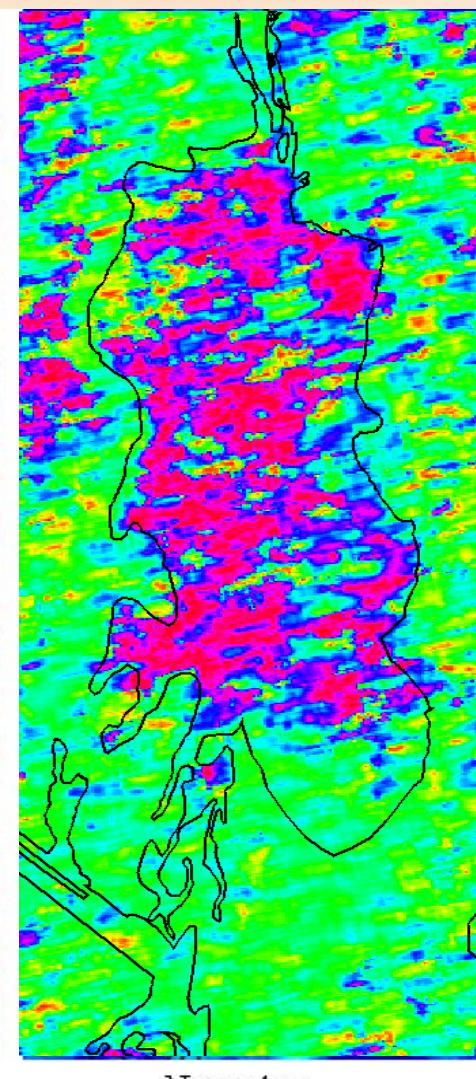
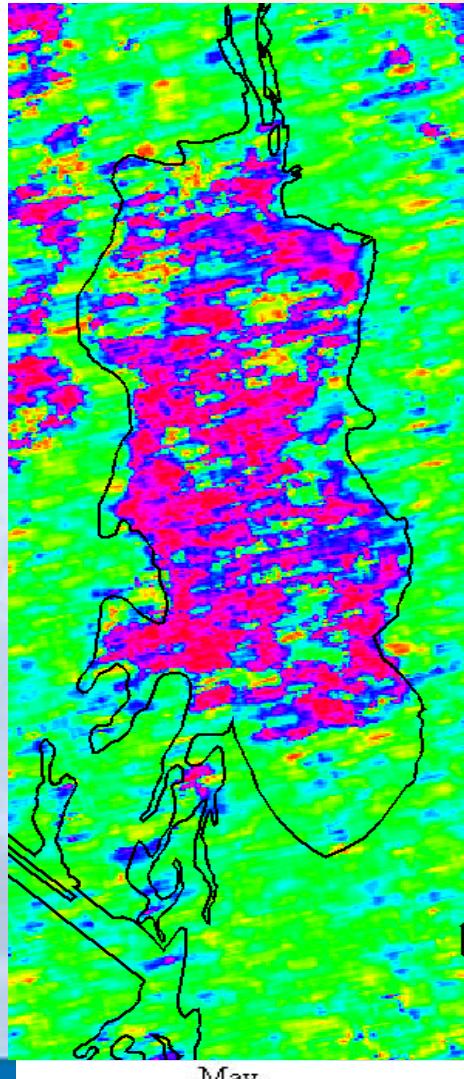
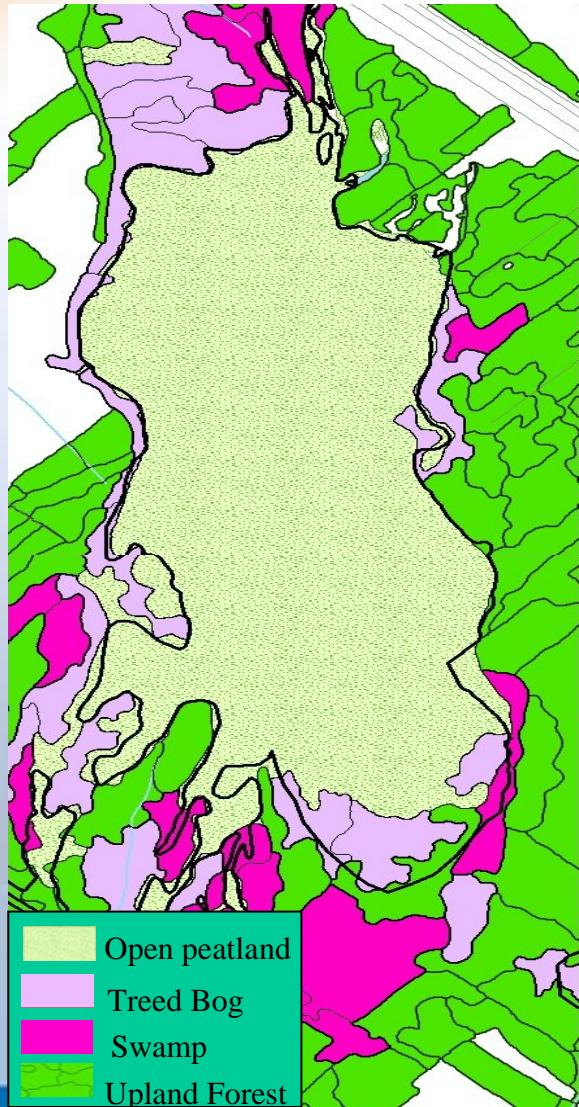


- Surface runoff direction
- Stream
- Elevation contour line (m)





Pauli Phase $\arg(HH-VV, HH+VV)$ not sensitive to subsurface water flow variations



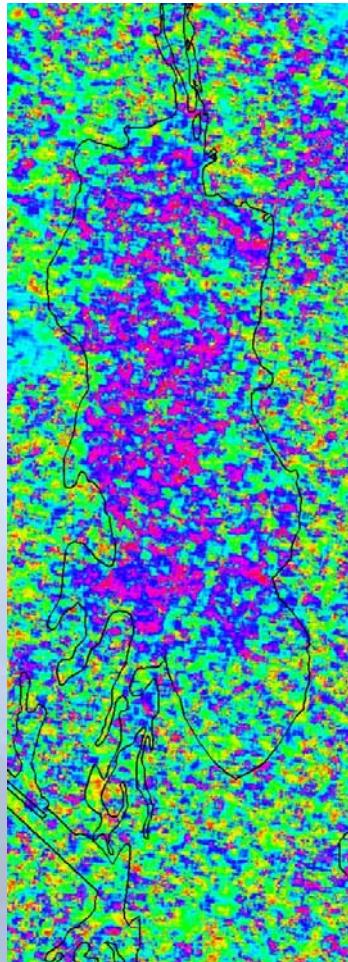
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Ressources naturelles
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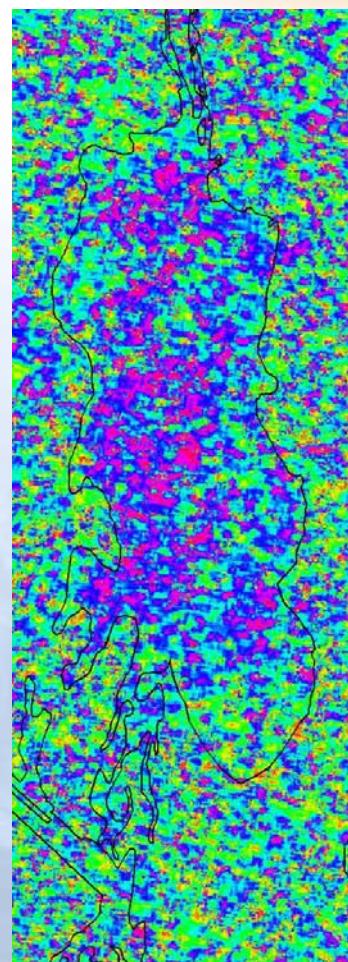
R. Touzi, PolinSAR13, Frascatti, Jan. 31

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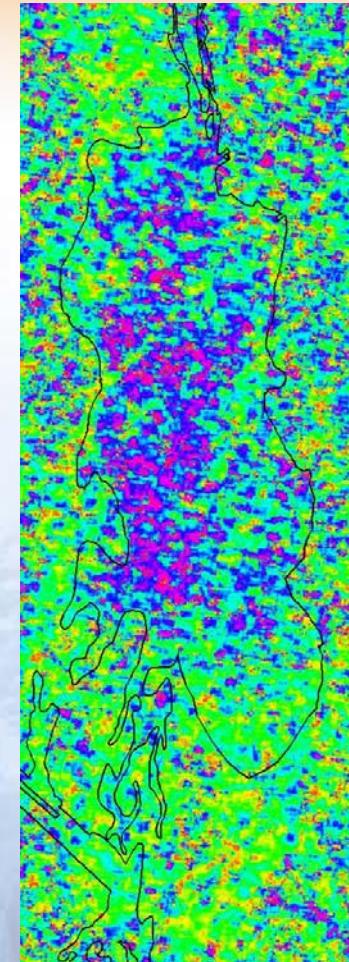
C-band-Radarsat2 not sensitive to peatland subsurface water flow (C-band + HV S/N not sufficiently low)



Jul-10



Aug-10



Nov-10



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27

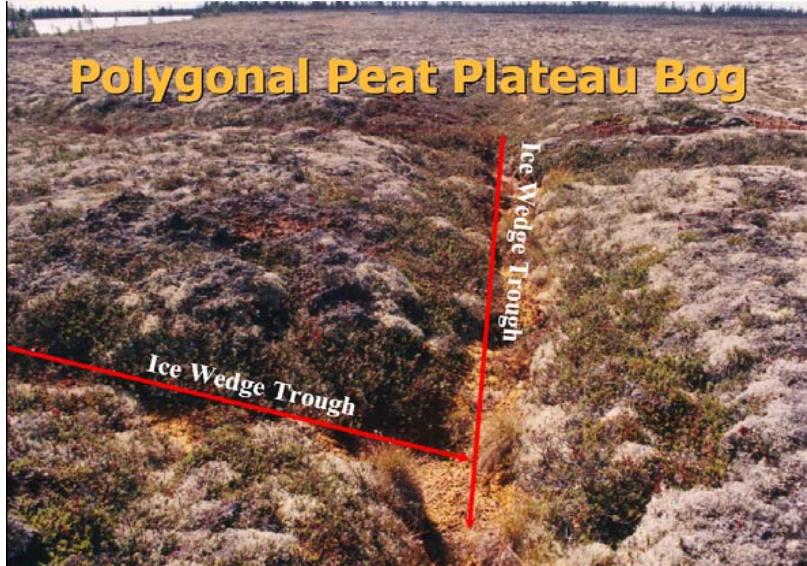
R. Touzi, PolinSAR13, Frascatti, Jan. 31

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Polarimetric L-band PALSAR for Monitoring of peatland subsurface water flow

➡ Bog-fen transformations



Larry Dyke 2009 GSC

Climate Change effect:

- * Bogs transformed to Fen
 - Affect polar bear denning habitat which is entirely within bogs with thick peat deposits
 - Polar Bear under threat

➡ Alos => Bog & Fen monitoring



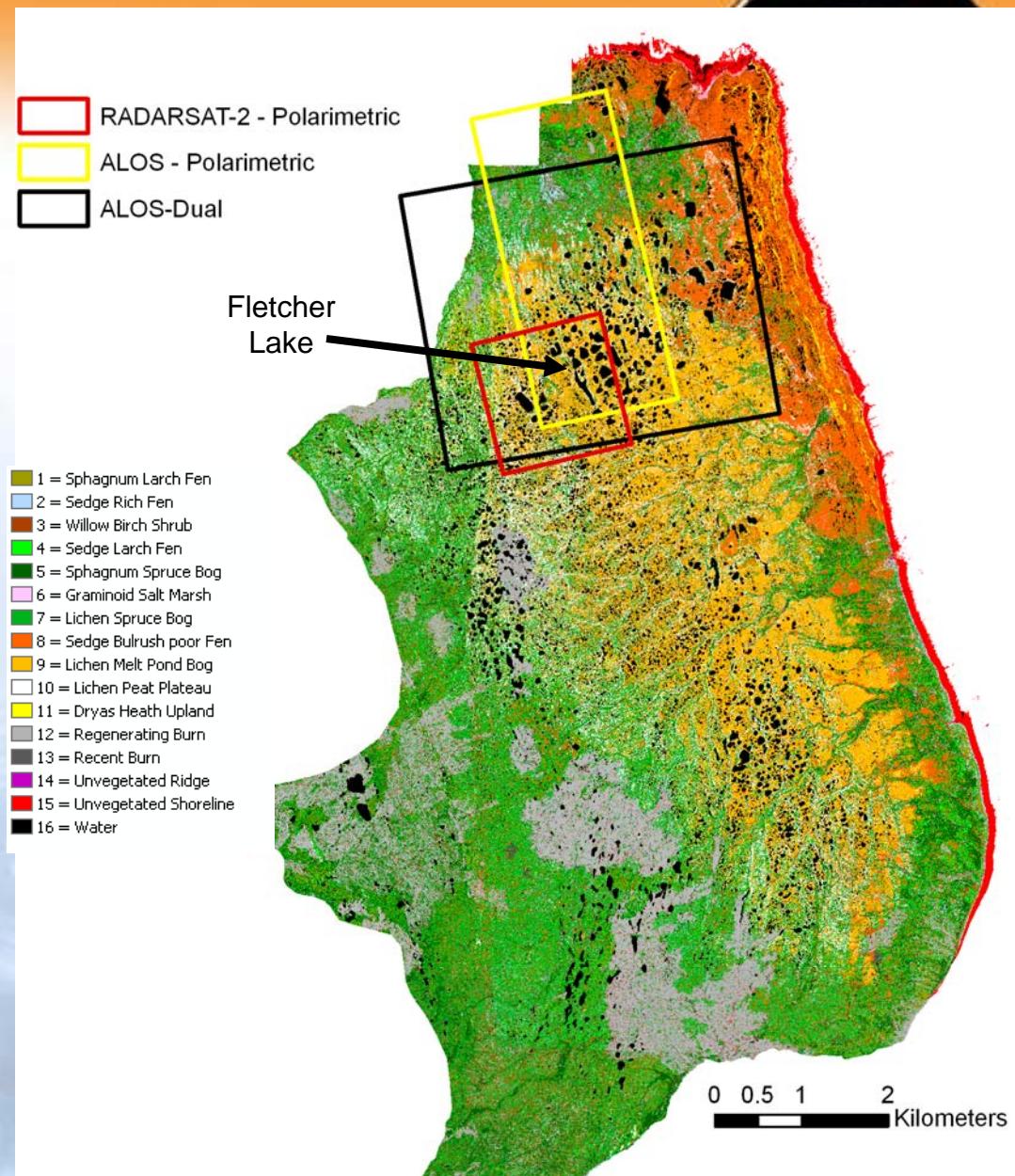
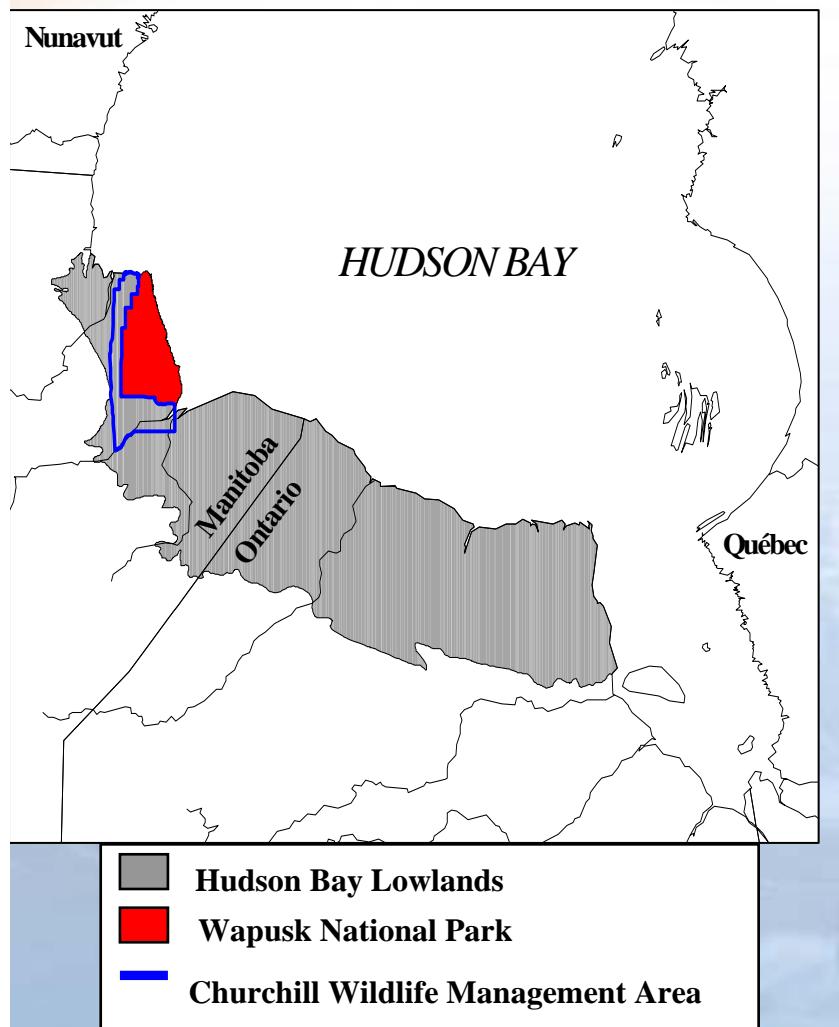
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R. Touzi, PolinSAR

Wapusk National Park RADARSAT-2 and ALOS Acquisitions

Canada Centre for Remote Sensing • Earth Sciences Sector



Ryan Brook's Classification
(Landsat-TM5, July, 27th, 1996)



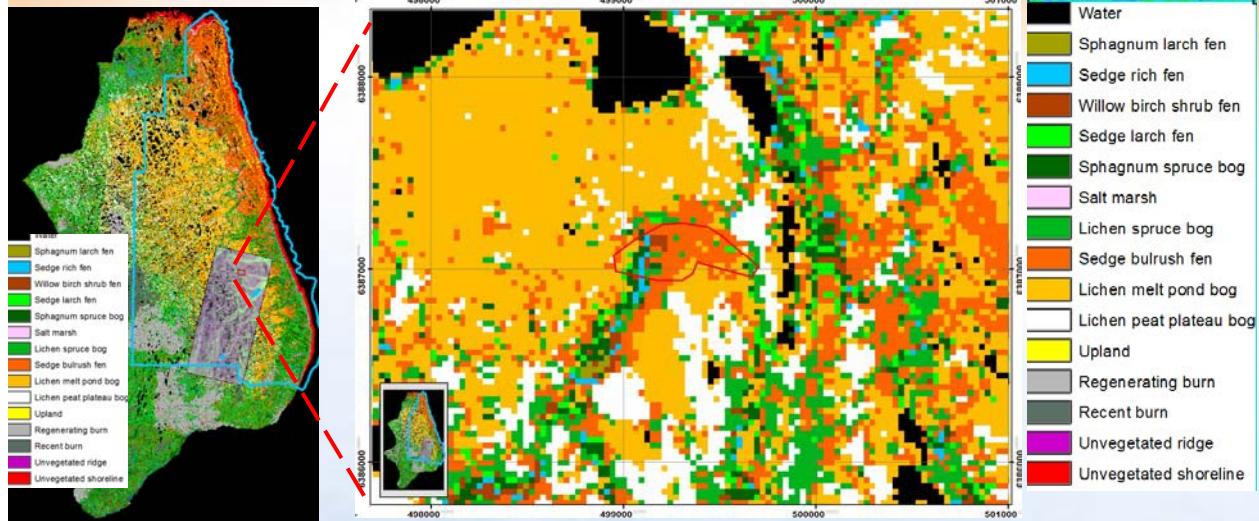
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Ressources Naturelles
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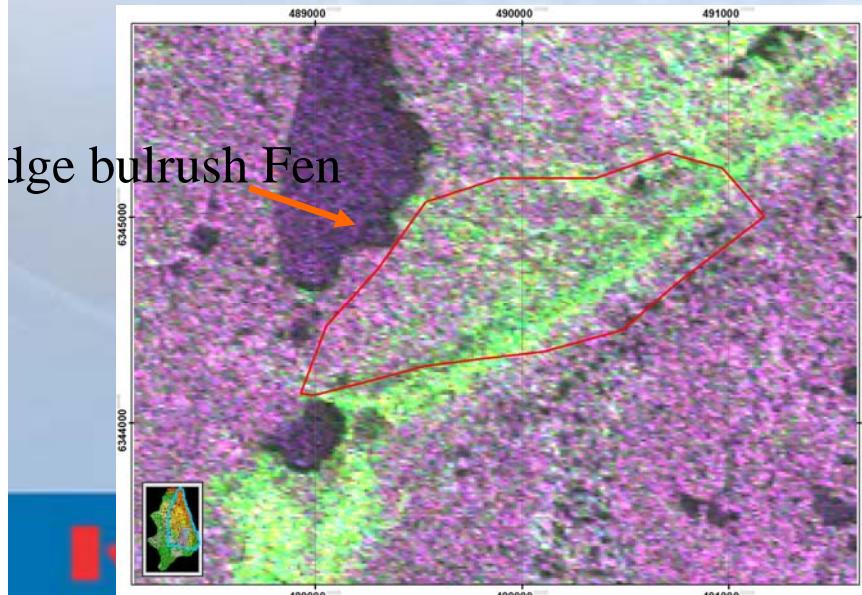
Subsurface Water Flow Change Sedge bulrush Fen & Litchen melt pond bog

Jun 8: Active layer 13 cm
Jul 24: Active layer 27 cm



Sedge bulrush Fen

ALOS HH, HV, VV (Descending, Jun 8, 2010)

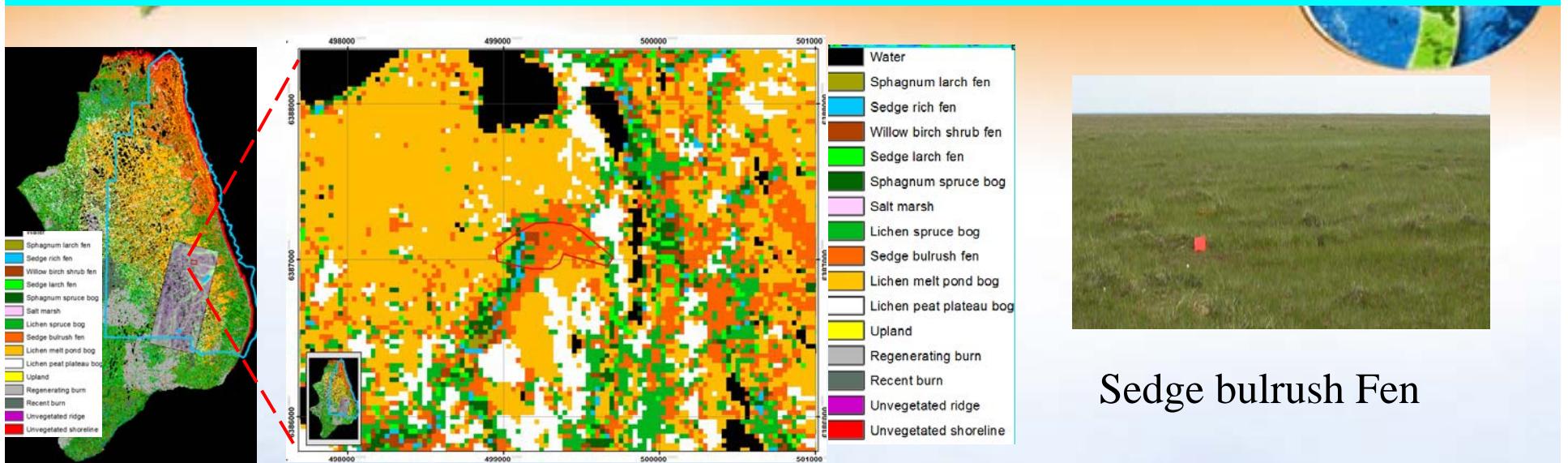


30
inSAR13, Fra

ALOS HH, HV, VV (Descending, Jul 24, 2010)

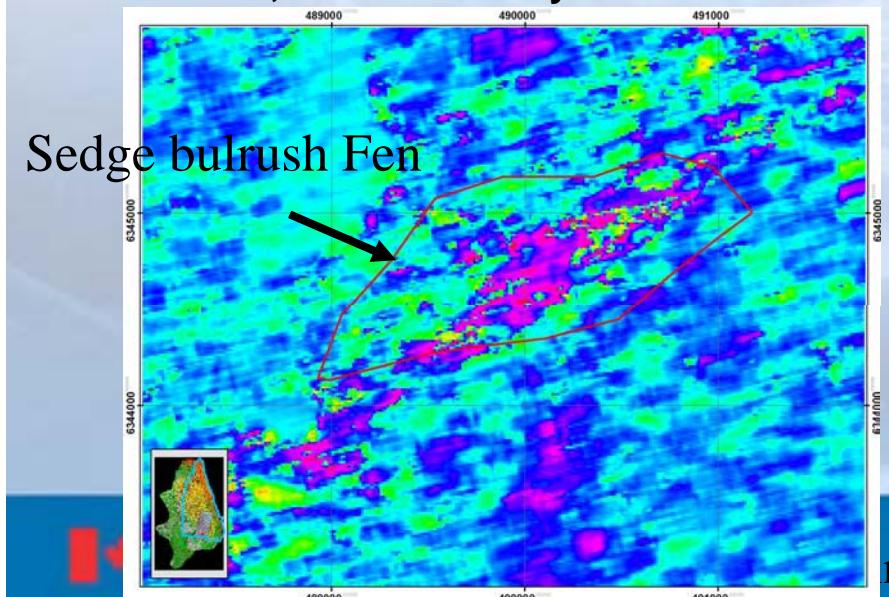


► Touzi scattering Phase Detects Subsurface Water Flow Change
Sedge bulrush Fen & Litchen melt pond bog



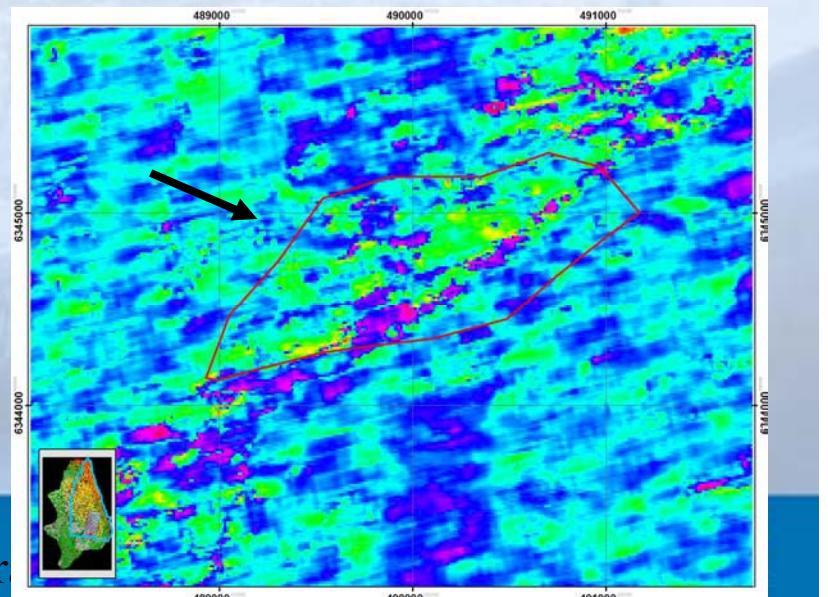
Sedge bulrush Fen

June 8, 2010: Active layer 13 cm



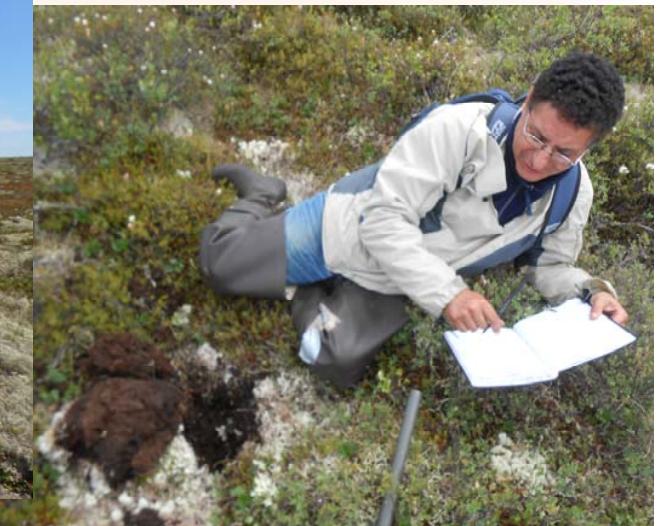
31
nSAR13, Fr

July 24, 2010: Active layer 30cm



Validated July 6, 2012

Lichen melt pond bog



➤ No water under peat bog surface

➤ Active layer
(20cm)



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R. Touzi, PolinSAR13, Frascati

Sedge bulrush Fen



➤ Water 13 cm
under peat fen
surface



➤ Active layer
thickness (20cm)



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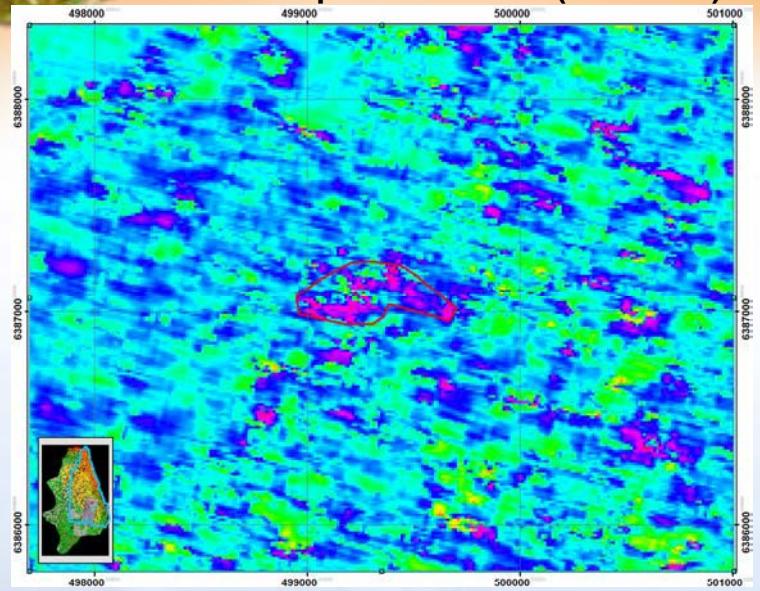
R. Touzi, PolinSAR13, Frascatti, Jan. 31

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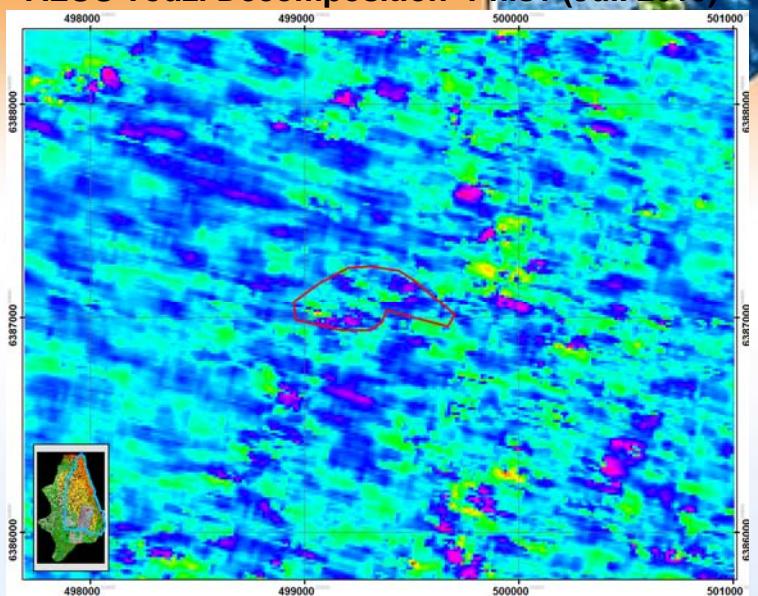
Radarsat2 Not sensitive to peatland subsurface water

• Earth Sciences Sector

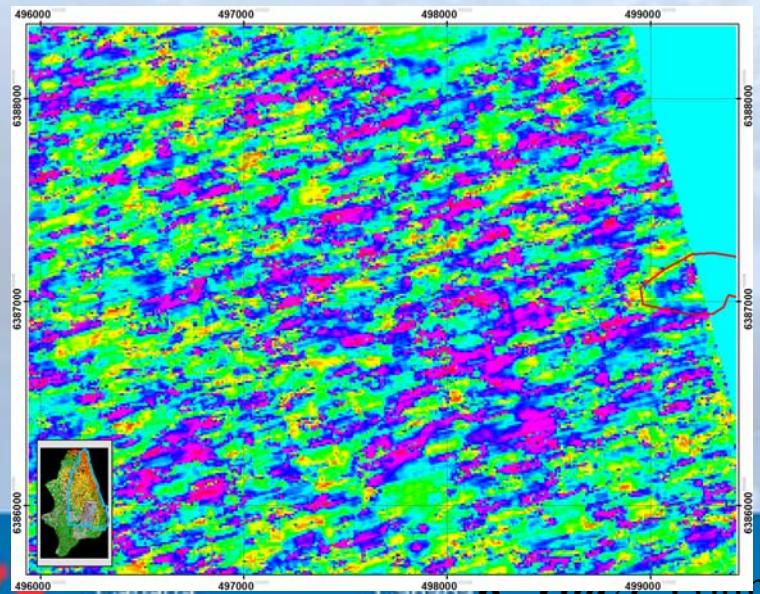
ALOS Touzi Decomposition- Phis1 (Jun. 2010)



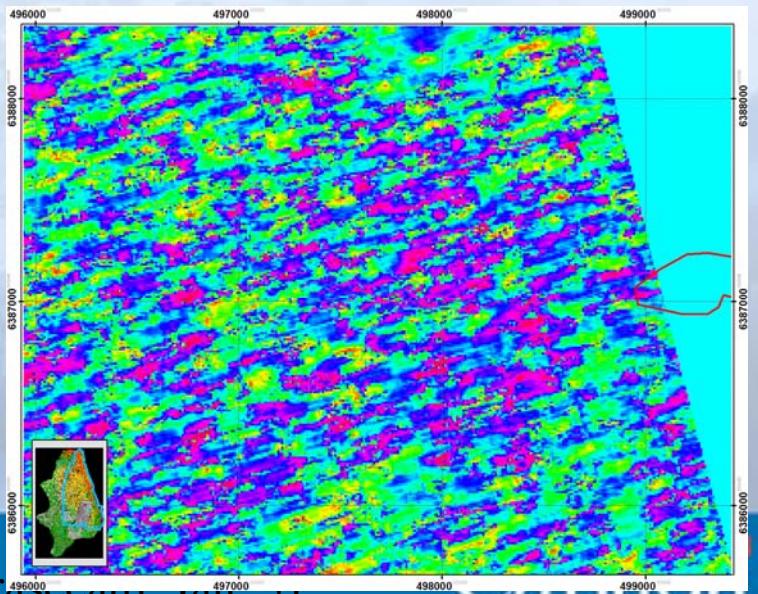
ALOS Touzi Decomposition- Phis1 (Jul. 2010)



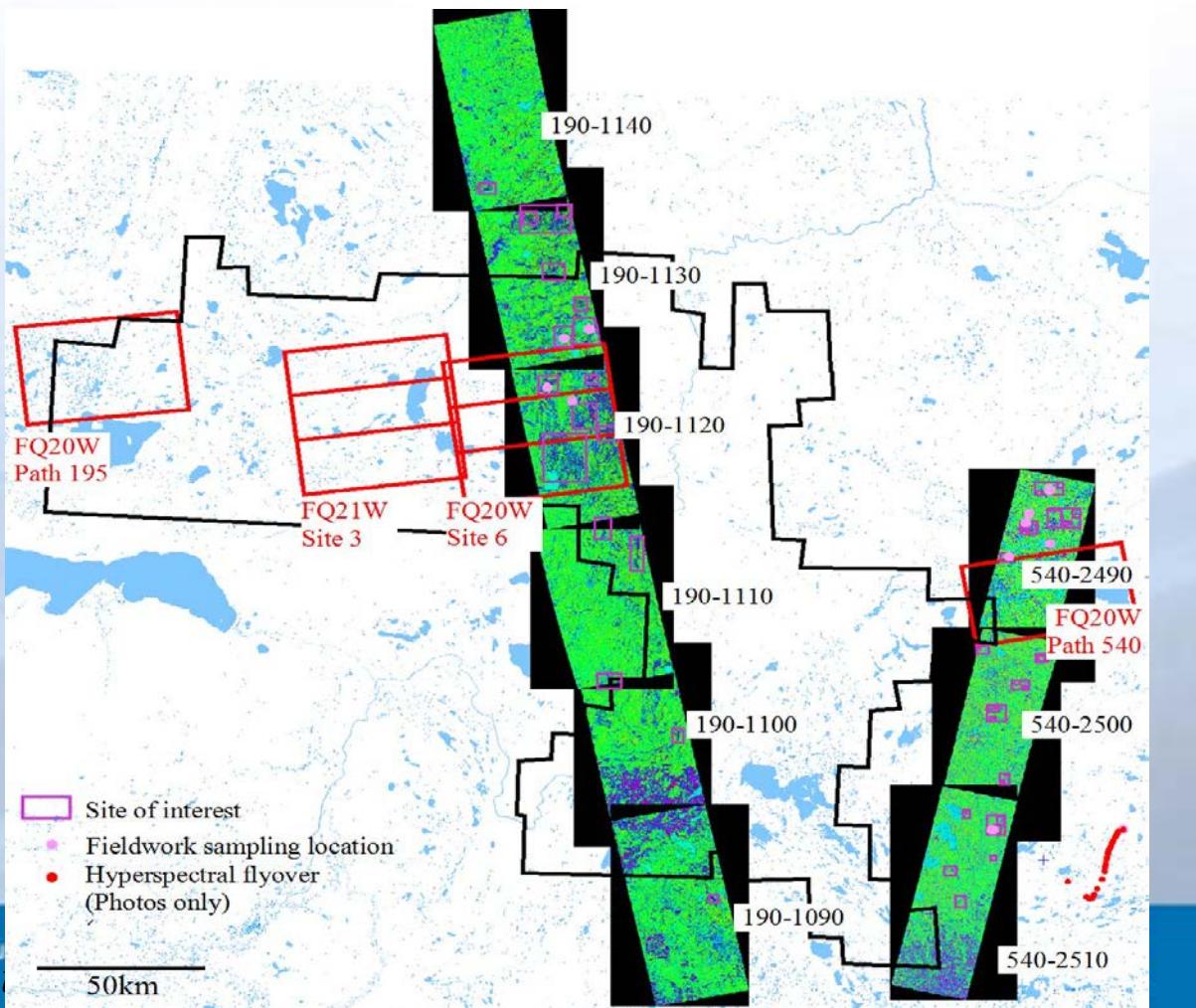
RS-2 Touzi Decomposition- Phis1 (Jun. 2010)



RS-2 Touzi Decomposition- Phis1 (Jul. 2010)



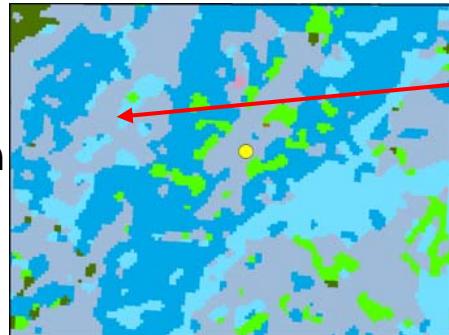
Investigation of Polarimetric ALOS and RS2 for peatland monitoring in the Athabasca Oil Sands Region



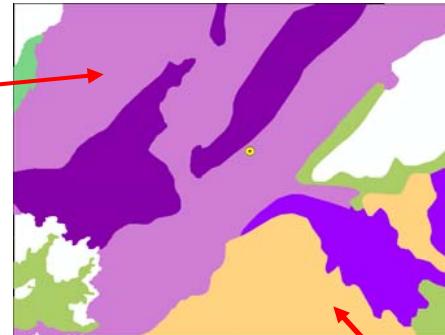
* Landsat=> Treed Fen confused with black Spruce Bog !!!

👉 Touzi ALOS phase ⇒ better class discrimination

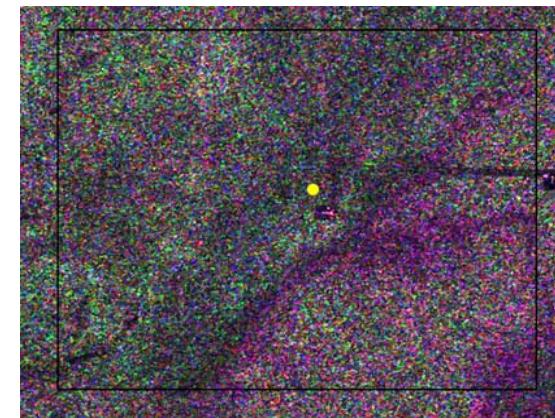
Landsat Classification



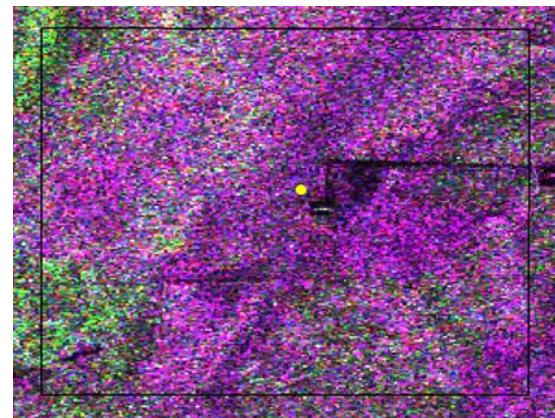
- Graminoid Wetlands
- Shrubby Wetlands
- Black Spruce Bog
- Closed White Spruce
- Closed Jack Pine



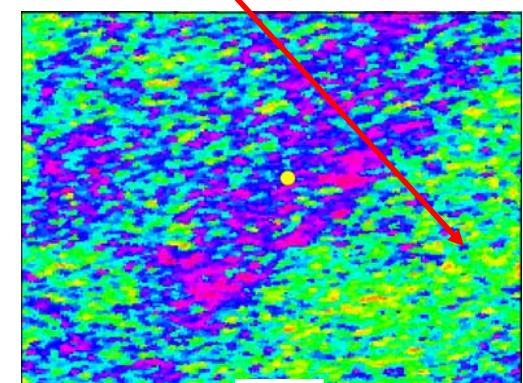
Wetland Inventory



RS2_RGB (R:HH, G:HV, B:VV)



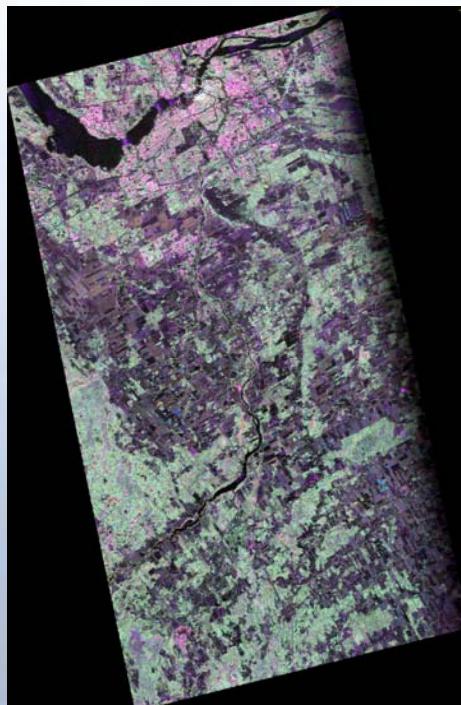
ALOS_RGB (R:HH, G:HV, B:VV)



$\Phi_{\alpha s1}$



Complementarity with the X-band High resolution TerraSAR (6.6mx1.18m)



ALOS



RADARSAT-2



TerraSAR-X
2010-05-10



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R. Touzi, PolInSAR 1G; Fraenetti, Jan. 31

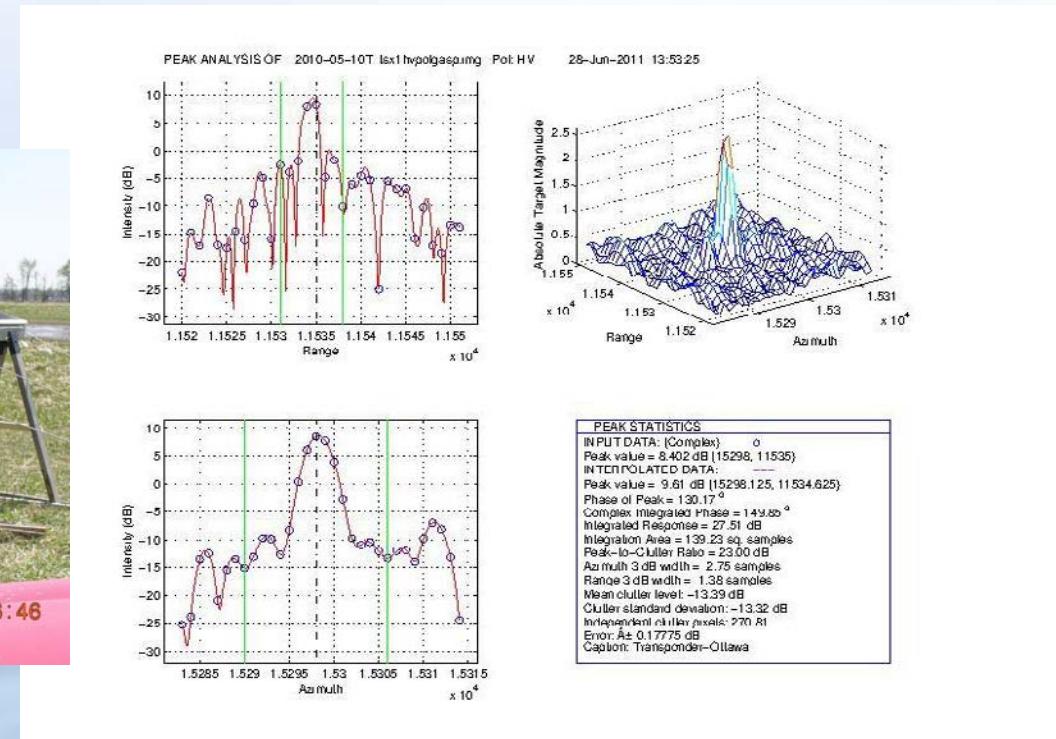
Canada



Calibration of Polarimetric TerraSAR



- 👉 Significant return at HV: -25dB X-talk should be removed
- ⇒ Touzi calibration method validated with ALOS and Radarsat2 => *IEEE TGRS* 2009, and *TGRS* 2013





Conclusion

- ▶ Polarimetric L-band PALSAR very promising for monitoring subarctic peatland & hydrology
- ▶ Touzi Φ_{as} sensitive to the water flow underneath peat
 - Peat thickness monitoring ➡ polar bear habitat
 - Monitoring of Bog-Fen transformation due to CC
- X-C-L band complementarities is being investigated using polarimetric PALSAR and Radarsat2 and TerraSAR
- ▶ Peatland Classification using optic sensors (Landsat) and polarimetric SAR for accurate peatland classification and bog-fen transformation monitoring
- ⇒ ALOS2 and Radarsat2: With Operational polarimetric capabilities and large swath (**50 km**)
- ⇒ Future L-band TerraSAR TDX with **Digital Antenna Beaming** ⇒ **500 km** swath
- ▶ Future missions L, C, and P band with **Digital Antenna Beaming** ➡ large swath

